# Future Random Matrix Tools for Large Dimensional Signal Processing EUSIPCO 2014, Lisbon, Portugal. 

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## High-dimensional data

- Consider $n$ observations $\mathbf{x}_{1}, \cdots, \mathbf{x}_{n}$ of size $N$, independent and identically distributed with zero-mean and covariance $\mathbf{C}_{N}$, i.e, $\mathbb{E}\left[\mathbf{x}_{1} \mathbf{x}_{1}^{H}\right]=C_{N}$,
- Let $\mathbf{X}_{N}=\left[\mathbf{x}_{1}, \cdots, \mathbf{x}_{n}\right]$. The sample covariance estimate $\hat{S}_{N}$ of $\mathbf{C}_{N}$ is given by: $\hat{S}_{N}=\frac{1}{n} \mathbf{X}_{N} \mathbf{X}_{N}^{H}=\frac{1}{n} \sum_{i=1}^{n} x_{i} x_{i}^{*}$,
- From the law of large numbers, as $n \rightarrow+\infty$,

$$
\hat{S}_{N} \xrightarrow{\text { a.s. }} \mathbf{C}_{N} .
$$

$\rightarrow$ Convergence in the operator norm

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- In practice, it might be difficult to afford $n \rightarrow+\infty$,
- if $n \gg N, \hat{S}_{N}$ can be sufficiently accurate,
- if $N / n=\mathcal{O}(1)$, we model this scenario by the following assumption: $N \rightarrow+\infty$ and $n \rightarrow+\infty$ with $\frac{N}{n} \rightarrow c$,
- Under this assumption, we have pointwise convergence to each element of $C_{N}$, i.e,

$$
\left(\hat{S}_{N}\right)_{i, j} \xrightarrow{\text { a.s. }}\left(C_{N}\right)_{i, j}
$$

but $\left\|S_{N}-C_{N}\right\|$ does not converge to zero.
$\rightarrow$ The convergence in the operator norm does not hold.

## Illustration

Consider $C_{N}=I_{N}$, the spectrum of $\hat{S}_{N}$ is different from that of $C_{N}$


Figure: Spectrum of eigenvalues when $N=400$ and $n=2000$
$\longrightarrow$ The asymptotic spectrum can be characterized by the Marchenko-Pastur Law.

## Reasons of interest for signal processing

- Scale similarity in array processing applications: large antenna arrays vs limited number of observations,
- Need for detection and estimation based on large dimensional random inputs: subspace methods in array processing.
- The assumption "number of obervations $\gg$ dimension of observation" is no longer valid: large arrays, systems with fast dynamics.


## Example

MUSIC with "few" samples (or in large arrays) Call $\mathbf{A}(\Theta)=\left[\mathbf{a}\left(\theta_{1}\right), \ldots, \mathbf{a}\left(\theta_{K}\right)\right] \in \mathbb{C}^{N \times K}, N$ large, $K$ small, the steering vectors to identify and $\mathbf{X}=\left[\mathbf{x}_{1}, \ldots, \mathbf{x}_{n}\right] \in \mathbb{C}^{N \times n}$ the $n$ samples, taken from

$$
\mathbf{x}_{t}=\sum_{k=1}^{K} \mathbf{a}\left(\theta_{k}\right) \sqrt{p}_{k} s_{k, t}+\sigma w_{t} .
$$

The MUSIC localization function reads $\gamma(\theta)=\mathbf{a}(\theta)^{\mathrm{H}} \hat{\mathbf{U}}_{W} \hat{\mathbf{U}}_{W}^{\mathrm{H}} \mathbf{a}(\theta)$ in the "signal vs. noise" spectral decomposition $\mathbf{X X}^{H}=\hat{\mathbf{U}}_{S} \hat{\Lambda}_{S} \hat{\mathbf{U}}_{S}^{\mathrm{H}}+\hat{\mathbf{U}}_{W} \hat{\boldsymbol{\Lambda}}_{W} \hat{\mathbf{U}}_{W}^{\mathrm{H}}$.

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Writing equivalently $\mathbf{A}(\Theta) \mathbf{P A}(\Theta)^{\mathrm{H}}+\sigma^{2} \mathbf{I}_{N}=\mathbf{U}_{S} \Lambda_{S} \mathbf{U}_{S}^{\mathrm{H}}+\sigma^{2} \mathbf{U}_{W} \mathbf{U}_{W}^{\mathrm{H}}$, as $n, N \rightarrow \infty, n / N \rightarrow c$, from our previous remarks

$$
\hat{\mathbf{U}}_{w} \hat{\mathbf{U}}_{w}^{H} \nrightarrow \mathbf{U}_{W} \mathbf{U}_{W}^{H}
$$

$\Rightarrow$ Music is NOT consistent in the large $N$, $n$ regime! We need improved RMT-based solutions.

