## Construction of Lyapunov functions via relative entropy with application to caching

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## Outline



2 How to make the fixed point method work (sufficient condition)

#### 3 What: application to caching policy

#### 4 Conclusion

State space explosion and mean-field method



We need to keep track

$$\mathbb{P}(X_1(t)=i_1,\ldots,X_n(t)=i_n)$$

 $3^{13} \approx 10^6$  states.

State space explosion and mean-field method



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 $3^{13}\approx 10^6$  states.

The decoupling assumption is

 $\mathbb{P}(X_1(t) = i_1, \ldots, X_n(t) = i_n) \approx \mathbb{P}(X_1(t) = i_1) \ldots \mathbb{P}(X_n(t) = i_n)$ 

Problem: is this valid?

## Decoupling assumption: (always) valid in transient regime



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Decoupling assumption: (always) valid in transient regime

Theorem (Kurtz (70'), Benaim, Le Boudec (08),...)

For many systems and any fixed t, if  $x \mapsto xQ(x)$  is Lipschitz-continuous then, as the number of objects N goes to infinity:

$$\lim_{\mathsf{V}\to\infty}\mathbb{P}(X_k(t)=i)=x_{k,i}(t),$$

where x satisfies  $\dot{x} = xQ(x)$ .



#### The fixed point method

We know that  $x_i(t) \approx \mathbb{P}(X(t) = i)$  satisfies  $\dot{x} = xQ(x)$ .

Does 
$$\mathbb{P}(X = i)$$
 satisfies  $xQ(x) = 0$ ?

Method was used in many papers:

- Bianchi 00<sup>2</sup>
- Ramaiyan et al. 08<sup>3</sup>
- Kwak et al. 05<sup>4</sup>
- Kumar et al 08<sup>5</sup>

<sup>&</sup>lt;sup>2</sup>Performance analysis of the IEEE 802.11 distributed coordination function. – G. Bianchi. – IEEE J. Select. Areas Commun. 2000.

<sup>&</sup>lt;sup>3</sup>Fixed point analys is of single cell IEEE 802.11e WLANs: Uniqueness, multistability. – V. Ramaiyan, A. Kumar, and E. Altman. – ACM/IEEE Trans. Networking. Oct. 2008.

<sup>&</sup>lt;sup>4</sup>Performance analysis of exponential backoff. – B.-J. Kwak, N.-O. Song, and L. Miller. – ACM/IEEE Trans. Networking. 2005.

New insights from a fixed-point analysis of single cell IEEE 802.11 WLANs. – A. Kumar, E. Altman, D. Miorandi, and M. Goyal. – ACM/IEEE Trans. Networking 2007

It does not always work<sup>67</sup>



- Markov chain is irreducible.
- Unique fixed point xQ(x) = 0.

<sup>&</sup>lt;sup>6</sup>Benaim Le Boudec 08

<sup>&</sup>lt;sup>7</sup>Cho, Le Boudec, Jiang, On the Asymptotic Validity of the Decoupling Assumption for Analyzing 802.11 MAC Protoco. 2010

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	Fixed	point	Stat. measure			
	xQ(x) = 0		N = 1000			
	xs	хı	$\pi_S$	$\pi_I$		
a = .3	0.209	0.234	0.209	0.234		

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## It does not always work







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Link between the decoupling assumption and  $\dot{x} = xQ(x)$ 

$$\mathbb{P}(X_1(t)=i_1,\ldots,X_n(t)=i_n)\approx\underbrace{\mathbb{P}(X_1(t)=i_1)}_{=x_{1,i_1}(t)}\ldots\underbrace{\mathbb{P}(X_n(t)=i_n)}_{=x_{n,i_n}(t)}$$

When we zoom on one object

$$\mathbb{P}(X_1(t+dt)=j|X_1(t)=i)\approx\mathbb{E}\left[\mathbb{P}(X_1(t)=j|X_1=i\wedge X_2\ldots X_n)\right]\\\approx Q_{i,j}^{(1)}(\mathbf{x}):=\sum_{i_2\ldots i_n}K_{(i,i_2\ldots i_n)\to (j,j_2\ldots j_n)}x_{2,i_2}\ldots x_{n,i_n}$$

We then get: 
$$\frac{d}{dt} x_{1,j}(t) \approx \sum_{i} x_{1,i} Q_{i,j}^{(1)}(\mathbf{x})$$

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Markov chain

Transient regime $\dot{p} = pK$ I $t \to \infty$  $\downarrow$ Stationary $\pi K = 0$ 







Theorem ((i) Benaim Le Boudec 08,(ii) Le Boudec 12)

The stationary distribution  $\pi^N$  concentrates on the fixed points if : (i) All trajectories of the ODE converges to the fixed points. (ii) (or) The markov chain is reversible.

