The bias of mean field approximation

Nicolas Gast (Inria, Grenoble)

joint work with Sebastian Allmeier (Inria)

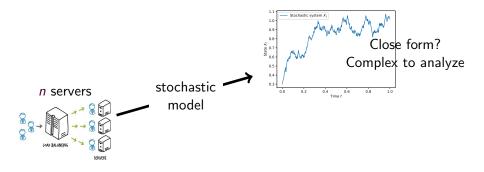
Séminaire Univ. Laval (Québec) April 2022

Motivation: Studying interacting particle systems

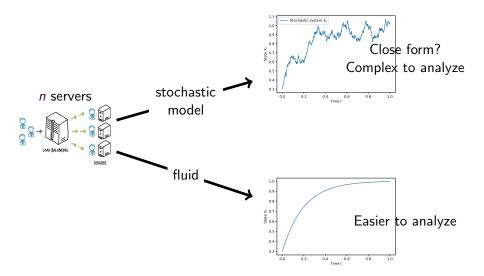


• Stochastic models are complex.

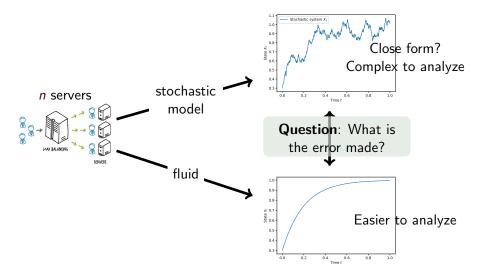
Fluid / mean field approximation simplifies the analysis



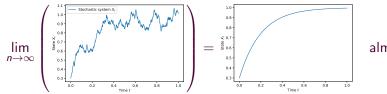
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Fluid approximation is often justified by a law of large numbers



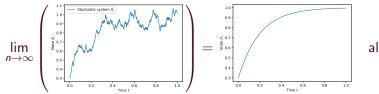
almost surely.

• Bound between X_t and $\phi_t(X_0)$ by using Gronwall's lemma.

$$X_t - X_0 - \int_0^t f(X_s) ds$$
 is a martingale.

• This gives a $O(1/\sqrt{n})$ convergence-rate.

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Talk: Explain mean-field approximation through examples.Show tools to provide sharp convergence results.

(Main) Related work

- Kurtz, 70s.
 - ► Fluid limits, diffusion limits (mostly transient regime)
- Application to queues
 - Fluid limits (Bramson, Dai 90s)
 - Interacting queues and mean-field: Load balancing (Mitzenmacher 01 + many recent)
- Stein's method:
 - Stein (1986)
 - ▶ Application to queueing: Braverman, Dai (2017–)
 - ► Application to mean-field models: Ying (2017).
- Refined mean field / Size expansions
 - ► Computational biology: Grima et al (2010s)
 - ► G. Van Houdt (2018), Allmeier G. (2021,2022).

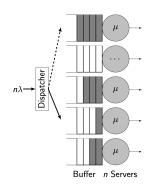
Outline

1 Mean field approximation in queueing theory

- 2 Guarantee of approximation for density dependent processes
- 3 Element of proofs: Generators and Stein's method
- 4 Conclusion

Example: SQ(2) model

Dispatcher sends to the shortest among two random queues.



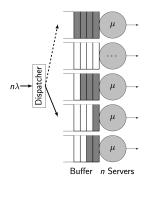
Natural Markov model: $(Q_1 \ldots Q_n)$.

• Complexity grows with *n*.

 $\mathbf{Q} = (4, 0, 3, 1, 2).$

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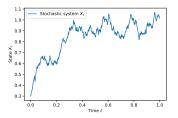
 $\mathbf{X} = (1, 0.8, 0.6, 0.4, 0.2, 0, \dots).$

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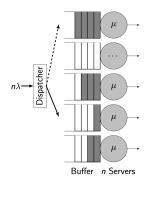
"Simplified" process: "empirical measure"

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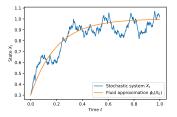
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How to construct the fluid approximation? (=hydrodynamic limit)

The transitions on X_i are:

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The fixed point is a good approximation of the average queue length:

n	10	100	1000	Fixed point	
Average queue length, $\lambda/\mu=0.9$	2.804	2.393	2.357	2.353	

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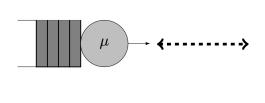
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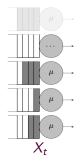
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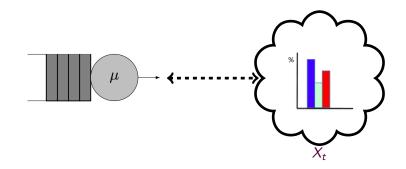
п	10	100	1000	Fixed point
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Bias	0.45	0.039	0.004	0

Why is this approximation called a "mean field approximation" (as in physics)





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- X_t is the law of the queue.
- The queue interacts with its law (McKean-Vlasov process).