## Outline

```
Part 1: Fundamentals of Random Matrix Theory
    1.1. The Stieltjes Transform Method
    1.2 Extreme eigenvalues
    1.3 Extreme eigenvalues: the spiked models
    1.4 Spectrum Analysis and G-estimation
Application to Signal Sensing and Array Processing
    2.1 Eigenvalue-based detection
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Advanced Random Matrix Models for Robust Estimation
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## Stieltjes Transform

## Definition

Let $F$ be a real probability distribution function. The Stieltjes transform $m_{F}$ of $F$ is the function defined, for $z \in \mathbb{C}^{+}$, as

$$
m_{F}(z)=\int \frac{1}{\lambda-z} d F(\lambda)
$$

For $a<b$ continuity points of $F$, denoting $z=x+i y$, we have the inverse formula

$$
F(b)-F(a)=\lim _{y \rightarrow 0} \frac{1}{\pi} \int_{a}^{b} \Im\left[m_{F}(x+i y)\right] d x
$$

If $F$ has a density $f$ at $x$, then

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Equivalence $F \leftrightarrow m_{F}$
Similar to the Fourier transform, knowing $m_{F}$ is the same as knowing $F$.

## Stieltjes transform of a Hermitian matrix

- Let $\mathbf{X}$ be a $N \times N$ random matrix. Denote by $d F^{X}$ the empirical measure of its eigenvalues $\lambda_{1}, \cdots, \lambda_{N}$, i.e, $d F^{X}=\frac{1}{N} \sum_{i=1}^{N} \delta_{\lambda_{i}}$. The Stieltjes transform of $\mathbf{X}$ denoted by $m_{\mathbf{X}}=m_{F}$ is the stieltjes transform of its empirical measure:

$$
m_{\mathbf{X}}(z)=\int \frac{1}{\lambda-z} d F(\lambda)=\frac{1}{N} \sum_{i=1}^{N} \frac{1}{\lambda_{i}-z}=\frac{1}{N} \operatorname{tr}\left(\mathbf{X}-z \mathbf{I}_{N}\right)^{-1} .
$$

- The Stieltjes transform of a random matrix is the trace of the resolvent matrix $\mathbf{Q}(\boldsymbol{z})=\left(\mathbf{X}-z \mathbf{I}_{N}\right)^{-1}$. The resolvent matrix plays a key role in the derivation of many of the results of random matrix theory.
- For compactly supported $F, m_{F}(z)$ is linked to the moments $M_{k}=\mathbb{E} \frac{1}{N} \operatorname{tr} \mathbf{X}^{k}$,

$$
m_{F}(z)=-\sum_{k=0}^{+\infty} M_{k} z^{-k-1}
$$

- $m_{F}$ is defined in general on $\mathbb{C}_{+}$but exists everywhere outside the support of $F$.


## Side remark: the "Shannon"-transform

A. M. Tulino, S. Verdù, "Random matrix theory and wireless communications," Now Publishers Inc., 2004.

Definition
Let $F$ be a probability distribution, $m_{F}$ its Stieltjes transform, then the Shannon-transform $\mathcal{V}_{F}$ of $F$ is defined as

$$
\nu_{F}(x) \triangleq \int_{0}^{\infty} \log (1+x \lambda) d F(\lambda)=\int_{x}^{\infty}\left(\frac{1}{t}-m_{F}(-t)\right) d t
$$

- This quantity is fundamental to wireless communication purposes!
- Note that $m_{F}$ itself is of interest, not $F$ !


## Proof of the Marčenko-Pastur law

V. A. Marčenko, L. A. Pastur, "Distributions of eigenvalues for some sets of random matrices", Math USSR-Sbornik, vol. 1, no. 4, pp. 457-483, 1967.
The theorem to be proven is the following

## Theorem

Let $\mathbf{X}_{N} \in \mathbb{C}^{N \times n}$ have i.i.d. zero mean variance $1 / n$ entries with finite eighth order moments. As $n, N \rightarrow \infty$ with $\frac{N}{n} \rightarrow c \in(0, \infty)$, the e.s.d. of $\mathbf{X}_{N} \mathbf{X}_{N}^{H}$ converges almost surely to a nonrandom distribution function $F_{c}$ with density $f_{c}$ given by

$$
f_{c}(x)=\left(1-c^{-1}\right)^{+} \delta(x)+\frac{1}{2 \pi c x} \sqrt{(x-a)^{+}(b-x)^{+}}
$$

where $a=(1-\sqrt{c})^{2}$, and $b=(1+\sqrt{c})^{2}$.

## The Marčenko-Pastur density



Figure: Marčenko-Pastur law for different limit ratios $c=\lim _{N \rightarrow \infty} N / n$.

## Diagonal entries of the resolvent

Since we want an expression of $m_{F}$, we start by identifying the diagonal entries of the resolvent $\left(\mathbf{X}_{N} \mathbf{X}_{N}^{H}-z \mathbf{I}_{N}\right)^{-1}$ of $\mathbf{X}_{N} \mathbf{X}_{N}^{H}$. Denote

$$
\mathbf{x}_{N}=\left[\begin{array}{c}
\mathbf{y}^{\mathrm{H}} \\
\mathbf{Y}
\end{array}\right]
$$

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\mathbf{y}^{\mathrm{H}} \\
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\end{array}\right]
$$

Now, for $z \in \mathbb{C}^{+}$, we have

$$
\left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathrm{H}}-z \mathbf{I}_{N}\right)^{-1}=\left[\begin{array}{cc}
\mathbf{y}^{\mathrm{H}} \mathbf{y}-\mathbf{z} & \mathbf{y}^{\mathrm{H}} \mathbf{Y}^{\mathrm{H}} \\
\mathbf{Y} \mathbf{y} & \mathbf{Y} \mathbf{Y}^{\mathrm{H}}-z \mathbf{I}_{N-1}
\end{array}\right]^{-1}
$$

Consider the first diagonal element of $\left(\mathbf{R}_{N}-z \mathbf{I}_{N}\right)^{-1}$. From the matrix inversion lemma,

$$
\left(\begin{array}{ll}
\mathbf{A} & \mathbf{B} \\
\mathbf{C} & \mathbf{D}
\end{array}\right)^{-1}=\left(\begin{array}{cc}
\left(\mathbf{A}-\mathbf{B D}^{-1} \mathbf{C}\right)^{-1} & -\mathbf{A}^{-1} \mathbf{B}\left(\mathbf{D}-\mathbf{C A}^{-1} \mathbf{B}\right)^{-1} \\
-\left(\mathbf{A}-\mathbf{B D}^{-1} \mathbf{C}\right)^{-1} \mathbf{C A}^{-1} & \left(\mathbf{D}-\mathbf{C A}^{-1} \mathbf{B}\right)^{-1}
\end{array}\right)
$$

which here gives

$$
\left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{H}-z \mathbf{I}_{N}\right)^{-1}\right]_{11}=\frac{1}{-z-z \mathbf{y}^{H}\left(\mathbf{Y}^{H} \mathbf{Y}-z \mathbf{I}_{n}\right)^{-1} \mathbf{y}}
$$

## Trace Lemma

Z. Bai, J. Silverstein, "Spectral Analysis of Large Dimensional Random Matrices", Springer Series in Statistics, 2009.

To go further, we need the following result,
Theorem
Let $\left\{\mathbf{A}_{N}\right\} \in \mathbb{C}^{N \times N}$ with bounded spectral norm. Let $\left\{\mathbf{x}_{N}\right\} \in \mathbb{C}^{N}$, be a random vector of i.i.d. entries with zero mean, variance $1 / N$ and finite $8^{\text {th }}$ order moment, independent of $\mathbf{A}_{N}$. Then

$$
\mathbf{x}_{N}^{\mathrm{H}} \mathbf{A}_{N} \mathbf{x}_{N}-\frac{1}{N} \operatorname{tr} \mathbf{A}_{N} \xrightarrow{\text { a.s. }} 0 .
$$

For large $N$, we therefore have approximately

$$
\left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{H}-z \mathbf{I}_{N}\right)^{-1}\right]_{11} \simeq \frac{1}{-z-z \frac{1}{N} \operatorname{tr}\left(\mathbf{Y}^{\mathrm{H}} \mathbf{Y}-z \mathbf{I}_{n}\right)^{-1}}
$$

## Rank-1 perturbation lemma

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

It is somewhat intuitive that adding a single column to $\mathbf{Y}$ won't affect the trace in the limit.

## Theorem

Let $\mathbf{A}$ and $\mathbf{B}$ be $N \times N$ with $\mathbf{B}$ Hermitian positive definite, and $\mathbf{v} \in \mathbb{C}^{N}$. For $z \in \mathbb{C} \backslash \mathbb{R}^{-}$,

$$
\left|\frac{1}{N} \operatorname{tr}\left(\left(\mathbf{B}-z \mathbf{I}_{N}\right)^{-1}-\left(\mathbf{B}+\mathbf{v} \mathbf{v}^{\mathbf{H}}-z \mathbf{I}_{N}\right)^{-1}\right) \mathbf{A}\right| \leqslant \frac{1}{N} \frac{\|\mathbf{A}\|}{\operatorname{dist}\left(\mathbf{z}, \mathbb{R}^{+}\right)}
$$

with $\|\mathbf{A}\|$ the spectral norm of $\mathbf{A}$, and $\operatorname{dist}(z, A)=\inf _{y \in A}\|y-z\|$.
Therefore, for large $N$, we have approximately,

$$
\begin{aligned}
{\left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathrm{H}}-z \mathbf{I}_{N}\right)^{-1}\right]_{11} } & \simeq \frac{1}{-z-z \frac{1}{N} \operatorname{tr}\left(\mathbf{Y}^{\mathrm{H}} \mathbf{Y}-z \mathbf{I}_{n}\right)^{-1}} \\
& \simeq \frac{1}{-z-z \frac{1}{N} \operatorname{tr}\left(\mathbf{X}_{N}^{\mathrm{H}} \mathbf{X}_{N}-z \mathbf{I}_{n}\right)^{-1}} \\
& =\frac{1}{-z-z \frac{n}{N} m_{\underline{F}}(z)}
\end{aligned}
$$

in which we recognize the Stieltjes transform $m_{\underline{E}}$ of the I.s.d. of $\mathbf{X}_{N}^{H} \mathbf{X}_{N}$.

## End of the proof

We have again the relation

$$
\frac{n}{N} m_{\underline{E}}(z)=m_{F}(z)+\frac{N-n}{N} \frac{1}{z}
$$

hence

$$
\left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{H}-z \mathbf{I}_{N}\right)^{-1}\right]_{11} \simeq \frac{1}{\frac{n}{N}-1-z-z m_{F}(z)}
$$

Note that the choice $(1,1)$ is irrelevant here, so the expression is valid for all pair ( $i, i$ ). Summing over the $N$ terms and averaging, we finally have

$$
m_{F}(z)=\frac{1}{N} \operatorname{tr}\left(\mathbf{X}_{N} \mathbf{X}_{N}^{H}-z \mathbf{I}_{N}\right)^{-1} \simeq \frac{1}{c-1-z-z m_{F}(z)}
$$

which solve a polynomial of second order. Finally

$$
m_{F}(z)=\frac{c-1}{2 z}-\frac{1}{2}+\frac{\sqrt{(c-1-z)^{2}-4 z}}{2 z} .
$$

From the inverse Stieltjes transform formula, we then verify that $m_{F}$ is the Stieltjes transform of the Marčenko-Pastur law.

## Related bibliography

- V. A. Marčenko, L. A. Pastur, "Distributions of eigenvalues for some sets of random matrices", Math USSR-Sbornik, vol. 1, no. 4, pp. 457-483, 1967.
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- A. M. Tulino, S. Verdù, "Random matrix theory and wireless communications," Now Publishers Inc., 2004.


## Asymptotic results involving Stieltjes transform

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

## Theorem

Let $\mathbf{Y}_{N}=\frac{1}{\sqrt{n}} \mathbf{X}_{N} \mathbf{C}_{N}^{\frac{1}{2}}$, where $\mathbf{X}_{N} \in \mathbb{C}^{n \times N}$ has i.i.d entries of mean 0 and variance 1 . Consider the regime $n, N \rightarrow+\infty$ with $\frac{N}{n} \rightarrow c$. Let $\underline{\underline{m}}_{N}$ be the Stieltjes transform associated to $\mathbf{X}_{N} \mathbf{X}_{N}^{*}$. Then, $\underline{\underline{m}}_{N}-\underline{m}_{N} \rightarrow 0$ almost surely for all $z \in \mathbb{C} \backslash \mathbb{R}_{+}$, where $\underline{m}_{N}(z)$ is the unique solution in the set $\left\{z \in \mathbb{C}_{+}, \underline{m}_{N}(z) \in \mathbb{C}_{+}\right\}$to:

$$
\underline{m}_{N}(z)=\left(\int \frac{c t d F^{\mathrm{C}_{N}}}{1+t \underline{m}_{N}(z)}-z\right)^{-1}
$$

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$$

- in general, no explicit expression for $\underline{F}_{N}$, the distribution whose Stietljes transform is $\underline{m}_{N}(z)$.
- The theorem above characterizes also the Stieltjes transform of $\mathbf{B}_{N}=\mathbf{X}_{N}^{H} \mathbf{X}_{N}$ denoted by $m_{N}$,

$$
m_{N}=c \underline{m}_{N}+(c-1) \frac{1}{z}
$$

This gives access to the spectrum of the sample covariance matrix model of $\mathbf{x}$, when $\mathbf{y}_{i}=\mathbf{C}_{N}^{\frac{1}{2}} \mathbf{x}_{i}, \mathbf{x}_{i}$ i.i.d., $\mathbf{C}_{N}=E\left[\mathbf{y y}^{\mathrm{H}}\right]$.

## Getting $F^{\prime}$ from $m_{F}$

- Remember that, for $a<b$ real,

$$
F^{\prime}(x)=\lim _{y \rightarrow 0} \frac{1}{\pi} \Im\left[m_{F}(x+i y)\right]
$$

where $m_{F}$ is (up to now) only defined on $\mathbb{C}^{+}$.

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- to plot the density $F^{\prime}$,
- first approach: span $z=x+i y$ on the line $\{x \in \mathbb{R}, y=\varepsilon\}$ parallel but close to the real axis, solve $m_{F}(z)$ for each $z$, and plot $\mathfrak{\Im}\left[m_{F}(z)\right]$.


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Example (Sample covariance matrix)
For $N$ multiple of 3, let $F^{C}(x)=\frac{1}{3} \mathbf{1}_{x \leqslant 1}+\frac{1}{3} \mathbf{1}_{x \leqslant 3}+\frac{1}{3} \mathbf{1}_{x \leqslant K}$ and let $\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{Z}_{N}^{H} \mathbf{Z}_{N} \mathbf{C}_{N}^{\frac{1}{2}}$ with $F^{B_{N}} \rightarrow F$, then

$$
\begin{aligned}
m_{F} & =c m_{\underline{E}}+(c-1) \frac{1}{z} \\
m_{\underline{E}}(z) & =\left(c \int \frac{t}{1+\operatorname{tm}_{\underline{E}}(z)} d F^{C}(t)-z\right)^{-1}
\end{aligned}
$$

We take $c=1 / 10$ and alternatively $K=7$ and $K=4$.

## Spectrum of the sample covariance matrix



Figure: Histogram of the eigenvalues of $\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{Z}_{N}^{\mathrm{H}} \mathbf{Z}_{N} \mathbf{C}_{N}^{\frac{1}{2}}, N=3000, n=300$, with $\mathbf{C}_{N}$ diagonal composed of three evenly weighted masses in (i) 1,3 and 7 on top, (ii) 1,3 and 4 at bottom.

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## Support of a distribution

The support of a density $f$ is the closure of the set $\{x, f(x) \neq 0\}$.
For instance the support of the marčenko-Pastur law is $\left[(1-\sqrt{c})^{2},(1+\sqrt{c})^{2}\right]$.


Figure: Marčenko-Pastur law for different limit ratios $c=0.5$.

## Extreme eigenvalues

- Limiting spectral results are insufficient to infer about the location of extreme eigenvalues.
- Example: Consider $d F_{N}(x)=\frac{1}{N} \sum_{k=1}^{N} \delta_{a_{k}}$. Then, $d F_{N}^{0}=\frac{N-1}{N} d F_{N}+\frac{1}{N} \delta_{A_{N}}(x)$ and $d F_{N}$ with $A_{N} \geqslant a_{N}$ satisfy:

$$
d F_{N}-d F_{N}^{0} \Rightarrow 0
$$

- However, the supports of $F_{N}$ and $F_{N_{0}}$ differ by the mass $A_{N}$.

Question: How is the behaviour of the extreme eigenvalues of random covariance matrices?

## No eigenvalue outside the support of sample covariance matrices

Z. D. Bai, J. W. Silverstein, "No eigenvalues outside the support of the limiting spectral distribution of large-dimensional sample covariance matrices," The Annals of Probability, vol. 26, no. 1 pp. 316-345, 1998.

## Theorem

Let $\mathbf{X}_{N} \in \mathbb{C}^{N \times n}$ with i.i.d. entries with zero mean, unit variance and infinite fourth order. Let $\mathbf{C}_{N} \in \mathbb{C}^{N \times N}$ be nonrandom and bounded in norm. Let $\underline{m}_{N}$ be the unique solution in $\mathbb{C}_{+}$of

$$
\underline{m}_{N}=-\left(z-\frac{N}{n} \int \frac{\tau}{1+\tau \underline{m}_{N}} d F^{\mathrm{C}_{N}}(\tau)\right)^{-1}, \quad \underline{m}_{N}(z)=\frac{N}{n} m_{N}(z)+\frac{N-n}{n} \frac{1}{z}, z \in \mathbb{C}_{+},
$$

Let $F_{N}$ be the distribution associated to the Stieltjes transform $m_{N}(z)$. Consider
$\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{H} \mathbf{C}_{N}^{\frac{1}{2}}$. We know that $F^{\mathbf{B}_{N}}-F_{N}$ converge weakly to zero. Choose $N_{0} \in \mathbb{N}$ and $[a, b], a>0$, outside the support of $F_{N}$ for all $N \geqslant N_{0}$. Denote $\mathcal{L}_{N}$ the set of eigenvalues of $\mathbf{B}_{N}$. Then,

$$
P\left(\mathcal{L}_{N} \cap[a, b] \neq \emptyset \text { i.o. }\right)=0 .
$$

## No eigenvalue outside the support: which models?

J. W. Silverstein, P. Debashis, "No eigenvalues outside the support of the limiting empirical spectral distribution of a separable covariance matrix," J. of Multivariate Analysis vol. 100, no. 1, pp. 37-57, 2009.

- It has already been shown that (for all large $N$ ) there is no eigenvalues outside the support of
- Marčenko-Pastur law: $\mathbf{X X}{ }^{H}$, X i.i.d. with zero mean, variance $1 / N$, finite $4^{\text {th }}$ order moment.
- Sample covariance matrix: $\mathbf{C}^{\frac{1}{2}} \mathbf{X X} \mathbf{X}^{H} \mathbf{C}^{\frac{1}{2}}$ and $\mathbf{X}^{H} \mathbf{C X}, \mathbf{X}$ i.i.d. with zero mean, variance $1 / N$, finite $4^{\text {th }}$ order moment.
- Doubly-correlated matrix: $\mathbf{R}^{\frac{1}{2}} \mathbf{X C X} \mathbf{X}^{H} \mathbf{R}^{\frac{1}{2}}, \mathbf{X}$ with i.i.d. zero mean, variance $1 / N$, finite $4^{\text {th }}$ order moment.


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J. W. Silverstein, Z.D. Bai, Y.Q. Yin, "A note on the largest eigenvalue of a large dimensional sample covariance matrix," Journal of Multivariate Analysis, vol. 26, no. 2, pp. 166-168, 1988.
- If $4^{\text {th }}$ order moment is infinite,

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\lim \sup _{N} \lambda_{\max }^{\mathrm{xx}}=\infty
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J. Silverstein, Z. Bai, "No eigenvalues outside the support of the limiting spectral distribution of information-plus-noise type matrices" to appear in Random Matrices: Theory and Applications.

- Only recently, information plus noise models, $\mathbf{X}$ with i.i.d. zero mean, variance $1 / N$, finite $4^{\text {th }}$ order moment

$$
(\mathbf{X}+\mathbf{A})(\mathbf{X}+\mathbf{A})^{\mathrm{H}},
$$

and the generally correlation model where each column of $\mathbf{X}$ has correlation $\mathbf{R}_{i}$,

## Extreme eigenvalues: Deeper into the spectrum

- In order to derive statistical detection tests, we need more information on the extreme eigenvalues.


## Extreme eigenvalues: Deeper into the spectrum

- In order to derive statistical detection tests, we need more information on the extreme eigenvalues.
- We will study the fluctuations of the extreme eigenvalues (second order statistics)
- However, the Stieltjes transform method is not adapted here!


## Distribution of the largest eigenvalues of $\mathbf{X X}{ }^{H}$

C. A. Tracy, H. Widom, "On orthogonal and symplectic matrix ensembles," Communications in Mathematical Physics, vol. 177, no. 3, pp. 727-754, 1996.
K. Johansson, "Shape Fluctuations and Random Matrices," Comm. Math. Phys. vol. 209, pp. 437-476, 2000.

## Theorem

Let $\mathrm{X} \in \mathbb{C}^{N \times n}$ have i.i.d. Gaussian entries of zero mean and variance $1 / n$. Denoting $\lambda_{N}^{+}$the largest eigenvalue of $\mathbf{X X}{ }^{\mathrm{H}}$, then

$$
N^{\frac{2}{3}} \frac{\lambda_{N}^{+}-(1+\sqrt{c})^{2}}{(1+\sqrt{c})^{\frac{4}{3}} c^{\frac{1}{2}}} \Rightarrow X^{+} \sim F^{+}
$$

with $c=\lim _{N} N / n$ and $F^{+}$the Tracy-Widom distribution given by

$$
F^{+}(t)=\exp \left(-\int_{t}^{\infty}(x-t)^{2} q^{2}(x) d x\right)
$$

with $q$ the Painlevé II function that solves the differential equation

$$
\begin{aligned}
q^{\prime \prime}(x) & =x q(x)+2 q^{3}(x) \\
q(x) & \sim_{x \rightarrow \infty} \operatorname{Ai}(x)
\end{aligned}
$$

in which $\operatorname{Ai}(x)$ is the Airy function.

The law of Tracy-Widom


Centered-scaled largest eigenvalue of $\mathbf{X X}{ }^{\mathbf{H}}$
Figure: Distribution of $N^{\frac{2}{3}} c^{-\frac{1}{2}}(1+\sqrt{c})^{-\frac{4}{3}}\left[\lambda_{N}^{+}-(1+\sqrt{c})^{2}\right]$ against the distribution of $X^{+}$(distributed as Tracy-Widom law) for $N=500, n=1500, c=1 / 3$, for the covariance matrix model XX ${ }^{\mathrm{H}}$. Empirical distribution taken over 10,000 Monte-Carlo simulations.

## Techniques of proof

Method of proof requires very different tools:

- orthogonal (Laguerre) polynomials: to write joint unordered eigenvalue distribution as a kernel determinant.

$$
\rho_{N}\left(\lambda_{1}, \ldots, \lambda_{p}\right)=\operatorname{det}_{i, j=1}^{p} K_{N}\left(\lambda_{i}, \lambda_{j}\right)
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- Fredholm determinants: we can write hole probability as a Fredholm determinant.

$$
\begin{aligned}
P\left(N^{2 / 3}\left(\lambda_{i}-(1+\sqrt{c})^{2}\right) \in A, i=1, \ldots, N\right) & =1+\sum_{k \geqslant 1} \frac{(-1)^{k}}{k!} \int_{A^{c}} \cdots \int_{A^{c}} \operatorname{det}_{i, j=1}^{k} K_{N}\left(x_{i}, x_{j}\right) \prod d x_{i} \\
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- kernel theory: show that $K_{N}$ converges to a Airy kernel.

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K_{N}(x, y) \rightarrow K_{\text {Airy }}(x, y)=\frac{\operatorname{Ai}(x) \mathrm{Ai}^{\prime}(y)-\mathrm{Ai}^{\prime}(x) \mathrm{Ai}(y)}{x-y}
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$$

- differential equation tricks: hole probability in $[t, \infty)$ gives right-most eigenvalue distribution, which is simplified as solution of a Painelvé differential equation: the Tracy-Widom distribution.

$$
F^{+}(t)=e^{-\int_{t}^{\infty}(x-t) q(x)^{2} d x}, \quad q^{\prime \prime}=t q+2 q^{3}, q(x) \sim_{x \rightarrow \infty} \operatorname{Ai}(x)
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- deeper result than limit eigenvalue result
- gives a hint on convergence speed
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- deeper result than limit eigenvalue result
- gives a hint on convergence speed
- fairly biased on the left: even fewer eigenvalues outside the support.
- can be shown to hold for other distributions than Gaussian under mild assumptions


## Outline

