## Computing the bias of mean field approximation

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### Stochastic information models on 'dense' graphs



- Propagation of an information over time
- Steady-state properties (e.g. % of informed people)

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Objective of the talk (and outline)

1 What is mean field approximation?

2 How to characterize the bias of this approximation?





## Outline

#### 1 What is mean field approximation?

2 How to characterize the bias of this approximation?

#### 3 What about multiscale models?

#### 4 Conclusion

Running example: Simple information propagation model.



Population of n persons where each person can be "Informed" or "Outdated". x is the proportion of "informed" people.

- Informed persons loose information at rate 1.
- Outdated persons become informed at rate 1 + x

#### Stochastic model

If X is the proportion of "informed" people, then:

$$X \mapsto X - \frac{1}{n}$$
 at rate  $nX$   
 $X \mapsto X + \frac{1}{n}$  at rate  $n(1 - X^2) = n(1 - X)(1 + X)$ 



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 at rate  $nX$  average change:  $-X$   
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• The transient regime.

• The fixed point:  
$$x(\infty) = (\sqrt{5} - 1)/2$$

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How accurate is this approximation?

## Accuracy of the mean field approximation

n	5	10	100	$\infty$
$\mathbb{P}(someone informed)$	0.593	0.601	0.61679642	$(\sqrt{5}-1)/2 \approx 0.618.$
Error	0.025	0.125	0.0012	0

Table: Steady-state values

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Theorem: (G. Bortolussi, Tribastone) For this model, if  $\mathbb{E}\left[X^{(n)}\right]$  is the probability that someone is "informed" and if the  $x(\infty) = (\sqrt{5} - 1)/2$  is the mean field approximation, then:

$$\mathbb{E}\left[X^{(n)}\right] = x(\infty) + \frac{1}{20n}(\sqrt{5}-1) + \frac{1}{50n^2}(\sqrt{5}-3) + O(1/n^3).$$

## Outline



#### 2 How to characterize the bias of this approximation?





We study a generic interaction model

We consider a population of n objects with two types of interactions:

• Unilateral transitions:

Object k jumps from state i to j at rate  $r_{ii}^{(k)}$ 

• Pairwise interactions:

Object k, k' simultaneously jump from states (i, i') to (j, j') at rate  $r_{ij,i'j'}^{(k,k')}/n$ 

If the rates do not depend on k, we call the model homogeneous.

#### Mean field approximation for homogeneous models

$$X_s^{(n)}(t) = \frac{1}{n} \{ \# \text{ objects in state } s \text{ at } t \}$$

The transitions are:

$$\mathbf{X}^{(n)} 
ightarrow \mathbf{X}^{(n)} + rac{1}{n}(e_j - e_i)$$
 at rate  $nr_{ij}X_i$ .  
 $\mathbf{X}^{(n)} 
ightarrow \mathbf{X}^{(n)} + rac{1}{n}(e_j - e_i + e_{j'} - e_{i'})$  at rate  $nr_{ij,i'j'}X_iX_{i'}$ .

This is a density dependent population process (Kurtz 70s).

(one example is our information propagation model)

## Mean field method for non-homogeneous models

$$X_s^{(n)}(t) = \frac{1}{n} \{ \# \text{ objects in state } s \text{ at } t \} \Rightarrow X^{(n)} \text{ is not Markovian.}$$

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Solution: represent model using indicators:

$$Y_{(k,s)}^{(n)}(t) = \begin{cases} 1 & \text{if object } k \text{ is in state } s \text{ at time } t \\ 0 & \text{otherwise} \end{cases}$$

 $\mathbf{Y}^{(n)}$  is Markovian.

$$\begin{split} \mathbf{Y}^{(n)} &\to \mathbf{Y}^{(n)} + e_{k,j} - e_{k,i} & \text{at rate } r_{ij}^{(k)} Y_{k,i}. \\ \mathbf{Y}^{(n)} &\to \mathbf{Y}^{(n)} + e_{k,j} - e_{k,i} + e_{k',j'} - e_{k',i'} & \text{at rate } \frac{1}{n} r_{ij,i'j'}^{(k,k')} Y_{k,i} Y_{k',i'}. \end{split}$$