This corresponds to assuming that queues are independent.

This extends to non-homogeneous settings

$$X_i^{(n)} = \frac{1}{n} \{ \# \text{ objects in state } i \} \implies X^{(n)} \text{ is not Markovian.}$$

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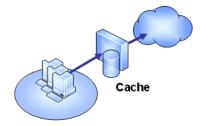
$$X_i^{(n)} = \frac{1}{n} \{ \# \text{ objects in state } i \} \implies X^{(n)} \text{ is not Markovian.}$$

The solution is to use *one-hot encoding*:

$$Y_{(k,i)} = \begin{cases} 1 & \text{if object } k \text{ is in state } i \text{ at time } t \\ 0 & \text{otherwise} \end{cases}$$

 $\mathbf{Y}^{(n)}$ is Markovian. We can construct a hydrodynamic limit for \mathbf{y} .

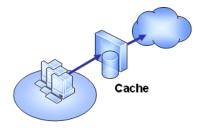
Example: cache replacement policies



Requests for k arrive at rate λ_k .

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Random replacement policy.

 $Y_k = 1$ if object k is in the cache.

$$\dot{y}_{k} = \underbrace{\lambda_{k}(1 - y_{k})}_{\text{object } k \text{ is requested while outside}} - \underbrace{\sum_{j} \lambda_{j}(1 - y_{j})}_{\text{another object enters}} \underbrace{\frac{y_{k}}{\# \text{ cache size}}}_{\text{object } k \text{ is replaced}}$$

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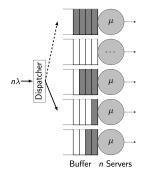
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Density dependent population process



Example: SQ(2) in the supermarket model

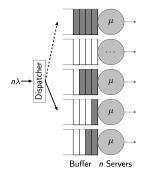
Mean Field Methodology: • $X_s^{(n)}(t) = \frac{1}{n} \{ \# \text{ objects in state } s \text{ at } t \}$

Kurtz's density dependent population model:

$$X^{(n)} o X^{(n)} + rac{1}{n} \ell$$
 at rate $neta_\ell(X)$

Drift :
$$f(x) = \sum_{\ell} \ell \beta_{\ell}(x)$$
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Drift :
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The mean field approximation is the solution of

of $\dot{x} = f(x)$

What is the bias of mean field approximaiton?

Consider a density dependent population process in \mathbb{R}^d and assume that $\beta_\ell(x)$ are bounded.

Theorem (G., Bortolussi, Tribastone 2019) If the drift is C^2 , there exists an (easily computable) vector V(t) such that for any finite time:

$$\mathbb{E}[X_t] = \underbrace{\phi_t(X_0)}_{\text{mean field approx.}} + \underbrace{\frac{1}{n}V(t)}_{\text{First order bias}} + O(\frac{1}{n^2})$$

This holds uniformly in time if the ODE has a unique exponentially stable attractor.

V(t) is the first-order expansion of the bias of the approximation.

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The expansion is in general very accurate for small n

n	10	100	1000	$+\infty$
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n	10	100	1000	$+\infty$
Average queue length for SQ(2), $ ho=0.9$	2.804	2.393	2.357	-
Refined approximation	2.751	2.393	2.357	2.353

where

- mean field = $\Phi_t(x)$.
- Refined = mean-field + V/n.

Intuition: Where does the 1/n term come from? The moment closure approach

Consider a system for which X becomes X + 1/n at rate nX^2 . We have:

 $\frac{d}{dt}\mathbb{E}\left[X\right] = \mathbb{E}\left[X^2\right]$

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(refined approximation)

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$$\frac{d}{dt}\mathbb{E}\left[X^{3}\right] = \mathbb{E}\left[\frac{3X^{4}}{n} + \frac{4X^{3}}{n^{2}} + \frac{X^{2}}{n^{3}}\right]$$

$$\vdots$$

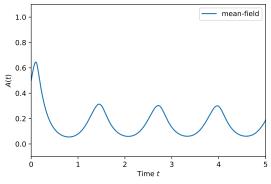
The moment equations are never closed.