```
Part 1: Fundamentals of Random Matrix Theory
    1.1. The Stieltjes Transform Method
    1.2 Extreme eigenvalues
    1.3 Extreme eigenvalues: the spiked models
    1.4 Spectrum Analysis and G-estimation
Application to Signal Sensing and Array Processing
    2.1 Eigenvalue-based detection
    2.2 The spiked G-MUSIC algorithm
Advanced Random Matrix Models for Robust Estimation
    3.1 Robust Estimation of Scatter
    3.2 Spiked model extension and robust G-MUSIC
    3.3 Robust shrinkage and application to mathematical finance
    3.4 Optimal robust GLRT detectors
Future Directions
    4.1 Kernel matrices and kernel methods
    4.2 Neural networks
```


## Spiked models

- We consider $n$ independent observations $\mathbf{x}_{1}, \cdots, \mathbf{x}_{n}$ of size $N$,
- The correlation structure is in general "white + low rank",

$$
\mathbb{E}\left[\mathbf{x}_{1} \mathbf{x}_{1}^{\mathrm{H}}\right]=\mathbf{I}+\mathbf{P}
$$

where $\mathbf{P}$ is of low rank,

- Objective: to infer the eigenvalues and/or the eigenvectors of $\mathbf{P}$


## The first result

J. Baik, J. W. Silverstein, "Eigenvalues of large sample covariance matrices of spiked population models," Journal of Multivariate Analysis, vol. 97, no. 6, pp. 1382-1408, 2006.

Theorem
Let $\mathbf{B}_{N}=\frac{1}{n}(\mathbf{I}+\mathbf{P})^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{H}(\mathbf{I}+\mathbf{P})^{\frac{1}{2}}$, where $\mathbf{X}_{N} \in \mathbb{C}^{N \times n}$ has i.i.d., zero mean and unit variance entries, and $\mathbf{P}_{N} \in \mathbb{R}^{N \times N}$ with eigenvalues given by:

$$
\operatorname{eig}(\mathbf{P})=\operatorname{diag}(\omega_{1}, \ldots, \omega_{K}, \underbrace{0, \ldots, \ldots, 0}_{N-K})
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with $\omega_{1}>\ldots>\omega_{K}>-1, c=\lim _{N} N / n$. Let $\lambda_{1}, \cdots, \lambda_{N}$ be the eigenvalues of $B_{N}$. We then have

- if $\omega_{j}>\sqrt{c}, \lambda_{j} \xrightarrow{\text { a.s. }} 1+\omega_{j}+c \frac{1+\omega_{j}}{\omega_{j}}$ (i.e. beyond the Marčenko-Pastur bulk!)
- if $\omega_{j} \in(0, \sqrt{c}], \lambda_{j} \xrightarrow{\text { a.s. }}(1+\sqrt{c})^{2}$ (i.e. right-edge of the Marčenko-Pastur bulk!)
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- for the other eigenvalues, we discriminate over $c$ :
- if $\omega_{j}<-\sqrt{c}, c<1, \lambda_{j} \xrightarrow{\text { a.s. }} 1+\omega_{j}+c \frac{1+\omega_{j}}{\omega_{j}}$ (i.e. beyond the Marčenko-Pastur bulk!)
- if $\omega_{j}<-\sqrt{c}, c>1, \lambda_{j} \xrightarrow{\text { a.s. }}(1-\sqrt{c})^{2}$ (i.e. left-edge of the Marčenko-Pastur bulk!)


## Illustration of spiked models



Eigenvalues
Figure: Eigenvalues of $\mathbf{B}_{N}=\frac{1}{n}(\mathbf{P}+\mathbf{I})^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}{ }^{\mathrm{H}}(\mathbf{P}+\mathbf{I})^{\frac{1}{2}}$, where $\omega_{1}=\omega_{2}=1$ and $\omega_{3}=\omega_{4}=2$ Dimensions: $N=500, n=1500$.

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- if $c$ is large, or alternatively, if some "population spikes" are small, part to all of the population spikes are attracted by the support!
- if so, no way to decide on the existence of the spikes from looking at the largest eigenvalues
- in signal processing words, signals might be missed using largest eigenvalues methods.
- as a consequence,
- the more the sensors ( $N$ ),
- the larger $c=\lim N / n$,
- the more probable we miss a spike


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- We start with a study of the limiting extreme eigenvalues.


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& =\operatorname{det}\left(\mathbf{I}_{N}+\mathbf{P}\right) \operatorname{det}\left(\mathbf{X} \mathbf{X}^{H}-x \mathbf{I}_{N}\right)^{-1} \operatorname{det}\left(\mathbf{I}_{N}+x \mathbf{P}\left(\mathbf{I}_{N}+\mathbf{P}\right)^{-1}\left(\mathbf{X X}^{H}-x \mathbf{I}_{N}\right)^{-1}\right) .
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- if $x$ eigenvalue of $\mathbf{B}_{N}$ but not of $\mathbf{X} \mathbf{X}^{H}$, then for $n$ large, $x>(1+\sqrt{c})^{2}$ (edge of MP law support) and
$\operatorname{det}\left(\mathbf{I}_{N}+x \mathbf{P}\left(\mathbf{I}_{N}+\mathbf{P}\right)^{-1}\left(\mathbf{X X} \mathbf{X}^{H}-x \mathbf{I}_{N}\right)^{-1}\right)=\operatorname{det}\left(\mathbf{I}_{r}+x \boldsymbol{\Omega}\left(\mathbf{I}_{N}+\boldsymbol{\Omega}\right)^{-1} \mathbf{U}^{H}\left(\mathbf{X X}^{H}-x \mathbf{I}_{N}\right)^{-1} \mathbf{U}\right)=0$ with $\mathbf{P}=\mathbf{U} \boldsymbol{\Omega} \mathbf{U}^{\mathbf{H}}, \mathbf{U} \in \mathbb{C}^{N \times r}$.


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- due to unitary invariance of $\mathbf{X}$,

$$
\mathbf{U}^{\mathrm{H}}\left(\mathbf{X} \mathbf{X}^{\mathrm{H}}-x \mathbf{I}_{N}\right)^{-1} \mathbf{U} \xrightarrow{\text { a.s. }} \int(t-x)^{-1} d F^{M P}(t) \mathbf{I}_{r} \triangleq m(x) \mathbf{I}_{r}
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with $F^{M P}$ the MP law, and $m(x)$ the Stieltjes transform of the MP law (often known for $r=1$ as trace lemma).

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with $F^{M P}$ the MP law, and $m(x)$ the Stieltjes transform of the MP law (often known for $r=1$ as trace lemma).

- finally, we have that the limiting solutions $x_{k}$ satisfy $x_{k} m\left(x_{k}\right)+\left(1+\omega_{k}\right) \omega_{k}^{-1}=0$.
- replacing $m(x)$, this is finally:

$$
\lambda_{k} \xrightarrow{\text { a.s. }} x_{k} \triangleq 1+\omega_{k}+c\left(1+\omega_{k}\right) \omega_{k}^{-1}, \text { if } \omega_{k}>\sqrt{c}
$$

## Comments on the result

- there exists a "phase transition" when the largest population eigenvalues move from inside to outside $(0,1+\sqrt{c})$.


## Comments on the result

- there exists a "phase transition" when the largest population eigenvalues move from inside to outside $(0,1+\sqrt{c})$.
- more importantly, for $t_{1}<1+\sqrt{c}$, we still have the same Tracy-Widom,
- no way to see the spike even when zooming in
- in fact, simulation suggests that convergence rate to the Tracy-Widom is slower with spikes.


## Outline

## Part 1: Fundamentals of Random Matrix Theory

1.1. The Stieltjes Transform Method
1.2 Extreme eigenvalues
1.3 Extreme eigenvalues: the spiked models
1.4 Spectrum Analysis and G-estimation

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Application to Signal Sensing and Array Processing
```

2.1 Eigenvalue-based detection
2.2 The spiked G-MUSIC algorithm

Advanced Random Matrix Models for Robust Estimation
3.1 Robust Estimation of Scatter
3.2 Spiked model extension and robust G-MUSIC
3.3 Robust shrinkage and application to mathematical finance
3.4 Optimal robust GLRT detectors

Future Directions
4.1 Kernel matrices and kernel methods
4.2 Neural networks

## Stieltjes transform inversion for covariance matrix models

J. W. Silverstein, S. Choi, "Analysis of the limiting spectral distribution of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 295-309, 1995.