## Lyapunov functions

A solution of  $\frac{d}{dt}x(t) = xQ(x(t))$  converges to the fixed points of xQ(x) = 0, if there exists a Lyapunov function f, that is:

- Lower bounded:  $\inf_{x} f(x) > +\infty$
- Decreasing along trajectories:

$$\frac{d}{dt}f(x(t)) < 0,$$

whenever  $x(t)Q(x(t)) \neq 0$ .

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## How to find a Lyapnuov functionEnergy? Distance? Entropy? Luck?

# The relative entropy is a Lyapunov function for Markov chains

Let Q be the generator of an irreducible Markov chain and  $\pi$  be its stationary distribution. Let P(t) be the solution of  $\frac{d}{dt}P(t) = P(t)Q$ .

Theorem (e.g. Budhiraja et al 15, Dupuis-Fischer 11) The relative entropy $R(P||\pi) = \sum_{i} P_i \log \frac{P_i}{\pi_i}$ 

is a Lyapunov function:

 $\frac{d}{dt}R(P(t)\|\pi)<0,$ 

with equality if and only if  $P(t) = \pi$ .

## Relative entropy for mean-field models

Assume that Q(x) be a generator of an irreducible Markov chain and let  $\pi(x)$  be its stationary distribution. Let P(t) be the solution of  $\frac{d}{dt}P(t) = P(t)Q(P(t))$ . Then

$$\frac{d}{dt}R(P(t)||\pi(t)) = \underbrace{\frac{d}{dt}P(t)\frac{\partial}{\partial P}R(P(t),\pi(t))}_{\leq 0} + \underbrace{\frac{d}{dt}\pi(t)\frac{\partial}{\partial \pi}R(P(t),\pi(t))}_{=-\sum_{i}x_{i}(t)\frac{d}{dt}\log\pi_{i}(t)}$$
$$\leq -\sum_{i}x_{i}(t)\frac{d}{dt}\log\pi_{i}(t)$$

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#### Theorem

If there exists a lower bounded integral F(x) of  $-\sum_{i} x_i(t) \frac{d}{dt} \log \pi_i(t)$ , then  $x \mapsto R(x || \pi(x)) + F(x)$  is a Lyapunov function for the mean-field model.

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I consider a cache (virtually) divided into lists



IRM Probability request  $p_i$ RAND Upon hit/miss: Exchanged with random from next list.

data source

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IRM Probability request *p<sub>i</sub>* RAND Upon hit/miss: Exchanged with random from next list. I consider a cache (virtually) divided into lists



IRM Probability request *p<sub>i</sub>* RAND Upon hit/miss: Exchanged with random from next list.

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We construct the ODE by assuming independence Let  $H_i(t)$  be the popularity in list *i*.



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If  $x_{k,i}(t)$  is the probability that item k is in list i at time t:

$$\begin{split} \dot{x}_{k,i}(t) &= p_k x_{k,i-1}(t) - \underbrace{\sum_{j} p_j x_{j,i-1}(t)}_{i} \frac{x_{k,i}(t)}{m_i} \\ &+ \mathbf{1}_{\{i < h\}} \left( \underbrace{\sum_{j} p_j x_{j,i}(t)}_{i} \frac{x_{k,i+1}(t)}{m_{i+1}} - p_k x_{k,i}(t) \right) \end{split}$$

ODE of the type  $\dot{x} = xQ(x)$ .

#### Transient regime: this approximation is accurate

THEOREM 6. For any T > 0, there exists a constant C > 0 that depends on T such that, for any probability distribution over n items and list sizes  $m_1 \dots m_h$ , we have:

$$\mathbf{E}\left[\sup_{t\in\{0\dots\tau\},i\in\{0\dots h\}}|H_i(t)-\delta_i(t)|\right] \leq C\sqrt{\max_{k=1}^n p_k + \max_{i=0}^n \frac{1}{m_i}},$$

where  $\tau := \left\lceil T / (\max_{k=1}^{n} p_k + \max_{i=0}^{h} \frac{1}{m_i}) \right\rceil.$ 