- They can be closed by assuming $\mathbb{E}\left[(X \mathbb{E}[X])^d\right] \approx 0$
- This gives a $O(1/n^{\lfloor (d+1)/2 \rfloor})$ -accurate approximation.

Does it always work?

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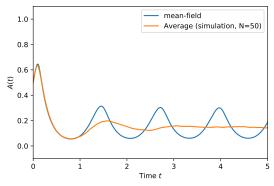
• Interchange of limit : does $\lim_{N \to \infty} \lim_{t \to \infty} = \lim_{t \to \infty} \lim_{N \to \infty} ?$



Example: SIR model with cyclic behavior.

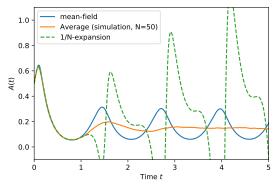
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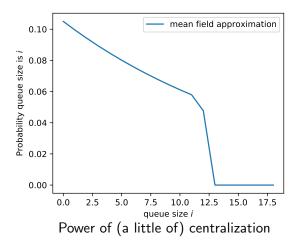
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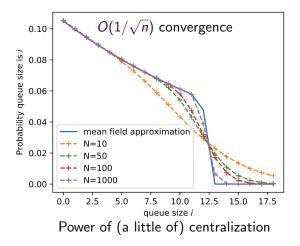
- Interchange of limit
- 2 Non-smooth dynamics

Xu, Tsitsiklis 2011



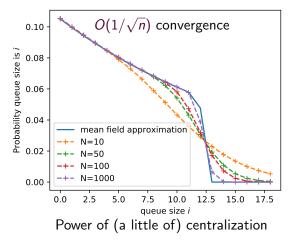
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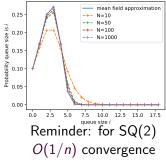
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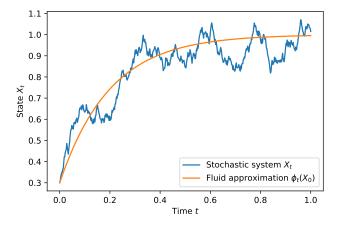
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We compare a stochastic system and a fluid approximation

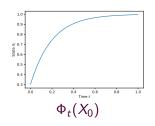


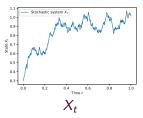
Important notations:

- Stochastic system $X_t \in \mathcal{X}$.
- Fluid approximation $\dot{x} = f(x)$. Solution starting from X_0 is $\phi_t(X_0)$.

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To compare X_t and $\phi_t(X_0)$, we zoom on infinitesimal changes

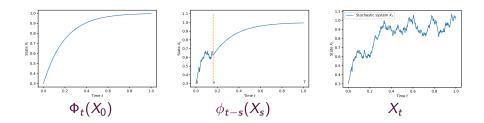




We want to compare:

 $\mathbb{E}\left[X_t\right] - \phi_t(X_0)$

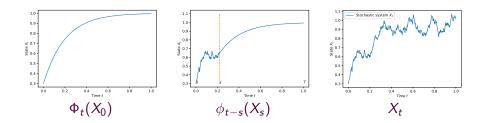
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$$\mathbb{E}[X_t] - \phi_t(X_0) = \int_0^t \mathbb{E}\left[\frac{d}{ds}\phi_{t-s}(X_s)\right] ds$$

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To study infinitesimal changes, we need generators

 G^{sto} Generator of the stochastic system. For a test function $h: \mathcal{X} \to \mathbb{R}$:

$$G^{\mathrm{sto}}h(x) = \lim_{t\to 0} \frac{1}{t}\mathbb{E}\left[h(X_t) - h(X_0) \mid X_0 = x\right].$$

Example: if X_t is a Markov chain of generator K:

$$G^{\mathrm{sto}}h(x) = \sum_{y \in \mathcal{X}} K_{xy}(h(y) - h(x)).$$

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 G^{ODE} Generator of the ODE. For a test function $h: \mathcal{X} \to \mathbb{R}$:

$$G^{\text{ODE}}h(x) = \lim_{t \to 0} \frac{1}{t} (h(\Phi_t(x)) - h(x))$$
$$= \nabla h(x) \cdot f(x).$$

Typically $f(x) = G^{\text{sto}}I(x)$, where I is the identity function.

