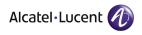
# Eigen-Inference Statistical Methods for Cognitive Radio

Romain Couillet<sup>1,2</sup>, Mérouane Debbah<sup>1</sup>

<sup>1</sup>Alcatel-Lucent Chair on Flexible Radio, Supélec, Gif sur Yvette, FRANCE <sup>2</sup>ST-Ericsson, Sophia-Antipolis, FRANCE {romain.couillet,merouane.debbah}@supelec.fr

European Wireless





# Outline

# Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

# Bandom Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## Bandom Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

# Outline

# Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

#### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

C. E. Shannon, "A Mathematical Theory of Communication," Bell System Technical Journal, 1948.

N. Wiener, "Cybernetics, or Control and Communication in the Animal and the Machine," Herman et Cie, The Technology Press, 1948.



Claude Shannon, 1916-2001



Norbert Wiener, 1894-1964

#### Shannon, Wiener and Cognitive Radios Information and Noise against Black Box and Feedback

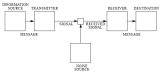


Fig. 1-Schematic diagram of a general communication system

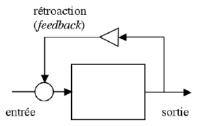


FIG. 1 – Boucle de rétroaction

(I) < ((()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) <

# Shannon, Wiener and Cognitive Radios 2008: 60 years later... MIMO Random Networks



( ) < </p>

# Shannon, Wiener and Cognitive Radios 2008: 60 years later... MIMO Random Networks



( ) < </p>

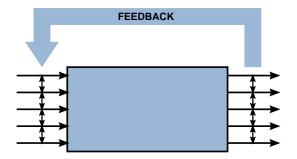
# Shannon, Wiener and Cognitive Radios 2008: 60 years later... MIMO Random Networks

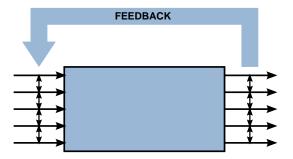


# 2008: 60 years later... Flexible MIMO Random Networks



2008: 60 years later... Flexible MIMO Random Networks

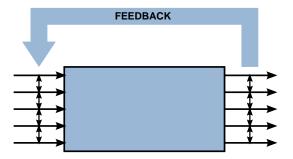




#### We must learn and control the black box

- within a fraction of time
- with finite energy.

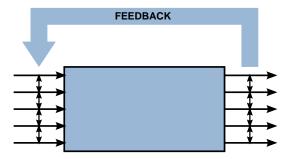
In many cases, the number of inputs/outputs (the dimensionality of the system) is of the same order as the time scale changes of the box.



We must learn and control the black box

- within a fraction of time
- with finite energy.

In many cases, the number of inputs/outputs (the dimensionality of the system) is of the same order as the time scale changes of the box.

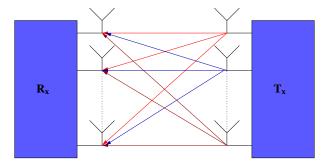


We must learn and control the black box

- within a fraction of time
- with finite energy.

In many cases, the number of inputs/outputs (the dimensionality of the system) is of the same order as the time scale changes of the box.

# Shannon. Wiener and Cognitive Radios Example: Multi-antenna systems

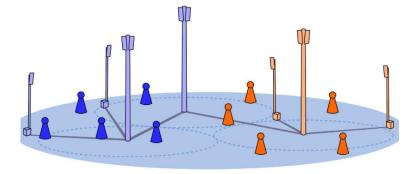


э

590

< □ > < □ > < □ > < □ > < □ >

# Shannon, Wiener and Cognitive Radios Example: Cognitive Network MIMO



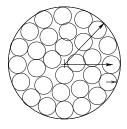
12/04/2010 13 / 110

( ) < </p>





 $C = H(\mathbf{y}) - H(\mathbf{y} \mid \mathbf{x})$ = log det (\pi e \mathbf{R}\_y) - log det (\pi e \mathbf{R}\_n)



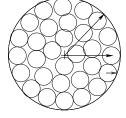
$$C = \log\left(\frac{\det\left(\mathbf{R}_{y}\right)}{\det\left(\mathbf{R}_{n}\right)}\right)$$

(a)





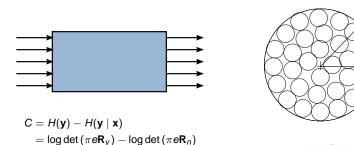
 $C = H(\mathbf{y}) - H(\mathbf{y} \mid \mathbf{x})$  $= \log \det (\pi e \mathbf{R}_y) - \log \det (\pi e \mathbf{R}_y)$ 





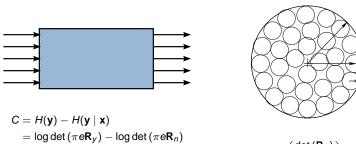
(日)

12/04/2010 14 / 110



$$C = \log\left(\frac{\det\left(\mathbf{R}_{Y}\right)}{\det\left(\mathbf{R}_{n}\right)}\right)$$

 $\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$ 



 $C = \log\left(\frac{\det\left(\mathbf{R}_{y}\right)}{\det\left(\mathbf{R}_{n}\right)}\right)$ 

イロト イヨト イヨト イヨト

 $\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$ 

#### Shannon. Wiener and Coantilve Radios Understanding the network in a finite time

$$\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$$

$$Rate = \log \frac{\det (\mathbf{R}_{y})}{\det (\mathbf{R}_{n})}$$

In the Gaussian case, one can write

$$\mathbf{y}_i = \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} \mathbf{u}_{\mathbf{i}}$$

where **u**<sub>i</sub> is zero mean i.i.d Gaussian.

One has only n samples:

$$\hat{\mathbf{R}} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{y}_i \mathbf{y}_i^H = \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} (\frac{1}{L} \mathbf{U} \mathbf{U}^H) \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} \rightarrow \frac{1}{L} \mathbf{U} \mathbf{U}^H \mathbf{R}_{\mathbf{y}}$$

• The non-zero eigenvalues of  $\hat{\mathbf{R}}$  are the same as the eigenvalues of  $\frac{1}{T} \mathbf{U} \mathbf{U}^{H} \mathbf{R}_{\mathbf{y}}$ .

• We know the eigenvalues of  $\frac{1}{T}UU^{H}$  and  $\hat{R}$ . Can we determine the eigenvalues of  $R_{y}$ ?

#### Shannon. Wiener and Coantilve Radios Understanding the network in a finite time

$$\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$$

$$Rate = \log \frac{\det(\mathbf{R_y})}{\det(\mathbf{R_n})}$$

In the Gaussian case, one can write

$$\mathbf{y}_i = \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} \mathbf{u}_{\mathbf{i}}$$

where  $\mathbf{u}_i$  is zero mean i.i.d Gaussian.

• One has only *n* samples:

$$\hat{\mathbf{R}} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{y}_i \mathbf{y}_i^H = \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} (\frac{1}{L} \mathbf{U} \mathbf{U}^H) \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} \rightarrow \frac{1}{L} \mathbf{U} \mathbf{U}^H \mathbf{R}_{\mathbf{y}}$$

• The non-zero eigenvalues of  $\hat{\mathbf{R}}$  are the same as the eigenvalues of  $\frac{1}{T}\mathbf{U}\mathbf{U}^{H}\mathbf{R}_{y}$ .

• We know the eigenvalues of  $\frac{1}{7}UU^{H}$  and  $\hat{R}$ . Can we determine the eigenvalues of  $R_{v}$ ?

#### Shannon. Wiener and Coantilve Radios Understanding the network in a finite time

$$\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$$

$$\text{Rate} = \text{log}\,\frac{\text{det}\,(\textbf{R}_{\textbf{y}})}{\text{det}\,(\textbf{R}_{\textbf{n}})}$$

In the Gaussian case, one can write

$$\mathbf{y}_i = \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} \mathbf{u}_{\mathbf{i}}$$

where  $\mathbf{u}_i$  is zero mean i.i.d Gaussian.

• One has only *n* samples:

$$\hat{\mathbf{R}} = \frac{1}{n} \sum_{i=1}^{n} \mathbf{y}_i \mathbf{y}_i^H = \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} (\frac{1}{L} \mathbf{U} \mathbf{U}^H) \mathbf{R}_{\mathbf{y}}^{\frac{1}{2}} \rightarrow \frac{1}{L} \mathbf{U} \mathbf{U}^H \mathbf{R}_{\mathbf{y}}$$

- The non-zero eigenvalues of  $\hat{\mathbf{R}}$  are the same as the eigenvalues of  $\frac{1}{T}\mathbf{U}\mathbf{U}^{H}\mathbf{R}_{y}$ .
- We know the eigenvalues of  $\frac{1}{L}UU^{H}$  and  $\hat{R}$ . Can we determine the eigenvalues of  $R_{y}$ ?

 $\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$ 

The capacity per dimension is given by:

$$C = \frac{1}{N}\log\det\left(\mathbf{I} + \frac{1}{\sigma^2}\mathbf{W}\mathbf{W}^H\right) = \frac{1}{N}\sum_{i=1}^N\log(1 + \frac{1}{\sigma^2}\lambda_i) = \int\log(1 + \frac{1}{\sigma^2}\lambda)f^N(\lambda)d\lambda$$

with

$$f^N(\lambda) = \frac{1}{N} \sum_{i=1}^N \delta(\lambda - \lambda_i)$$

All we need to know is how the empirical eigenvalue distribution behaves. It is often sufficient to determine the moments  $M_1^N, M_2^N, \ldots$ 

$$M_k^N = \frac{1}{N} \sum_{i=1}^N \lambda_i^k$$

Sometimes, we need more involved tools, such as Fourier transform, or Stieltjes transform...

・ロト ・回ト ・ヨト ・ヨト

 $\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$ 

The capacity per dimension is given by:

$$C = \frac{1}{N}\log\det\left(\mathbf{I} + \frac{1}{\sigma^2}\mathbf{W}\mathbf{W}^H\right) = \frac{1}{N}\sum_{i=1}^N\log(1 + \frac{1}{\sigma^2}\lambda_i) = \int\log(1 + \frac{1}{\sigma^2}\lambda)f^N(\lambda)d\lambda$$

with

$$f^N(\lambda) = \frac{1}{N} \sum_{i=1}^N \delta(\lambda - \lambda_i)$$

All we need to know is how the empirical eigenvalue distribution behaves. It is often sufficient to determine the moments  $M_1^N, M_2^N, \ldots$ 

$$M_k^N = \frac{1}{N} \sum_{i=1}^N \lambda_i^k$$

Sometimes, we need more involved tools, such as Fourier transform, or Stieltjes transform...

$$\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$$

The capacity per dimension is given by:

$$C = \frac{1}{N}\log\det\left(\mathbf{I} + \frac{1}{\sigma^2}\mathbf{W}\mathbf{W}^H\right) = \frac{1}{N}\sum_{i=1}^N\log(1 + \frac{1}{\sigma^2}\lambda_i) = \int\log(1 + \frac{1}{\sigma^2}\lambda)f^N(\lambda)d\lambda$$

with

$$f^N(\lambda) = \frac{1}{N} \sum_{i=1}^N \delta(\lambda - \lambda_i)$$

All we need to know is how the empirical eigenvalue distribution behaves. It is often sufficient to determine the moments  $M_1^N, M_2^N, \dots$ 

$$M_k^N = \frac{1}{N} \sum_{i=1}^N \lambda_i^k$$

Sometimes, we need more involved tools, such as Fourier transform, or Stieltjes transform...

$$\mathbf{y} = \mathbf{W}\mathbf{x} + \mathbf{n}$$

The capacity per dimension is given by:

$$C = \frac{1}{N}\log\det\left(\mathbf{I} + \frac{1}{\sigma^2}\mathbf{W}\mathbf{W}^H\right) = \frac{1}{N}\sum_{i=1}^N\log(1 + \frac{1}{\sigma^2}\lambda_i) = \int\log(1 + \frac{1}{\sigma^2}\lambda)f^N(\lambda)d\lambda$$

with

$$f^N(\lambda) = \frac{1}{N} \sum_{i=1}^N \delta(\lambda - \lambda_i)$$

All we need to know is how the empirical eigenvalue distribution behaves. It is often sufficient to determine the moments  $M_1^N, M_2^N, \dots$ 

$$M_k^N = \frac{1}{N} \sum_{i=1}^N \lambda_i^k$$

Sometimes, we need more involved tools, such as Fourier transform, or Stieltjes transform...

# Outline

# Shannon, Wiener and Cognitive Radios

# Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

#### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

Image: A matrix

# Outline

# Shannon, Wiener and Cognitive Radios

#### Tools for Random Matrix Theory

## Introduction to Large Dimensional Random Matrix Theory

- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

#### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

Image: A matrix

Let  $\mathbf{w}_1, \mathbf{w}_2 \ldots \in \mathbb{C}^N$  be independently drawn from an *N*-variate process of mean zero and covariance  $\mathbf{R} = \mathrm{E}[\mathbf{w}_1\mathbf{w}_1^H] \in \mathbb{C}^{N \times N}$ .

#### Law of large numbers

As  $n \to \infty$ ,

$$\frac{1}{n}\sum_{i=1}^{n}\mathbf{w}_{i}\mathbf{w}_{i}^{\mathsf{H}}=\mathbf{W}\mathbf{W}^{\mathsf{H}}\xrightarrow{\text{a.s.}}\mathbf{R}$$

In reality, one cannot afford  $n \to \infty$ .

• if  $n \gg N$ ,

$$\mathbf{R}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{w}_i \mathbf{w}_i^{\mathsf{H}}$$

is a "good" estimate of R.

• if N/n = O(1), and if both (n, N) are large, we can still say, for all (i, j),

$$(\mathbf{R}_n)_{ij} \stackrel{\mathrm{a.s.}}{\longrightarrow} (\mathbf{R})_{ij}$$

What about the global behaviour? What about the eigenvalue distribution?

・ロト ・回ト ・ヨト ・ヨト

Let  $\mathbf{w}_1, \mathbf{w}_2 \ldots \in \mathbb{C}^N$  be independently drawn from an *N*-variate process of mean zero and covariance  $\mathbf{R} = \mathrm{E}[\mathbf{w}_1\mathbf{w}_1^H] \in \mathbb{C}^{N \times N}$ .

Law of large numbers

As  $n \to \infty$ ,

$$\frac{1}{n}\sum_{i=1}^{n}\mathbf{w}_{i}\mathbf{w}_{i}^{\mathsf{H}}=\mathbf{W}\mathbf{W}^{\mathsf{H}}\xrightarrow{\text{a.s.}}\mathbf{R}$$

In reality, one cannot afford  $n \to \infty$ .

• if  $n \gg N$ ,

$$\mathbf{R}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{w}_i \mathbf{w}_i^{\mathsf{H}}$$

is a "good" estimate of R.

• if N/n = O(1), and if both (n, N) are large, we can still say, for all (i, j),

 $(\mathbf{R}_n)_{ij} \stackrel{\mathrm{a.s.}}{\longrightarrow} (\mathbf{R})_{ij}$ 

What about the global behaviour? What about the eigenvalue distribution?

・ロ・ ・ 四・ ・ ヨ・ ・ ヨ・

Let  $\mathbf{w}_1, \mathbf{w}_2 \ldots \in \mathbb{C}^N$  be independently drawn from an *N*-variate process of mean zero and covariance  $\mathbf{R} = \mathrm{E}[\mathbf{w}_1\mathbf{w}_1^H] \in \mathbb{C}^{N \times N}$ .

# Law of large numbers

As  $n \to \infty$ ,

$$\frac{1}{n}\sum_{i=1}^{n}\mathbf{w}_{i}\mathbf{w}_{i}^{\mathsf{H}}=\mathbf{W}\mathbf{W}^{\mathsf{H}}\xrightarrow{\text{a.s.}}\mathbf{R}$$

In reality, one cannot afford  $n \to \infty$ .

• if  $n \gg N$ ,

$$\mathbf{R}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{w}_i \mathbf{w}_i^{\mathsf{H}}$$

is a "good" estimate of R.

• if N/n = O(1), and if both (n, N) are large, we can still say, for all (i, j),

$$(\mathbf{R}_n)_{ij} \xrightarrow{\text{a.s.}} (\mathbf{R})_{ij}$$

What about the global behaviour? What about the eigenvalue distribution?

Let  $\mathbf{w}_1, \mathbf{w}_2 \ldots \in \mathbb{C}^N$  be independently drawn from an *N*-variate process of mean zero and covariance  $\mathbf{R} = \mathrm{E}[\mathbf{w}_1\mathbf{w}_1^H] \in \mathbb{C}^{N \times N}$ .

# Law of large numbers

As  $n \to \infty$ ,

$$\frac{1}{n}\sum_{i=1}^{n}\mathbf{w}_{i}\mathbf{w}_{i}^{\mathsf{H}}=\mathbf{W}\mathbf{W}^{\mathsf{H}}\xrightarrow{\text{a.s.}}\mathbf{R}$$

In reality, one cannot afford  $n \to \infty$ .

• if  $n \gg N$ ,

$$\mathbf{R}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{w}_i \mathbf{w}_i^{\mathsf{H}}$$

is a "good" estimate of R.

• if N/n = O(1), and if both (n, N) are large, we can still say, for all (i, j),

$$(\mathbf{R}_n)_{ij} \stackrel{\mathrm{a.s.}}{\longrightarrow} (\mathbf{R})_{ij}$$

What about the global behaviour? What about the eigenvalue distribution?

#### Tools for Random Matrix Theory Introduction to Large Dimensional Random Matrix Theo Empirical and limit spectra of Wishart matrices

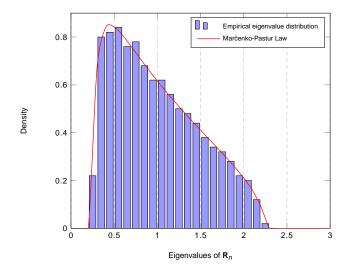


Figure: Histogram of the eigenvalues of  $\mathbf{R}_n$  for n = 2000, N = 500,  $\mathbf{R} = \mathbf{I}_N$ 

# The Marčenko-Pastur Law

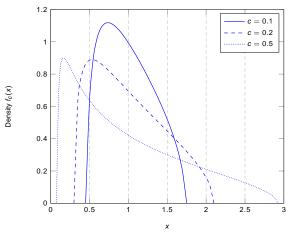


Figure: Marčenko-Pastur law for different limit ratios  $c = \lim N/n$ .

Introduction to Large Dimensional Random Matrix Theory

# Deriving the Marčenko-Pastur law

• We wish to determine the density  $f_c(\lambda)$  of the asymptotic law, defined by

$$f_{c}(\lambda) = \lim_{\substack{N \to \infty \\ n \to \infty \\ N/n \to c}} \sum_{i=1}^{N} \delta\left(\lambda - \lambda_{i}(\mathbf{R}_{n})\right)$$

• Denoting  $\alpha = N/n$ , the moments of this distribution are given by

$$M_1^N = \frac{1}{N} \operatorname{tr} \mathbf{R}_n = \frac{1}{N} \sum_{i=1}^N \lambda_i(\mathbf{R}_n) \to \int \lambda f_c(\lambda) d\lambda = 1$$
  

$$M_2^N = \frac{1}{N} \operatorname{tr} \mathbf{R}_n^2 = \frac{1}{N} \sum_{i=1}^N \lambda_i(\mathbf{R}_n)^2 \to \int \lambda^2 f_c(\lambda) d\lambda = 1 + \alpha$$
  

$$M_3^N = \frac{1}{N} \operatorname{tr} \mathbf{R}_n^3 = \frac{1}{N} \sum_{i=1}^N \lambda_i(\mathbf{R}_n)^3 \to \int \lambda^3 f_c(\lambda) d\lambda = \alpha^2 + 3\alpha + 1$$
  

$$\cdots = \cdots$$

• These moments correspond to a *unique* distribution function (under mild assumptions), which has density the Marčenko-Pastur law

$$f(x) = (1 - \frac{1}{\alpha})^+ \delta(x) + \frac{\sqrt{(x - a)^+ (b - x)^+}}{2\pi\alpha x}, \text{ with } a = (1 - \sqrt{\alpha})^2, b = (1 + \sqrt{\alpha})^2.$$

Introduction to Large Dimensional Random Matrix Theory

# Deriving the Marčenko-Pastur law

• We wish to determine the density  $f_c(\lambda)$  of the asymptotic law, defined by

$$f_{c}(\lambda) = \lim_{\substack{N \to \infty \\ n \to \infty \\ N/n \to c}} \sum_{i=1}^{N} \delta\left(\lambda - \lambda_{i}(\mathbf{R}_{n})\right)$$

• Denoting  $\alpha = N/n$ , the moments of this distribution are given by

$$M_1^N = \frac{1}{N} \operatorname{tr} \mathbf{R}_n = \frac{1}{N} \sum_{i=1}^N \lambda_i(\mathbf{R}_n) \to \int \lambda f_c(\lambda) d\lambda = 1$$
  

$$M_2^N = \frac{1}{N} \operatorname{tr} \mathbf{R}_n^2 = \frac{1}{N} \sum_{i=1}^N \lambda_i(\mathbf{R}_n)^2 \to \int \lambda^2 f_c(\lambda) d\lambda = 1 + \alpha$$
  

$$M_3^N = \frac{1}{N} \operatorname{tr} \mathbf{R}_n^3 = \frac{1}{N} \sum_{i=1}^N \lambda_i(\mathbf{R}_n)^3 \to \int \lambda^3 f_c(\lambda) d\lambda = \alpha^2 + 3\alpha + 1$$
  

$$\cdots = \cdots$$

 These moments correspond to a *unique* distribution function (under mild assumptions), which has density the Marčenko-Pastur law

$$f(x) = (1 - \frac{1}{\alpha})^+ \delta(x) + \frac{\sqrt{(x - a)^+ (b - x)^+}}{2\pi \alpha x}, \text{ with } a = (1 - \sqrt{\alpha})^2, b = (1 + \sqrt{\alpha})^2.$$

# Outline

# Shannon, Wiener and Cognitive Radios

## Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

### 5 Random Matrix Theory and Multi-Source Power Estimation

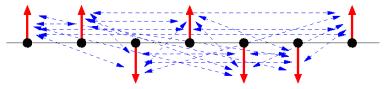
- Free Probability Approach
- Analytic Approach

# Wigner and semi-circle law

### Schrödinger's equation

$$H\Phi_i = E_i \Phi_i$$

where  $\Phi_i$  is the wave function,  $E_i$  is the energy level, *H* is the Hamiltonian.



Magnetic interactions between the spins of electrons

Tools for Random Matrix Theory History of Mathematical Advances The birth of large dimensional random matrix theory



Eugene Paul Wigner, 1902-1995

Eigen-Inference Statistical Methods for Cognitive Radi

E. Wigner, "Characteristic vectors of bordered matrices with infinite dimensions," The annals of mathematics, vol. 62, pp. 546-564, 1955.

$$\mathbf{X}_{N} = \frac{1}{\sqrt{N}} \begin{bmatrix} 0 & +1 & +1 & +1 & -1 & -1 & \cdots \\ +1 & 0 & -1 & +1 & +1 & +1 & \cdots \\ +1 & -1 & 0 & +1 & +1 & +1 & \cdots \\ +1 & +1 & +1 & 0 & +1 & +1 & \cdots \\ -1 & +1 & +1 & +1 & 0 & -1 & \cdots \\ -1 & +1 & +1 & +1 & -1 & 0 & \cdots \\ \vdots & \ddots \end{bmatrix}$$

As the matrix dimension increases, what can we say about the eigenvalues (energy levels)?