- We know for the model $\mathbf{C}_{N}^{\frac{1}{2}} \mathbf{X}_{N}, \mathbf{X}_{N} \in \mathbb{C}^{N \times n}$ that, if $F^{\mathbf{C}_{N}} \Rightarrow F^{C}$, the Stieltjes transform of the e.s.d. of $\underline{\mathbf{B}}_{N}=\frac{1}{n} \mathbf{X}_{N}^{\mathrm{H}} \mathbf{C}_{N} \mathbf{X}_{N}$ satisfies $m_{\underline{B}_{N}}(z) \xrightarrow{\text { a.s. }} m_{\underline{E}}(z)$, with

$$
m_{\underline{E}}(z)=\left(-z-c \int \frac{t}{1+t_{\underline{E}}(z)} d F^{C}(t)\right)^{-1}
$$

which is unique on the set $\left\{z \in \mathbb{C}^{+}, m_{\underline{E}}(z) \in \mathbb{C}^{+}\right\}$.

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- This can be inverted into

$$
z_{\underline{E}}(m)=-\frac{1}{m}-c \int \frac{t}{1+t m} d F^{C}(t)
$$

for $m \in \mathbb{C}^{+}$.

## Stieltjes transform inversion and spectrum characterization

Remember that we can evaluate the spectrum density by taking a complex line close to $\mathbb{R}$ and evaluating $\mathfrak{I}\left[m_{\underline{E}}(z)\right]$ along this line. Now we can do better.

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It is shown that

$$
\lim _{\substack{z \rightarrow x \in \mathbb{R}^{*} \\ z \in \mathbb{C}^{+}}} m_{\underline{E}}(z)=m_{0}(x) \quad \text { exists. }
$$

We also have,

- for $x_{0}$ inside the support, the density $\underline{f}(x)$ of $\underline{F}$ in $x_{0}$ is $\frac{1}{\pi} \mathfrak{I}\left[m_{0}\right]$ with $m_{0}$ the unique solution $m \in \mathbb{C}^{+}$of

$$
\left[z_{\underline{E}}(m)=\right] x_{0}=-\frac{1}{m}-c \int \frac{t}{1+t m} d F^{C}(t)
$$

- let $m_{0} \in \mathbb{R}^{*}$ and $x_{F}$ the equivalent to $z_{E}$ on the real line. Then " $x_{0}$ outside the support of $\underline{E}$ " is equivalent to " $x_{\underline{E}}^{\prime}\left(m_{\underline{E}}\left(x_{0}\right)\right)>0, m_{\underline{E}}\left(x_{0}\right) \neq 0,-1 / m_{\underline{E}}\left(x_{0}\right)$ outside the support of $F^{C}$ ".


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This provides another way to determine the support!. For $m \in(-\infty, 0)$, evaluate $x_{\underline{\underline{E}}}(m)$. Whenever $x_{\underline{E}}$ decreases, the image is outside the support. The rest is inside.

## Another way to determine the spectrum: spectrum to analyze



Eigenvalues
Figure: Histogram of the eigenvalues of $\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{H} \mathbf{C}_{N}^{\frac{1}{2}}, N=300, n=3000$, with $\mathbf{C}_{N}$ diagonal composed of three evenly weighted masses in 1, 3 and 7 .

## Another way to determine the spectrum: inverse function method


$m$
Figure: Stieltjes transform of $\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{H} \mathbf{C}_{N}^{\frac{1}{2}}, N=300, n=3000$, with $\mathbf{C}_{N}$ diagonal composed of three evenly weighted masses in 1,3 and 7 . The support of $F$ is read on the vertical axis, whenever $m_{F}$ is decreasing.

## Cluster boundaries in sample covariance matrix models

Xavier Mestre, "Improved estimation of eigenvalues of covariance matrices and their associated subspaces using their sample estimates," IEEE Transactions on Information Theory, vol. 54, no. 11, Nov. 2008.

## Theorem

Let $\mathbf{X}_{N} \in \mathbb{C}^{N \times n}$ have i.i.d. entries of zero mean, unit variance, and $\mathbf{C}_{N}$ be diagonal such that $F^{\mathrm{C}_{N}} \Rightarrow F^{C}$, as $n, N \rightarrow \infty, N / n \rightarrow c$, where $F^{C}$ has $K$ masses in $t_{1}, \ldots, t_{K}$ with multiplicity $n_{1}, \ldots, n_{K}$ respectively. Then the I.s.d. of $\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{H} \mathbf{C}_{N}^{\frac{1}{2}}$ has support $\mathcal{S}$ given by

$$
\mathcal{S}=\left[x_{1}^{-}, x_{1}^{+}\right] \cup\left[x_{2}^{-}, x_{2}^{+}\right] \cup \ldots \cup\left[x_{Q}^{-}, x_{Q}^{+}\right]
$$

with $x_{q}^{-}=x_{F}\left(m_{q}^{-}\right), x_{q}^{+}=x_{F}\left(m_{q}^{+}\right)$, and

$$
x_{F}(m)=-\frac{1}{m}-c \frac{1}{n} \sum_{k=1}^{K} n_{k} \frac{t_{k}}{1+t_{k} m}
$$

with $2 Q$ the number of real-valued solutions counting multiplicities of $x_{F}^{\prime}(m)=0$ denoted in order $m_{1}^{-}<m_{1}^{+} \leqslant m_{2}^{-}<m_{2}^{+} \leqslant \ldots \leqslant m_{Q}^{-}<m_{Q}^{+}$.

## Comments on spectrum characterization

Previous results allows to determine

- the spectrum boundaries
- the number $Q$ of clusters
- as a consequence, the total separation $(Q=K)$ or not $(Q<K)$ of the spectrum in $K$ clusters.


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Mestre goes further: to determine local separability of the spectrum,

- identify the $K$ inflexion points, i.e. the $K$ solutions $m_{1}, \ldots, m_{K}$ to

$$
x_{F}^{\prime \prime}(m)=0
$$

- check whether $x_{F}^{\prime}\left(m_{i}\right)>0$ and $x_{F}^{\prime}\left(m_{i+1}\right)>0$
- if so, the cluster in between corresponds to a single population eigenvalue.


## Exact eigenvalue separation

Z. D. Bai, J. W. Silverstein, "Exact Separation of Eigenvalues of Large Dimensional Sample Covariance Matrices," The Annals of Probability, vol. 27, no. 3, pp. 1536-1555, 1999.

- Recall that the result on "no eigenvalue outside the support"
- says where eigenvalues are not to be found
- does not say, as we feel, that (if cluster separation) in cluster $k$, there are exactly $n_{k}$ eigenvalues.


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- Recall that the result on "no eigenvalue outside the support"
- says where eigenvalues are not to be found
- does not say, as we feel, that (if cluster separation) in cluster $k$, there are exactly $n_{k}$ eigenvalues.
- This is in fact the case,



## Eigeninference: Introduction of the problem

- Reminder: for a sequence $\mathbf{x}_{1}, \ldots, x_{n} \in \mathbb{C}^{N}$ of independent random variables,

$$
\hat{\mathbf{C}}_{N}=\frac{1}{n} \sum_{k=1}^{n} \mathbf{x}_{k} \mathbf{x}_{k}^{\mathrm{H}}
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is an $n$-consistent estimator of $\mathbf{C}_{N}=E\left[\mathbf{x}_{1} \mathrm{x}_{1}^{\mathrm{H}}\right]$.

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- If $n, N$ have comparable sizes, this no longer holds.
- Typically, $n, N$-consistent estimators of the full $\mathbf{C}_{N}$ matrix perform very badly.
- If only the eigenvalues of $\mathbf{C}_{N}$ are of interest, things can be done. The process of retrieving information about eigenvalues, eigenspace projections, or functional of these is called eigen-inference.


## Girko and the $G$-estimators

V. Girko, "Ten years of general statistical analysis," http://www.general-statistical-analysis.girko.freewebspace.com/chapter14.pdf

- Girko has come up with more than $50 \mathrm{~N}, n$-consistent estimators, called $G$-estimators (Generalized estimators). Among those, we find
- $G_{1}$-estimator of generalized variance. For

$$
G_{1}\left(\hat{\mathbf{C}}_{N}\right)=\alpha_{n}^{-1}\left[\log \operatorname{det}\left(\mathbf{C}_{N}\right)+\log \frac{n(n-1)^{N}}{(n-N) \prod_{k=1}^{N}(n-k)}\right]
$$

with $\alpha_{n}$ any sequence such that $\alpha_{n}^{-2} \log (n /(n-N)) \rightarrow 0$, we have

$$
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- However, Girko's proofs are rarely readable, if existent.


## A long standing problem

X. Mestre, "Improved estimation of eigenvalues and eigenvectors of covariance matrices using their sample estimates," IEEE trans. on Information Theory, vol. 54, no. 11, pp. 5113-5129, 2008.

- Consider the model $\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{H} \mathbf{C}_{N}^{\frac{1}{2}}$, where $F^{\mathbf{C}_{N}}$ is formed of a finite number of masses $t_{1}, \ldots, t_{K}$.
- It has long been thought the inverse problem of estimating $t_{1}, \ldots, t_{K}$ from the Stieltjes transform method was not possible.
- Only trials were iterative convex optimization methods.


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- It has long been thought the inverse problem of estimating $t_{1}, \ldots, t_{K}$ from the Stieltjes transform method was not possible.
- Only trials were iterative convex optimization methods.
- The problem was partially solved by Mestre in 2008!
- His technique uses elegant complex analysis tools. The description of this technique is the subject of this course.


## Reminders

- Consider the sample covariance matrix model $\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{H} \mathbf{C}_{N}^{\frac{1}{2}}$.
- Up to now, we saw:
- that there is no eigenvalue outside the support with probability 1 for all large $N$.
- that for all large $N$, when the spectrum is divided into clusters, the number of empirical eigenvalues in each cluster is exactly as we expect.


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- Up to now, we saw:
- that there is no eigenvalue outside the support with probability 1 for all large $N$.
- that for all large $N$, when the spectrum is divided into clusters, the number of empirical eigenvalues in each cluster is exactly as we expect.
- these results are of crucial importance for the following.


## Eigen-inference for the sample covariance matrix model

X. Mestre, "Improved estimation of eigenvalues and eigenvectors of covariance matrices using their sample estimates," IEEE trans. on Information Theory, vol. 54, no. 11, pp. 5113-5129, 2008.