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Nicolas Gast - 22 / 29

Using the generators, we can compare the two systems

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In particular:

$$\mathbb{E}[X_t] - \phi_t(X_0) = \int_0^t \mathbb{E}\left[(G^{\text{sto}} - G^{\text{ODE}})\phi_{t-s}(X_s) \right] ds$$
$$= (G^{\text{sto}} - G^{\text{ODE}}) \int_0^t \mathbb{E}\left[\phi_{t-s}(X_s)\right] ds$$

(Taking the limit $t \to \infty$, we obtain Stein's method).

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Recap

For finite *t*:

$$\underbrace{\mathbb{E}\left[X_{t}\right]}_{\text{Stochastic system}} - \underbrace{\phi_{t}(X_{0})}_{\text{deterministic approx.}} = (G^{\text{sto}} - G^{\text{ODE}}) \int_{0}^{t} \mathbb{E}\left[\phi_{t-s}(X_{s})\right] ds$$

For $t = +\infty$, if $x^* = \phi_{\infty}(X_0)$ does not depend on X_0 , we have:

$$\underbrace{\mathbb{E}\left[h(X_{\infty})\right]}_{\text{Starbatic actor deterministic approx}} - \underbrace{h(x^*)}_{\text{deterministic approx}} = (G^{\text{sto}} - G^{\text{ODE}}) \int_0^\infty \mathbb{E}\left[\phi_t(X_{\infty})\right] ds.$$

Stochastic system deterministic approx.

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To prove that the sto \approx deterministic, we prove that: • for some $h \in \mathcal{H}$, $(G^{\text{sto}} - G^{\text{ODE}})h$ is small. • $\int_0^t \mathbb{E}[\phi_{t-s}]$ or $\int_0^\infty \mathbb{E}[\phi_t]$ belongs to this \mathcal{H} .

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Application to density dependent population processes (1/2)

The generator of the density dependent population process is:

$$G^{\text{sto}}h(x) = \sum_{\ell} \left(h(x + \frac{1}{n}\ell) - h(x) \right) n\beta_{\ell}(x)$$

= $\underbrace{\nabla h \cdot f(x)}_{\text{generator of the ODE, } G^{\text{ODE}}} + \frac{1}{n} \underbrace{\nabla^2 h \cdot Q(x)}_{\text{Diffusion term}} + O(1/n^2).$

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= $\underbrace{\nabla h \cdot f(x)}_{\text{generator of the ODE, } G^{\text{ODE}}} + \frac{1}{n} \underbrace{\nabla^2 h \cdot Q(x)}_{\text{Diffusion term}} + O(1/n^2).$

As a consequence

• $(G^{\text{sto}} - G^{\text{ODE}})h = O(1/n)$ if h is C^2 . \Rightarrow Set \mathcal{H} of slide 24 is C^2 .

• The hidden constant depends on $\|\nabla^2 h \cdot Q\|$. Studying this gives V(t).

Consequence for the error of mean field model (2/2)

• For finite-horizon, the function $h(x) = \int_0^r \phi_s(x) ds$ is C^2 if the drift function f is C^2 .

• For infinite-horizon model, $h(x) = \int_0^\infty (\phi_s(x) - x^*) ds$ is C^2 if in addition x^* is an exponentially stable attractor.

The two functions belongs to " \mathcal{H} " \Rightarrow Error = O(1/n).

Some historical remarks

- Ying 2016: L_2 error is $O(1/\sqrt{n})$ for steady-state.
- G. 2017: Bias is O(1/n).
- G. 2018, 2019: Expansion terms for the bias.
- G. Allmeier 2022: Extension to heterogeneous models.

More recently:

- This works for heterogeneous models.
- Error bounds for averaging methods (multi-scale models)

Outline

1 Mean field approximation in queueing theory

2 Guarantee of approximation for density dependent processes

3 Element of proofs: Generators and Stein's method



Conclusion

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We question its validity / accuracy.

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Many open questions: optimization (bandit problems), (sparse) geometric models, non-Markovian.

Slides and references: http://polaris.imag.fr/nicolas.gast

References

Results on which this talk is based:

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- A Refined Mean Field Approximation by Gast and Van Houdt. SIGMETRICS 2018 (best paper award)
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Paper cited as open problems:

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