If X<sub>N</sub> ∈ C<sup>N×N</sup> is Hermitian with i.i.d. entries of mean 0, variance 1/N above the diagonal, then F<sup>X<sub>N</sub></sup> a.s. F where F has density f the semi-circle law

$$f(x) = \frac{1}{2\pi} \sqrt{(4-x^2)^+}$$

Shown from the method of moments

$$\lim_{N\to\infty}\frac{1}{N}\operatorname{tr} \mathbf{X}_N^{2k} = \frac{1}{k+1}C_k^{2k}$$

### which are exactly the moments of f(x)!

• If  $X_N \in \mathbb{C}^{N \times N}$  has i.i.d. 0 mean, variance 1/N entries, then asymptotically its complex eigenvalues distribute uniformly on the complex unit circle.

If X<sub>N</sub> ∈ C<sup>N×N</sup> is Hermitian with i.i.d. entries of mean 0, variance 1/N above the diagonal, then F<sup>X<sub>N</sub></sup> a.s. F where F has density f the semi-circle law

$$f(x) = \frac{1}{2\pi} \sqrt{(4-x^2)^+}$$

Shown from the method of moments

$$\lim_{N\to\infty}\frac{1}{N}\operatorname{tr} \mathbf{X}_N^{2k} = \frac{1}{k+1}C_k^{2k}$$

which are exactly the moments of f(x)!

 If X<sub>N</sub> ∈ C<sup>N×N</sup> has i.i.d. 0 mean, variance 1/N entries, then asymptotically its complex eigenvalues distribute uniformly on the complex unit circle.

イロン 不良 とうほう イロン

# Semi-circle law

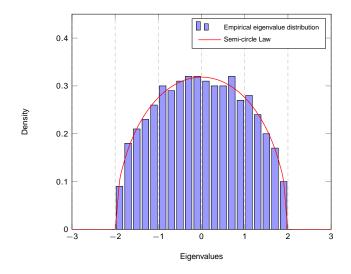


Figure: Histogram of the eigenvalues of Wigner matrices and the semi-circle law, for N = 500

ъ

# Circular law

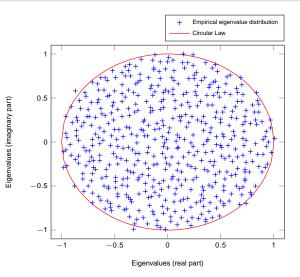


Figure: Eigenvalues of  $X_N$  with i.i.d. standard Gaussian entries, for N = 500.

- much study has surrounded the Marčenko-Pastur law, the Wigner semi-circle law etc.
- for practical purposes, we often need more general matrix models
  - products and sums of random matrices
  - i.i.d. models with correlation/variance profile
  - distribution of inverses etc.
- for these models, it is often impossible to have a closed-form expression of the limiting distribution.
- sometimes we do not have a limiting convergence.

To study these models, the method of moments is not enough! A consistent powerful mathematical framework is required.

- much study has surrounded the Marčenko-Pastur law, the Wigner semi-circle law etc.
- for practical purposes, we often need more general matrix models
  - products and sums of random matrices
  - i.i.d. models with correlation/variance profile
  - distribution of inverses etc.
- for these models, it is often impossible to have a closed-form expression of the limiting distribution.
- sometimes we do not have a limiting convergence.

To study these models, the method of moments is not enough! A consistent powerful mathematical framework is required.

- much study has surrounded the Marčenko-Pastur law, the Wigner semi-circle law etc.
- for practical purposes, we often need more general matrix models
  - products and sums of random matrices
  - i.i.d. models with correlation/variance profile
  - distribution of inverses etc.
- for these models, it is often impossible to have a closed-form expression of the limiting distribution.
- sometimes we do not have a limiting convergence.

To study these models, the method of moments is not enough! A consistent powerful mathematical framework is required.

- much study has surrounded the Marčenko-Pastur law, the Wigner semi-circle law etc.
- for practical purposes, we often need more general matrix models
  - products and sums of random matrices
  - i.i.d. models with correlation/variance profile
  - distribution of inverses etc.
- for these models, it is often impossible to have a closed-form expression of the limiting distribution.
- sometimes we do not have a limiting convergence.

To study these models, the method of moments is not enough! A consistent powerful mathematical framework is required.

# Outline

## Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances

### The Moment Approach and Free Probability

- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

### 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

• The Hermitian matrix  $\mathbf{R}_N \in \mathbb{C}^{N \times N}$  has successive *empirical* moments  $M_k^N$ , k = 1, 2, ...,

$$M_k^N = \frac{1}{N} \sum_{i=1}^N \lambda_i^k$$

In classical probability theory, for A, B independent,

$$c_k(A+B) = c_k(A) + c_k(B)$$

with  $c_k(X)$  the cumulants of X. The cumulants  $c_k$  are connected to the moments  $m_k$  by,

$$m_k = \sum_{\pi \in \mathcal{P}(k)} \prod_{V \in \pi} c_{|V|}$$

A natural extension of classical probability for non-commutative random variables exist, called Free Probability

• The Hermitian matrix  $\mathbf{R}_N \in \mathbb{C}^{N \times N}$  has successive *empirical* moments  $M_k^N$ , k = 1, 2, ...,

$$M_k^N = \frac{1}{N} \sum_{i=1}^N \lambda_i^k$$

• In classical probability theory, for A, B independent,

$$c_k(A+B)=c_k(A)+c_k(B)$$

with  $c_k(X)$  the cumulants of X. The cumulants  $c_k$  are connected to the moments  $m_k$  by,

$$m_k = \sum_{\pi \in \mathcal{P}(k)} \prod_{V \in \pi} c_{|V|}$$

A natural extension of classical probability for non-commutative random variables exist, called Free Probability

・ロト ・回ト ・ヨト ・ヨト

• The Hermitian matrix  $\mathbf{R}_N \in \mathbb{C}^{N \times N}$  has successive *empirical* moments  $M_k^N$ , k = 1, 2, ...,

$$M_k^N = \frac{1}{N} \sum_{i=1}^N \lambda_i^k$$

• In classical probability theory, for A, B independent,

$$c_k(A+B)=c_k(A)+c_k(B)$$

with  $c_k(X)$  the cumulants of X. The cumulants  $c_k$  are connected to the moments  $m_k$  by,

$$m_k = \sum_{\pi \in \mathcal{P}(k)} \prod_{V \in \pi} c_{|V|}$$

A natural extension of classical probability for non-commutative random variables exist, called Free Probability

# Free probability

Free probability applies to asymptotically large random matrices. We denote the moments without superscript.

- To connect the moments of A + B to those of A and B, independence is not enough. A and B must be asymptotically free,
  - two Gaussian matrices are free
  - a Gaussian matrix and any deterministic matrix are free
  - unitary (Haar distributed) matrices are free
  - a Haar matrix and a Gaussian matrix are free etc.

• Similarly as in classical probability, we define free cumulants  $C_k$ ,

 $C_1 = M_1$   $C_2 = M_2 - M_1^2$  $C_3 = M_3 - 3M_1M_2 + 2M_1^2$ 

R. Speicher, "Combinatorial theory of the free product with amalgamation and operator-valued free probability theory," Mem. A.M.S., vol. 627, 1998.

Combinatorial description by non-crossing partitions,

$$M_n = \sum_{\pi \in NC(n)} \prod_{V \in \pi} C_{|V|}$$

(I) < ((()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) <

# Free probability

Free probability applies to asymptotically large random matrices. We denote the moments without superscript.

- To connect the moments of A + B to those of A and B, independence is not enough. A and B must be asymptotically free,
  - two Gaussian matrices are free
  - a Gaussian matrix and any deterministic matrix are free
  - unitary (Haar distributed) matrices are free
  - a Haar matrix and a Gaussian matrix are free etc.
- Similarly as in classical probability, we define free cumulants  $C_k$ ,

$$C_1 = M_1$$
  

$$C_2 = M_2 - M_1^2$$
  

$$C_3 = M_3 - 3M_1M_2 + 2M_1^2$$

R. Speicher, "Combinatorial theory of the free product with amalgamation and operator-valued free probability theory," Mem. A.M.S., vol. 627, 1998.

Combinatorial description by non-crossing partitions,

$$M_n = \sum_{\pi \in NC(n)} \prod_{V \in \pi} C_{|V|}$$

# Free probability

Free probability applies to asymptotically large random matrices. We denote the moments without superscript.

- To connect the moments of A + B to those of A and B, independence is not enough. A and B must be asymptotically free,
  - two Gaussian matrices are free
  - a Gaussian matrix and any deterministic matrix are free
  - unitary (Haar distributed) matrices are free
  - a Haar matrix and a Gaussian matrix are free etc.
- Similarly as in classical probability, we define free cumulants  $C_k$ ,

$$C_1 = M_1$$
  

$$C_2 = M_2 - M_1^2$$
  

$$C_3 = M_3 - 3M_1M_2 + 2M_1^2$$

R. Speicher, "Combinatorial theory of the free product with amalgamation and operator-valued free probability theory," Mem. A.M.S., vol. 627, 1998.

• Combinatorial description by non-crossing partitions,

$$M_n = \sum_{\pi \in NC(n)} \prod_{V \in \pi} C_{|V|}$$

# Non-crossing partitions

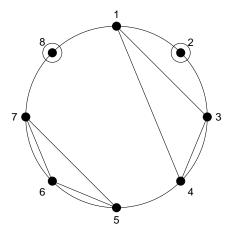


Figure: Non-crossing partition  $\pi = \{\{1, 3, 4\}, \{2\}, \{5, 6, 7\}, \{8\}\}$  of *NC*(8).

( ) < </p>

Tools for Random Matrix Theory The Moment Approach and Free Probability Moments of sums and products of random matrices

### Combinatorial calculus of all moments

#### Theorem

For free random matrices A and B, we have the relationship,

$$C_k(\mathbf{A} + \mathbf{B}) = C_k(\mathbf{A}) + C_k(\mathbf{B})$$

$$M_n(\mathbf{AB}) = \sum_{(\pi_1, \pi_2) \in NC(n)} \prod_{\substack{V_1 \in \pi_1 \\ V_2 \in \pi_2}} C_{|V_1|}(\mathbf{A}) C_{|V_2|}(\mathbf{B})$$

in conjunction with free moment-cumulant formula, gives all moments of sum and product.

#### Theorem

If F is a compactly supported distribution function, then F is determined by its moments.

• In the absence of support compactness, it is impossible to retrieve the distribution function from moments. This is in particular the case of Vandermonde matrices.

Tools for Random Matrix Theory The Moment Approach and Free Probability Moments of sums and products of random matrices

### Combinatorial calculus of all moments

#### Theorem

For free random matrices A and B, we have the relationship,

$$C_k(\mathbf{A} + \mathbf{B}) = C_k(\mathbf{A}) + C_k(\mathbf{B})$$

$$M_n(\mathbf{AB}) = \sum_{(\pi_1, \pi_2) \in NC(n)} \prod_{\substack{V_1 \in \pi_1 \\ V_2 \in \pi_2}} C_{|V_1|}(\mathbf{A}) C_{|V_2|}(\mathbf{B})$$

in conjunction with free moment-cumulant formula, gives all moments of sum and product.

#### Theorem

If F is a compactly supported distribution function, then F is determined by its moments.

 In the absence of support compactness, it is impossible to retrieve the distribution function from moments. This is in particular the case of Vandermonde matrices.

# Free convolution

• In classical probability theory, for independent A, B,

$$\mu_{A+B}(\mathbf{x}) = \mu_A(\mathbf{x}) * \mu_B(\mathbf{x}) \stackrel{\Delta}{=} \int \mu_A(t) \mu_B(\mathbf{x}-t) dt$$

• In free probability, for free A, B, we use the notations

$$\mu_{\mathbf{A}+\mathbf{B}} = \mu_{\mathbf{A}} \boxplus \mu_{\mathbf{B}}, \ \mu_{\mathbf{A}} = \mu_{\mathbf{A}+\mathbf{B}} \boxminus \mu_{\mathbf{B}}, \ \mu_{\mathbf{A}\mathbf{B}} = \mu_{\mathbf{A}} \boxtimes \mu_{\mathbf{B}}, \ \mu_{\mathbf{A}} = \mu_{\mathbf{A}+\mathbf{B}} \boxtimes \mu_{\mathbf{B}}$$

Ø. Ryan, M. Debbah, "Multiplicative free convolution and information-plus-noise type matrices," Arxiv preprint math.PR/0702342, 2007.

#### Theorem

Convolution of the information-plus-noise model Let  $\mathbf{W}_N \in \mathbb{C}^{N \times n}$  have i.i.d. Gaussian entries of mean 0 and variance 1,  $\mathbf{A}_N \in \mathbb{C}^{N \times n}$ , such that  $\mu_{\frac{1}{n}\mathbf{A}_N\mathbf{A}_N^H} \Rightarrow \mu_A$ , as  $n/N \to c$ . Then the eigenvalue distribution of

$$\mathbf{B}_{N} = \frac{1}{n} \left( \mathbf{A}_{N} + \sigma \mathbf{W}_{N} \right) \left( \mathbf{A}_{N} + \sigma \mathbf{W}_{N} \right)^{\mathsf{H}}$$

converges weakly and almost surely to  $\mu_B$  such that

$$\mu_{B} = \left( \left( \mu_{A} \boxtimes \mu_{c} \right) \boxplus \delta_{\sigma^{2}} \right) \boxtimes \mu_{c}$$

with  $\mu_c$  the Marčenko-Pastur law with ratio c.

# Free convolution

• In classical probability theory, for independent A, B,

$$\mu_{A+B}(\mathbf{x}) = \mu_A(\mathbf{x}) * \mu_B(\mathbf{x}) \stackrel{\Delta}{=} \int \mu_A(t) \mu_B(\mathbf{x}-t) dt$$

• In free probability, for free A, B, we use the notations

$$\mu_{\mathbf{A}+\mathbf{B}} = \mu_{\mathbf{A}} \boxplus \mu_{\mathbf{B}}, \ \mu_{\mathbf{A}} = \mu_{\mathbf{A}+\mathbf{B}} \boxminus \mu_{\mathbf{B}}, \ \mu_{\mathbf{A}\mathbf{B}} = \mu_{\mathbf{A}} \boxtimes \mu_{\mathbf{B}}, \ \mu_{\mathbf{A}} = \mu_{\mathbf{A}+\mathbf{B}} \boxtimes \mu_{\mathbf{B}}$$

Ø. Ryan, M. Debbah, "Multiplicative free convolution and information-plus-noise type matrices," Arxiv preprint math.PR/0702342, 2007.

#### Theorem

Convolution of the information-plus-noise model Let  $\mathbf{W}_N \in \mathbb{C}^{N \times n}$  have i.i.d. Gaussian entries of mean 0 and variance 1,  $\mathbf{A}_N \in \mathbb{C}^{N \times n}$ , such that  $\mu_{\frac{1}{n}\mathbf{A}_N\mathbf{A}_N^H} \Rightarrow \mu_A$ , as  $n/N \to c$ . Then the eigenvalue distribution of

$$\mathbf{B}_{N} = \frac{1}{n} \left( \mathbf{A}_{N} + \sigma \mathbf{W}_{N} \right) \left( \mathbf{A}_{N} + \sigma \mathbf{W}_{N} \right)^{\mathsf{H}}$$

converges weakly and almost surely to  $\mu_B$  such that

$$\mu_{\mathsf{B}} = \left( \left( \mu_{\mathsf{A}} \boxtimes \mu_{\mathsf{c}} \right) \boxplus \delta_{\sigma^2} \right) \boxtimes \mu_{\mathsf{c}}$$

with  $\mu_c$  the Marčenko-Pastur law with ratio c.

Tools for Random Matrix Theory The Moment Approach and Free Probability Similarities between classical and free probability

	Classical Probability	Free probability
Moments	$m_k = \int x^k dF(x)$	$M_k = \int x^k dF(x)$
Cumulants	$m_n = \sum_{\pi \in \mathcal{P}(n)}^J \prod_{V \in \pi} c_{ V }$	$M_n = \sum_{\pi \in \mathcal{NC}(n)}^J \prod_{V \in \pi} C_{ V }$
Independence	classical independence	freeness
Additive convolution	$f_{A+B} = f_A * f_B$	$\mu_{\mathbf{A}+\mathbf{B}} = \mu_{\mathbf{A}} \boxplus \mu_{\mathbf{B}}$
Multiplicative convolution	f <sub>AB</sub>	$\mu_{AB} = \mu_{A} \boxtimes \mu_{B}$
Sum Rule	$c_k(A+B) = c_k(A) + c_k(B)$	$C_k(\mathbf{A} + \mathbf{B}) = C_k(\mathbf{A}) + C_k(\mathbf{B})$
Central Limit	$\frac{1}{\sqrt{n}}\sum_{i=1}^n x_i \to \mathcal{N}(0,1)$	$\frac{1}{\sqrt{n}}\sum_{i=1}^{n}X_{i} \Rightarrow \text{semi-circle law}$

イロト イヨト イヨト イヨト

Tools for Random Matrix Theory The Moment Approach and Free Probability Bibliography on Free Probability related work

- D. Voiculescu, "Addition of certain non-commuting random variables," Journal of functional analysis, vol. 66, no. 3, pp. 323-346, 1986.
- R. Speicher, "Combinatorial theory of the free product with amalgamation and operator-valued free probability theory," Mem. A.M.S., vol. 627, 1998.
- R. Seroul, D. O'Shea, "Programming for Mathematicians," Springer, 2000.
- H. Bercovici, V. Pata, "The law of large numbers for free identically distributed random variables," The Annals of Probability, pp. 453-465, 1996.
- A. Nica, R. Speicher, "On the multiplication of free N-tuples of noncommutative random variables," American Journal of Mathematics, pp. 799-837, 1996.
- Ø. Ryan, M. Debbah, "Multiplicative free convolution and information-plus-noise type matrices," Arxiv preprint math.PR/0702342, 2007.
- N. R. Rao, A. Edelman, "The polynomial method for random matrices," Foundations of Computational Mathematics, vol. 8, no. 6, pp. 649-702, 2008.
- Ø. Ryan, M. Debbah, "Asymptotic Behavior of Random Vandermonde Matrices With Entries on the Unit Circle," IEEE Trans. on Information Theory, vol. 55, no. 7, pp. 3115-3147, 2009.

(I) < ((()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) <

# Outline

## Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability

### Introduction of the Stieltjes Transform

Summary of what we know and what is left to be done

### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

### 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

Image: A matrix

# The Stieltjes transform

### Definition

Let *F* be a real distribution function. The Stieltjes transform  $m_F$  of *F* is the function defined, for  $z \in \mathbb{C} \setminus \mathbb{R}$ , as

$$m_F(z) = \int \frac{1}{\lambda - z} dF(\lambda)$$

For a < b real, denoting z = x + iy, we have the inverse formula

$$F'(x) = \lim_{y\to 0} \frac{1}{\pi} \Im[m_F(x+iy)]$$

Knowing the Stieltjes transform is knowing the eigenvalue distribution!

# The Stieltjes transform

### Definition

Let *F* be a real distribution function. The Stieltjes transform  $m_F$  of *F* is the function defined, for  $z \in \mathbb{C} \setminus \mathbb{R}$ , as

$$m_F(z) = \int \frac{1}{\lambda - z} dF(\lambda)$$

For a < b real, denoting z = x + iy, we have the inverse formula

$$F'(x) = \lim_{y\to 0} \frac{1}{\pi} \Im[m_F(x+iy)]$$

Knowing the Stieltjes transform is knowing the eigenvalue distribution!

• If *F* is the eigenvalue distribution of a Hermitian matrix  $\mathbf{X}_N \in \mathbb{C}^{N \times N}$ , we might denote  $m_{\mathbf{X}} \stackrel{\Delta}{=} m_F$ , and

$$m_{\mathbf{X}}(z) = \int \frac{1}{\lambda - z} dF(\lambda) = \frac{1}{N} \operatorname{tr} (\mathbf{X}_N - z \mathbf{I}_N)^{-1}$$

For compactly supported eigenvalue distribution,

$$m_F(z) = -\frac{1}{z} \int \frac{1}{1 - \frac{\lambda}{z}} = -\sum_{k=0}^{\infty} M_k^N z^{-k-1}$$

The Stieltjes transform is doubly more powerful than the moment approach!

- conveys more information than any *K*-finite sequence  $M_1, \ldots, M_K$ .
- is not handicapped by the support compactness constraint.
- however, Stieltjes transform methods, while stronger, are more painful to work with.

• If *F* is the eigenvalue distribution of a Hermitian matrix  $\mathbf{X}_N \in \mathbb{C}^{N \times N}$ , we might denote  $m_{\mathbf{X}} \stackrel{\Delta}{=} m_F$ , and

$$m_{\mathbf{X}}(z) = \int \frac{1}{\lambda - z} dF(\lambda) = \frac{1}{N} \operatorname{tr} (\mathbf{X}_N - z \mathbf{I}_N)^{-1}$$

• For compactly supported eigenvalue distribution,

$$m_F(z) = -\frac{1}{z} \int \frac{1}{1 - \frac{\lambda}{z}} = -\sum_{k=0}^{\infty} M_k^N z^{-k-1}$$

The Stieltjes transform is doubly more powerful than the moment approach!

- conveys more information than any *K*-finite sequence  $M_1, \ldots, M_K$ .
- is not handicapped by the support compactness constraint.
- however, Stieltjes transform methods, while stronger, are more painful to work with.

・ロト ・回ト ・ヨト ・ヨト

• If *F* is the eigenvalue distribution of a Hermitian matrix  $\mathbf{X}_N \in \mathbb{C}^{N \times N}$ , we might denote  $m_{\mathbf{X}} \stackrel{\Delta}{=} m_F$ , and

$$m_{\mathbf{X}}(z) = \int \frac{1}{\lambda - z} dF(\lambda) = \frac{1}{N} \operatorname{tr} (\mathbf{X}_N - z \mathbf{I}_N)^{-1}$$

• For compactly supported eigenvalue distribution,

$$m_F(z) = -\frac{1}{z} \int \frac{1}{1-\frac{\lambda}{z}} = -\sum_{k=0}^{\infty} M_k^N z^{-k-1}$$

The Stieltjes transform is doubly more powerful than the moment approach!

- conveys more information than any *K*-finite sequence  $M_1, \ldots, M_K$ .
- is not handicapped by the support compactness constraint.
- however, Stieltjes transform methods, while stronger, are more painful to work with.

# Tools for Random Matrix Theory Introduction of the Stielties Transform

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

#### Theorem

Let  $\underline{\mathbf{B}}_N = \mathbf{X}_N \mathbf{T}_N \mathbf{X}_N^{\mathsf{H}} \in \mathbb{C}^{N \times N}$ ,  $\mathbf{X}_N \in \mathbb{C}^{N \times n}$  has i.i.d. entries of mean 0 and variance 1/N,  $F^{\mathbf{T}_N} \Rightarrow F^{\mathsf{T}}$ ,  $n/N \to c$ . Then,  $F^{\underline{\mathbf{B}}_N} \Rightarrow \underline{F}$  almost surely,  $\underline{F}$  having Stieltjes transform

$$\underline{m}_{\underline{F}}(z) = \left(c \int \frac{t}{1 + t \underline{m}_{\underline{F}}(z)} dF^{T}(t) - z\right)^{-1} = \left[\frac{1}{N} \operatorname{tr} \mathbf{T}_{N} \left(\underline{m}_{\underline{F}}(z) \mathbf{T}_{N} + \mathbf{I}_{N}\right)^{-1} - z\right]^{-1}$$

which has a unique solution  $m_{\underline{F}}(z) \in \mathbb{C}^+$  if  $z \in \mathbb{C}^+$ , and  $m_{\underline{F}}(z) > 0$  if z < 0.