## Theorem

Consider the model $\mathbf{B}_{N}=\frac{1}{n} \mathbf{C}_{N}^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{H} \mathbf{C}_{N}^{\frac{1}{2}}$, with $\mathbf{X}_{N} \in \mathbb{C}^{N \times n}$, i.i.d. with entries of zero mean, unit variance, and $\mathbf{C}_{N} \in \mathbb{R}^{N \times N}$ is diagonal with $K$ distinct entries $t_{1}, \ldots, t_{K}$ of multiplicity $N_{1}, \ldots, N_{K}$ of same order as $n$. Let $k \in\{1, \ldots, K\}$. Then, if the cluster associated to $t_{k}$ is separated from the clusters associated to $k-1$ and $k+1$, as $N, n \rightarrow \infty, N / n \rightarrow c$,

$$
\hat{t}_{k}=\frac{n}{N_{k}} \sum_{m \in \mathcal{N}_{k}}\left(\lambda_{m}-\mu_{m}\right)
$$

is an $N$, $n$-consistent estimator of $t_{k}$, where $\mathcal{N}_{k}=\left\{N-\sum_{i=k}^{K} N_{i}+1, \ldots, N-\sum_{i=k+1}^{K} N_{i}\right\}$, $\lambda_{1}, \ldots, \lambda_{N}$ are the eigenvalues of $\mathbf{B}_{N}$ and $\mu_{1}, \ldots, \mu_{N}$ are the $N$ solutions of

$$
\underline{m}_{\mathbf{x}_{N}^{H}} \mathbf{c}_{N} \mathbf{x}_{N}(\mu)=0
$$

or equivalently, $\mu_{1}, \ldots, \mu_{N}$ are the eigenvalues of $\operatorname{diag}(\boldsymbol{\lambda})-\frac{1}{N} \sqrt{\boldsymbol{\lambda}} \sqrt{\boldsymbol{\lambda}}^{\top}$.

## Remarks on Mestre's result

Assuming cluster separation, the result consists in

- taking the empirical ordered $\lambda_{i}$ 's inside the cluster (note that exact separation ensures there are $N_{k}$ of these!)
- getting the ordered eigenvalues $\mu_{1}, \ldots, \mu_{N}$ of

$$
\operatorname{diag}(\boldsymbol{\lambda})-\frac{1}{N} \sqrt{\lambda} \sqrt{\lambda}^{\top}
$$

with $\boldsymbol{\lambda}=\left(\lambda_{1}, \ldots, \lambda_{N}\right)^{\top}$. Keep only those of index inside $\mathcal{N}_{k}$.

- take the difference and scale.


## How to obtain this result?

- Major trick requires tools from complex analysis


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$$
\underline{m}_{N}(z)=\left(-z-c \int \frac{t}{1+t \underline{m}_{N}(z)} d F^{\mathrm{C}_{N}(t)}\right)^{-1}
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with $\underline{m}_{N}$ the deterministic equivalent of $m_{\underline{B}_{N}}$. This is the only random matrix result we need.

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- Before going further, we need some reminders from complex analysis.


## Limiting spectrum of the sample covariance matrix

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," J. of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

Reminder:

- If $F^{\mathrm{C}_{N}} \Rightarrow F^{C}$, then $m_{\mathbf{B}_{N}}(z) \xrightarrow{\text { a.s. }} m_{F}(z)$ such that

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m_{\underline{E}}(z)=\left(c \int \frac{t}{1+t m_{\underline{E}}(z)} d F^{C}(t)-z\right)^{-1}
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or equivalently

$$
m_{F C}\left(-1 / m_{\underline{E}}(z)\right)=-z m_{\underline{E}}(z) m_{F}(z)
$$

with $m_{\underline{E}}(z)=c m_{F}(z)+(c-1) \frac{1}{z}$ and $N / n \rightarrow c$.

## Reminders of complex analysis

- Cauchy integration formula


## Theorem

Let $U \subset \mathbb{C}$ be an open set and $f: U \rightarrow \mathbb{C}$ be holomorphic on $U$. Let $\gamma \subset U$ be a continuous contour (i.e. closed path). Then, for a inside the surface formed by $\gamma$, we have

$$
\frac{1}{2 \pi i} \oint_{\gamma} \frac{f(z)}{z-a} d z=f(a)
$$

while for a outside the surface formed by $\gamma$,

$$
\frac{1}{2 \pi i} \oint_{\gamma} \frac{f(z)}{z-a} d z=0
$$

## Complex integration

- From Cauchy integral formula, denoting $\mathcal{C}_{k}$ a contour enclosing only $t_{k}$,

$$
t_{k}=\frac{1}{2 \pi i} \oint_{\mathrm{C}_{k}} \frac{\omega}{\omega-t_{k}} d \omega
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- After the variable change $\omega=-1 / m_{\underline{E}}(z)$,

$$
t_{k}=\frac{N}{N_{k}} \frac{1}{2 \pi i} \oint_{\mathcal{C}_{巨, k}} z m_{F}(z) \frac{m_{\underline{E}}^{\prime}(z)}{m_{\underline{E}}^{2}(z)} d z,
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$$

- When the system dimensions are large,

$$
m_{F}(z) \simeq m_{\mathbf{B}_{N}}(z) \triangleq \frac{1}{N} \sum_{k=1}^{N} \frac{1}{\lambda_{k}-z}, \quad \text { with } \quad\left(\lambda_{1}, \ldots, \lambda_{N}\right)=\operatorname{eig}\left(\mathbf{B}_{N}\right)=\operatorname{eig}\left(\mathbf{Y} \mathbf{Y}^{\mathbf{H}}\right) .
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- After the variable change $\omega=-1 / m_{\underline{E}}(z)$,

$$
t_{k}=\frac{N}{N_{k}} \frac{1}{2 \pi i} \oint_{\mathrm{C}_{\underline{E}, k}} z m_{F}(z) \frac{m_{\underline{E}}^{\prime}(z)}{m_{\underline{E}}^{2}(z)} d z,
$$

- When the system dimensions are large,

$$
m_{F}(z) \simeq m_{\mathbf{B}_{N}}(z) \triangleq \frac{1}{N} \sum_{k=1}^{N} \frac{1}{\lambda_{k}-z}, \quad \text { with } \quad\left(\lambda_{1}, \ldots, \lambda_{N}\right)=\operatorname{eig}\left(\mathbf{B}_{N}\right)=\operatorname{eig}\left(\mathbf{Y} \mathbf{Y}^{\mathbf{H}}\right)
$$

- Dominated convergence arguments then show

$$
t_{k}-\hat{t}_{k} \xrightarrow{\text { a.s. }} 0 \quad \text { with } \quad \hat{t}_{k}=\frac{N}{N_{k}} \frac{1}{2 \pi i} \oint_{\mathrm{C}_{\underline{E}, k}} z m_{\mathbf{B}_{N}}(z) \frac{m_{\mathbf{B}_{N}}^{\prime}(z)}{m_{\underline{B}_{N}}^{2}(z)} d z
$$

## Understanding the contour change


m

- IF $\mathcal{C}_{\underline{E}, k}$ encloses cluster $k$ with real points $m_{1}<m_{2}$
- THEN $-1 / m_{1}=x_{1}<t_{k}<x_{2}=-1 / m_{2}$ and $\mathcal{C}_{k}$ encloses $t_{k}$.


## Poles and residues

- we find two sets of poles (outside zeros):
- $\lambda_{1}, \ldots, \lambda_{N}$, the eigenvalues of $\mathbf{B}_{N}$.
- the solutions $\mu_{1}, \ldots, \mu_{N}$ to $\underline{\underline{\hat{m}}}_{N}(z)=0$.


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- residue calculus, denote $f(w)=\left(\frac{n}{N} w m_{\underline{B}_{N}}(w)+\frac{n-N}{N}\right) \frac{m_{\underline{B}_{N}}^{\prime}(w)}{m_{\underline{B}_{N}}(w)^{2}}$,
- the $\lambda_{k}$ 's are poles of order 1 and

$$
\lim _{z \rightarrow \lambda_{k}}\left(z-\lambda_{k}\right) f(z)=-\frac{n}{N} \lambda_{k}
$$

- the $\mu_{k}$ 's are also poles of order 1 and by L'Hospital's rule

$$
\lim _{z \rightarrow \mu_{k}}\left(z-\lambda_{k}\right) f(z)=\lim _{z \rightarrow \mu_{k}} \frac{n}{N} \frac{\left(z-\mu_{k}\right) z m_{\underline{B}_{N}}^{\prime}(z)}{m_{\underline{B}_{N}}(z)}=\frac{n}{N} \mu_{k}
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$$

- So, finally

$$
\hat{t}_{k}=\frac{n}{N_{k}} \sum_{m \in \text { contour }}\left(\lambda_{m}-\mu_{m}\right)
$$

## Which poles in the contour?

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$$
\lambda_{1}<\mu_{2}<\lambda_{2}<\ldots<\mu_{N}<\lambda_{N}
$$

- what about $\mu_{1}$ ? the trick is to use the fact that

$$
\frac{1}{2 \pi i} \oint_{\mathrm{C}_{k}} \frac{1}{z} d z=0
$$

which leads to

$$
\frac{1}{2 \pi i} \oint_{\partial \Gamma_{k}} \frac{m_{\underline{E}}^{\prime}(w)}{m_{\underline{E}}(w)^{2}} d w=0
$$

the empirical version of which is

$$
\#\left\{i: \lambda_{i} \in \Gamma_{k}\right\}-\#\left\{i: \mu_{i} \in \Gamma_{k}\right\}
$$

Since their difference tends to 0 , there are as many $\lambda_{k}$ 's as $\mu_{k}$ 's in the contour, hence $\mu_{1}$ is asymptotically in the integration contour.

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## Problem formulation

- We want to test the hypothesis $\mathcal{H}_{0}$ against $\mathcal{H}_{1}$,

$$
\mathbb{C}^{N \times n} \ni \mathbf{Y}= \begin{cases}\mathbf{h} \mathbf{x}^{T}+\sigma \mathbf{W} & , \text { information plus noise, hypothesis } \mathcal{H}_{1} \\ \sigma \mathbf{W} & , \text { pure noise, hpothesis } \mathcal{H}_{0}\end{cases}
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with $\mathbf{h} \in \mathbb{C}^{N}, \mathbf{x} \in \mathbb{C}^{N}, \mathbf{W} \in \mathbb{C}^{N \times n}$.

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- We assume no knowledge whatsoever but that W has i.i.d. (non-necessarily Gaussian) entries.


## Exploiting the conditioning number

L. S. Cardoso, M. Debbah, P. Bianchi, J. Najim, "Cooperative spectrum sensing using random matrix theory," International Symposium on Wireless Pervasive Computing, pp. 334-338, 2008.

- under either hypothesis,
- if $\mathcal{H}_{0}$, for $N$ large, we expect $F_{\mathrm{YYH}}$ close to the Marčenko-Pastur law, of support $\left[\sigma^{2}(1-\sqrt{c})^{2}, \sigma^{2}(1+\sqrt{c})^{2}\right]$.
- if $\mathcal{H}_{1}$, if population spike more than $1+\sqrt{\frac{N}{n}}$, largest eigenvalue is further away.
- the conditioning number of $\mathbf{Y Y}^{H}$ is therefore asymptotically, as $N, n \rightarrow \infty, N / n \rightarrow c$,
- if $\mathcal{H}_{0}$,

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\operatorname{cond}(\mathbf{Y}) \triangleq \frac{\lambda_{\max }}{\lambda_{\min }} \rightarrow \frac{(1-\sqrt{c})^{2}}{(1+\sqrt{c})^{2}}
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- if $\mathcal{H}_{1}$,

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\operatorname{cond}(\mathbf{Y}) \rightarrow t_{1}+\frac{c t_{1}}{t_{1}-1}>\frac{(1-\sqrt{c})^{2}}{(1+\sqrt{c})^{2}}
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with $t_{1}=\sum_{k=1}^{N}\left|h_{k}\right|^{2}+\sigma^{2}$

- the conditioning number is independent of $\sigma$. We then have the decision criterion, whether or not $\sigma$ is known,

$$
\text { decide } \begin{cases}\mathcal{H}_{0}: & \text { if } \operatorname{cond}\left(\mathbf{Y} \mathbf{Y}^{\mathrm{H}}\right) \leqslant \frac{\left(1-\sqrt{\frac{N}{n}}\right)^{2}}{\left(1+\sqrt{\frac{N}{n}}\right)^{2}}+\varepsilon \\ \mathcal{H}_{1}: & \text { otherwise. }\end{cases}
$$

for some security margin $\varepsilon$.