#### Stationary distribution: uniqueness of the fixed point

THEOREM 7. The mean-field model (8) has a unique fixed point. For this fixed point, the probability that item k is part of list i, for k = 1, ..., n and i = 0, ..., h, is given by

$$x_{k,i} = \frac{p_k^i z_i}{1 + \sum_{j=1}^h p_k^j z_j},$$

where  $\mathbf{z} = (z_1, \ldots, z_h)$  is the unique solution of the equation

$$\sum_{k=1}^{n} \frac{p_k^i z_i}{1 + \sum_{j=1}^{h} p_k^j z_j} = m_i.$$
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• By simulation: very accurate

$m_1$	$m_2$	$m_3$	$m_4$	exact	mean field
2	2	96	-	0.3166	0.3169
10	30	60	-	0.3296	0.3299
20	$^{2}$	78	-	0.3273	0.3276
90	8	$^{2}$	-	0.4094	0.4100
1	4	10	85	0.3039	0.3041
5	15	25	55	0.3136	0.3139
25	25	25	25	0.3345	0.3348
60	$^{2}$	$^{2}$	36	0.3514	0.3517

#### Relative entropy for the caching model

The stationary measure  $\pi_{k,i}$  satisfy:  $\pi_{k,i}(\mathbf{x}) = \frac{\prod_{j=1}^{i-1} \lambda_{k,j} / \mu_j(\mathbf{x})}{\sum_{i'=1}^{h} \prod_{j=1}^{j'-1} \lambda_{k,j} / \mu_j(\mathbf{x})}.$  $\sum_{k=1}^{n} \sum_{k=1}^{n} x_{k,i}(t) \frac{d}{dt} \log(\pi_{k,i}(\mathbf{x}(t)))$  $=\sum_{i=1}^{h}\sum_{k=1}^{n}x_{k,i}(t)\frac{d}{dt}\log\left(\prod_{j=1}^{i-1}\mu_{j}(\mathbf{x})\right)$  $=m_{i}$  $\sum_{k=1}^{n} \sum_{i=1}^{h} x_{k,i}(t) \frac{d}{dt} \log \left( \sum_{j'=1}^{h} \prod_{j=1}^{j'-1} \lambda_{k,j} / \mu_j(\mathbf{x}) \right)$ 

• Very similar to (Fricker, G. 14), (Fricker et al. 12) (Tibi 11).

## Outline



2) How to make the fixed point method work (sufficient condition)

#### 3 What: application to caching policy



## Conclusion

- Decoupling assumption: OK in transient.
- The fixed point method is not always valid. We need either:
  - Reversibility
  - Lyapunov function
- To find Lyapunov functions: we need problem-specific.
  - Physics: energy.
  - Markov chains: relative entropy (since it it decrease along trajectories)

Yet... the method is not robust (e.g.: non-IRM, LRU instead of RAND)

## Thank you!

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#### Outline



**(5)** On the non-optimality of too many lists

Increasing the number of lists is not always better<sup>8</sup>

The scheme seems to sort the number of items from least popular to most popular:

less popular popular items
$$m_{1-} \cdots m_{j+1} \cdots m_{h}$$

Six lists: 
$$m = (1, 1, 1, 1, 1, 1)$$
 ?>?
 Three lists:  $m = (1, 1, 4)$ .

<sup>&</sup>lt;sup>8</sup>contrary to the conjecture of O. I. Aven, E. G. Coffman, Jr., and Y. A. Kogan. Stochastic Analysis of Computer Storage. Kluwer Academic Publishers, Norwell, MA, USA, 1987.

Increasing the number of lists is not always better

Six lists:  $\mathbf{m} = (1, 1, 1, 1, 1, 1)$ 

Three lists: m = (1, 1, 4).

policy	m	$M(\mathbf{m})$	lower bound
Optimal	RAND(1,1,4)	0.005284	0.004925
	$\operatorname{RAND}(1,1,3,1)$	0.005299	0.004884
	RAND(1,1,2,2)	0.005317	0.004884
	RAND(1,1,2,1,1)	0.005321	0.004879
	RAND(1,1,1,3)	0.005338	0.004884
	RAND(1,1,1,2,1)	0.005343	0.004879
	RAND(1,1,1,1,2)	0.005347	0.004879
CLIMB	RAND(1,1,1,1,1,1)	0.005348	0.004878
	RAND(1,2,3)	0.005428	0.004925
	RAND(1,2,2,1)	0.005439	0.004884
LRU	LRU(6)	0.005880	_
RANDOM	RAND(6)	0.015350	0.015350

Table 1: CLIMB is not optimal for IRM model: p = (49, 49, 49, 49, 7, 1, 1)/205 and m = 6.

Having 3 lists of sizes (1, 1, 4) is better than 6 lists of size 1. The same holds for the mean-field approximation.