- in general, no explicit expression for <u>F</u>.
- Stieltjes transform of  $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}} \mathbf{X}_N^H \mathbf{X}_N \mathbf{T}_N^{\frac{1}{2}}$  with asymptotic distribution *F*,

$$m_F = cm_{\underline{F}} + (c-1)\frac{1}{z}$$

Spectrum of the sample covariance matrix model  $\mathbf{B}_N = \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^H$ , with  $\mathbf{X}_N^H = [\mathbf{x}_1, \dots, \mathbf{x}_n]$ ,  $\mathbf{x}_i$  i.i.d. with zero mean and covariance  $\mathbf{T}_N = \mathrm{E}[\mathbf{x}_1 \mathbf{x}_1^H]$ .

# Tools for Random Matrix Theory Introduction of the Stielties Transform

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

#### Theorem

Let  $\underline{\mathbf{B}}_N = \mathbf{X}_N \mathbf{T}_N \mathbf{X}_N^{\mathsf{H}} \in \mathbb{C}^{N \times N}$ ,  $\mathbf{X}_N \in \mathbb{C}^{N \times n}$  has i.i.d. entries of mean 0 and variance 1/N,  $F^{\mathbf{T}_N} \Rightarrow F^{\mathsf{T}}$ ,  $n/N \to c$ . Then,  $F^{\underline{\mathbf{B}}_N} \Rightarrow \underline{F}$  almost surely,  $\underline{F}$  having Stieltjes transform

$$\underline{m}_{\underline{F}}(z) = \left(c \int \frac{t}{1 + t \underline{m}_{\underline{F}}(z)} dF^{T}(t) - z\right)^{-1} = \left[\frac{1}{N} \operatorname{tr} \mathbf{T}_{N} \left(\underline{m}_{\underline{F}}(z) \mathbf{T}_{N} + \mathbf{I}_{N}\right)^{-1} - z\right]^{-1}$$

which has a unique solution  $m_{\underline{F}}(z) \in \mathbb{C}^+$  if  $z \in \mathbb{C}^+$ , and  $m_{\underline{F}}(z) > 0$  if z < 0.

- in general, no explicit expression for <u>F</u>.
- Stieltjes transform of  $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}} \mathbf{X}_N^H \mathbf{X}_N \mathbf{T}_N^{\frac{1}{2}}$  with asymptotic distribution *F*,

$$m_F = cm_{\underline{F}} + (c-1)\frac{1}{z}$$

Spectrum of the sample covariance matrix model  $\mathbf{B}_N = \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^H$ , with  $\mathbf{X}_N^H = [\mathbf{x}_1, \dots, \mathbf{x}_n]$ ,  $\mathbf{x}_i$  i.i.d. with zero mean and covariance  $\mathbf{T}_N = E[\mathbf{x}_1 \mathbf{x}_1^H]$ .

# Getting F' from $m_F$

Remember that, for a < b real,</p>

$$f(x) \stackrel{\Delta}{=} F'(x) = \lim_{y \to 0} \frac{1}{\pi} \Im[m_F(x + iy)]$$

• to plot the density f(x), span z = x + iy on the line  $\{x \in \mathbb{R}, y = \varepsilon\}$  parallel but close to the real axis, solve  $m_F(z)$  for each z, and plot  $\Im[m_F(z)]$ .

#### Example (Sample covariance matrix)

For N multiple of 3, let  $dF^T(x) = \frac{1}{3}\delta(x-1) + \frac{1}{3}\delta(x-3) + \frac{1}{3}\delta(x-K)$  and let  $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}}\mathbf{X}_N^H\mathbf{X}_N\mathbf{T}_N^{\frac{1}{2}}$  with  $F^{\mathbf{B}_N} \to F$ , then

$$m_{F} = cm_{\underline{F}} + (c-1)\frac{1}{z}$$
$$m_{\underline{F}}(z) = \left(c\int \frac{t}{1+tm_{\underline{F}}(z)}dF^{T}(t) - z\right)^{-1}$$

We take c = 1/10 and alternatively K = 7 and K = 4.

イロト イヨト イヨト イヨト

# Getting F' from $m_F$

Remember that, for a < b real,</p>

$$f(x) \stackrel{\Delta}{=} F'(x) = \lim_{y \to 0} \frac{1}{\pi} \Im[m_F(x + iy)]$$

• to plot the density f(x), span z = x + iy on the line  $\{x \in \mathbb{R}, y = \varepsilon\}$  parallel but close to the real axis, solve  $m_F(z)$  for each z, and plot  $\Im[m_F(z)]$ .

#### Example (Sample covariance matrix)

For N multiple of 3, let  $dF^T(x) = \frac{1}{3}\delta(x-1) + \frac{1}{3}\delta(x-3) + \frac{1}{3}\delta(x-K)$  and let  $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}}\mathbf{X}_N^H\mathbf{X}_N\mathbf{T}_N^{\frac{1}{2}}$  with  $F^{\mathbf{B}_N} \to F$ , then

$$m_F = cm_{\underline{F}} + (c-1)\frac{1}{z}$$
$$m_{\underline{F}}(z) = \left(c\int \frac{t}{1+tm_{\underline{F}}(z)}dF^T(t) - z\right)^{-1}$$

We take c = 1/10 and alternatively K = 7 and K = 4.

## Getting F' from $m_F$

Remember that, for a < b real,</p>

$$f(x) \stackrel{\Delta}{=} F'(x) = \lim_{y \to 0} \frac{1}{\pi} \Im[m_F(x + iy)]$$

• to plot the density f(x), span z = x + iy on the line  $\{x \in \mathbb{R}, y = \varepsilon\}$  parallel but close to the real axis, solve  $m_F(z)$  for each z, and plot  $\Im[m_F(z)]$ .

#### Example (Sample covariance matrix)

For *N* multiple of 3, let  $dF^T(x) = \frac{1}{3}\delta(x-1) + \frac{1}{3}\delta(x-3) + \frac{1}{3}\delta(x-K)$  and let  $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}}\mathbf{X}_N^H\mathbf{X}_N\mathbf{T}_N^{\frac{1}{2}}$  with  $F^{\mathbf{B}_N} \to F$ , then

$$m_{F} = cm_{\underline{F}} + (c-1)\frac{1}{z}$$
$$m_{\underline{F}}(z) = \left(c\int \frac{t}{1+tm_{\underline{F}}(z)}dF^{T}(t) - z\right)^{-1}$$

We take c = 1/10 and alternatively K = 7 and K = 4.

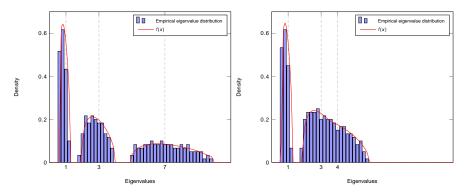


Figure: Histogram of the eigenvalues of  $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}} \mathbf{X}_N^{H} \mathbf{X}_N \mathbf{T}_N^{\frac{1}{2}}$ , N = 3000, n = 300, with  $\mathbf{T}_N$  diagonal composed of three evenly weighted masses in (i) 1, 3 and 7 on top, (ii) 1, 3 and 4 at bottom.

## The Shannon Transform

A. M. Tulino, S. Verdù, "Random matrix theory and wireless communications," Now Publishers Inc., 2004.

### Definition

Let *F* be a probability distribution,  $m_F$  its Stieltjes transform, then the Shannon-transform  $V_F$  of *F* is defined as

$$\mathcal{V}_{\mathcal{F}}(x) \stackrel{\Delta}{=} \int_{0}^{\infty} \log(1 + x\lambda) dF(\lambda) = \int_{x}^{\infty} \left(\frac{1}{t} - m_{\mathcal{F}}(-t)\right) dt$$

If *F* is the distribution function of the eigenvalues of  $\mathbf{XX}^{\mathsf{H}} \in \mathbb{C}^{N \times N}$ ,

$$\mathcal{V}_F(x) = rac{1}{N} \log \det \left( \mathbf{I}_N + x \mathbf{X} \mathbf{X}^\mathsf{H} 
ight).$$

Note that this last relation is fundamental to wireless communication purposes!

## Outline

## Shannon, Wiener and Cognitive Radios

## Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

## 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

# Models studied with analytic tools

- Stieltjes transform: models involving i.i.d. matrices
  - sample covariance matrix models,  $XTX^{H}$  and  $T^{\frac{1}{2}}X^{H}XT^{\frac{1}{2}}$
  - doubly correlated models,  $R^{\frac{1}{2}}XTX^{H}R^{\frac{1}{2}}$ . With X Gaussian, Kronecker model.
  - doubly correlated models with external matrix,  $\mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} + \mathbf{A}$ .
  - variance profile, **XX**<sup>H</sup>, where **X** has i.i.d. entries with mean 0, variance  $\sigma_{i,i}^2$
  - Ricean channels,  $\mathbf{X}\mathbf{X}^{H} + \mathbf{A}$ , where **X** has a variance profile.
  - sum of doubly correlated i.i.d. matrices,  $\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k}^{H} \mathbf{R}_{k}^{\frac{1}{2}}$ .
  - information-plus-noise models  $(\mathbf{X} + \mathbf{A})(\mathbf{X} + \mathbf{A})^{H}$
  - frequency-selective doubly-correlated channels  $(\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k} \mathbf{R}_{k}^{\frac{1}{2}}) (\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k} \mathbf{R}_{k}^{\frac{1}{2}})$
  - sum of frequency-selective doubly-correlated channels  $\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{H}_{k} \mathbf{T}_{k} \mathbf{H}_{k}^{H} \mathbf{R}_{k}^{\frac{1}{2}}$ , where  $\mathbf{H}_{k} = \sum_{l=1}^{L} \mathbf{R}_{kl}^{\prime \frac{1}{2}} \mathbf{X}_{kl} \mathbf{T}_{kl}^{\prime} \mathbf{X}_{kl}^{H} \mathbf{R}_{kl}^{\prime \frac{1}{2}}$ .
- R- and S-transforms: models involving a column subset W of unitary matrices
  - doubly correlated Haar matrix  $\mathbf{R}^{\frac{1}{2}} \mathbf{W} \mathbf{T} \mathbf{W}^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}}$
  - sum of simply correlated Haar matrices  $\sum_{k=1}^{K} \mathbf{W}_k \mathbf{T}_k \mathbf{W}_k^{\mathsf{H}}$

In most cases, **T** and **R** can be taken random, but independent of **X**. More involved random matrices, such as Vandermonde matrices, were not yet studied.

# Models studied with analytic tools

- Stieltjes transform: models involving i.i.d. matrices
  - sample covariance matrix models,  $XTX^{H}$  and  $T^{\frac{1}{2}}X^{H}XT^{\frac{1}{2}}$
  - doubly correlated models, R<sup>1/2</sup> XTX<sup>H</sup>R<sup>1/2</sup>. With X Gaussian, Kronecker model.
  - doubly correlated models with external matrix,  $\mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} + \mathbf{A}$ .
  - variance profile, **XX**<sup>H</sup>, where **X** has i.i.d. entries with mean 0, variance  $\sigma_{i,i}^2$
  - Ricean channels,  $\mathbf{X}\mathbf{X}^{H} + \mathbf{A}$ , where **X** has a variance profile.
  - sum of doubly correlated i.i.d. matrices,  $\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k}^{H} \mathbf{R}_{k}^{\frac{1}{2}}$ .
  - information-plus-noise models  $(\mathbf{X} + \mathbf{A})(\mathbf{X} + \mathbf{A})^{H}$
  - frequency-selective doubly-correlated channels  $(\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k} \mathbf{R}_{k}^{\frac{1}{2}}) (\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k} \mathbf{R}_{k}^{\frac{1}{2}})$
  - sum of frequency-selective doubly-correlated channels  $\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{H}_{k} \mathbf{T}_{k} \mathbf{H}_{k}^{H} \mathbf{R}_{k}^{\frac{1}{2}}$ , where  $\mathbf{H}_{k} = \sum_{l=1}^{L} \mathbf{R}_{kl}^{\prime \frac{1}{2}} \mathbf{X}_{kl} \mathbf{T}_{kl}^{\prime} \mathbf{X}_{kl}^{H} \mathbf{R}_{kl}^{\prime \frac{1}{2}}$ .
- R- and S-transforms: models involving a column subset W of unitary matrices
  - doubly correlated Haar matrix  $\mathbf{R}^{\frac{1}{2}} \mathbf{W} \mathbf{T} \mathbf{W}^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}}$
  - sum of simply correlated Haar matrices  $\sum_{k=1}^{K} \mathbf{W}_k \mathbf{T}_k \mathbf{W}_k^{H}$

In most cases, **T** and **R** can be taken random, but independent of **X**. More involved random matrices, such as Vandermonde matrices, were not yet studied.

# Models studied with analytic tools

- Stieltjes transform: models involving i.i.d. matrices
  - sample covariance matrix models,  $XTX^{H}$  and  $T^{\frac{1}{2}}X^{H}XT^{\frac{1}{2}}$
  - doubly correlated models,  $R^{\frac{1}{2}}XTX^{H}R^{\frac{1}{2}}$ . With X Gaussian, Kronecker model.
  - doubly correlated models with external matrix,  $\mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} + \mathbf{A}$ .
  - variance profile, **XX**<sup>H</sup>, where **X** has i.i.d. entries with mean 0, variance  $\sigma_{i,i}^2$
  - Ricean channels,  $\mathbf{X}\mathbf{X}^{H} + \mathbf{A}$ , where **X** has a variance profile.
  - sum of doubly correlated i.i.d. matrices,  $\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k}^{H} \mathbf{R}_{k}^{\frac{1}{2}}$ .
  - information-plus-noise models  $(\mathbf{X} + \mathbf{A})(\mathbf{X} + \mathbf{A})^{H}$
  - frequency-selective doubly-correlated channels  $(\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k} \mathbf{R}_{k}^{\frac{1}{2}}) (\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k} \mathbf{R}_{k}^{\frac{1}{2}})$
  - sum of frequency-selective doubly-correlated channels  $\sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{H}_{k} \mathbf{T}_{k} \mathbf{H}_{k}^{H} \mathbf{R}_{k}^{\frac{1}{2}}$ , where  $\mathbf{H}_{k} = \sum_{l=1}^{L} \mathbf{R}_{kl}^{\prime \frac{1}{2}} \mathbf{X}_{kl} \mathbf{T}_{kl}^{\prime} \mathbf{X}_{kl}^{H} \mathbf{R}_{kl}^{\prime \frac{1}{2}}$ .
- R- and S-transforms: models involving a column subset W of unitary matrices
  - doubly correlated Haar matrix  $\mathbf{R}^{\frac{1}{2}} \mathbf{W} \mathbf{T} \mathbf{W}^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}}$
  - sum of simply correlated Haar matrices  $\sum_{k=1}^{K} \mathbf{W}_k \mathbf{T}_k \mathbf{W}_k^{H}$

In most cases, **T** and **R** can be taken random, but independent of **X**. More involved random matrices, such as Vandermonde matrices, were not yet studied.

#### asymptotic results

- most of the above models with Gaussian X.
- products  $V_1V_1^HT_1V_2V_2^HT_2...$  of Vandermonde and deterministic matrices
- conjecture: any probability space of matrices invariant to row or column permutations.
- marginal studies, not yet fully explored
  - rectangular free convolution: singular values of rectangular matrices
  - finite size models. Instead of almost sure convergence of  $m_{X_N}$  as  $N \to \infty$ , we can study finite size behaviour of  $E[m_{X_N}]$ .

(I) < ((()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) <

#### asymptotic results

- most of the above models with Gaussian X.
- products  $V_1V_1^HT_1V_2V_2^HT_2...$  of Vandermonde and deterministic matrices
- conjecture: any probability space of matrices invariant to row or column permutations.
- marginal studies, not yet fully explored
  - rectangular free convolution: singular values of rectangular matrices
  - finite size models. Instead of almost sure convergence of m<sub>X<sub>N</sub></sub> as N → ∞, we can study finite size behaviour of E[m<sub>X<sub>N</sub></sub>].

## Open problems, to be explored

- Stieltjes transform methods for more structured matrices: e.g. Vandermonde matrices
- clean framework for band matrix models
- finite dimensional methods for Ricean matrices
- other ?

## Related bibliography

- R. B. Dozier, J. W. Silverstein, "On the empirical distribution of eigenvalues of large dimensional information-plus-noise-type matrices," Journal of Multivariate Analysis, vol. 98, no. 4, pp. 678-694, 2007.
- J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.
- J. W. Silverstein, S. Choi "Analysis of the limiting spectral distribution of large dimensional random matrices" Journal of Multivariate Analysis, vol. 54, no. 2, pp. 295-309, 1995.
- F. Benaych-Georges, "Rectangular random matrices, related free entropy and free Fisher's information," Arxiv preprint math/0512081, 2005.
- Ø. Ryan, M. Debbah, "Multiplicative free convolution and information-plus-noise type matrices," Arxiv preprint math.PR/0702342, 2007.
- V. L. Girko, "Theory of Random Determinants," Kluwer, Dordrecht, 1990.
- R. Couillet, M. Debbah, J. W. Silverstein, "A deterministic equivalent for the capacity analysis of correlated multi-user MIMO channels," submitted to IEEE Trans. on Information Theory.
- V. L. Girko, "Theory of Random Determinants," Kluwer, Dordrecht, 1990.
- W. Hachem, Ph. Loubaton, J. Najim, "Deterministic Equivalents for Certain Functionals of Large Random Matrices", Annals of Applied Probability, vol. 17, no. 3, 2007.
- M. J. M. Peacock, I. B. Collings, M. L. Honig, "Eigenvalue distributions of sums and products of large random matrices via incremental matrix expansions," IEEE Trans. on Information Theory, vol. 54, no. 5, pp. 2123, 2008.
- D. Petz, J. Réffy, "On Asymptotics of large Haar distributed unitary matrices," Periodica Math. Hungar., vol. 49, pp. 103-117, 2004.
- Ø. Ryan, A. Masucci, S. Yang, M. Debbah, "Finite dimensional statistical inference," submitted to IEEE Trans. on Information Theory, Dec. 2009.

## Technical Bibliography

- W. Rudin, "Real and complex analysis," New York, 1966.
- P. Billingsley, "Probability and measure," Wiley New York, 2008.
- P. Billingsley, "Convergence of probability measures," Wiley New York, 1968.

## Outline

## Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

## 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

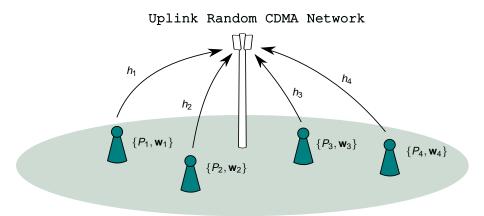
## 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

## Random Matrix Theory and Performance Analysis Example of use: uplink random CDMA



- System model conditions,
  - uplink random CDMA
  - K mobile users, 1 base station
  - N chips per CDMA spreading code.
  - User  $k, k \in \{1, \ldots, K\}$  has code  $\mathbf{w}_k \sim \mathcal{CN}(0, \mathbf{I}_N)$
  - User k transmits the symbol  $s_k$ .
  - User k's channel is  $h_k \sqrt{P_k}$ , with  $P_k$  the power of user k
- The base station receives

$$\mathbf{y} = \sum_{k=1}^{K} h_k \mathbf{w}_k \sqrt{P_k} s_k + \mathbf{n}$$

This can be written in the more compact form

$$\mathbf{y} = \mathbf{WHP}^{\frac{1}{2}}\mathbf{s} + \mathbf{n}$$

with

• 
$$\mathbf{s} = [\mathbf{s}_1, \dots, \mathbf{s}_K]^{\mathsf{T}} \in \mathbb{C}^K$$
,  
•  $\mathbf{W} = [\mathbf{w}_1, \dots, \mathbf{w}_K] \in \mathbb{C}^{N \times K}$ ,  
•  $\mathbf{P} = \operatorname{diag}(P_1, \dots, P_K) \in \mathbb{C}^{K \times K}$ .  
•  $\mathbf{H} = \operatorname{diag}(h_1, \dots, h_K) \in \mathbb{C}^{K \times K}$ .

(I) < ((()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) <

## Outline

## Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

## 3 Random Matrix Theory and Performance Analysis

### The Uplink CDMA MMSE Decoder

The Uplink CDMA Matched-Filter and Optimal Decoder

## 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

Consists into taking

$$r_k = \mathbf{w}_k^{\mathsf{H}} \left( \mathbf{W} \mathbf{H} \mathbf{P} \mathbf{H}^{\mathsf{H}} \mathbf{W}^{\mathsf{H}} + \sigma^2 \mathbf{I}_N \right)^{-1} \mathbf{y}$$

## as symbol for user k.

The SINR for user's k signal is

$$P_{k}|h_{k}|^{2}\mathbf{w}_{k}^{\mathsf{H}}(\sum_{\substack{1 \le i \le K \\ i \ne k}} P_{i}|h_{i}|^{2}\mathbf{w}_{i}\mathbf{w}_{j}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k}$$

$$= P_{k}|h_{k}|^{2}\mathbf{w}_{k}^{\mathsf{H}}(\mathsf{W}\mathsf{H}\mathsf{P}\mathsf{H}^{\mathsf{H}}\mathsf{W}^{\mathsf{H}} - P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k}.$$

$$(1)$$

## Now we have the following result

### Theorem (Trace Lemma)

If  $x \in \mathbb{C}^N$  is i.i.d. with entries of zero mean, variance 1/N, and  $A \in \mathbb{C}^{N \times N}$  is independent of x, then

$$\mathbf{x}^{\mathsf{H}}\mathbf{A}\mathbf{x} = \sum_{i,j} x_i^* x_j A_{ij} \xrightarrow{\text{a.s.}} \frac{1}{N} \operatorname{tr} \mathbf{A}.$$

• Applying this result, for N large,

$$\mathbf{w}_{k}^{\mathsf{H}}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k}-\frac{1}{N}\operatorname{tr}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N})^{-1}\xrightarrow{\mathrm{a.s.}}0$$

Consists into taking

$$\mathbf{r}_{k} = \mathbf{w}_{k}^{\mathsf{H}} \left( \mathbf{W} \mathbf{H} \mathbf{P} \mathbf{H}^{\mathsf{H}} \mathbf{W}^{\mathsf{H}} + \sigma^{2} \mathbf{I}_{N} \right)^{-1} \mathbf{y}$$

as symbol for user k.