## Comments on the method

- Advantages:
- much simpler than finite size analysis
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- Drawbacks:
- only stands for very large $N$ (dimension $N$ for which asymptotic results arise function of $\sigma$ !)
- ad-hoc method, does not rely on performance criterion.


## Generalized likelihood ratio test

P. Bianchi, M. Debbah, M. Maida, J. Najim, "Performance of Statistical Tests for Source Detection using Random Matrix Theory," IEEE Trans. on Information Theory, vol. 57, no. 4, pp. 2400-2419, 2011.

- Alternative generalized likelihood ratio test (GLRT) decision criterion, i.e.

$$
C(\mathbf{Y})=\frac{\sup _{\sigma^{2}, \mathbf{h}} P_{\mathbf{Y} \mid \mathbf{h}, \sigma^{2}}\left(\mathbf{Y}, \mathbf{h}, \sigma^{2}\right)}{\sup _{\sigma^{2}} P_{\mathbf{Y} \mid \sigma^{2}}\left(\mathbf{Y} \mid \sigma^{2}\right)} .
$$

- Denote

$$
T_{N}=\frac{\lambda_{\max }\left(\mathbf{Y} \mathbf{Y}^{H}\right)}{\frac{1}{N} \operatorname{tr} \mathbf{Y} \mathbf{Y}^{H}}
$$

To guarantee a maximum false alarm ratio of $\alpha$,

$$
\text { decide } \begin{cases}\mathcal{H}_{1}: & \text { if }\left(1-\frac{1}{N}\right)^{(1-N) n} T_{N}^{-n}\left(1-\frac{\mathbf{T}_{N}}{N}\right)^{(1-N) n}>\xi_{N} \\ \mathcal{H}_{0}: & \text { otherwise. }\end{cases}
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for some threshold $\xi_{N}$ that can be explicitly given as a function of $\alpha$.

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$$

for some threshold $\xi_{N}$ that can be explicitly given as a function of $\alpha$.

- Optimal test with respect to GLR.
- Performs better than conditioning number test.


## Performance comparison for unknown $\sigma^{2}, P$



Figure: ROC curve for a priori unknown $\sigma^{2}$ of the Neyman-Pearson test, conditioning number method and GLRT, $K=1, N=4, M=8, S N R=0 \mathrm{~dB}$. For the Neyman-Pearson test, both uniform and Jeffreys prior, with exponent $\beta=1$, are provided.

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## Source localization

A uniform array of $M$ antennas receives signal from $K$ radio sources during $n$ signal snapshots. Objective: Estimate the arrival angles $\theta_{1}, \cdots, \theta_{K}$.


## Source Localization using Music Algorithm

We consider the scenario of $K$ sources and $N$ antenna-array capturing $n$ observations:

$$
\mathbf{x}_{t}=\sum_{k=1}^{K} \mathbf{a}\left(\theta_{k}\right) s_{k, t}+\sigma \mathbf{w}_{t}, t=1, \cdots, n
$$

- $\mathbf{A}_{N}=\left[\mathbf{a}_{N}\left(\theta_{1}\right), \cdots, \mathbf{a}_{N}\left(\theta_{K}\right)\right]$ with $\mathbf{a}_{N}(\theta)=\left[\begin{array}{c}1 \\ e^{\imath \pi \sin \theta} \\ \ldots \\ e^{\imath(N-1) \pi \sin \theta}\end{array}\right]$
- $\sigma^{2}$ is the noise variance and is set 1 for simplicity,
- Objective: infer $\theta_{1}, \cdots, \theta_{K}$ from the $n$ observations
- Let $\mathbf{X}_{N}=\left[\mathbf{x}_{1}, \cdots, \mathbf{x}_{n}\right]$, then,

$$
\mathbf{X}=\mathbf{A S}+\mathbf{W}=\left[\begin{array}{ll}
\mathbf{A} & \mathbf{I}_{N}
\end{array}\right]\left[\begin{array}{c}
\mathbf{S} \\
\mathbf{W}
\end{array}\right]
$$

- If $K$ is finite while $n, N \rightarrow+\infty$, the model correponds to the spiked covariance model.
- MUSIC Algorithm: Let $\Pi$ be the orthogonal projection matrix on the span of AA* and $\Pi^{\perp}=\mathbf{I}_{N}-\boldsymbol{\Pi}$ (orthogonal projector on the noise subspace). Angles $\theta_{1}, \cdots, \theta_{K}$ are the unique ones verifying

$$
\eta(\theta) \triangleq \mathbf{a}_{N}(\theta)^{*} \Pi \mathbf{a}_{N}(\theta)=0
$$

## Traditional MUSIC algorithm

- Traditional MUSIC algorithm: Angles are estimated as local minima of:

$$
\mathbf{a}_{N}(\theta)^{*} \hat{\boldsymbol{\Pi}} \mathbf{a}_{N}(\theta)
$$

where $\hat{\Pi}$ is the orthogonal projection matrix on the eigenspace associated to the $K$ largest eigenvalues of $\frac{1}{n} \mathbf{X}_{N} \mathbf{X}_{N}^{*}$

- It is well-known that this estimator is consistent when $n \rightarrow+\infty$ with $K, N$ fixed,
- We consider the case of $K$ finite $\longrightarrow$ spiked covariance model
- What happens when $n, N \rightarrow+\infty$ ?


## Asymptotic behaviour of the traditional MUSIC (1)

$\rightarrow$ We first need to understand the spectrum of $\frac{1}{n} \mathbf{X X}{ }^{H}$

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$\rightarrow$ Denote $\mathbf{P}=\mathbf{A} \mathbf{A}^{H}=\mathbf{U}_{S} \boldsymbol{\Omega} \mathbf{U}_{S}^{H}, \boldsymbol{\Omega}=\operatorname{diag}\left(\boldsymbol{\omega}_{1}, \ldots, \boldsymbol{\omega}_{K}\right)$, and $\mathbf{Z}=\left[\mathbf{S}^{\top} \mathbf{W}^{\top}\right]^{\top}$ to recover (up to one row) the generic spiked model

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$$
\mathbf{X}=\left(\mathbf{I}_{N}+\mathbf{P}\right)^{\frac{1}{2}} \mathbf{Z}
$$

- Reminder: If $x$ eigenvalue of $\frac{1}{n} \mathbf{X} \mathbf{X}^{H}$ with $x>(1+\sqrt{c})^{2}$ (edge of MP law), for all large $n$,

$$
x \triangleq \lambda_{k} \xrightarrow{\text { a.s. }} \rho_{k} \triangleq 1+\omega_{k}+c\left(1+\omega_{k}\right) \omega_{k}^{-1}, \text { if } \omega_{k}>\sqrt{c}
$$

for some $k$.

Asymptotic behaviour of the traditional MUSIC (2)
$\rightarrow$ Recall the MUSIC approach: we want to estimate

$$
\eta(\theta)=\mathbf{a}(\theta)^{\mathrm{H}} \mathbf{U}_{W} \mathbf{U}_{W}^{H} \mathbf{a}(\theta) \quad\left(\mathbf{U}_{W} \in \mathbb{C}^{N \times(N-K)} \text { such that } \mathbf{U}_{W}^{\mathrm{H}} \mathbf{U}_{S}=0\right)
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$$

$\rightarrow$ Instead of this quantity, we start with the study of

$$
\mathbf{a}(\theta)^{\mathrm{H}} \hat{\mathbf{u}}_{i} \hat{\mathbf{u}}_{i}^{\mathrm{H}} \mathbf{a}(\theta), \quad k=1, \ldots, K
$$

with $\hat{\mathbf{u}}_{1}, \ldots, \hat{\mathbf{u}}_{N}$ the eigenvectors belonging to $\lambda_{1} \geqslant \ldots \geqslant \lambda_{N}$.
$\rightarrow$ To fall back on known RMT quantities, we use the Cauchy-integral:

$$
\mathbf{a}(\theta)^{\mathrm{H}} \hat{\mathbf{u}}_{i} \hat{\mathbf{u}}_{i}^{\mathrm{H}} \mathbf{a}(\theta)=-\frac{1}{2 \pi \imath} \oint_{\mathrm{C}_{i}} \mathbf{a}(\theta)^{\mathrm{H}}\left(\frac{1}{n} \mathbf{X} \mathbf{X}^{\mathrm{H}}-z \mathbf{I}_{N}\right)^{-1} \mathbf{a}(\theta) d z
$$

with $\mathcal{C}_{i}$ a contour enclosing $\lambda_{i}$ only.

## Asymptotic behaviour of the traditional MUSIC (2)

$\rightarrow$ Recall the MUSIC approach: we want to estimate

$$
\eta(\theta)=\mathbf{a}(\theta)^{\mathrm{H}} \mathbf{U}_{W} \mathbf{U}_{W}^{\mathrm{H}} \mathbf{a}(\theta) \quad\left(\mathbf{U}_{W} \in \mathbb{C}^{N \times(N-K)} \text { such that } \mathbf{U}_{W}^{\mathrm{H}} \mathbf{U}_{S}=0\right)
$$

$\rightarrow$ Instead of this quantity, we start with the study of

$$
\mathbf{a}(\theta)^{\mathrm{H}} \hat{\mathbf{u}}_{i} \hat{\mathbf{u}}_{i}^{\mathrm{H}} \mathbf{a}(\theta), \quad k=1, \ldots, K
$$

with $\hat{\mathbf{u}}_{1}, \ldots, \hat{\mathbf{u}}_{N}$ the eigenvectors belonging to $\lambda_{1} \geqslant \ldots \geqslant \lambda_{N}$.
$\rightarrow$ To fall back on known RMT quantities, we use the Cauchy-integral:

$$
\mathbf{a}(\theta)^{\mathrm{H}} \hat{\mathbf{u}}_{i} \hat{\mathbf{u}}_{i}^{\mathrm{H}} \mathbf{a}(\theta)=-\frac{1}{2 \pi \imath} \oint_{\mathcal{C}_{i}} \mathbf{a}(\theta)^{\mathrm{H}}\left(\frac{1}{n} \mathbf{X} \mathbf{X}^{\mathrm{H}}-z \mathbf{I}_{N}\right)^{-1} \mathbf{a}(\theta) d z
$$

with $\mathcal{C}_{i}$ a contour enclosing $\lambda_{i}$ only.
$\rightarrow$ Woodbury's identity $(A+U C V)^{-1}=A^{-1}-A^{-1} U\left(C^{-1}+V A^{-1} U\right)^{-1} V A^{-1}$ gives:

$$
\mathbf{a}^{H} \hat{\mathbf{u}}_{i} \hat{\mathbf{u}}_{i}^{H} \mathbf{a}=\frac{-1}{2 \pi \imath} \oint_{\mathcal{C}_{i}} \mathbf{a}^{H}\left(\mathbf{I}_{N}+\mathbf{P}\right)^{-\frac{1}{2}}\left(\frac{\mathbf{z Z}}{n}-z \mathbf{I}_{N}\right)^{-1}\left(\mathbf{I}_{N}+\mathbf{P}\right)^{-\frac{1}{2}} \mathbf{a} d z+\frac{1}{2 \pi \imath} \oint_{\mathcal{C}_{i}} \hat{a}_{1}^{H} \widehat{\mathbf{H}}^{-1} \hat{\mathbf{a}}_{2} d z
$$

where $\mathbf{P}=\mathbf{U}_{S} \boldsymbol{\Omega} \mathbf{U}_{S}^{H}$, and

$$
\begin{cases}\hat{\mathbf{H}} & =\mathbf{I}_{K}+z \boldsymbol{\Omega}\left(\mathbf{I}_{K}+\boldsymbol{\Omega}\right)^{-1} \mathbf{U}_{S}^{H}\left(\frac{1}{n} \mathbf{Z} Z^{H}-z \mathbf{I}_{N}\right)^{-1} \mathbf{U}_{S} \\ \hat{\mathbf{a}}_{1}^{H} & =z \mathbf{a}(\theta)^{H}\left(\mathbf{I}_{N}+\mathbf{P}\right)^{-\frac{1}{2}}\left(\frac{1}{n} \mathbf{Z} \mathbf{Z}^{H}-z \mathbf{I}_{N}\right)^{-1} \mathbf{U}_{S} \\ \hat{\mathbf{a}}_{2} & =\boldsymbol{\Omega}\left(\mathbf{I}_{K}+\boldsymbol{\Omega}\right)^{-1} \mathbf{U}_{S}^{H}\left(\frac{1}{n} \mathbf{Z} \mathbf{Z}^{H}-z \mathbf{I}_{N}\right)^{-1}\left(\mathbf{I}_{N}+\mathbf{P}\right)^{-\frac{1}{2}} \mathbf{a}(\theta)\end{cases}
$$