# Mean field approximaiton and result

The drift is:

 $f(\mathbf{y}) = \sum_{\text{all transitions}} \text{Transition change for } \mathbf{y} \times \text{Rate of transition at } \mathbf{y}.$ 

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Theorem (Allmeier, G. 2022) There exists an (easily computable) vector V(t) such that for any finite time:

**P** [Object k is in state s at t] =  $y_{k,s}(t) + \frac{1}{n}V_{k,s}(t) + O(\frac{1}{n^2})$ .

 $V_{k,s}(t)$  is the bias of the mean field approximation.

## Idea of proof

• We can show that  $\operatorname{cov}(Y_{k,s}Y_{k',s'})(t) = \frac{1}{n}W(t) + O(1/N^2)$ , where W(t) satisfies a (time inhomogeneous) linear ODE:

$$\dot{W} = A(y(t))W + WA^{T}(y(t)) + Q(x(t)).$$

• We then have  $\mathbb{E}[Y_{k,s}(t)] = y(t) + V(t)$ , where V(t) satisfies a (time inhomogeneous) linear ODE:

$$\dot{V} = A(y(t))V + B(x(t)) \cdot W(t).$$

The moment closure approach

Consider a system for which X becomes X + 1/n at rate  $nX^2$ . We have:

 $\frac{d}{dt}\mathbb{E}\left[X\right] = \mathbb{E}\left[X^2\right]$ 

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$$\frac{d}{dt}\mathbb{E}\left[X^2\right] = 2\mathbb{E}\left[X^3\right] + \frac{1}{n}\mathbb{E}\left[X^2\right]$$

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(refined approximation)

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$$\frac{d}{dt}\mathbb{E}\left[X^{3}\right] = \mathbb{E}\left[\frac{3X^{4}}{n} + \frac{4X^{3}}{n^{2}} + \frac{X^{2}}{n^{3}}\right]$$

$$\vdots$$

The moment equations are never closed.

- They can be closed by assuming  $\mathbb{E}\left[(X \mathbb{E}[X])^d\right] \approx 0$
- This gives a  $O(1/n^{\lfloor (d+1)/2 \rfloor})$ -accurate approximation.

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Communication with interference



Interference graph.

n nodes per class A, B or C

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Interference graph.

n nodes per class A, B or C

State is X, Y

- $X_{i,s}$  = proportion of nodes of class *i* with  $\geq S$  messages.
- $Y_i = 1$  if class i talks.



This is a two timescale model "Fast process": Y. ((0,1,0) This is a two timescale model



"Slow process": X.

Arrival/departure:

$$X_{i,s} \mapsto X_{i,s} \pm \frac{1}{n}$$

Rate depends on y.

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Two approximations:  $\mathbf{P}[Y(t) = y] \approx \pi_y(X(t))$  | Drift f(X, Y)

$$\dot{x} = \sum_{y} \pi_{y}(x) f(x, y)$$
(Averaging technique):

## Accuracy results (Allmeier, G. 2022)

Theorem. If X(t) is the two timescale process, if the rates are twice differentiable and the evolution the the fast process is "unichain", then:

$$\mathbb{E}[X(t)] = x(t) + \frac{1}{n}C(t) + O(1/n^2).$$

Holds uniformly in time if the ODE has an exponentially stable attractor.

## Numerical example

With n = 1 node per class!



Jobs arrive at rate 1, activation rate = 3. Job duration is 1/3.

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- Numerical library: https://pypi.org/project/rmftool/

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We question its validity / accuracy.

- We characterize the bias for different models (smooth homogeneous, heterogeneous, multi-scale).
- To do so, we take correlations into account.
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Many open questions: (sparse) geometric models, non-Markovian, controlled systems

More slides and references: http://polaris.imag.fr/nicolas.gast

#### References

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Paper cited as open problems:

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