• The SINR for user's k signal is  $\gamma_{k}^{(\text{MMSE})} = P_{k}|h_{k}$ 

$${}^{(\text{MMSE})}_{k} = \boldsymbol{P}_{k} |\boldsymbol{h}_{k}|^{2} \mathbf{w}_{k}^{\text{H}} (\sum_{\substack{1 \le i \le K \\ i \ne k}} \boldsymbol{P}_{i} |\boldsymbol{h}_{i}|^{2} \mathbf{w}_{i} \mathbf{w}_{i}^{\text{H}} + \sigma^{2} \mathbf{I}_{N})^{-1} \mathbf{w}_{k}$$
(1)

$$= P_k |h_k|^2 \mathbf{w}_k^{\mathsf{H}} (\mathbf{W} \mathbf{H} \mathbf{P} \mathbf{H}^{\mathsf{H}} \mathbf{W}^{\mathsf{H}} - P_k |h_k|^2 \mathbf{w}_k \mathbf{w}_k^{\mathsf{H}} + \sigma^2 \mathbf{I}_N)^{-1} \mathbf{w}_k.$$
(2)

Now we have the following result

### Theorem (Trace Lemma)

If  $x \in \mathbb{C}^N$  is i.i.d. with entries of zero mean, variance 1/N, and  $A \in \mathbb{C}^{N \times N}$  is independent of x, then

$$\mathbf{x}^{\mathsf{H}}\mathbf{A}\mathbf{x} = \sum_{i,j} x_i^* x_j A_{ij} \xrightarrow{\text{a.s.}} \frac{1}{N} \operatorname{tr} \mathbf{A}.$$

• Applying this result, for N large,

$$\mathbf{w}_{k}^{\mathsf{H}}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k}-\frac{1}{N}\operatorname{tr}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N})^{-1}\xrightarrow{\mathrm{a.s.}}0$$

Consists into taking

$$r_k = \mathbf{w}_k^{\mathsf{H}} \left( \mathbf{W} \mathbf{H} \mathbf{P} \mathbf{H}^{\mathsf{H}} \mathbf{W}^{\mathsf{H}} + \sigma^2 \mathbf{I}_N \right)^{-1} \mathbf{y}$$

as symbol for user k.

• The SINR for user's k signal is

$$P_{k}^{(\text{MMSE})} = P_{k}|h_{k}|^{2}\mathbf{w}_{k}^{\mathsf{H}}\left(\sum_{\substack{1 \le i \le K \\ i \ne k}} P_{i}|h_{i}|^{2}\mathbf{w}_{i}\mathbf{w}_{i}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N}\right)^{-1}\mathbf{w}_{k}$$
(1)

$$= P_k |h_k|^2 \mathbf{w}_k^{\mathsf{H}} (\mathbf{W} \mathbf{H} \mathbf{P} \mathbf{H}^{\mathsf{H}} \mathbf{W}^{\mathsf{H}} - P_k |h_k|^2 \mathbf{w}_k \mathbf{w}_k^{\mathsf{H}} + \sigma^2 \mathbf{I}_N)^{-1} \mathbf{w}_k.$$
(2)

## Now we have the following result

## Theorem (Trace Lemma)

If  $\mathbf{x} \in \mathbb{C}^N$  is i.i.d. with entries of zero mean, variance 1/N, and  $\mathbf{A} \in \mathbb{C}^{N \times N}$  is independent of  $\mathbf{x}$ , then

$$\mathbf{x}^{\mathsf{H}}\mathbf{A}\mathbf{x} = \sum_{i,j} x_i^* x_j A_{ij} \xrightarrow{\text{a.s.}} \frac{1}{N} \operatorname{tr} \mathbf{A}.$$

Applying this result, for N large,

$$\mathbf{w}_{k}^{\mathsf{H}}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k}-\frac{1}{N}\operatorname{tr}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N})^{-1}\xrightarrow{\mathrm{a.s.}}0$$

Consists into taking

$$\mathbf{r}_{k} = \mathbf{w}_{k}^{\mathsf{H}} \left( \mathbf{W} \mathbf{H} \mathbf{P} \mathbf{H}^{\mathsf{H}} \mathbf{W}^{\mathsf{H}} + \sigma^{2} \mathbf{I}_{N} \right)^{-1} \mathbf{y}$$

as symbol for user k.

• The SINR for user's k signal is

$$P_{k}^{(\text{MMSE})} = P_{k}|h_{k}|^{2}\mathbf{w}_{k}^{\mathsf{H}}\left(\sum_{\substack{1 \le i \le K \\ i \ne k}} P_{i}|h_{i}|^{2}\mathbf{w}_{i}\mathbf{w}_{i}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N}\right)^{-1}\mathbf{w}_{k}$$
(1)

$$= P_k |h_k|^2 \mathbf{w}_k^{\mathsf{H}} (\mathbf{W} \mathbf{H} \mathbf{P} \mathbf{H}^{\mathsf{H}} \mathbf{W}^{\mathsf{H}} - P_k |h_k|^2 \mathbf{w}_k \mathbf{w}_k^{\mathsf{H}} + \sigma^2 \mathbf{I}_N)^{-1} \mathbf{w}_k.$$
(2)

Now we have the following result

## Theorem (Trace Lemma)

If  $\mathbf{x} \in \mathbb{C}^N$  is i.i.d. with entries of zero mean, variance 1/N, and  $\mathbf{A} \in \mathbb{C}^{N \times N}$  is independent of  $\mathbf{x}$ , then

$$\mathbf{x}^{\mathsf{H}}\mathbf{A}\mathbf{x} = \sum_{i,j} x_i^* x_j A_{ij} \xrightarrow{\text{a.s.}} \frac{1}{N} \operatorname{tr} \mathbf{A}.$$

• Applying this result, for N large,

$$\mathbf{w}_{k}^{\mathsf{H}}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k}-\frac{1}{N}\operatorname{tr}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N})^{-1}\xrightarrow{\mathrm{a.s.}}0$$

# $\mathbf{w}_{k}^{\mathsf{H}}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}} - P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k} - \frac{1}{N}\operatorname{tr}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}} - P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N})^{-1} \xrightarrow{\text{a.s.}} 0.$

## Second important result,

Theorem (Rank 1 perturbation Lemma)

Let  $\mathbf{A} \in \mathbb{C}^{N \times N}$ ,  $\mathbf{x} \in \mathbb{C}^N$ , t > 0, then

$$\left|\frac{1}{N}\operatorname{tr}(\mathbf{A}+t\mathbf{I}_N)^{-1}-\frac{1}{N}\operatorname{tr}(\mathbf{A}+\mathbf{x}\mathbf{x}^{\mathsf{H}}+t\mathbf{I}_N)^{-1}\right|\leq \frac{1}{tN}$$

As N grows large,

$$\frac{1}{N}\operatorname{tr}\left(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N}\right)^{-1}-\frac{1}{N}\operatorname{tr}\left(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N}\right)^{-1}\rightarrow0,$$

• The RHS is the Stieltjes transform of **WHPH<sup>H</sup>W<sup>H</sup>** in  $z = -\sigma^2$ !

$$m_{\mathbf{WHPH}^{\mathrm{H}}\mathbf{W}^{\mathrm{H}}}(-\sigma^{2})$$

# $\mathbf{w}_{k}^{\mathsf{H}}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}} - P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k} - \frac{1}{N}\operatorname{tr}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}} - P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N})^{-1} \xrightarrow{\text{a.s.}} 0.$

Second important result,

Theorem (Rank 1 perturbation Lemma)

Let  $\mathbf{A} \in \mathbb{C}^{N \times N}$ ,  $\mathbf{x} \in \mathbb{C}^N$ , t > 0, then

$$\left|\frac{1}{N}\operatorname{tr}(\mathbf{A}+t\mathbf{I}_N)^{-1}-\frac{1}{N}\operatorname{tr}(\mathbf{A}+\mathbf{x}\mathbf{x}^{\mathsf{H}}+t\mathbf{I}_N)^{-1}\right|\leq\frac{1}{tN}$$

As N grows large,

$$\frac{1}{N}\operatorname{tr}\left(\mathsf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N}\right)^{-1}-\frac{1}{N}\operatorname{tr}\left(\mathsf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N}\right)^{-1}\rightarrow0,$$

• The RHS is the Stieltjes transform of **WHPH<sup>H</sup>W<sup>H</sup>** in  $z = -\sigma^2$ !

$$m_{\mathbf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}}(-\sigma^2)$$

# $\mathbf{w}_{k}^{\mathsf{H}}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}} - P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N})^{-1}\mathbf{w}_{k} - \frac{1}{N}\operatorname{tr}(\mathbf{W}\mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}} - P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}} + \sigma^{2}\mathbf{I}_{N})^{-1} \xrightarrow{\text{a.s.}} 0.$

Second important result,

Theorem (Rank 1 perturbation Lemma)

Let  $\mathbf{A} \in \mathbb{C}^{N \times N}$ ,  $\mathbf{x} \in \mathbb{C}^N$ , t > 0, then

$$\left|\frac{1}{N}\operatorname{tr}(\mathbf{A}+t\mathbf{I}_N)^{-1}-\frac{1}{N}\operatorname{tr}(\mathbf{A}+\mathbf{x}\mathbf{x}^{\mathsf{H}}+t\mathbf{I}_N)^{-1}\right|\leq\frac{1}{tN}$$

As N grows large,

$$\frac{1}{N}\operatorname{tr}\left(\mathsf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}-P_{k}|h_{k}|^{2}\mathbf{w}_{k}\mathbf{w}_{k}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N}\right)^{-1}-\frac{1}{N}\operatorname{tr}\left(\mathsf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N}\right)^{-1}\rightarrow0,$$

• The RHS is the Stieltjes transform of **WHPH<sup>H</sup>W<sup>H</sup>** in  $z = -\sigma^2$ !

$$m_{\mathbf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}}(-\sigma^2)$$

590

## From previous result,

$$m_{\mathbf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}}(-\sigma^{2}) - m_{N}(-\sigma^{2}) \xrightarrow{\text{a.s.}} 0$$

with  $m_N(-\sigma^2)$  the unique positive solution of

$$m = \left[\frac{1}{N} \operatorname{tr} \mathbf{HPH}^{\mathsf{H}} \left(m\mathbf{HPH}^{\mathsf{H}} + \mathbf{I}_{\mathcal{K}}\right)^{-1} + \sigma^{2}\right]^{-1}$$

## independent of k!

This is also

$$m = \left[\sigma^{2} + \frac{1}{N} \sum_{1 \le i \le K} \frac{P_{i}|h_{i}|^{2}}{1 + mP_{i}|h_{i}|^{2}}\right]^{-1}$$

Finally,

$$\gamma_k^{(\text{MMSE})} - m_N(-\sigma^2) \xrightarrow{\text{a.s.}} 0$$

and the capacity reads

$$C^{(\text{MMSE})}(\sigma^2) - \log_2(1 + m_N(-\sigma^2)) \stackrel{\text{a.s.}}{\longrightarrow} 0.$$

## From previous result,

$$m_{\mathbf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}}(-\sigma^{2}) - m_{N}(-\sigma^{2}) \xrightarrow{\mathrm{a.s.}} 0$$

with  $m_N(-\sigma^2)$  the unique positive solution of

$$m = \left[\frac{1}{N} \operatorname{tr} \mathbf{HPH}^{\mathsf{H}} \left(m\mathbf{HPH}^{\mathsf{H}} + \mathbf{I}_{\mathcal{K}}\right)^{-1} + \sigma^{2}\right]^{-1}$$

independent of k!

This is also

$$m = \left[\sigma^{2} + \frac{1}{N} \sum_{1 \le i \le K} \frac{P_{i}|h_{i}|^{2}}{1 + mP_{i}|h_{i}|^{2}}\right]^{-1}$$

Finally,

$$\gamma_k^{(\text{MMSE})} - m_N(-\sigma^2) \xrightarrow{\text{a.s.}} 0$$

and the capacity reads

$$C^{(\text{MMSE})}(\sigma^2) - \log_2(1 + m_N(-\sigma^2)) \xrightarrow{\text{a.s.}} 0.$$

## From previous result,

$$m_{\mathbf{WHPH}^{\mathsf{H}}\mathbf{W}^{\mathsf{H}}}(-\sigma^{2}) - m_{N}(-\sigma^{2}) \xrightarrow{\text{a.s.}} 0$$

with  $m_N(-\sigma^2)$  the unique positive solution of

$$m = \left[\frac{1}{N} \operatorname{tr} \mathbf{HPH}^{\mathsf{H}} \left(m\mathbf{HPH}^{\mathsf{H}} + \mathbf{I}_{\mathcal{K}}\right)^{-1} + \sigma^{2}\right]^{-1}$$

independent of k!

This is also

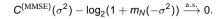
$$m = \left[\sigma^{2} + \frac{1}{N} \sum_{1 \le i \le K} \frac{P_{i}|h_{i}|^{2}}{1 + mP_{i}|h_{i}|^{2}}\right]^{-1}$$

Finally,

$$\gamma_k^{(\text{MMSE})} - m_N(-\sigma^2) \xrightarrow{\text{a.s.}} 0$$

and the capacity reads

$$C^{(\text{MMSE})}(\sigma^2) - \log_2(1 + m_N(-\sigma^2)) \stackrel{\text{a.s.}}{\longrightarrow} 0.$$



• AWGN channel,  $P_k = P$ ,  $h_k = 1$ ,

$$C^{(\mathrm{MMSE})}(\sigma^2) \xrightarrow{\mathrm{a.s.}} c \log_2\left(1 + rac{-(\sigma^2 + (c-1)P) + \sqrt{(\sigma^2 + (c-1)P)^2 + 4P\sigma^2}}{2\sigma^2}
ight)$$

• Rayleigh channel,  $P_k = P$ ,  $|h_k|$  Rayleigh,

$$m = \left[\sigma^2 + c \int \frac{Pt}{1 + Ptm} e^{-t} dt\right]^{-1}$$

and

$$C_{\text{MMSE}}(\sigma^2) \xrightarrow{\text{a.s.}} c \int \log_2 \left(1 + Ptm(-\sigma^2)\right) e^{-t} dt.$$

200

(日) (同) (E) (E) (E)

## Outline

## Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

## 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

R. Couillet, M. Debbah, J. W. Silverstein, "A Deterministic Equivalent for the Capacity Analysis of Correlated Multi-User MIMO Channels," IEEE Trans. on Information Theory, *accepted*, on arXiv.

• Similarly, we can compute deterministic equivalents for the matched-filter performance,

$$C_{\mathrm{MF}}(\sigma^2) - \frac{1}{N} \sum_{k=1}^{K} \log_2 \left( 1 + \frac{P_k |h_k|^2}{\frac{1}{N} \sum_{i=1}^{K} P_i |h_i|^2 + \sigma^2} \right) \xrightarrow{\mathrm{a.s.}} 0$$

AWGN case,

$$C_{\mathrm{MF}}(\sigma^2) \xrightarrow{\mathrm{a.s.}} c \log_2\left(1 + \frac{P}{Pc + \sigma^2}\right)$$

Rayleigh case,

$$C_{\rm MF}(\sigma^2) \xrightarrow{{\rm a.s.}} -c \log_2(e) e^{\frac{Pc+\sigma^2}{P}} {\rm Ei}\left(-\frac{Pc+\sigma^2}{P}\right)$$

... and the optimal joint-decoder performance

$$\begin{split} C_{\text{opt}}(\sigma^2) - \log_2 \left( 1 + \frac{1}{\sigma^2 N} \sum_{k=1}^K \frac{P_k |h_k|^2}{1 + c P_k |h_k|^2 m_N(-\sigma^2)} \right) &- \frac{1}{N} \sum_{k=1}^K \log_2 \left( 1 + c P_k |h_k|^2 m_N(-\sigma^2) \right) \\ &- \log_2(e) \left( \sigma^2 m_N(-\sigma^2) - 1 \right) \xrightarrow{\text{a.s.}} 0. \end{split}$$

with  $m_N(-\sigma^2)$  defined as previously.

• Similar expressions are obtained for the AWGN and Rayleigh cases,

R. Couillet, M. Debbah, J. W. Silverstein, "A Deterministic Equivalent for the Capacity Analysis of Correlated Multi-User MIMO Channels," IEEE Trans. on Information Theory, *accepted*, on arXiv.

Similarly, we can compute deterministic equivalents for the matched-filter performance,

$$C_{\mathrm{MF}}(\sigma^2) - \frac{1}{N} \sum_{k=1}^{K} \log_2 \left( 1 + \frac{P_k |h_k|^2}{\frac{1}{N} \sum_{i=1}^{K} P_i |h_i|^2 + \sigma^2} \right) \xrightarrow{\mathrm{a.s.}} 0$$

AWGN case,

$$C_{\mathrm{MF}}(\sigma^2) \xrightarrow{\mathrm{a.s.}} c \log_2\left(1 + \frac{P}{Pc + \sigma^2}\right)$$

Rayleigh case,

$$C_{\rm MF}(\sigma^2) \xrightarrow{{\rm a.s.}} -c \log_2(e) e^{\frac{Pc+\sigma^2}{P}} {\rm Ei}\left(-\frac{Pc+\sigma^2}{P}\right)$$

... and the optimal joint-decoder performance

$$C_{\text{opt}}(\sigma^{2}) - \log_{2} \left( 1 + \frac{1}{\sigma^{2}N} \sum_{k=1}^{K} \frac{P_{k}|h_{k}|^{2}}{1 + cP_{k}|h_{k}|^{2}m_{N}(-\sigma^{2})} \right) - \frac{1}{N} \sum_{k=1}^{K} \log_{2} \left( 1 + cP_{k}|h_{k}|^{2}m_{N}(-\sigma^{2}) \right) - \log_{2}(e) \left( \sigma^{2}m_{N}(-\sigma^{2}) - 1 \right) \xrightarrow{\text{a.s.}} 0.$$

with  $m_N(-\sigma^2)$  defined as previously.

Similar expressions are obtained for the AWGN and Rayleigh cases.

Image: A matrix

## Simulation results: AWGN case

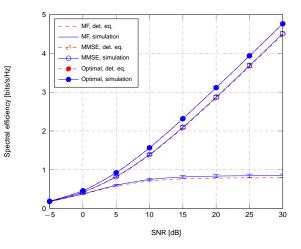


Figure: Spectral efficiency of random CDMA decoders, AWGN channels. Comparison between simulations and deterministic equivalents (det. eq.), for the matched-filter, the MMSE decoder and the optimal decoder, K = 16 users, N = 32 chips per code. Rayleigh channels. Error bars indicate two standard deviations.

Image: A matrix

Simulation results: Rayleigh case

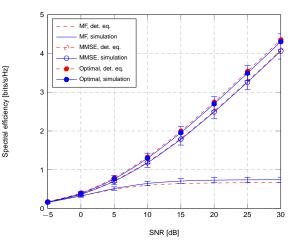


Figure: Spectral efficiency of random CDMA decoders, Rayleigh fading channels. Comparison between simulations and deterministic equivalents (det. eq.), for the matched-filter, the MMSE decoder and the optimal decoder, K = 16 users, N = 32 chips per code. Rayleigh channels. Error bars indicate two standard deviations.

Random Matrix Theory and Performance Analysis The Uplink CDMA Matched-Filter and Optimal Decoder Simulation results: Performance as a function of K/N

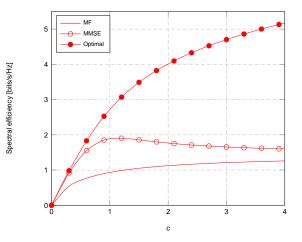


Figure: Spectral efficiency of random CDMA decoders, for different asymptotic ratios c = K/N, SNR=10 dB, AWGN channels. Deterministic equivalents for the matched-filter, the MMSE decoder and the optimal decoder. Rayleigh channels.

## Outline

## Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

#### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

## Random Matrix Theory and Signal Source Sensing

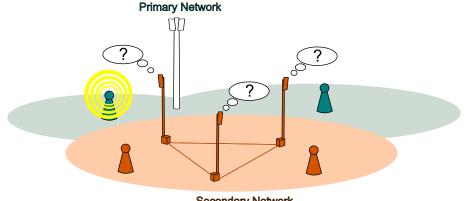
- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

## 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

Image: A matrix

## Random Matrix Theory and Signal Source Sensing Signal Sensing in Cognitive Radios



Secondary Network

( ) < </p>

Decide on presence of informative signal or pure noise.

## Limited a priori Knowledge

- Known parameters: the prior information I
  - N sensors
  - L sampling periods
  - unit transmit power
  - unit channel variance
- Possibly unknown parameters
  - M signal sources
  - noise power equals  $\sigma^2$

#### One situation, one solution

For a given prior information *I*, there must be a unique solution to the detection problem.

・ロト ・回ト ・ヨト ・ヨト

Decide on presence of informative signal or pure noise.

### Limited a priori Knowledge

- Known parameters: the prior information I
  - N sensors
  - L sampling periods
  - unit transmit power
  - unit channel variance
- Possibly unknown parameters
  - M signal sources
  - noise power equals  $\sigma^2$

#### One situation, one solution

For a given prior information *I*, there must be a unique solution to the detection problem.

Decide on presence of informative signal or pure noise.

### Limited a priori Knowledge

- Known parameters: the prior information I
  - N sensors
  - L sampling periods
  - unit transmit power
  - unit channel variance
- Possibly unknown parameters
  - M signal sources
  - noise power equals  $\sigma^2$

#### One situation, one solution

For a given prior information *I*, there must be a unique solution to the detection problem.

### Signal detection is a typical hypothesis testing problem.

•  $\mathcal{H}_0$ : only background noise.

$$\mathbf{Y} = \boldsymbol{\sigma} \boldsymbol{\Theta} = \boldsymbol{\sigma} \begin{pmatrix} \theta_{11} & \cdots & \theta_{1L} \\ \vdots & \ddots & \vdots \\ \theta_{N1} & \cdots & \theta_{NL} \end{pmatrix}$$

•  $\mathcal{H}_1$ : informative signal plus noise.

$$\mathbf{Y} = \begin{pmatrix} h_{11} & \dots & h_{1M} & \sigma & \cdots & 0\\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots\\ h_{N1} & \dots & h_{NM} & 0 & \cdots & \sigma \end{pmatrix} \begin{pmatrix} \mathbf{s}_{1}^{(1)} & \cdots & \cdots & \mathbf{s}_{1}^{(L)} \\ \vdots & \vdots & \vdots & \vdots \\ \mathbf{s}_{M}^{(1)} & \cdots & \cdots & \mathbf{s}_{M}^{(L)} \\ \theta_{11} & \cdots & \cdots & \theta_{1L} \\ \vdots & \vdots & \vdots & \vdots \\ \theta_{M1} & \cdots & \cdots & \theta_{NM} \end{pmatrix}$$

(ロ) (同) (E) (E)

Signal detection is a typical hypothesis testing problem.

•  $\mathcal{H}_0$ : only background noise.

$$\mathbf{Y} = \sigma \mathbf{\Theta} = \sigma \begin{pmatrix} \theta_{11} & \cdots & \theta_{1L} \\ \vdots & \ddots & \vdots \\ \theta_{N1} & \cdots & \theta_{NL} \end{pmatrix}$$

•  $\mathcal{H}_1$ : informative signal plus noise.

$$\mathbf{Y} = \begin{pmatrix} h_{11} & \dots & h_{1M} & \sigma & \dots & 0\\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots\\ h_{N1} & \dots & h_{NM} & 0 & \dots & \sigma \end{pmatrix} \begin{pmatrix} \mathbf{s}_{1}^{(1)} & \dots & \dots & \mathbf{s}_{1}^{(L)}\\ \vdots & \vdots & \vdots & \vdots \\ \mathbf{s}_{M}^{(1)} & \dots & \dots & \mathbf{s}_{M}^{(L)}\\ \theta_{11} & \dots & \dots & \theta_{1L}\\ \vdots & \vdots & \vdots & \vdots\\ \theta_{M1} & \dots & \dots & \theta_{NM} \end{pmatrix}$$

Sac

(ロ) (同) (E) (E)

Signal detection is a typical hypothesis testing problem.