## Asymptotic behaviour of the traditional MUSIC (3)

- For large $n$, the first term has no pole, while the second converges to

$$
T_{i} \triangleq \frac{1}{2 \pi \imath} \oint_{\mathcal{C}_{i}} \mathbf{a}_{1}^{H} \mathbf{H}^{-1} \mathbf{a}_{2} d z \text {, with }\left\{\begin{aligned}
\mathbf{H} & =\mathbf{I}_{K}+z m(z) \boldsymbol{\Omega}\left(\mathbf{I}_{K}+\boldsymbol{\Omega}\right)^{-1} \\
\mathbf{a}_{1}^{H} & =z m(z) \mathbf{a}^{*}\left(\mathbf{I}_{N}+\mathbf{P}\right)^{-\frac{1}{2}} \mathbf{U}_{S} \\
\mathbf{a}_{2} & =m(z) \boldsymbol{\Omega}\left(\mathbf{I}_{K}+\boldsymbol{\Omega}\right)^{-1} \mathbf{U}_{S}^{H}\left(\mathbf{I}_{N}+\mathbf{P}\right)^{-\frac{1}{2}} \mathbf{a}
\end{aligned}\right.
$$

which after development is

$$
T_{i}=\sum_{\ell=1}^{K} \frac{1}{1+\omega_{\ell}} \frac{1}{2 \pi \imath} \oint_{\mathrm{C}_{i}} \frac{z m^{2}(z)}{\frac{1+\omega_{\ell}}{\omega_{\ell}}+z m(z)} d z
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$$

- Using residue calculus, the sole pole is in $\rho_{i}$ and we find

$$
\mathbf{a}(\theta)^{H} \hat{\mathbf{u}}_{i} \hat{\mathbf{u}}_{i}^{H} \mathbf{a}(\theta) \xrightarrow{\text { a.s. }} \frac{1-c \omega_{i}^{-2}}{1+c \omega_{i}^{-1}} \mathbf{a}(\theta)^{H} \mathbf{u}_{i} \mathbf{u}_{i}^{H} \mathbf{a}(\theta) .
$$

Therefore,

$$
\hat{\mathfrak{\eta}}(\theta)=\mathbf{a}(\theta)^{\mathrm{H}} \hat{\Pi} \mathbf{a}(\theta) \xrightarrow{\text { a.s. }} \mathbf{a}(\theta) \mathbf{a}(\theta)^{\mathrm{H}}-\sum_{i=1}^{K} \frac{1-c \omega_{i}^{-2}}{1+c \omega_{i}^{-1}} \mathbf{a}(\theta)^{\mathrm{H}} \mathbf{u}_{i} \mathbf{u}_{i}^{\mathrm{H}} \mathbf{a}(\theta)
$$

## Improved G-MUSIC

Recall that:

$$
\mathbf{a}(\theta)^{\mathrm{H}} \mathbf{u}_{k} \mathbf{u}_{k}^{\mathrm{H}} \mathbf{a}(\theta)-\frac{1+c \omega_{k}^{-1}}{1-c \omega_{k}^{-2}} \mathbf{a}(\theta)^{\mathrm{H}} \hat{\mathbf{u}}_{k} \hat{\mathbf{u}}_{k}^{\mathrm{H}} \mathbf{a}(\theta) \xrightarrow{\text { a.s. }} 0
$$

$\rightarrow$ The $\omega_{k}$ are however unknown. But they can be estimated from

$$
\lambda_{k} \xrightarrow{\text { a.s. }} \rho_{k}=1+\omega_{k}+c\left(1+\omega_{k}\right) \omega_{k}^{-1}
$$

$\rightarrow$ This gives finally

$$
\hat{\eta}_{G}(\theta) \simeq \mathbf{a}(\theta)^{H} \mathbf{a}(\theta)-\sum_{k=1}^{K} \frac{1+c \hat{\omega}_{k}^{-1}}{1-c \hat{\omega}_{k}^{-2}} \mathbf{a}(\theta)^{H} \hat{\mathbf{u}}_{k} \hat{\mathbf{u}}_{k}^{H} \mathbf{a}(\theta)
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with

$$
\hat{\omega}_{k}=\frac{\hat{\lambda}_{k}-(c+1)}{2}+\sqrt{\left.\left(c+1-\hat{\lambda}_{k}\right)^{2}-4 c\right)}
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$$

$\rightarrow$ We then obtain another ( $N, n$ )-consistent MUSIC estimator, only valid for $K$ finite!

## Simulation results



Figure: MUSIC against G-MUSIC for DoA detection of $K=3$ signal sources, $N=20$ sensors, $M=150$ samples, SNR of 10 dB . Angles of arrival of $10^{\circ}, 35^{\circ}$, and $37^{\circ}$.

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- 1.2. Extreme eigenvalues: no eigenvalue outside the support, exact separation, Tracy-Widom law
- 1.3. Extreme eigenvalues: the spiked models
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## Advanced Random Matrix Models for Robust Estimation

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## Covariance estimation and sample covariance matrices

P.J. Huber, "Robust Statistics", 1981.
$\longrightarrow$ Many statistical inference techniques rely on the sample covariance matrix (SCM) taken from i.i.d. observations $x_{1}, \ldots, x_{n}$ of a r.v. $x \in \mathbb{C}^{N}$.

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- The main reasons are:
- Assuming $E[x]=0, E\left[x x^{*}\right]=C_{N}$, with $X=\left[x_{1}, \ldots, x_{n}\right]$, by the LLN

$$
\hat{S}_{N} \triangleq \frac{1}{n} X X^{*} \xrightarrow{\text { a.s. }} C_{N} \text { as } n \rightarrow \infty .
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- The SCM $\hat{S}_{N}$ is the ML estimate of $C_{N}$ for Gaussian $x$
$\rightarrow$ One therefore expects $\hat{\theta}$ to closely approximate $\theta$ for all finite $n$.
- This approach however has two limitations:
- if $N, n$ are of the same order of magnitude,

$$
\left\|\hat{S}_{N}-C_{N}\right\| \nrightarrow 0 \text { as } N, n \rightarrow \infty, N / n \rightarrow c>0 \text {, so that in general }|\hat{\theta}-\theta| \nrightarrow 0
$$

$\rightarrow$ This motivated the introduction of G-estimators.

- if $x$ is not Gaussian, but has heavier tails, $\hat{S}_{N}$ is a poor estimator for $C_{N}$.
$\rightarrow$ This motivated the introduction of robust estimators.


## Reminders on robust estimation

J. T. Kent, D. E. Tyler, "Redescending M-estimates of multivariate location and scatter", 1991. R. A. Maronna, "Robust M-estimators of multivariate location and scatter", 1976.
Y. Chitour, F. Pascal, "Exact maximum likelihood estimates for SIRV covariance matrix: Existence and algorithm analysis", 2008.
$\rightarrow$ The objectives of robust estimators:

- Replace the SCM $\hat{S}_{N}$ by another estimate $\hat{C}_{N}$ of $C_{N}$ which:
- rejects (or downscales) observations deterministically
- or rejects observations inconsistent with the full set of observations
$\rightarrow$ Example: Huber estimator, $\hat{C}_{N}$ defined as solution of

$$
\hat{C}_{N}=\frac{1}{n} \sum_{i=1}^{n} \beta_{i} x_{i} x_{i}^{*} \text { with } \beta_{i}=\alpha \min \left\{1, \frac{k^{2}}{\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}}\right\} \text { for some } \alpha>1, k^{2} \text { function of } \hat{C}_{N} \text {. }
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$$

- Provide scale-free estimators of $C_{N}$ :
$\rightarrow$ Example: Tyler's estimator: if one observes $x_{i}=\tau_{i} z_{i}$ for unknown scalars $\tau_{i}$,

$$
\hat{C}_{N}=\frac{1}{n} \sum_{i=1}^{n} \frac{1}{\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}} x_{i} x_{i}^{*}
$$

- existence and uniqueness of $\hat{C}_{N}$ defined up to a constant.
- few constraints on $x_{1}, \ldots, x_{n}$ ( $N+1$ of them must be linearly independent)


## Reminders on robust estimation

$\rightarrow$ The objectives of robust estimators:

- replace the SCM $\hat{S}_{N}$ by the ML estimate for $C_{N}$. $\rightarrow$ Example: Maronna's estimator for elliptical $x$

$$
\hat{C}_{N}=\frac{1}{n} \sum_{i=1}^{n} u\left(\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}\right) x_{i} x_{i}^{*}
$$

with $u(s)$ such that
(i) $u(s)$ is continuous and non-increasing on [ $0, \infty$ )
(ii) $\phi(s)=s u(s)$ is non-decreasing, bounded by $\phi_{\infty}>1$. Moreover, $\phi(s)$ increases where $\phi(s)<\phi_{\infty}$. (note that Huber's estimator is compliant with Maronna's estimators)

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(note that Huber's estimator is compliant with Maronna's estimators)

- existence is not too demanding
- uniqueness imposes strictly increasing $u(s)$ (inconsistent with Huber's estimate)
- consistency result: $\hat{C}_{N} \rightarrow C_{N}$ if $u(s)$ meets the ML estimator for $C_{N}$.


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## Robust RMT estimation

Can we study the performance of estimators based on the $\hat{C}_{N}$ ?

- what are the spectral properties of $\hat{C}_{N}$ ?
- can we generate RMT-based estimators relying on $\hat{C}_{N}$ ?


## Setting and assumptions

- Assumptions:
- Take $x_{1}, \ldots, x_{n} \in \mathbb{C}^{N}$ "elliptical-like" random vectors, i.e. $x_{i}=\sqrt{\tau_{i}} C_{N}^{\frac{1}{2}} w_{i}$ where
- $\tau_{1}, \ldots, \tau_{n} \in \mathbb{R}^{+}$random or deterministic with $\frac{1}{n} \sum_{i=1}^{n} \tau_{i} \xrightarrow{\text { a.s. }} 1$
- $w_{1}, \ldots, w_{n} \in \mathbb{C}^{N}$ random independent with $w_{i} / \sqrt{N}$ uniformly distributed over the unit-sphere
- $C_{N} \in \mathbb{C}^{N \times N}$ deterministic, with $C_{N} \succ 0$ and $\lim \sup _{N}\left\|C_{N}\right\|<\infty$
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- Additional technical assumption: Let $v_{n} \triangleq \frac{1}{n} \sum_{i=1}^{n} \delta_{\tau_{i}}$. For each $a>b>0$, a.s.

$$
\limsup _{t \rightarrow \infty} \frac{\lim \sup _{n} v_{n}((t, \infty))}{\phi(a t)-\phi(b t)}=0
$$

$\rightarrow$ Controls relative speed of the tail of $v_{n}$ versus the flattening speed of $\phi(x)$ as $x \rightarrow \infty$. Examples:

- $\tau_{i}<M$ for each $i$. In this case, $v_{n}((t, \infty))=0$ a.s. for $t>M$.
- For $u(t)=(1+\alpha) /(\alpha+t), \alpha>0$, and $\tau_{i}$ i.i.d., it is sufficient to have $E\left[\tau_{1}^{1+\varepsilon}\right]<\infty$.