•  $\mathcal{H}_0$ : only background noise.

$$\mathbf{Y} = \sigma \mathbf{\Theta} = \sigma \begin{pmatrix} \theta_{11} & \cdots & \theta_{1L} \\ \vdots & \ddots & \vdots \\ \theta_{N1} & \cdots & \theta_{NL} \end{pmatrix}$$

•  $\mathcal{H}_1$ : informative signal plus noise.

$$\mathbf{Y} = \begin{pmatrix} h_{11} & \dots & h_{1M} & \sigma & \dots & 0\\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots\\ h_{N1} & \dots & h_{NM} & 0 & \dots & \sigma \end{pmatrix} \begin{pmatrix} \mathbf{S}_{1}^{(1)} & \dots & \dots & \mathbf{S}_{1}^{(L)}\\ \vdots & \vdots & \vdots & \vdots\\ \mathbf{S}_{M}^{(1)} & \dots & \dots & \mathbf{S}_{M}^{(L)}\\ \theta_{11} & \dots & \dots & \theta_{1L}\\ \vdots & \vdots & \vdots & \vdots\\ \theta_{N1} & \dots & \dots & \theta_{NL} \end{pmatrix}$$

Sac

### Outline

### Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

#### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

### 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

### Solution

### Solution of hypothesis testing is the function

$$C(\mathbf{Y}) = \frac{P_{\mathcal{H}_1|\mathbf{Y}}(\mathbf{Y})}{P_{\mathcal{H}_0|\mathbf{Y}}(\mathbf{Y})} = \frac{P_{\mathcal{H}_1} \cdot P_{\mathbf{Y}|\mathcal{H}_1}(\mathbf{Y})}{P_{\mathcal{H}_0} \cdot P_{\mathbf{Y}|\mathcal{H}_0}(\mathbf{Y})}$$

If the receiver does not know if  $\mathcal{H}_1$  is more likely than  $\mathcal{H}_0$ ,

$$P_{\mathcal{H}_1} = P_{\mathcal{H}_0} = \frac{1}{2}$$

Therefore,

$$C(\mathbf{Y}) = \frac{P_{\mathbf{Y}|\mathcal{H}_1}(\mathbf{Y})}{P_{\mathbf{Y}|\mathcal{H}_0}(\mathbf{Y})}$$

( ) < </p>

### Solution

Solution of hypothesis testing is the function

$$C(\mathbf{Y}) = \frac{P_{\mathcal{H}_1|\mathbf{Y}}(\mathbf{Y})}{P_{\mathcal{H}_0|\mathbf{Y}}(\mathbf{Y})} = \frac{P_{\mathcal{H}_1} \cdot P_{\mathbf{Y}|\mathcal{H}_1}(\mathbf{Y})}{P_{\mathcal{H}_0} \cdot P_{\mathbf{Y}|\mathcal{H}_0}(\mathbf{Y})}$$

If the receiver does not know if  $\mathcal{H}_1$  is more likely than  $\mathcal{H}_0$ ,

$$P_{\mathcal{H}_1} = P_{\mathcal{H}_0} = \frac{1}{2}$$

Therefore,

$$C(\mathbf{Y}) = \frac{P_{\mathbf{Y}|\mathcal{H}_1}(\mathbf{Y})}{P_{\mathbf{Y}|\mathcal{H}_0}(\mathbf{Y})}$$

・ロト ・回ト ・ヨト ・ヨト

### Solution

Solution of hypothesis testing is the function

$$C(\mathbf{Y}) = \frac{P_{\mathcal{H}_1|\mathbf{Y}}(\mathbf{Y})}{P_{\mathcal{H}_0|\mathbf{Y}}(\mathbf{Y})} = \frac{P_{\mathcal{H}_1} \cdot P_{\mathbf{Y}|\mathcal{H}_1}(\mathbf{Y})}{P_{\mathcal{H}_0} \cdot P_{\mathbf{Y}|\mathcal{H}_0}(\mathbf{Y})}$$

If the receiver does not know if  $\mathcal{H}_1$  is more likely than  $\mathcal{H}_0$ ,

$$P_{\mathcal{H}_1} = P_{\mathcal{H}_0} = \frac{1}{2}$$

Therefore,

$$C(\mathbf{Y}) = \frac{P_{\mathbf{Y}|\mathcal{H}_1}(\mathbf{Y})}{P_{\mathbf{Y}|\mathcal{H}_0}(\mathbf{Y})}$$

・ロト ・回ト ・ヨト ・ヨ

### Odds for hypothesis $\mathcal{H}_0$

If the SNR is known then the maximum Entropy Principle leads to

$$P_{\mathbf{Y}|\mathcal{H}_0}(\mathbf{Y}) = rac{1}{(\pi\sigma^2)^{NL}} e^{-rac{1}{\sigma^2} \operatorname{tr} \mathbf{Y} \mathbf{Y}^H}$$

(ロ) (同) (E) (E)

# Odds for hypothesis $\mathcal{H}_1$

If known N, M, SNR only then

$$\begin{aligned} P_{\mathbf{Y}|\mathcal{H}_{1}}(\mathbf{Y}) &= \int_{\Sigma} P_{\mathbf{Y}|\Sigma\mathcal{H}_{1}}(\mathbf{Y},\Sigma) P_{\Sigma}(\Sigma) d\Sigma \\ &= \int_{\mathcal{U}(N) \times \mathbb{R}^{+N}} P_{\mathbf{Y}|\Sigma\mathcal{H}_{1}}(\mathbf{Y},\mathbf{U},L\Lambda) P_{\Lambda}(\Lambda) d\mathbf{U} d\Lambda \end{aligned}$$

with

$$\boldsymbol{\Sigma} = L \begin{pmatrix} h_{11} & \dots & h_{1M} & \sigma & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ h_{N1} & \dots & h_{NM} & 0 & \dots & \sigma \end{pmatrix} \begin{pmatrix} h_{11} & \dots & h_{1M} & \sigma & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ h_{N1} & \dots & h_{NM} & 0 & \dots & \sigma \end{pmatrix}^{H}$$
$$= \mathbf{U} (L\mathbf{\Lambda}) \mathbf{U}^{H}$$

(ロ) (同) (E) (E)

### Odds for hypothesis $\mathcal{H}_1$ (2)

# Case M = 1. Maximum Entropy distribution for **H** is Gaussian i.i.d channel. *Unordered* eigenvalue distribution for $\Sigma$ ,

$$P_{\mathbf{\Lambda}}(\mathbf{\Lambda})d\mathbf{\Lambda} = \mathbf{1}_{(\lambda_1 > \sigma^2)} \frac{1}{N} (\lambda_1 - \sigma^2)^{N-1} \frac{\mathbf{e}^{-(\lambda_1 - \sigma^2)}}{(N-1)!} \prod_{i=2}^N \delta(\lambda_i - \sigma^2) d\lambda_1 \dots d\lambda_N$$

Maximum Entropy distribution for  $Y|\Sigma \mathcal{H}_1$  is correlated Gaussian,

$$P_{\mathbf{Y}|\boldsymbol{\Sigma} \boldsymbol{h}_{1}}(\mathbf{Y},\mathbf{U},\boldsymbol{L}\boldsymbol{\Lambda}) = \frac{1}{\pi^{LN}\det(\boldsymbol{\Lambda})^{L}} e^{-\operatorname{tr}\left(\mathbf{Y}\mathbf{Y}^{H}\mathbf{U}\boldsymbol{\Lambda}^{-1}\mathbf{U}^{H}\right)}$$

Sac

## Odds for hypothesis $\mathcal{H}_1$ (2)

# Case M = 1. Maximum Entropy distribution for **H** is Gaussian i.i.d channel. *Unordered* eigenvalue distribution for $\Sigma$ ,

$$P_{\mathbf{\Lambda}}(\mathbf{\Lambda})d\mathbf{\Lambda} = \mathbf{1}_{(\lambda_1 > \sigma^2)} \frac{1}{N} (\lambda_1 - \sigma^2)^{N-1} \frac{\mathbf{e}^{-(\lambda_1 - \sigma^2)}}{(N-1)!} \prod_{i=2}^N \delta(\lambda_i - \sigma^2) d\lambda_1 \dots d\lambda_N$$

Maximum Entropy distribution for  $\boldsymbol{Y}|\boldsymbol{\Sigma}\mathcal{H}_1$  is correlated Gaussian,

$$P_{\mathbf{Y}|\boldsymbol{\Sigma} \boldsymbol{I}_{1}}(\mathbf{Y}, \mathbf{U}, \boldsymbol{L} \boldsymbol{\Lambda}) = \frac{1}{\pi^{LN} \det(\boldsymbol{\Lambda})^{L}} e^{-\operatorname{tr}\left(\mathbf{Y} \mathbf{Y}^{H} \mathbf{U} \boldsymbol{\Lambda}^{-1} \mathbf{U}^{H}\right)}$$

● *M* = 1,

$$P_{\mathbf{Y}|I_1}(\mathbf{Y}) = \frac{e^{\sigma^2 - \frac{1}{\sigma^2} \sum_{i=1}^N \lambda_i}}{N \pi^{LN} \sigma^{2(N-1)(L-1)}} \sum_{l=1}^N \frac{e^{\frac{\lambda_l}{\sigma^2}}}{\prod_{\substack{i=1\\i \neq l}}^N (\lambda_l - \lambda_i)} J_{N-L-1}(\sigma^2, \lambda_l)$$

with  $(\lambda_1, \ldots, \lambda_N) = eig(\mathbf{Y}\mathbf{Y}^H)$  and

$$J_k(x,y) = \int_x^{+\infty} t^k e^{-t - \frac{y}{t}} dt$$

From which we have the Neyman-Pearson test

$$C_{\mathbf{Y}|l_{1}}(\mathbf{Y}) = \frac{1}{N} \sum_{l=1}^{N} \frac{\sigma^{2(N+L-1)} e^{\sigma^{2} + \frac{\lambda_{l}}{\sigma^{2}}}}{\prod_{\substack{i=1\\i\neq l}}^{N} (\lambda_{l} - \lambda_{i})} J_{N-L-1}(\sigma^{2}, \lambda_{l})$$

Neyman-Pearson test only depends on the eigenvalues! But in an involved way!

● *M* = 1,

$$P_{\mathbf{Y}|l_1}(\mathbf{Y}) = \frac{e^{\sigma^2 - \frac{1}{\sigma^2} \sum_{i=1}^N \lambda_i}}{N \pi^{LN} \sigma^{2(N-1)(L-1)}} \sum_{l=1}^N \frac{e^{\frac{\lambda_l}{\sigma^2}}}{\prod_{\substack{i=1\\i \neq l}}^N (\lambda_l - \lambda_i)} J_{N-L-1}(\sigma^2, \lambda_l)$$

with  $(\lambda_1, \ldots, \lambda_N) = eig(\mathbf{Y}\mathbf{Y}^H)$  and

$$J_k(x,y) = \int_x^{+\infty} t^k e^{-t - \frac{y}{t}} dt$$

• From which we have the Neyman-Pearson test

$$C_{\mathbf{Y}|l_1}(\mathbf{Y}) = \frac{1}{N} \sum_{l=1}^{N} \frac{\sigma^{2(N+L-1)} e^{\sigma^2 + \frac{\lambda_l}{\sigma^2}}}{\prod_{\substack{i=1\\i\neq l}}^{N} (\lambda_l - \lambda_i)} J_{N-L-1}(\sigma^2, \lambda_l)$$

Neyman-Pearson test only depends on the eigenvalues! But in an involved way!

● *M* = 1,

$$P_{\mathbf{Y}|I_1}(\mathbf{Y}) = \frac{e^{\sigma^2 - \frac{1}{\sigma^2} \sum_{i=1}^N \lambda_i}}{N \pi^{LN} \sigma^{2(N-1)(L-1)}} \sum_{l=1}^N \frac{e^{\frac{\lambda_l}{\sigma^2}}}{\prod_{\substack{i=1\\i \neq l}}^N (\lambda_l - \lambda_i)} J_{N-L-1}(\sigma^2, \lambda_l)$$

with  $(\lambda_1, \ldots, \lambda_N) = eig(\mathbf{Y}\mathbf{Y}^H)$  and

$$J_k(x,y) = \int_x^{+\infty} t^k e^{-t - \frac{y}{t}} dt$$

From which we have the Neyman-Pearson test

$$C_{\mathbf{Y}|l_1}(\mathbf{Y}) = \frac{1}{N} \sum_{l=1}^{N} \frac{\sigma^{2(N+L-1)} e^{\sigma^2 + \frac{\lambda_l}{\sigma^2}}}{\prod_{\substack{i=1\\i\neq l}}^{N} (\lambda_l - \lambda_i)} J_{N-L-1}(\sigma^2, \lambda_l)$$

Neyman-Pearson test only depends on the eigenvalues! But in an involved way!

● *M* = 1,

$$P_{\mathbf{Y}|l_1}(\mathbf{Y}) = \frac{e^{\sigma^2 - \frac{1}{\sigma^2} \sum_{i=1}^N \lambda_i}}{N \pi^{LN} \sigma^{2(N-1)(L-1)}} \sum_{l=1}^N \frac{e^{\frac{\lambda_l}{\sigma^2}}}{\prod_{\substack{i=1\\i \neq l}}^N (\lambda_l - \lambda_i)} J_{N-L-1}(\sigma^2, \lambda_l)$$

with  $(\lambda_1, \ldots, \lambda_N) = eig(\mathbf{Y}\mathbf{Y}^H)$  and

$$J_k(x,y) = \int_x^{+\infty} t^k e^{-t - \frac{y}{t}} dt$$

From which we have the Neyman-Pearson test

$$C_{\mathbf{Y}|l_1}(\mathbf{Y}) = \frac{1}{N} \sum_{l=1}^{N} \frac{\sigma^{2(N+L-1)} e^{\sigma^2 + \frac{\lambda_l}{\sigma^2}}}{\prod_{\substack{i=1\\i\neq l}}^{N} (\lambda_l - \lambda_i)} J_{N-L-1}(\sigma^2, \lambda_l)$$

Neyman-Pearson test only depends on the eigenvalues! But in an involved way!

A D A A B A A B A A B

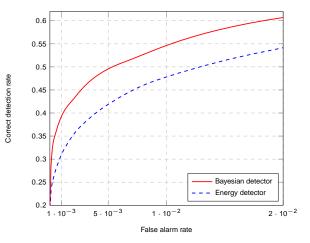


Figure: ROC curve for SIMO transmission, M = 1, N = 4, L = 8, SNR = -3 dB, FAR range of practical interest.

### What if *N<sub>t</sub>* is unknown?

Need to integrate out prior for M

$$P(\mathbf{Y}|l_0) = \sum_{i=1}^{M_{\text{max}}} P(\mathbf{Y}|"M = i", l_0) \cdot P("M = i"|l_0)$$
$$= \frac{1}{M_{\text{max}}} \sum_{i=1}^{M_{\text{max}}} P(\mathbf{Y}|"M = i", l_0)$$

( ) < </p>

- We need to integrate out the prior for  $\sigma^2$ .
- This leads to

$$C(\mathbf{Y}) = \frac{\int P_{\mathbf{Y}|\sigma^2, l'_{\mathcal{M}}}(\mathbf{Y}, \sigma^2) P_{\sigma^2}(\sigma^2) d\sigma^2}{\int P_{\mathbf{Y}|\sigma^2, \mathcal{H}_0}(\mathbf{Y}, \sigma^2) P_{\sigma^2}(\sigma^2) d\sigma^2}$$

- prior  $P_{\sigma^2}(\sigma^2)$  is chosen to be
  - uniform over  $[\sigma_{-}^2, \sigma_{+}^2]$
  - Jeffrey over  $(0,\infty)$

- We need to integrate out the prior for  $\sigma^2$ .
- This leads to

$$C(\mathbf{Y}) = \frac{\int P_{\mathbf{Y}|\sigma^2, I'_{M}}(\mathbf{Y}, \sigma^2) P_{\sigma^2}(\sigma^2) d\sigma^2}{\int P_{\mathbf{Y}|\sigma^2, \mathcal{H}_0}(\mathbf{Y}, \sigma^2) P_{\sigma^2}(\sigma^2) d\sigma^2}$$

- prior  $P_{\sigma^2}(\sigma^2)$  is chosen to be
  - uniform over  $[\sigma_-^2,\sigma_+^2]$
  - Jeffrey over  $(0,\infty)$

(I) < ((()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) <

### Outline

### Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

#### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

### 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

If  $\mathcal{H}_0$ , then the eigenvalues of  $\frac{1}{N}\mathbf{Y}\mathbf{Y}^H$  asymptotically distribute as

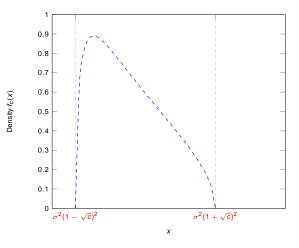


Figure: Marčenko-Pastur law with  $c = \lim N/L$ .

Z. D. Bai, J. W. Silverstein, "No eigenvalues outside the support of the limiting spectral distribution of large-dimensional sample covariance matrices," The Annals of Probability, vol. 26, no.1 pp. 316-345, 1998.

#### Theorem

 $P(no \text{ eigenvalues outside } [\sigma^2(1-\sqrt{c})^2, \sigma^2(1+\sqrt{c})^2] \text{ for all large } N) = 1$ 

• If  $\mathcal{H}_0$ 

$$\frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}{\lambda_{\min}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})} \xrightarrow{\text{a.s.}} \frac{(1+\sqrt{c})^2}{(1-\sqrt{c})^2}$$

independent of the SNR!

Z. D. Bai, J. W. Silverstein, "No eigenvalues outside the support of the limiting spectral distribution of large-dimensional sample covariance matrices," The Annals of Probability, vol. 26, no.1 pp. 316-345, 1998.

#### Theorem

P(no eigenvalues outside  $[\sigma^2(1-\sqrt{c})^2, \sigma^2(1+\sqrt{c})^2]$  for all large N) = 1

• If  $\mathcal{H}_0$ ,

$$\frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}{\lambda_{\min}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})} \xrightarrow{\text{a.s.}} \frac{(1+\sqrt{c})^2}{(1-\sqrt{c})^2}$$

independent of the SNR!

Z. D. Bai, J. W. Silverstein, "No eigenvalues outside the support of the limiting spectral distribution of large-dimensional sample covariance matrices," The Annals of Probability, vol. 26, no.1 pp. 316-345, 1998.

#### Theorem

 $P(no \text{ eigenvalues outside } [\sigma^2(1-\sqrt{c})^2, \sigma^2(1+\sqrt{c})^2] \text{ for all large } N) = 1$ 

• If  $\mathcal{H}_0$ ,

$$\frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}{\lambda_{\min}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})} \xrightarrow{\text{a.s.}} \frac{(1+\sqrt{c})^2}{(1-\sqrt{c})^2}$$

independent of the SNR!

L. S. Cardoso, M. Debbah, P. Bianchi, J. Najim, "Cooperative spectrum sensing using random matrix theory," International Symposium on Wireless Pervasive Computing, Santorini, Greece, 2008.

conditioning number test

$$C_{\text{cond}}(\mathbf{Y}) = \frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}{\lambda_{\min}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}$$

- if  $C_{\text{cond}}(\mathbf{Y}) > \tau$ , presence of a signal.
- if  $C_{\text{cond}}(\mathbf{Y}) < \tau$ , absence of signal.
- but this is ad-hoc! how good does it compare to optimal?
- can we find non ad-hoc approaches?

L. S. Cardoso, M. Debbah, P. Bianchi, J. Najim, "Cooperative spectrum sensing using random matrix theory," International Symposium on Wireless Pervasive Computing, Santorini, Greece, 2008.

conditioning number test

$$C_{\text{cond}}(\mathbf{Y}) = \frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}{\lambda_{\min}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}$$

- if  $C_{\text{cond}}(\mathbf{Y}) > \tau$ , presence of a signal.
- if  $C_{\text{cond}}(\mathbf{Y}) < \tau$ , absence of signal.
- but this is ad-hoc! how good does it compare to optimal?
- can we find non ad-hoc approaches?

Random Matrix Theory and Signal Source Sensing Large Dimensional Random Matrix Analysis Alternative Tests in Large Random Matrix Theory (2)

Bianchi, J. Najim, M. Maida, M. Debbah, "Performance of Some Eigen-based Hypothesis Tests for Collaborative Sensing," Proceedings of IEEE Statistical Signal Processing Workshop, 2009.

#### Generalized Likelihood Ratio Test

Alternative test to Neyman-Pearson,

$$C_{\text{GLRT}}(\mathbf{Y}) = \frac{\sup_{\mathbf{H},\sigma^2} P_{\mathcal{H}_1|\mathbf{Y},\mathbf{H},\sigma^2}(\mathbf{Y})}{\sup_{\sigma^2} P_{\mathcal{H}_0|\mathbf{Y},\sigma^2}(\mathbf{Y})}$$

- based on ratios of maximum likelihood
- clearly sub-optimal but avoid the need for priors.
- GLRT test

$$C_{\text{GLRT}}(\mathbf{Y}) = \left( \left(1 - \frac{1}{N}\right)^{N-1} \frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\text{H}})}{\frac{1}{N}\sum_{i=1}^{N}\lambda_i} \left(1 - \frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\text{H}})}{\sum_{i=1}^{N}\lambda_i}\right)^{N-1} \right)^{-1}$$

Contrary to the ad-hoc conditioning number test, GLRT based on



Random Matrix Theory and Signal Source Sensing Large Dimensional Random Matrix Analysis Alternative Tests in Large Random Matrix Theory (2)

Bianchi, J. Najim, M. Maida, M. Debbah, "Performance of Some Eigen-based Hypothesis Tests for Collaborative Sensing," Proceedings of IEEE Statistical Signal Processing Workshop, 2009.

#### Generalized Likelihood Ratio Test

Alternative test to Neyman-Pearson,

$$C_{\text{GLRT}}(\mathbf{Y}) = \frac{\sup_{\mathbf{H},\sigma^2} P_{\mathcal{H}_1|\mathbf{Y},\mathbf{H},\sigma^2}(\mathbf{Y})}{\sup_{\sigma^2} P_{\mathcal{H}_0|\mathbf{Y},\sigma^2}(\mathbf{Y})}$$

- based on ratios of maximum likelihood
- clearly sub-optimal but avoid the need for priors.
- GLRT test

$$C_{\text{GLRT}}(\mathbf{Y}) = \left( \left(1 - \frac{1}{N}\right)^{N-1} \frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\text{H}})}{\frac{1}{N}\sum_{i=1}^{N}\lambda_i} \left(1 - \frac{\lambda_{\max}(\frac{1}{N}\mathbf{Y}\mathbf{Y}^{\text{H}})}{\sum_{i=1}^{N}\lambda_i}\right)^{N-1} \right)^{-L}$$

Contrary to the ad-hoc conditioning number test, GLRT based on

 $\frac{\lambda_{\max}}{\frac{1}{N}\operatorname{tr}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}$ 

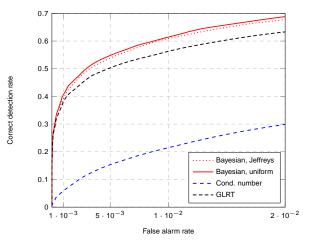


Figure: ROC curve for a priori unknown  $\sigma^2$  of the Bayesian method, conditioning number method and GLRT method, M = 1, N = 4, L = 8, SNR = 0 dB. For the Bayesian method, both uniform and Jeffreys prior, with exponent  $\alpha = 1$ , are provided.

### Outline

### Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

#### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

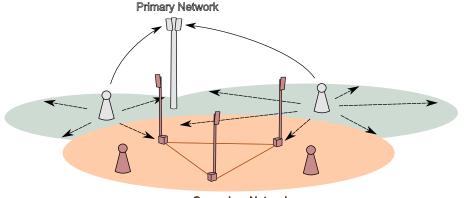
### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

### 5 Random Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

# Application Context: Coverage range in Femtocells



Secondary Network

イロン イヨン イヨン イヨ

a device embedded with N antennas receives a signal

- originating from multiple sources
- number of sources K is not necessarily known
- source k is equipped with  $n_k$  antennas (ideally  $n_k >> 1$ )
- signal k goes through unknown MIMO channel  $\mathbf{H}_k \in \mathbb{C}^{N \times n_k}$
- the variance  $\sigma^2$  of the additive noise is not necessarily known
- the problem is to infer
  - $P_1, ..., P_K$  knowing  $K, n_1, ..., n_K$
  - $P_1, \ldots, P_K$  and  $n_1, \ldots, n_K$  knowing K
  - *K*, *P*<sub>1</sub>, ..., *P*<sub>K</sub> and  $n_1, ..., n_k$

we will regard the problem under the angle of

- free deconvolution: i.e. from the moments of the receive YY<sup>H</sup>, infer those of P, and infer on P
- Stieltjes transform: i.e. from analytical formulas on the asymptotic eigenvalue distribution of  $YY^H$ , we derive consistent estimates of each  $P_k$ .

a device embedded with N antennas receives a signal

- originating from multiple sources
- number of sources K is not necessarily known
- source k is equipped with  $n_k$  antennas (ideally  $n_k >> 1$ )
- signal k goes through unknown MIMO channel  $\mathbf{H}_k \in \mathbb{C}^{N \times n_k}$
- the variance  $\sigma^2$  of the additive noise is not necessarily known
- the problem is to infer
  - $P_1, \ldots, P_K$  knowing  $K, n_1, \ldots, n_K$
  - $P_1, \ldots, P_K$  and  $n_1, \ldots, n_K$  knowing K
  - $K, P_1, \ldots, P_K$  and  $n_1, \ldots, n_k$

we will regard the problem under the angle of

- free deconvolution: i.e. from the moments of the receive YY<sup>H</sup>, infer those of **P**, and infer on **P**
- Stieltjes transform: i.e. from analytical formulas on the asymptotic eigenvalue distribution of **YY**<sup>H</sup>, we derive consistent estimates of each *P*<sub>k</sub>.

a device embedded with N antennas receives a signal

- originating from multiple sources
- number of sources K is not necessarily known
- source k is equipped with  $n_k$  antennas (ideally  $n_k >> 1$ )
- signal k goes through unknown MIMO channel  $\mathbf{H}_k \in \mathbb{C}^{N \times n_k}$
- the variance  $\sigma^2$  of the additive noise is not necessarily known
- the problem is to infer
  - $P_1, \ldots, P_K$  knowing  $K, n_1, \ldots, n_K$
  - $P_1, \ldots, P_K$  and  $n_1, \ldots, n_K$  knowing K
  - $K, P_1, \ldots, P_K$  and  $n_1, \ldots, n_P$

we will regard the problem under the angle of

- free deconvolution: i.e. from the moments of the receive YY<sup>H</sup>, infer those of P, and infer on P
- Stieltjes transform: i.e. from analytical formulas on the asymptotic eigenvalue distribution of  $YY^H$ , we derive consistent estimates of each  $P_k$ .

a device embedded with N antennas receives a signal

- originating from multiple sources
- number of sources K is not necessarily known
- source k is equipped with  $n_k$  antennas (ideally  $n_k >> 1$ )
- signal k goes through unknown MIMO channel  $\mathbf{H}_k \in \mathbb{C}^{N \times n_k}$
- the variance  $\sigma^2$  of the additive noise is not necessarily known
- the problem is to infer
  - $P_1, \ldots, P_K$  knowing  $K, n_1, \ldots, n_K$
  - $P_1, \ldots, P_K$  and  $n_1, \ldots, n_K$  knowing K
  - *K*, *P*<sub>1</sub>, . . . , *P*<sub>K</sub> and *n*<sub>1</sub>, . . . , *n*<sub>K</sub>

we will regard the problem under the angle of

- free deconvolution: i.e. from the moments of the receive YY<sup>H</sup>, infer those of P, and infer on P
- Stieltjes transform: i.e. from analytical formulas on the asymptotic eigenvalue distribution of  $\mathbf{Y}\mathbf{Y}^{\mathsf{H}}$ , we derive consistent estimates of each  $P_k$ .

a device embedded with N antennas receives a signal

- originating from multiple sources
- number of sources K is not necessarily known
- source k is equipped with  $n_k$  antennas (ideally  $n_k >> 1$ )
- signal k goes through unknown MIMO channel  $\mathbf{H}_k \in \mathbb{C}^{N \times n_k}$
- the variance  $\sigma^2$  of the additive noise is not necessarily known
- the problem is to infer
  - $P_1, \ldots, P_K$  knowing  $K, n_1, \ldots, n_K$
  - $P_1, \ldots, P_K$  and  $n_1, \ldots, n_K$  knowing K
  - *K*, *P*<sub>1</sub>, . . . , *P*<sub>K</sub> and *n*<sub>1</sub>, . . . , *n*<sub>K</sub>

## we will regard the problem under the angle of

- free deconvolution: i.e. from the moments of the receive YY<sup>H</sup>, infer those of P, and infer on P
- Stieltjes transform: i.e. from analytical formulas on the asymptotic eigenvalue distribution of  $\mathbf{Y}\mathbf{Y}^{\mathsf{H}}$ , we derive consistent estimates of each  $P_k$ .

a device embedded with N antennas receives a signal

- originating from multiple sources
- number of sources K is not necessarily known
- source k is equipped with  $n_k$  antennas (ideally  $n_k >> 1$ )
- signal k goes through unknown MIMO channel  $\mathbf{H}_k \in \mathbb{C}^{N \times n_k}$
- the variance  $\sigma^2$  of the additive noise is not necessarily known
- the problem is to infer
  - $P_1, \ldots, P_K$  knowing  $K, n_1, \ldots, n_K$
  - $P_1, \ldots, P_K$  and  $n_1, \ldots, n_K$  knowing K
  - *K*, *P*<sub>1</sub>, . . . , *P*<sub>K</sub> and *n*<sub>1</sub>, . . . , *n*<sub>K</sub>

we will regard the problem under the angle of

- free deconvolution: i.e. from the moments of the receive **YY**<sup>H</sup>, infer those of **P**, and infer on **P**
- Stieltjes transform: i.e. from analytical formulas on the asymptotic eigenvalue distribution of YY<sup>H</sup>, we derive consistent estimates of each P<sub>k</sub>.

- at time *t*, source *k* transmit signal  $\mathbf{x}_{k}^{(t)} \in \mathbb{C}^{n_{k}}$  with i.i.d. entries of zero mean and variance 1.
- we denote P<sub>k</sub> the power emitted by user k
- the channel  $\mathbf{H}_k \in \mathbb{C}^{N \times n_k}$  from user *k* to the receiver has i.i.d. entries of zero mean and variance 1/N.
- at time *t*, the additive noise is denoted  $\sigma \mathbf{w}^{(t)}$ , with  $\mathbf{w}^{(t)} \in \mathbb{C}^N$  with i.i.d. entries of zero mean and variance 1.
- hence the receive signal  $\mathbf{y}^{(t)}$  at time t,

$$\mathbf{y}^{(t)} = \sum_{k=1}^{K} \mathbf{H}_k \sqrt{P_k} \mathbf{x}_k^{(t)} + \sigma \mathbf{w}_k^{(t)}$$

Gathering *M* time instant into  $\mathbf{Y} = [\mathbf{y}^{(1)} \dots \mathbf{y}^{(M)}] \in \mathbb{C}^{N \times M}$ , this can be written

$$\mathbf{Y} = \sum_{k=1}^{K} \mathbf{H}_k \sqrt{P_k} \mathbf{X}_k + \sigma \mathbf{W} = \mathbf{H} \mathbf{P}^{\frac{1}{2}} \mathbf{X} + \sigma \mathbf{W}$$

with  $\mathbf{H} = [\mathbf{H}_1 \dots \mathbf{H}_K] \in \mathbb{C}^{N \times n}$ ,  $n = \sum_{k=1}^K n_k$ ,  $\mathbf{P} = \text{diag}(P_1, \dots, P_1, P_2, \dots, P_2, \dots, P_K, \dots, P_K)$  where  $P_k$  has multiplicity  $n_k$  on the diagonal,  $\mathbf{X}^{H} = [\mathbf{X}_1^{H} \dots \mathbf{X}_K^{H}]^{H} \in \mathbb{C}^{n \times M}$ ,  $\mathbf{X}_k = [\mathbf{x}_k^{(1)} \dots \mathbf{x}_k^{(M)}] \in \mathbb{C}^{n_k \times M}$ ,  $\mathbf{W}$  defined similarly.

- at time *t*, source *k* transmit signal  $\mathbf{x}_{k}^{(t)} \in \mathbb{C}^{n_{k}}$  with i.i.d. entries of zero mean and variance 1.
- we denote P<sub>k</sub> the power emitted by user k
- the channel  $\mathbf{H}_k \in \mathbb{C}^{N \times n_k}$  from user *k* to the receiver has i.i.d. entries of zero mean and variance 1/N.
- at time *t*, the additive noise is denoted  $\sigma \mathbf{w}^{(t)}$ , with  $\mathbf{w}^{(t)} \in \mathbb{C}^N$  with i.i.d. entries of zero mean and variance 1.
- hence the receive signal  $\mathbf{y}^{(t)}$  at time t,

$$\mathbf{y}^{(t)} = \sum_{k=1}^{K} \mathbf{H}_k \sqrt{P_k} \mathbf{x}_k^{(t)} + \sigma \mathbf{w}_k^{(t)}$$

Gathering *M* time instant into  $\mathbf{Y} = [\mathbf{y}^{(1)} \dots \mathbf{y}^{(M)}] \in \mathbb{C}^{N \times M}$ , this can be written

$$\mathbf{Y} = \sum_{k=1}^{K} \mathbf{H}_k \sqrt{P_k} \mathbf{X}_k + \sigma \mathbf{W} = \mathbf{H} \mathbf{P}^{\frac{1}{2}} \mathbf{X} + \sigma \mathbf{W}$$

with  $\mathbf{H} = [\mathbf{H}_1 \dots \mathbf{H}_K] \in \mathbb{C}^{N \times n}$ ,  $n = \sum_{k=1}^K n_k$ ,  $\mathbf{P} = \text{diag}(P_1, \dots, P_1, P_2, \dots, P_2, \dots, P_K, \dots, P_K)$  where  $P_k$  has multiplicity  $n_k$  on the diagonal,  $\mathbf{X}^H = [\mathbf{X}_1^H \dots \mathbf{X}_K^H]^H \in \mathbb{C}^{n \times M}$ ,  $\mathbf{X}_k = [\mathbf{x}_k^{(1)} \dots \mathbf{x}_k^{(M)}] \in \mathbb{C}^{n_k \times M}$ ,  $\mathbf{W}$  defined similarly.

( \_ ) ( \_ ] ) ( \_ ) ( \_ ) ( \_ ) )

# Outline

# Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

## 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

# 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

# Bandom Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

Random Matrix Theory and Multi-Source Power Estimation

Free Probability Approach

### Free probability provides tools to compute

$$d_k = \frac{1}{K} \sum_{i=1}^{K} \lambda(\mathbf{P})^k = \frac{1}{K} \sum_{i=1}^{K} P_i^k$$

### as a function of

$$m_k = \frac{1}{N} \sum_{i=1}^N \lambda(\frac{1}{M} \mathbf{Y} \mathbf{Y}^\mathsf{H})^k$$

- One can obtain all the successive sum powers of P<sub>1</sub>,..., P<sub>K</sub>.
- From that, we can infer on the values of each P<sub>k</sub>
- The tools come from the relations,
  - cumulant to moment (and also moment to cumulant)

$$M_n = \sum_{\pi \in NC(n)} \prod_{V \in \pi} C_{|V|}$$

• Sums of cumulants for asymptotically free A and B (of measure  $\mu_A \boxplus \mu_B$ ),

$$C_k(\mathbf{A} + \mathbf{B}) = C_k(\mathbf{A}) + C_k(\mathbf{B})$$

• Products of cumulants for asymptotically free A and B (of measure  $\mu_A \boxtimes \mu_B$ ),

$$M_n(\mathbf{AB}) = \sum_{\substack{(\pi_1, \pi_2) \in NC(n)}} \prod_{\substack{V_1 \in \pi_1 \\ V_2 \in \pi_2}} C_{|V_1|}(\mathbf{A}) C_{|V_2|}(\mathbf{B})$$

• Moments of information plus noise models  $\mathbf{B}_N = \frac{1}{n} (\mathbf{A}_N + \sigma \mathbf{W}_N) (\mathbf{A}_N + \sigma \mathbf{W}_N)^{\mathsf{H}}$ ,

$$\mu_B = \left( \left( \mu_A \boxtimes \mu_c \right) \boxplus \delta_{\sigma^2} \right) \boxtimes \mu_c$$

with  $\mu_c$  the Marcenko-Pastur law with ratio c

R. Couillet (Supélec)

Random Matrix Theory and Multi-Source Power Estimation

Free Probability Approach

### Free probability provides tools to compute

$$d_k = \frac{1}{K} \sum_{i=1}^K \lambda(\mathbf{P})^k = \frac{1}{K} \sum_{i=1}^K P_i^k$$

as a function of

$$m_k = rac{1}{N}\sum_{i=1}^N \lambda(rac{1}{M}\mathbf{Y}\mathbf{Y}^\mathsf{H})^k$$

One can obtain all the successive sum powers of P<sub>1</sub>,..., P<sub>K</sub>.

### From that, we can infer on the values of each P<sub>k</sub>!

The tools come from the relations,

cumulant to moment (and also moment to cumulant)

$$M_n = \sum_{\pi \in NC(n)} \prod_{V \in \pi} C_{|V|}$$

• Sums of cumulants for asymptotically free A and B (of measure  $\mu_A \boxplus \mu_B$ ),

$$C_k(\mathbf{A} + \mathbf{B}) = C_k(\mathbf{A}) + C_k(\mathbf{B})$$

• Products of cumulants for asymptotically free A and B (of measure  $\mu_A \boxtimes \mu_B$ ),

$$M_n(\mathbf{AB}) = \sum_{\substack{(\pi_1, \pi_2) \in NC(n) \\ V_1 \in \pi_1 \\ V_2 \in \pi_2}} \prod_{\substack{V_1 \in \pi_1 \\ V_2 \in \pi_2}} C_{|V_1|}(\mathbf{A}) C_{|V_2|}(\mathbf{B})$$

• Moments of information plus noise models  $\mathbf{B}_N = \frac{1}{n} (\mathbf{A}_N + \sigma \mathbf{W}_N) (\mathbf{A}_N + \sigma \mathbf{W}_N)^{H}$ ,

$$\mu_B = \left( \left( \mu_A \boxtimes \mu_c \right) \boxplus \delta_{\sigma^2} \right) \boxtimes \mu_c$$

with  $\mu_c$  the Marcenko-Pastur law with ratio c

R. Couillet (Supélec)

Random Matrix Theory and Multi-Source Power Estimation

Free Probability Approach

### Free probability provides tools to compute

$$d_k = \frac{1}{K} \sum_{i=1}^K \lambda(\mathbf{P})^k = \frac{1}{K} \sum_{i=1}^K P_i^k$$

as a function of

$$m_k = rac{1}{N} \sum_{i=1}^N \lambda (rac{1}{M} \mathbf{Y} \mathbf{Y}^\mathsf{H})^k$$

- One can obtain all the successive sum powers of  $P_1, \ldots, P_K$ .
- From that, we can infer on the values of each P<sub>k</sub>!
- The tools come from the relations,
  - cumulant to moment (and also moment to cumulant),

$$M_n = \sum_{\pi \in NC(n)} \prod_{V \in \pi} C_{|V|}$$

• Sums of cumulants for asymptotically free A and B (of measure  $\mu_A \boxplus \mu_B$ ),

$$C_k(\mathbf{A} + \mathbf{B}) = C_k(\mathbf{A}) + C_k(\mathbf{B})$$

• Products of cumulants for asymptotically free A and B (of measure  $\mu_A \boxtimes \mu_B$ ),

$$M_n(\mathbf{AB}) = \sum_{\substack{(\pi_1, \pi_2) \in NC(n)}} \prod_{\substack{V_1 \in \pi_1 \\ V_2 \in \pi_2}} C_{|V_1|}(\mathbf{A}) C_{|V_2|}(\mathbf{B})$$

• Moments of information plus noise models  $\mathbf{B}_N = \frac{1}{n} (\mathbf{A}_N + \sigma \mathbf{W}_N) (\mathbf{A}_N + \sigma \mathbf{W}_N)^H$ ,

$$\mu_{B} = \left( (\mu_{A} \boxtimes \mu_{c}) \boxplus \delta_{\sigma^{2}} \right) \boxtimes \mu_{c}$$

with  $\mu_c$  the Marčenko-Pastur law with ratio c.

R. Couillet (Supélec)

Sac

- one can deconvolve **YY**<sup>H</sup> in three steps,
  - an information-plus-noise model with "deterministic matrix"  $HP^{\frac{1}{2}}XX^{H}P^{\frac{1}{2}}H^{H}$ ,

$$\mathbf{Y}\mathbf{Y}^{\mathsf{H}} = (\mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W})(\mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W})^{\mathsf{H}}$$

- from  $\mathbf{HP}^{\frac{1}{2}} \mathbf{XX}^{H} \mathbf{P}^{\frac{1}{2}} \mathbf{H}^{H}$ , up to a Gram matrix commutation, we can deconvolve the signal  $\mathbf{X}$ ,  $\mathbf{P}^{\frac{1}{2}} \mathbf{HH}^{H} \mathbf{P}^{\frac{1}{2}} \mathbf{XX}^{H}$
- from  $\mathbf{P}^{\frac{1}{2}}\mathbf{H}\mathbf{H}^{H}\mathbf{P}^{\frac{1}{2}}$ , a new matrix commutation allows one to deconvolve  $\mathbf{H}\mathbf{H}^{H}$

PHH<sup>H</sup>

Sac

- one can deconvolve **YY**<sup>H</sup> in three steps,
  - an information-plus-noise model with "deterministic matrix"  $HP^{\frac{1}{2}}XX^{H}P^{\frac{1}{2}}H^{H}$ ,

$$\mathbf{Y}\mathbf{Y}^{\mathsf{H}} = (\mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W})(\mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W})^{\mathsf{H}}$$

- from  $\mathbf{HP}^{\frac{1}{2}}\mathbf{XX}^{H}\mathbf{P}^{\frac{1}{2}}\mathbf{H}^{H}$ , up to a Gram matrix commutation, we can deconvolve the signal **X**,  $\mathbf{P}^{\frac{1}{2}}\mathbf{HH}^{H}\mathbf{P}^{\frac{1}{2}}\mathbf{XX}^{H}$
- from P<sup>1/2</sup> HH<sup>H</sup>P<sup>1/2</sup>, a new matrix commutation allows one to deconvolve HH<sup>H</sup>
   PHH<sup>H</sup>

Sac

- one can deconvolve **YY**<sup>H</sup> in three steps,
  - an information-plus-noise model with "deterministic matrix"  $HP^{\frac{1}{2}}XX^{H}P^{\frac{1}{2}}H^{H}$ ,

$$\mathbf{Y}\mathbf{Y}^{\mathsf{H}} = (\mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W})(\mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W})^{\mathsf{H}}$$

- from  $\mathbf{HP}^{\frac{1}{2}}\mathbf{XX}^{H}\mathbf{P}^{\frac{1}{2}}\mathbf{H}^{H}$ , up to a Gram matrix commutation, we can deconvolve the signal **X**,  $\mathbf{P}^{\frac{1}{2}}\mathbf{HH}^{H}\mathbf{P}^{\frac{1}{2}}\mathbf{XX}^{H}$
- from  $\mathbf{P}^{\frac{1}{2}}\mathbf{H}\mathbf{H}^{H}\mathbf{P}^{\frac{1}{2}}$ , a new matrix commutation allows one to deconvolve  $\mathbf{H}\mathbf{H}^{H}$

In terms of free probability operations, this is

noise deconvolution

$$\boldsymbol{\mu}_{\frac{1}{M}\mathbf{HP}^{\frac{1}{2}}\mathbf{XX}^{\mathsf{H}}\mathbf{P}^{\frac{1}{2}}\mathbf{H}^{\mathsf{H}}} = \left( \left( \boldsymbol{\mu}_{\frac{1}{M}\mathbf{YY}^{\mathsf{H}}} \boxtimes \boldsymbol{\mu}_{\mathbf{C}} \right) \boxminus \boldsymbol{\delta}_{\sigma^{2}} \right) \boxtimes \boldsymbol{\mu}_{\mathbf{C}}$$

with  $\mu_c$  the Marčenko-Pastur law and c = N/M.

signal deconvolution

$$\mu_{\frac{1}{M}\mathbf{P}^{\frac{1}{2}}\mathbf{H}^{H}\mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X}\mathbf{X}^{H}} = \frac{N}{n}\mu_{\frac{1}{M}\mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X}\mathbf{X}^{H}\mathbf{P}^{\frac{1}{2}}\mathbf{H}^{H}} + \left(1 - \frac{N}{n}\right)\delta_{0}$$

channel deconvolution

$$\mu_{\mathbf{P}} = \mu_{\mathbf{P}\frac{1}{n}\mathbf{H}^{\mathsf{H}}\mathbf{H}} \boxtimes \mu_{\eta_{c_{1}}}$$

with  $c_1 = n/N$ 

In terms of free probability operations, this is

noise deconvolution

$$\boldsymbol{\mu}_{\frac{1}{M}\mathsf{HP}^{\frac{1}{2}}\mathsf{XX}^{\mathsf{H}}\mathsf{P}^{\frac{1}{2}}\mathsf{H}^{\mathsf{H}}} = \left( (\boldsymbol{\mu}_{\frac{1}{M}\mathsf{YY}^{\mathsf{H}}} \boxtimes \boldsymbol{\mu}_{c}) \boxminus \delta_{\sigma^{2}} \right) \boxtimes \boldsymbol{\mu}_{c}$$

with  $\mu_c$  the Marčenko-Pastur law and c = N/M.

signal deconvolution

$$\mu_{\frac{1}{M}\mathsf{P}^{\frac{1}{2}}\mathsf{H}^{\mathsf{H}}\mathsf{H}\mathsf{P}^{\frac{1}{2}}\mathsf{X}\mathsf{X}^{\mathsf{H}}} = \frac{N}{n}\mu_{\frac{1}{M}\mathsf{H}\mathsf{P}^{\frac{1}{2}}}\mathsf{X}\mathsf{X}^{\mathsf{H}}\mathsf{P}^{\frac{1}{2}}\mathsf{H}^{\mathsf{H}}} + \left(1 - \frac{N}{n}\right)\delta_{0}$$

channel deconvolution

$$\mu_{\mathbf{P}} = \mu_{\mathbf{P}\frac{1}{n}\mathbf{H}^{\mathsf{H}}\mathbf{H}} \boxtimes \mu_{\eta_{c_{1}}}$$

with  $c_1 = n/N$ 

Sac

(ロ) (同) (E) (E)

In terms of free probability operations, this is

noise deconvolution

$$\boldsymbol{\mu}_{\frac{1}{M}\mathsf{HP}^{\frac{1}{2}}\mathsf{XX}^{\mathsf{H}}\mathsf{P}^{\frac{1}{2}}\mathsf{H}^{\mathsf{H}}} = \left( (\boldsymbol{\mu}_{\frac{1}{M}\mathsf{YY}^{\mathsf{H}}} \boxtimes \boldsymbol{\mu}_{c}) \boxminus \delta_{\sigma^{2}} \right) \boxtimes \boldsymbol{\mu}_{c}$$

with  $\mu_c$  the Marčenko-Pastur law and c = N/M.

signal deconvolution

$$\mu_{\frac{1}{M}\mathsf{P}^{\frac{1}{2}}\mathsf{H}^{\mathsf{H}}\mathsf{H}\mathsf{P}^{\frac{1}{2}}\mathsf{X}\mathsf{X}^{\mathsf{H}}} = \frac{N}{n}\mu_{\frac{1}{M}\mathsf{H}\mathsf{P}^{\frac{1}{2}}}\mathsf{X}\mathsf{X}^{\mathsf{H}}\mathsf{P}^{\frac{1}{2}}\mathsf{H}^{\mathsf{H}}} + \left(1 - \frac{N}{n}\right)\delta_{0}$$

channel deconvolution

$$\mu_{\mathbf{P}} = \mu_{\mathbf{P}\frac{1}{n}\mathbf{H}^{\mathsf{H}}\mathbf{H}} \boxtimes \mu_{\eta_{c_{1}}}$$

with  $c_1 = n/N$ 

Sac

# Random Matrix Theory and Multi-Source Power Estimation Free Probability Approach Free deconvolution: moments

- from the three previous steps (plus addition of null eigenvalues), the moments of P can be computed from those of YY<sup>H</sup>.
- this process can be automatized by combinatorics softwares
- finite size formulas are also available
- the first moments  $m_k$  of  $\frac{1}{M} \mathbf{Y} \mathbf{Y}^H$  as a function of the first moments  $d_k$  of **P** read

$$\begin{split} m_1 &= N^{-1}nd_1 + 1 \\ m_2 &= \left(N^{-2}M^{-1}n + N^{-1}n\right)d_2 + \left(N^{-2}n^2 + N^{-1}M^{-1}n^2\right)d_1^2 \\ &+ \left(2N^{-1}n + 2M^{-1}n\right)d_1 + \left(1 + NM^{-1}\right) \\ m_3 &= \left(3N^{-3}M^{-2}n + N^{-3}n + 6N^{-2}M^{-1}n + N^{-1}M^{-2}n + N^{-1}n\right)d_3 \\ &+ \left(6N^{-3}M^{-1}n^2 + 6N^{-2}M^{-2}n^2 + 3N^{-2}n^2 + 3N^{-1}M^{-1}n^2\right)d_2d_1 \\ &+ \left(N^{-3}M^{-2}n^3 + N^{-3}n^3 + 3N^{-2}M^{-1}n^3 + N^{-1}M^{-2}n^3\right)d_1^3 \\ &+ \left(6N^{-2}M^{-1}n + 6N^{-1}M^{-2}n + 3N^{-1}n + 3M^{-1}n\right)d_2 \\ &+ \left(3N^{-2}M^{-2}n^2 + 3N^{-2}n^2 + 9N^{-1}M^{-1}n^2 + 3M^{-2}n^2\right)d_1^2 \\ &+ \left(3N^{-1}M^{-2}n + 3N^{-1}n + 9M^{-1}n + 3NM^{-2}n\right)d_1 \end{split}$$

$$m_k = \frac{1}{N} \sum_{i=1}^N \lambda (\frac{1}{M} \mathbf{Y} \mathbf{Y}^{\mathsf{H}})^k \text{ and } d_k = \frac{1}{K} \sum_{i=1}^K \lambda (\mathbf{P})^k = \frac{1}{K} \sum_{i=1}^K P_i^k$$

# Random Matrix Theory and Multi-Source Power Estimation Free Probability Approach Free deconvolution: moments

- from the three previous steps (plus addition of null eigenvalues), the moments of P can be computed from those of YY<sup>H</sup>.
- this process can be automatized by combinatorics softwares
- finite size formulas are also available
- the first moments  $m_k$  of  $\frac{1}{M}YY^H$  as a function of the first moments  $d_k$  of **P** read

$$\begin{split} m_1 &= N^{-1} n d_1 + 1 \\ m_2 &= \left( N^{-2} M^{-1} n + N^{-1} n \right) d_2 + \left( N^{-2} n^2 + N^{-1} M^{-1} n^2 \right) d_1^2 \\ &+ \left( 2 N^{-1} n + 2 M^{-1} n \right) d_1 + \left( 1 + N M^{-1} \right) \\ m_3 &= \left( 3 N^{-3} M^{-2} n + N^{-3} n + 6 N^{-2} M^{-1} n + N^{-1} M^{-2} n + N^{-1} n \right) d_3 \\ &+ \left( 6 N^{-3} M^{-1} n^2 + 6 N^{-2} M^{-2} n^2 + 3 N^{-2} n^2 + 3 N^{-1} M^{-1} n^2 \right) d_2 d_1 \\ &+ \left( N^{-3} M^{-2} n^3 + N^{-3} n^3 + 3 N^{-2} M^{-1} n^3 + N^{-1} M^{-2} n^3 \right) d_1^3 \\ &+ \left( 6 N^{-2} M^{-1} n + 6 N^{-1} M^{-2} n + 3 N^{-1} n + 3 M^{-1} n \right) d_2 \\ &+ \left( 3 N^{-2} M^{-2} n^2 + 3 N^{-2} n^2 + 9 N^{-1} M^{-1} n^2 + 3 M^{-2} n^2 \right) d_1^2 \\ &+ \left( 3 N^{-1} M^{-2} n + 3 N^{-1} n + 9 M^{-1} n + 3 N M^{-2} n \right) d_1 \end{split}$$

$$m_k = \frac{1}{N} \sum_{i=1}^N \lambda (\frac{1}{M} \mathbf{Y} \mathbf{Y}^{\mathsf{H}})^k \text{ and } d_k = \frac{1}{K} \sum_{i=1}^K \lambda (\mathbf{P})^k = \frac{1}{K} \sum_{i=1}^K P_i^k$$

# Random Matrix Theory and Multi-Source Power Estimation Free Probability Approach Free deconvolution: moments

- from the three previous steps (plus addition of null eigenvalues), the moments of P can be computed from those of YY<sup>H</sup>.
- this process can be automatized by combinatorics softwares
- finite size formulas are also available
- the first moments  $m_k$  of  $\frac{1}{M} \mathbf{Y} \mathbf{Y}^H$  as a function of the first moments  $d_k$  of **P** read

$$\begin{split} m_1 &= N^{-1} n d_1 + 1 \\ m_2 &= \left( N^{-2} M^{-1} n + N^{-1} n \right) d_2 + \left( N^{-2} n^2 + N^{-1} M^{-1} n^2 \right) d_1^2 \\ &+ \left( 2 N^{-1} n + 2 M^{-1} n \right) d_1 + \left( 1 + N M^{-1} \right) \\ m_3 &= \left( 3 N^{-3} M^{-2} n + N^{-3} n + 6 N^{-2} M^{-1} n + N^{-1} M^{-2} n + N^{-1} n \right) d_3 \\ &+ \left( 6 N^{-3} M^{-1} n^2 + 6 N^{-2} M^{-2} n^2 + 3 N^{-2} n^2 + 3 N^{-1} M^{-1} n^2 \right) d_2 d_1 \\ &+ \left( N^{-3} M^{-2} n^3 + N^{-3} n^3 + 3 N^{-2} M^{-1} n^3 + N^{-1} M^{-2} n^3 \right) d_1^3 \\ &+ \left( 6 N^{-2} M^{-1} n + 6 N^{-1} M^{-2} n + 3 N^{-1} n + 3 M^{-1} n \right) d_2 \\ &+ \left( 3 N^{-2} M^{-2} n^2 + 3 N^{-2} n^2 + 9 N^{-1} M^{-1} n^2 + 3 M^{-2} n^2 \right) d_1^2 \\ &+ \left( 3 N^{-1} M^{-2} n + 3 N^{-1} n + 9 M^{-1} n + 3 N M^{-2} n \right) d_1 \end{split}$$

$$m_k = \frac{1}{N} \sum_{i=1}^N \lambda (\frac{1}{M} \mathbf{Y} \mathbf{Y}^{\mathsf{H}})^k \text{ and } d_k = \frac{1}{K} \sum_{i=1}^K \lambda (\mathbf{P})^k = \frac{1}{K} \sum_{i=1}^K P_i^k$$

#### Random Matrix Theory and Multi-Source Power Estimation Free Probability Approach Free deconvolution: moments

- from the three previous steps (plus addition of null eigenvalues), the moments of P can be computed from those of YY<sup>H</sup>.
- this process can be automatized by combinatorics softwares
- finite size formulas are also available
- the first moments  $m_k$  of  $\frac{1}{M}\mathbf{Y}\mathbf{Y}^H$  as a function of the first moments  $d_k$  of **P** read

$$\begin{split} m_1 &= N^{-1} n d_1 + 1 \\ m_2 &= \left( N^{-2} M^{-1} n + N^{-1} n \right) d_2 + \left( N^{-2} n^2 + N^{-1} M^{-1} n^2 \right) d_1^2 \\ &+ \left( 2 N^{-1} n + 2 M^{-1} n \right) d_1 + \left( 1 + N M^{-1} \right) \\ m_3 &= \left( 3 N^{-3} M^{-2} n + N^{-3} n + 6 N^{-2} M^{-1} n + N^{-1} M^{-2} n + N^{-1} n \right) d_3 \\ &+ \left( 6 N^{-3} M^{-1} n^2 + 6 N^{-2} M^{-2} n^2 + 3 N^{-2} n^2 + 3 N^{-1} M^{-1} n^2 \right) d_2 d_1 \\ &+ \left( N^{-3} M^{-2} n^3 + N^{-3} n^3 + 3 N^{-2} M^{-1} n^3 + N^{-1} M^{-2} n^3 \right) d_1^3 \\ &+ \left( 6 N^{-2} M^{-1} n + 6 N^{-1} M^{-2} n + 3 N^{-1} n + 3 M^{-1} n \right) d_2 \\ &+ \left( 3 N^{-2} M^{-2} n^2 + 3 N^{-2} n^2 + 9 N^{-1} M^{-1} n^2 + 3 M^{-2} n^2 \right) d_1^2 \\ &+ \left( 3 N^{-1} M^{-2} n + 3 N^{-1} n + 9 M^{-1} n + 3 M M^{-2} n \right) d_1 \end{split}$$

$$m_k = \frac{1}{N} \sum_{i=1}^N \lambda (\frac{1}{M} \mathbf{Y} \mathbf{Y}^{\mathsf{H}})^k \text{ and } d_k = \frac{1}{K} \sum_{i=1}^K \lambda (\mathbf{P})^k = \frac{1}{K} \sum_{i=1}^K P_i^k$$

#### Random Matrix Theory and Multi-Source Power Estimation Free Probability Approach Free deconvolution: inferring powers

- For practical finite size applications, the deconvolved moments will exhibit errors. Different strategies are available,
- direct inversion with Newton-Girard formulas. Assuming perfect evaluation of  $\frac{1}{K} \sum_{k=1}^{K} P_k^m$ ,  $P_1, \ldots, P_K$  are given by the K solutions of the polynomial

$$X^{K} - \Pi_{1}X^{K-1} + \Pi_{2}X^{K-2} - \ldots + (-1)^{K}\Pi_{K}$$

where the  $\Pi_m$ 's (known as the *elementary symmetric polynomials*) are iteratively defined as

$$(-1)^k k \Pi_k + \sum_{i=1}^k (-1)^{k+i} S_i \Pi_{k-i} = 0$$

where  $S_k = \sum_{i=1}^k P_i^k$ .

- may lead to non-real solutions!
- o does not minimize any conventional error criterion
- convenient for one-shot power inference
- when multiple realizations are available, statistical solutions are preferable

- For practical finite size applications, the deconvolved moments will exhibit errors. Different strategies are available,
- direct inversion with Newton-Girard formulas. Assuming perfect evaluation of  $\frac{1}{K} \sum_{k=1}^{K} P_k^m$ ,  $P_1, \ldots, P_K$  are given by the K solutions of the polynomial

$$X^{K} - \Pi_{1}X^{K-1} + \Pi_{2}X^{K-2} - \ldots + (-1)^{K}\Pi_{K}$$

where the  $\Pi_m$ 's (known as the elementary symmetric polynomials) are iteratively defined as

$$(-1)^k k \Pi_k + \sum_{i=1}^k (-1)^{k+i} S_i \Pi_{k-i} = 0$$

where  $S_k = \sum_{i=1}^k P_i^k$ .

- may lead to non-real solutions!
- o does not minimize any conventional error criterion
- convenient for one-shot power inference
- when multiple realizations are available, statistical solutions are preferable

- For practical finite size applications, the deconvolved moments will exhibit errors. Different strategies are available,
- direct inversion with Newton-Girard formulas. Assuming perfect evaluation of  $\frac{1}{K} \sum_{k=1}^{K} P_k^m$ ,  $P_1, \ldots, P_K$  are given by the K solutions of the polynomial

$$X^{K} - \Pi_{1}X^{K-1} + \Pi_{2}X^{K-2} - \ldots + (-1)^{K}\Pi_{K}$$

where the  $\Pi_m$ 's (known as the elementary symmetric polynomials) are iteratively defined as

$$(-1)^k k \Pi_k + \sum_{i=1}^k (-1)^{k+i} S_i \Pi_{k-i} = 0$$

where  $S_k = \sum_{i=1}^k P_i^k$ .

- may lead to non-real solutions!
- does not minimize any conventional error criterion
- convenient for one-shot power inference
- when multiple realizations are available, statistical solutions are preferable

Z. D. Bai, J. W. Silverstein, "CLT of linear spectral statistics of large dimensional sample covariance matrices," Annals of Probability, vol. 32, no. 1A, pp. 553-605, 2004.

• for the model  $\mathbf{Y} = \mathbf{T}^{\frac{1}{2}} \mathbf{X}$ , an asymptotic central limit result is known for the moments, i.e. for  $m_k^{(N)}$  the order *k* empirical moment of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{\mathsf{H}}$  and  $m_k^{\circ(N)}$  its deterministic equivalent, as  $N \to \infty$ ,

$$N\left(m_k^{(N)}-m_k^{\circ(N)}\right)\Rightarrow X$$

where X is a central Gaussian random variable

- for the model under consideration, no such result is known.
- if a given model turns out to be Gaussian, then maximum-likelihood or MMSE estimators are of order. Denoting p = (P<sub>1</sub>,..., P<sub>K</sub>),

$$\hat{\mathbf{p}}_{\mathrm{ML}} = \arg\min_{\mathbf{p}} \log\det(\mathbf{C}(\mathbf{p})) + (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}}\mathbf{C}(\mathbf{p})^{-1}(\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))$$

with, for some p,  $\mathbf{m} = (m_1^{(N)}, \ldots, m_p^{(N)})$ ,  $\mathbf{m}^{\circ}(\mathbf{p}) = (m_1^{\circ^{(N)}}, \ldots, m_p^{\circ^{(N)}})$ , and  $\mathbf{C}(\mathbf{p})$  the covariance matrix of the Gaussian moment vector assuming powers  $\mathbf{p}$ . and for the MMSE,

$$\hat{p}_{\mathrm{MMSE}} = \frac{\int p \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1}(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))} dp}{\int \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1}(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))} dp}$$

R. Couillet (Supélec)

Z. D. Bai, J. W. Silverstein, "CLT of linear spectral statistics of large dimensional sample covariance matrices," Annals of Probability, vol. 32, no. 1A, pp. 553-605, 2004.

• for the model  $\mathbf{Y} = \mathbf{T}^{\frac{1}{2}} \mathbf{X}$ , an asymptotic central limit result is known for the moments, i.e. for  $m_k^{(N)}$  the order *k* empirical moment of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{\mathsf{H}}$  and  $m_k^{\circ(N)}$  its deterministic equivalent, as  $N \to \infty$ ,

$$N\left(m_k^{(N)}-m_k^{\circ(N)}
ight)\Rightarrow X$$

### where X is a central Gaussian random variable.

- If or the model under consideration, no such result is known.
- if a given model turns out to be Gaussian, then maximum-likelihood or MMSE estimators are of order. Denoting  $\mathbf{p} = (P_1, \dots, P_K)$ ,

$$\hat{\mathbf{p}}_{\mathrm{ML}} = \arg\min_{\mathbf{p}} \log \det(\mathbf{C}(\mathbf{p})) + (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}}\mathbf{C}(\mathbf{p})^{-1}(\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))$$

with, for some p,  $\mathbf{m} = (m_1^{(N)}, \ldots, m_p^{(N)})$ ,  $\mathbf{m}^{\circ}(\mathbf{p}) = (m_1^{\circ^{(N)}}, \ldots, m_p^{\circ^{(N)}})$ , and  $\mathbf{C}(\mathbf{p})$  the covariance matrix of the Gaussian moment vector assuming powers  $\mathbf{p}$ . and for the MMSE,

$$\hat{p}_{\mathrm{MMSE}} = \frac{\int p \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1}(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p})) dp}{\int \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1}(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p})) dp}}$$

R. Couillet (Supélec)

Z. D. Bai, J. W. Silverstein, "CLT of linear spectral statistics of large dimensional sample covariance matrices," Annals of Probability, vol. 32, no. 1A, pp. 553-605, 2004.

• for the model  $\mathbf{Y} = \mathbf{T}^{\frac{1}{2}} \mathbf{X}$ , an asymptotic central limit result is known for the moments, i.e. for  $m_k^{(N)}$  the order *k* empirical moment of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{\mathsf{H}}$  and  $m_k^{\circ(N)}$  its deterministic equivalent, as  $N \to \infty$ ,

$$N\left(m_k^{(N)}-m_k^{\circ(N)}
ight)\Rightarrow X$$

where X is a central Gaussian random variable.

- for the model under consideration, no such result is known.
- if a given model turns out to be Gaussian, then maximum-likelihood or MMSE estimators are of order. Denoting  $\mathbf{p} = (P_1, \dots, P_K)$ ,

$$\hat{\mathbf{p}}_{\mathrm{ML}} = \arg\min_{\mathbf{p}} \log\det(\mathbf{C}(\mathbf{p})) + (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}}\mathbf{C}(\mathbf{p})^{-1}(\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))$$

with, for some p,  $\mathbf{m} = (m_1^{(N)}, \ldots, m_p^{(N)})$ ,  $\mathbf{m}^{\circ}(\mathbf{p}) = (m_1^{\circ(N)}, \ldots, m_p^{\circ(N)})$ , and  $\mathbf{C}(\mathbf{p})$  the covariance matrix of the Gaussian moment vector assuming powers  $\mathbf{p}$ . and for the MMSE.

$$\hat{\mathbf{p}}_{\mathrm{MMSE}} = \frac{\int \mathbf{p} \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1} (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p})) d\mathbf{p}}{\int \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1} (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p})) d\mathbf{p}}$$

Z. D. Bai, J. W. Silverstein, "CLT of linear spectral statistics of large dimensional sample covariance matrices," Annals of Probability, vol. 32, no. 1A, pp. 553-605, 2004.

• for the model  $\mathbf{Y} = \mathbf{T}^{\frac{1}{2}} \mathbf{X}$ , an asymptotic central limit result is known for the moments, i.e. for  $m_k^{(N)}$  the order *k* empirical moment of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{\mathsf{H}}$  and  $m_k^{\circ(N)}$  its deterministic equivalent, as  $N \to \infty$ ,

$$N\left(m_k^{(N)}-m_k^{\circ(N)}
ight)\Rightarrow X$$

where X is a central Gaussian random variable.

- for the model under consideration, no such result is known.
- if a given model turns out to be Gaussian, then maximum-likelihood or MMSE estimators are of order. Denoting  $\mathbf{p} = (P_1, \dots, P_K)$ ,

$$\hat{\mathbf{p}}_{\mathrm{ML}} = \operatorname*{arg\,min}_{\mathbf{p}} \log \det(\mathbf{C}(\mathbf{p})) + (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1} (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))$$

with, for some p,  $\mathbf{m} = (m_1^{(N)}, \ldots, m_p^{(N)})$ ,  $\mathbf{m}^{\circ}(\mathbf{p}) = (m_1^{\circ(N)}, \ldots, m_p^{\circ(N)})$ , and  $\mathbf{C}(\mathbf{p})$  the covariance matrix of the Gaussian moment vector assuming powers  $\mathbf{p}$ .

and for the MMSE,

$$\hat{\mathbf{p}}_{\mathrm{MMSE}} = \frac{\int \mathbf{p} \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1}(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p})) d\mathbf{p}}{\int \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1}(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p})) d\mathbf{p}}$$

Z. D. Bai, J. W. Silverstein, "CLT of linear spectral statistics of large dimensional sample covariance matrices," Annals of Probability, vol. 32, no. 1A, pp. 553-605, 2004.

• for the model  $\mathbf{Y} = \mathbf{T}^{\frac{1}{2}} \mathbf{X}$ , an asymptotic central limit result is known for the moments, i.e. for  $m_k^{(N)}$  the order *k* empirical moment of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{\mathsf{H}}$  and  $m_k^{\circ(N)}$  its deterministic equivalent, as  $N \to \infty$ ,

$$N\left(m_k^{(N)}-m_k^{\circ(N)}
ight)\Rightarrow X$$

where X is a central Gaussian random variable.

- for the model under consideration, no such result is known.
- if a given model turns out to be Gaussian, then maximum-likelihood or MMSE estimators are of order. Denoting  $\mathbf{p} = (P_1, \dots, P_K)$ ,

$$\hat{\mathbf{p}}_{\mathrm{ML}} = \arg\min_{\mathbf{p}} \log \det(\mathbf{C}(\mathbf{p})) + (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1} (\mathbf{m} - \mathbf{m}^{\circ}(\mathbf{p}))$$

with, for some p,  $\mathbf{m} = (m_1^{(N)}, \dots, m_p^{(N)})$ ,  $\mathbf{m}^{\circ}(\mathbf{p}) = (m_1^{\circ(N)}, \dots, m_p^{\circ(N)})$ , and  $\mathbf{C}(\mathbf{p})$  the covariance matrix of the Gaussian moment vector assuming powers  $\mathbf{p}$ .

and for the MMSE,

$$\hat{\mathbf{p}}_{\text{MMSE}} = \frac{\int \mathbf{p} \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1}(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p})) d\mathbf{p}}{\int \det(\mathbf{C}^{-1}(\mathbf{p})) e^{-(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p}))^{\mathsf{T}} \mathbf{C}(\mathbf{p})^{-1}(\mathbf{m}-\mathbf{m}^{\circ}(\mathbf{p})) d\mathbf{p}}$$

### convenient approach, computationally not expensive

- necessarily suboptimal when finitely many moments are considered
- problem to move from moments to estimates: Newton-Girard method may lead to non real solutions.
- more elaborate methods, e.g. ML, MMSE, are prohibitively expensive

- convenient approach, computationally not expensive
- necessarily suboptimal when finitely many moments are considered
- problem to move from moments to estimates: Newton-Girard method may lead to non real solutions.
- more elaborate methods, e.g. ML, MMSE, are prohibitively expensive

- convenient approach, computationally not expensive
- necessarily suboptimal when finitely many moments are considered
- problem to move from moments to estimates: Newton-Girard method may lead to non real solutions.
- more elaborate methods, e.g. ML, MMSE, are prohibitively expensive

- convenient approach, computationally not expensive
- necessarily suboptimal when finitely many moments are considered
- problem to move from moments to estimates: Newton-Girard method may lead to non real solutions.
- more elaborate methods, e.g. ML, MMSE, are prohibitively expensive

# Outline

# Shannon, Wiener and Cognitive Radios

### Tools for Random Matrix Theory

- Introduction to Large Dimensional Random Matrix Theory
- History of Mathematical Advances
- The Moment Approach and Free Probability
- Introduction of the Stieltjes Transform
- Summary of what we know and what is left to be done

### 3 Random Matrix Theory and Performance Analysis

- The Uplink CDMA MMSE Decoder
- The Uplink CDMA Matched-Filter and Optimal Decoder

### 4 Random Matrix Theory and Signal Source Sensing

- Finite Random Matrix Analysis
- Large Dimensional Random Matrix Analysis

# Bandom Matrix Theory and Multi-Source Power Estimation

- Free Probability Approach
- Analytic Approach

### remember the matrix model

$$\mathbf{Y} = \mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W}$$

with  $\mathbf{W}, \mathbf{Y} \in \mathbb{C}^{N \times M}$ ,  $\mathbf{H} \in \mathbb{C}^{N \times n}$ ,  $\mathbf{X} \in \mathbb{C}^{n \times M}$ , and  $\mathbf{P} \in \mathbb{C}^{n \times n}$  diagonal.

this can be written in the following way

$$\mathbf{Y} = \begin{bmatrix} \mathbf{H}\mathbf{P}^{\frac{1}{2}} & \sigma \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{X} \\ \mathbf{W} \end{bmatrix} \in \mathbb{C}^{N \times M}$$

and extend it into the matrix

$$\mathbf{Y}_{\text{ext}} = \begin{bmatrix} \mathbf{H}\mathbf{P}^{\frac{1}{2}} & \sigma \mathbf{I} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{X} \\ \mathbf{W} \end{bmatrix} \in \mathbb{C}^{(N+n) \times M}$$

which is a sample covariance matrix model.

the population covariance matrix is

$$\begin{pmatrix} \mathbf{H}\mathbf{P}\mathbf{H}^{\mathsf{H}}+\sigma^{2}\mathbf{I}_{N} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{pmatrix}$$

itself a sample covariance matrix.

remember the matrix model

$$\mathbf{Y} = \mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W}$$

with  $\mathbf{W}, \mathbf{Y} \in \mathbb{C}^{N \times M}$ ,  $\mathbf{H} \in \mathbb{C}^{N \times n}$ ,  $\mathbf{X} \in \mathbb{C}^{n \times M}$ , and  $\mathbf{P} \in \mathbb{C}^{n \times n}$  diagonal.

this can be written in the following way

$$\mathbf{Y} = \begin{bmatrix} \mathbf{H}\mathbf{P}^{\frac{1}{2}} & \sigma \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{X} \\ \mathbf{W} \end{bmatrix} \in \mathbb{C}^{N \times M}$$

and extend it into the matrix

$$\mathbf{Y}_{\text{ext}} = \begin{bmatrix} \mathbf{H}\mathbf{P}^{\frac{1}{2}} & \sigma \mathbf{I} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{X} \\ \mathbf{W} \end{bmatrix} \in \mathbb{C}^{(N+n) \times M}$$

which is a sample covariance matrix model.

the population covariance matrix is

$$egin{pmatrix} \mathsf{HPH}^\mathsf{H} + \sigma^2 \mathbf{I}_N & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{pmatrix}$$

itself a sample covariance matrix.

remember the matrix model

$$\mathbf{Y} = \mathbf{H}\mathbf{P}^{\frac{1}{2}}\mathbf{X} + \sigma\mathbf{W}$$

with  $\mathbf{W}, \mathbf{Y} \in \mathbb{C}^{N \times M}$ ,  $\mathbf{H} \in \mathbb{C}^{N \times n}$ ,  $\mathbf{X} \in \mathbb{C}^{n \times M}$ , and  $\mathbf{P} \in \mathbb{C}^{n \times n}$  diagonal.

this can be written in the following way

$$\mathbf{Y} = \begin{bmatrix} \mathbf{H}\mathbf{P}^{\frac{1}{2}} & \sigma \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{X} \\ \mathbf{W} \end{bmatrix} \in \mathbb{C}^{N \times M}$$

and extend it into the matrix

$$\mathbf{Y}_{\text{ext}} = \begin{bmatrix} \mathbf{HP}^{\frac{1}{2}} & \sigma \mathbf{I} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \mathbf{X} \\ \mathbf{W} \end{bmatrix} \in \mathbb{C}^{(N+n) \times M}$$

which is a sample covariance matrix model.

the population covariance matrix is

$$\begin{pmatrix} \mathsf{H}\mathsf{P}\mathsf{H}^{\mathsf{H}}+\sigma^{2}\mathsf{I}_{N}&0\\ 0&0 \end{pmatrix}$$

itself a sample covariance matrix.

R. Couillet, J. W. Silverstein, Z. Bai, M. Debbah, "Eigen-inference Energy Estimation of Multiple Sources", IEEE Trans. on Information Theory, 2010, *submitted*.

• the asymptotic spectrum of  $\frac{1}{M}\mathbf{Y}\mathbf{Y}^{H}$  has Stietlies transform  $m(z), z \in \mathbb{C}^{+}$ , such that

$$m(z) = \frac{M}{N}\underline{m}_N(z) + \frac{M-N}{N}\frac{1}{z}$$

where  $\underline{m}_N(z)$  is the unique solution in  $\mathbb{C}^+$  of

$$\frac{1}{\underline{m}_N(z)} = -\sigma^2 + \frac{1}{f(z)} - \frac{1}{N} \sum_{k=1}^K \frac{n_k P_k}{1 + P_k f(z)}$$

where f(z) is given by

$$f(z) = \frac{M-N}{N}\underline{m}_N(z) - \frac{M}{N}z\underline{m}_N(z)^2$$

Random Matrix Theory and Multi-Source Power Estimation Asymptotic spectrum of  $\frac{1}{M}$  Analytic Approach

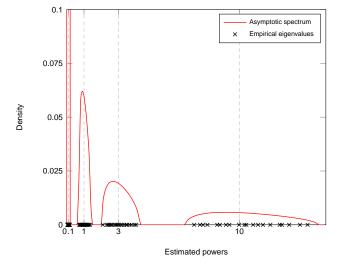


Figure: Empirical and asymptotic eigenvalue distribution of  $\frac{1}{M}\mathbf{Y}\mathbf{Y}^{H}$  when **P** has three distinct entries  $P_{1} = 1$ ,  $P_{2} = 3$ ,  $P_{3} = 10$ ,  $n_{1} = n_{2} = n_{3}$ , N/n = 10, M/N = 10,  $\sigma^{2} = 0.1$ . Empirical test: n = 60.

< □ > < 同

X. Mestre, "Improved estimation of eigenvalues and eigenvectors of covariance matrices using their sample estimates," IEEE trans. on Information Theory, vol. 54, no. 11, pp. 5113-5129, 2008.

### Cauchy integration formula

#### Theorem

Let f be holomorphic on  $\mathbb{C}$  and  $\gamma \subset \mathbb{C}$  be a continuous contour. Then, for a inside  $\gamma$  and b outside  $\gamma$ ,

$$f(\mathbf{a}) = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(\omega)}{\omega - \mathbf{a}} d\omega \text{ and } \mathbf{0} = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(\omega)}{\omega - \mathbf{b}} d\omega$$

• to estimate  $P_k$ , notice that, for some contour  $C_k$  enclosing  $P_k$ ,

$$P_{k} = -\frac{1}{2\pi i} \oint_{C_{k}} \frac{\omega}{P_{k} - \omega} d\omega = -\frac{n}{n_{k}} \frac{1}{2\pi i} \oint_{C_{k}} \frac{1}{N} \sum_{r=1}^{K} n_{r} \frac{\omega}{P_{r} - \omega} d\omega$$

• We recognize a Stieltjes transform of the distribution with masses in  $(P_1, \ldots, P_N)$ 

X. Mestre, "Improved estimation of eigenvalues and eigenvectors of covariance matrices using their sample estimates," IEEE trans. on Information Theory, vol. 54, no. 11, pp. 5113-5129, 2008.

### Cauchy integration formula

#### Theorem

Let f be holomorphic on  $\mathbb{C}$  and  $\gamma \subset \mathbb{C}$  be a continuous contour. Then, for a inside  $\gamma$  and b outside  $\gamma$ ,

$$f(\mathbf{a}) = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(\omega)}{\omega - \mathbf{a}} d\omega \text{ and } \mathbf{0} = \frac{1}{2\pi i} \oint_{\gamma} \frac{f(\omega)}{\omega - \mathbf{b}} d\omega$$

• to estimate  $P_k$ , notice that, for some contour  $C_k$  enclosing  $P_k$ ,

$$P_{k} = -\frac{1}{2\pi i} \oint_{C_{k}} \frac{\omega}{P_{k} - \omega} d\omega = -\frac{n}{n_{k}} \frac{1}{2\pi i} \oint_{C_{k}} \frac{1}{N} \sum_{r=1}^{K} n_{r} \frac{\omega}{P_{r} - \omega} d\omega$$

• We recognize a Stieltjes transform of the distribution with masses in  $(P_1, \ldots, P_N)$ 

• variable change. Write  $\frac{1}{N} \sum_{r=1}^{K} n_r \frac{\omega}{P_r - \omega}$  as a function of m(z), the asymptotic Stieltjes transform of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{H}$ ,

remember that 
$$(\frac{1}{\underline{m}_N(z)} = -\sigma^2 + \frac{1}{f(z)} - \frac{1}{N} \sum_{r=1}^{K} n_r \frac{P_r}{1 + P_r f(z)})$$

- if clusters are separated, the contour image encircles cluster k!
- approximation. For large N,  $m(z) \simeq \hat{m}(z) = \frac{1}{N} \operatorname{tr}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}} z\mathbf{I}_{N})^{-1}$ , the accessible data!
- **calculus.** We replace m(z) by  $\hat{m}(z)$  and do the (residue) calculus.

• variable change. Write  $\frac{1}{N} \sum_{r=1}^{K} n_r \frac{\omega}{P_r - \omega}$  as a function of m(z), the asymptotic Stieltjes transform of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{\mathsf{H}}$ ,

remember that 
$$\left(\frac{1}{\underline{m}_N(z)} = -\sigma^2 + \frac{1}{f(z)} - \frac{1}{N}\sum_{r=1}^K n_r \frac{P_r}{1 + P_r f(z)}\right)$$

- if clusters are separated, the contour image encircles cluster k!
- approximation. For large N,  $m(z) \simeq \hat{m}(z) = \frac{1}{N} \operatorname{tr}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}} z\mathbf{I}_{N})^{-1}$ , the accessible data!
- **calculus.** We replace m(z) by  $\hat{m}(z)$  and do the (residue) calculus.

• variable change. Write  $\frac{1}{N} \sum_{r=1}^{K} n_r \frac{\omega}{P_r - \omega}$  as a function of m(z), the asymptotic Stieltjes transform of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{\mathsf{H}}$ ,

remember that 
$$\left(\frac{1}{\underline{m}_N(z)} = -\sigma^2 + \frac{1}{f(z)} - \frac{1}{N}\sum_{r=1}^K n_r \frac{P_r}{1 + P_r f(z)}\right)$$

### • if clusters are separated, the contour image encircles cluster k!

- approximation. For large N,  $m(z) \simeq \hat{m}(z) = \frac{1}{N} \operatorname{tr}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}} z\mathbf{I}_{N})^{-1}$ , the accessible data!
- calculus. We replace m(z) by  $\hat{m}(z)$  and do the (residue) calculus.

• variable change. Write  $\frac{1}{N} \sum_{r=1}^{K} n_r \frac{\omega}{P_r - \omega}$  as a function of m(z), the asymptotic Stieltjes transform of  $\frac{1}{N} \mathbf{Y} \mathbf{Y}^{\mathsf{H}}$ ,

remember that 
$$\left(\frac{1}{\underline{m}_N(z)} = -\sigma^2 + \frac{1}{f(z)} - \frac{1}{N}\sum_{r=1}^K n_r \frac{P_r}{1 + P_r f(z)}\right)$$

- if clusters are separated, the contour image encircles cluster k!
- approximation. For large N,  $m(z) \simeq \hat{m}(z) = \frac{1}{N} \operatorname{tr}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}} z\mathbf{I}_{N})^{-1}$ , the accessible data!
- calculus. We replace m(z) by  $\hat{m}(z)$  and do the (residue) calculus.

200

R. Couillet, J. W. Silverstein, Z. Bai, M. Debbah, "Eigen-inference Energy Estimation of Multiple Sources", IEEE Trans. on Information Theory, 2010, *submitted*.

### Theorem

Let  $\mathbf{B}_N = \frac{1}{M} \mathbf{Y}^{\mathbf{H}} \in \mathbb{C}^{N \times N}$ , with  $\mathbf{Y}$  defined as previously. Denote its ordered eigenvalues vector  $\boldsymbol{\lambda} = (\lambda_1, \dots, \lambda_N), \lambda_1 < \dots, \lambda_N$ . Further assume asymptotic spectrum separability. Then, for  $k \in \{1, \dots, K\}$ , as N, n, M grow large, we have

$$\hat{P}_k - P_k \stackrel{\text{a.s.}}{\longrightarrow} 0$$

where the estimate  $\hat{P}_k$  is given by

$$\hat{P}_k = rac{NM}{n_k(M-N)} \sum_{i \in \mathcal{N}_k} (\eta_i - \mu_i)$$

with  $\mathcal{N}_{k} = \{N - \sum_{i=k}^{K} n_{i} + 1, \dots, N - \sum_{i=k+1}^{K} n_{i}\}$  the set of indexes matching the cluster corresponding to  $P_{k}$ ,  $(\eta_{1}, \dots, \eta_{N})$  the ordered eigenvalues of diag $(\lambda) - \frac{1}{N}\sqrt{\lambda}\sqrt{\lambda}^{\mathsf{T}}$  and  $(\mu_{1}, \dots, \mu_{N})$  the ordered eigenvalues of diag $(\lambda) - \frac{1}{M}\sqrt{\lambda}\sqrt{\lambda}^{\mathsf{T}}$ .

・ロト ・回ト ・ヨト ・ヨト

# Comments on the result

- very compact formula
- Iow computational complexity
- assuming cluster separation, it allows also to infer the number of eigenvalues, as well as the multiplicity of each eigenvalue.
- however, strong requirement on cluster separation
- if separation is not true, the mean of the eigenvalues instead of the eigenvalues themselves is computed.
- it is possible to infer K, all  $n_k$  and all  $P_k$  using the Stieltjes transform method.

- very compact formula
- Iow computational complexity
- assuming cluster separation, it allows also to infer the number of eigenvalues, as well as the multiplicity of each eigenvalue.
- however, strong requirement on cluster separation
- if separation is not true, the mean of the eigenvalues instead of the eigenvalues themselves is computed.
- it is possible to infer K, all  $n_k$  and all  $P_k$  using the Stieltjes transform method.

- very compact formula
- Iow computational complexity
- assuming cluster separation, it allows also to infer the number of eigenvalues, as well as the multiplicity of each eigenvalue.
- however, strong requirement on cluster separation
- if separation is not true, the mean of the eigenvalues instead of the eigenvalues themselves is computed.
- it is possible to infer K, all  $n_k$  and all  $P_k$  using the Stieltjes transform method.

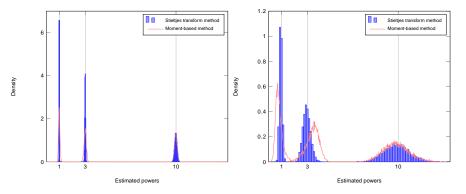


Figure: Multi-source power estimation, for K = 3,  $P_1 = 1$ ,  $P_2 = 3$ ,  $P_3 = 10$ ,  $n_1/n = n_2/n = n_3/n = 1/3$ , n/N = N/M = 1/10, SNR = 10 dB, for 10, 000 simulation runs; Top n = 60, bottom n = 6.

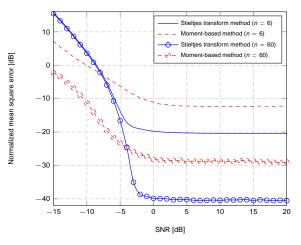


Figure: Normalized mean square error of the vector  $(\hat{P}_1, \hat{P}_2, \hat{P}_3)$ ,  $P_1 = 1$ ,  $P_2 = 3$ ,  $P_3 = 10$ ,  $n_1/n = n_2/n = n_3/n = 1/3$ , n/N = N/M = 1/10, for 10, 000 simulation runs.

## up to this day

- the moment approach is much simpler to derive
- it does not require any cluster separation
- the finite size case is treated in the mean, which the Stieltjes transform approach cannot do.
- however, the Stieltjes transform approach makes full use of the spectral knowledge, when the moment approach is limited to a few moments.
- the results are more natural, and more "telling"
- in the future, it is expected that the cluster separation requirement can be overtaken.
- a natural general framework attached to the Stieltjes transform method could arise
- central limit results on the estimates is expected

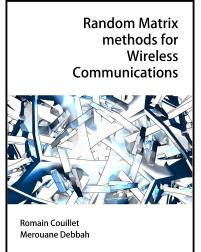
### up to this day

- the moment approach is much simpler to derive
- it does not require any cluster separation
- the finite size case is treated in the mean, which the Stieltjes transform approach cannot do.
- however, the Stieltjes transform approach makes full use of the spectral knowledge, when the moment approach is limited to a few moments.
- the results are more natural, and more "telling"
- in the future, it is expected that the cluster separation requirement can be overtaken.
- a natural general framework attached to the Stieltjes transform method could arise
- central limit results on the estimates is expected

- N. El Karoui, "Spectrum estimation for large dimensional covariance matrices using random matrix theory," Annals of Statistics, vol. 36, no. 6, pp. 2757-2790, 2008.
- N. R. Rao, J. A. Mingo, R. Speicher, A. Edelman, "Statistical eigen-inference from large Wishart matrices," Annals of Statistics, vol. 36, no. 6, pp. 2850-2885, 2008.
- R. Couillet, M. Debbah, "Free deconvolution for OFDM multicell SNR detection", PIMRC 2008, Cannes, France.
- X. Mestre, "Improved estimation of eigenvalues and eigenvectors of covariance matrices using their sample estimates," IEEE trans. on Information Theory, vol. 54, no. 11, pp. 5113-5129, 2008.
- R. Couillet, J. W. Silverstein, M. Debbah, "Eigen-inference for multi-source power estimation", submitted to ISIT 2010.
- Z. D. Bai, J. W. Silverstein, "No eigenvalues outside the support of the limiting spectral distribution of large-dimensional sample covariance matrices," The Annals of Probability, vol. 26, no.1 pp. 316-345, 1998.
- Z. D. Bai, J. W. Silverstein, "CLT of linear spectral statistics of large dimensional sample covariance matrices," Annals of Probability, vol. 32, no. 1A, pp. 553-605, 2004.
- J. Silverstein, Z. Bai, "Exact separation of eigenvalues of large dimensional sample covariance matrices" Annals of Probability, vol. 27, no. 3, pp. 1536-1555, 1999.
- Ø. Ryan, M. Debbah, "Free Deconvolution for Signal Processing Applications," IEEE International Symposium on Information Theory, pp. 1846-1850, 2007.

- Articles in Journals,
  - R. Couillet, J. W. Silverstein, Z. Bai, M. Debbah, "Eigen-Inference for Energy Estimation of Multiple Sources," IEEE Trans. on Information Theory, 2010, *submitted*.
  - R. Couillet, J. W. Silverstein, M. Debbah, "A Deterministic Equivalent for the Capacity Analysis of Correlated Multi-User MIMO Channels," IEEE Trans. on Information Theory, 2010, accepted for publication.
  - P. Bianchi, J. Najim, M. Maida, M. Debbah, "Performance of Some Eigen-based Hypothesis Tests for Collaborative Sensing," IEEE Trans. on Information Theory, 2010, accepted for publication.
  - R. Couillet, M. Debbah, "A Bayesian Framework for Collaborative Multi-Source Signal Sensing," IEEE Trans. on Signal Processing, 2010, accepted for publication.
  - S. Wagner, P. Couillet, M. Debbah, D. T. M. Slock, "Large System Analysis of Linear Precoding in MISO Broadcast Channels with Limited Feedback," IEEE Trans. on Information Theory, 2010, submitted.
  - A. Masucci, Ø. Ryan, S. Yang, M. Debbah, "Gaussian Finite Dimensional Statistical Inference," IEEE Trans. on Information Theory, 2009, *submitted*.
  - Ø. Ryan, M. Debbah, "Asymptotic Behaviour of Random Vandermonde Matrices with Entries on the Unit Circle," IEEE Trans. on Information Theory, vol. 55, no. 7 pp. 3115-3148, July 2009.
  - M. Debbah, R. Müller, "MIMO channel modeling and the principle of maximum entropy," IEEE Trans. on Information Theory, vol. 51, no. 5, pp. 1667-1690, 2005.
- Articles in International Conferences
  - R. Couillet, S. Wagner, M. Debbah, A. Silva, "The Space Frontier: Physical Limits of Multiple Antenna Information Transfer", Inter-Perf 2008, Athens, Greece. BEST STUDENT PAPER AWARD.
  - R. Couillet, M. Debbah, V. Poor, "Self-organized spectrum sharing in large MIMO multiple access channels", submitted to ISIT 2010.
  - R. Couillet, M. Debbah, "Uplink capacity of self-organizing clustered orthogonal CDMA networks in flat fading channels", ITW 2009 Fall, Taormina, Sicily.

# Coming up soon...



590

(ロ) (同) (E) (E)

## Romain Couillet, Mérouane Debbah, Random Matrix Methods for Wireless Communications.

### Theoretical aspects

- Preliminary
- 2 Tools for random matrix theory
- ③ Deterministic equivalents
- Gentral limit theorems
- Spectrum analysis
- 6 Eigen-inference
- Extreme eigenvalues
- 2 Applications to wireless communications
  - Introduction
  - System performance: capacity and rate-regions
    - Introduction
    - Performance of CDMA technologies
    - Performance of multiple antenna systems
    - Multi-user communications, rate regions and sum-rate
    - Oesign of multi-user receivers
    - Analysis of multi-cellular networks
    - Communications in ad-hoc networks
  - 3 Detection
  - ④ Estimation
  - G Modelling
  - Random matrix theory and self-organizing networks
  - Perspectives
  - 8 Conclusion

(I) < ((()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) < (()) <