## Heuristic approach

- Major issues with $\hat{C}_{N}$ :
- Defined implicitly
- Sum of non-independent rank-one matrices from vectors $\sqrt{u\left(\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}\right)} x_{i}\left(\hat{C}_{N}\right.$ depends on all $x_{j}^{\prime}$ s $)$.
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- But there is some hope:
- First remark: we can work with $C_{N}=I_{N}$ without generality restriction!
- Denote

$$
\hat{C}_{(j)}=\frac{1}{n} \sum_{i \neq j}^{n} u\left(\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}\right) x_{i} x_{i}^{*}
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$$
\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i} \simeq \tau_{i} \frac{1}{N} \operatorname{tr} \hat{C}_{(i)}^{-1} \simeq \tau_{i} \frac{1}{N} \operatorname{tr} \hat{C}_{N}^{-1} .
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$$

- Our heuristic approach:
- Rewrite $\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}$ as $f\left(\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}\right)$ for some function $f$ (later called $g^{-1}$ )
- Deduce that

$$
\hat{C}_{N}=\frac{1}{n} \sum_{i=1}^{n}(u \circ f)\left(\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}\right) x_{i} x_{i}^{*}
$$

- Use $\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i} \simeq \tau_{i} \frac{1}{N} \operatorname{tr} \hat{C}_{N}^{-1}$ to get

$$
\hat{C}_{N} \simeq \frac{1}{n} \sum_{i=1}^{n}(u \circ f)\left(\tau_{i} \frac{1}{N} \operatorname{tr} \hat{C}_{N}^{-1}\right) x_{i} x_{i}^{*}
$$

- Use random matrix results to find a limiting value $\gamma$ for $\frac{1}{N} \operatorname{tr} \hat{C}_{N}^{-1}$, and conclude

$$
\hat{C}_{N} \simeq \frac{1}{n} \sum_{i=1}^{n}(u \circ f)\left(\tau_{i} \gamma\right) x_{i} x_{i}^{*}
$$

## Heuristic approach in detail: $f$ and $\gamma$

- Determination of $f:$ Recall the identity $\left(A+t v v^{*}\right)^{-1} v=A^{-1} /\left(1+t v^{*} A^{-1} v\right)$. Then

$$
\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}=\frac{\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}}{1+c_{N} u\left(\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}\right) \frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}}
$$

so that

$$
\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}=\frac{\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}}{1-c_{N} \phi\left(\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}\right)} .
$$

Now the function $g: x \mapsto x /\left(1-c_{N} \phi(x)\right)$ is monotonous increasing (we use the assumption $\left.\phi_{\infty}<c^{-1}!\right)$, hence, with $f=g^{-1}$,

$$
\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1} x_{i}=g^{-1}\left(\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}\right)
$$

## Heuristic approach in detail: $f$ and $\gamma$

- Determination of $\gamma$ : From previous calculus, we expect

$$
\hat{C}_{N} \simeq \frac{1}{n} \sum_{i=1}^{n}\left(u \circ g^{-1}\right)\left(\tau_{i} \frac{1}{N} \operatorname{tr} \hat{C}_{N}^{-1}\right) x_{i} x_{i}^{*} \simeq \frac{1}{n} \sum_{i=1}^{n}\left(u \circ g^{-1}\right)\left(\tau_{i} \gamma\right) x_{i} x_{i}^{*}
$$

Hence

$$
\gamma \simeq \frac{1}{N} \operatorname{tr} \hat{C}_{N}^{-1} \simeq \frac{1}{N} \operatorname{tr}\left(\frac{1}{n} \sum_{i=1}^{n}\left(u \circ g^{-1}\right)\left(\tau_{i} \gamma\right) \tau_{i} w_{i} w_{i}^{*}\right)^{-1} .
$$

Since $\tau_{i}$ are independent of $w_{i}$ and $\gamma$ deterministic, this is a Bai-Silverstein model

$$
\frac{1}{n} W D W^{*}, W=\left[w_{1}, \ldots, w_{n}\right], \quad D=\operatorname{diag}\left(D_{i i}\right)=u \circ g^{-1}\left(\tau_{i} \gamma\right) .
$$

And we have:

$$
\begin{aligned}
\gamma \simeq \frac{1}{N} \operatorname{tr}\left(\frac{1}{n} W D W^{*}\right)^{-1}=m_{\frac{1}{n} W D W^{*}}(0) & \simeq\left(0+\int \frac{t\left(u \circ g^{-1}\right)(t \gamma)}{1+c\left(u \circ g^{-1}\right)(t \gamma) m_{\frac{1}{n} W D W^{*}}(0)} v_{N}(d t)\right) \\
& =\left(\frac{1}{n} \sum_{i=1}^{n} \frac{\tau_{i}\left(u \circ g^{-1}\right)\left(\tau_{i} \gamma\right)}{1+c \tau_{i}\left(u \circ g^{-1}\right)\left(\tau_{i} \gamma\right) m_{\frac{1}{n} W D W^{*}}(0)}\right)^{-1}
\end{aligned}
$$

Since $\gamma \simeq m_{\frac{1}{n} W D W^{*}}(0)$, this defines $\gamma$ as a solution of a fixed-point equation:

$$
\gamma=\left(\frac{1}{n} \sum_{i=1}^{n} \frac{\tau_{i}\left(u \circ g^{-1}\right)\left(\tau_{i} \gamma\right)}{1+c \tau_{i}\left(u \circ g^{-1}\right)\left(\tau_{i} \gamma\right) \gamma}\right)^{-1} .
$$

## Main result

R. Couillet, F. Pascal, J. W. Silverstein, "The Random Matrix Regime of Maronna's M-estimator with elliptically distributed samples", (submitted to) Elsevier Journal of Multivariate Analysis.

Theorem (Asymptotic Equivalence)
Under the assumptions defined earlier, we have

$$
\left\|\hat{C}_{N}-\hat{S}_{N}\right\| \xrightarrow{\text { a.s. }} 0, \text { where } \hat{S}_{N} \triangleq \frac{1}{n} \sum_{i=1}^{n} v\left(\tau_{i} \gamma\right) x_{i} x_{i}^{*}
$$

$v(x)=\left(u \circ g^{-1}\right)(x), \psi(x)=x v(x), g(x)=x /(1-c \phi(x))$ and $\gamma>0$ unique solution of

$$
1=\frac{1}{n} \sum_{i=1}^{n} \frac{\psi\left(\tau_{i} \gamma\right)}{1+c \psi\left(\tau_{i} \gamma\right)}
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## - Remarks:

- Th. says: first order substitution of $\hat{C}_{N}$ by $\hat{S}_{N}$ allowed for large $N, n$.
- It turns out that $v \sim u$ and $\psi \sim \phi$ in general behavior.
- Corollaries:

$$
\begin{gathered}
\max _{1 \leqslant i \leqslant n}\left|\lambda_{i}\left(\hat{S}_{N}\right)-\lambda_{i}\left(\hat{C}_{N}\right)\right| \xrightarrow{\text { a.s. }} 0 \\
\frac{1}{N} \operatorname{tr}\left(\hat{C}_{N}-z I_{N}\right)^{-1}-\frac{1}{N} \operatorname{tr}\left(\hat{S}_{N}-z I_{N}\right)^{-1} \xrightarrow{\text { a.s. }} 0
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$\longrightarrow$ Important feature for detection and estimation.

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$\longrightarrow$ Important feature for detection and estimation.

- Proof: So far in the tutorial, we do not have a rigorous proof!


## Proof

- Fundamental idea: Showing that all $\frac{1}{\tau_{i}} \frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}$ converge to the same limit $\gamma$.


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- Technical trick: Denote

$$
e_{i} \triangleq \frac{v\left(\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}\right)}{v\left(\tau_{i} \gamma\right)}
$$

and relabel terms such that

$$
e_{1} \leqslant \ldots \leqslant e_{n}
$$

We shall prove that, for each $\ell>0$,

$$
e_{1}>1-\ell \text { i.o. and } e_{n}<1+\ell \text { i.o. }
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- Some basic inequalities: Denoting $d_{i} \triangleq \frac{1}{\tau_{i}} \frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i}=\frac{1}{N} w_{i}^{*} \hat{C}_{(i)}^{-1} w_{i}$, we have

$$
\begin{aligned}
e_{j} & =\frac{v\left(\tau_{j} \frac{1}{N} w_{j}^{*}\left(\frac{1}{n} \sum_{i \neq j} \tau_{i} v\left(\tau_{i} d_{i}\right) w_{i} w_{i}^{*}\right)^{-1} w_{j}\right)}{v\left(\tau_{j} \gamma\right)}=\frac{v\left(\tau_{j} \frac{1}{N} w_{j}^{*}\left(\frac{1}{n} \sum_{i \neq j} \tau_{i} v\left(\tau_{i} \gamma\right) e_{i} w_{i} w_{i}^{*}\right)^{-1} w_{j}\right)}{v\left(\tau_{j} \gamma\right)} \\
& \leqslant \frac{v\left(\tau_{j} \frac{1}{N} w_{j}^{*}\left(\frac{1}{n} \sum_{i \neq j} \tau_{i} v\left(\tau_{i} \gamma\right) e_{n} w_{i} w_{i}^{*}\right)^{-1} w_{j}\right)}{v\left(\tau_{j} \gamma\right)}=\frac{v\left(\frac{\tau_{j}}{e_{n}} \frac{1}{N} w_{j}^{*}\left(\frac{1}{n} \sum_{i \neq j} \tau_{i} v\left(\tau_{i} \gamma\right) w_{i} w_{i}^{*}\right)^{-1} w_{j}\right)}{v\left(\tau_{j} \gamma\right)}
\end{aligned}
$$

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- Specialization to $e_{n}$ :

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e_{n} \leqslant \frac{v\left(\frac{\tau_{n}}{e_{n}} \frac{1}{N} w_{n}^{*}\left(\frac{1}{n} \sum_{i \neq n} \tau_{i} v\left(\tau_{i} \gamma\right) w_{i} w_{i}^{*}\right)^{-1} w_{n}\right)}{v\left(\tau_{n} \gamma\right)}
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or equivalently, recalling $\psi(x)=x v(x)$,

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- By trace lemma, we should have

$$
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(by definition of $\gamma$ as in previous slides)...

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- DANGER: by relabeling, $w_{n}$ no longer independent of $w_{1}, \ldots, w_{n-1}$ !
$\Rightarrow$ Broken trace lemma!


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(by definition of $\gamma$ as in previous slides)...

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$\Rightarrow$ Broken trace lemma!
- Solution: uniform convergence result.

By (higher order) moment bounds, Markov inequality, and Borel Cantelli, for all large $n$ a.s.

$$
\max _{1 \leqslant j \leqslant n}\left|\frac{1}{N} w_{j}^{*}\left(\frac{1}{n} \sum_{i \neq j} \tau_{i} v\left(\tau_{i} \gamma\right) w_{i} w_{i}^{*}\right)^{-1} w_{j}-\gamma\right|<\varepsilon .
$$

## Proof

- Back to original problem: For all large $n$ a.s., we then have (using growth of $\psi$ )

$$
\frac{\gamma-\varepsilon}{\gamma} \leqslant \frac{\psi\left(\frac{\tau_{n}}{e_{n}}(\gamma+\varepsilon)\right)}{\psi\left(\tau_{n} \gamma\right)} .
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- Bounded support for $\tau_{i}$ : If $0<\tau_{-}<\tau_{i}<\tau_{+}<\infty$ for all $i, n$, then on a subsequence where $\tau_{n} \rightarrow \tau_{0}$,

$$
\underbrace{\frac{\gamma-\varepsilon}{\gamma}}_{\rightarrow 1 \text { as } \varepsilon \rightarrow 0} \leqslant \underbrace{\frac{\psi\left(\frac{\tau_{0}}{1+\ell}(\gamma+\varepsilon)\right)}{\psi\left(\tau_{0} \gamma\right)}}_{\rightarrow \frac{\psi\left(\frac{\tau_{0}}{1+\ell} \gamma\right)}{\psi\left(\tau_{0} \gamma\right)}<1 \text { as } \varepsilon \rightarrow 0}
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CONTRADICTION!

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- Unbounded support for $\tau_{i}$ : Importance of relative growth of $\tau_{n}$ versus convergence of $\psi$ to $\psi_{\infty}$. Proof consists in dividing $\left\{\tau_{i}\right\}$ in two groups: few large ones versus all others. Sufficient condition:

$$
\limsup _{t \rightarrow \infty} \frac{\limsup _{n} v_{n}((t, \infty))}{\phi(a t)-\phi(b t)}=0 .
$$

## Simulations



Figure: Histogram of the eigenvalues of $\frac{1}{n} \sum_{i=1}^{n} x_{i} x_{i}^{*}$ for $n=2500, N=500, C_{N}=\operatorname{diag}\left(l_{125}, 3 l_{125}, 10 l_{250}\right), \tau_{1}$ with $\Gamma(.5,2)$-distribution.

## Simulations



Figure: Histogram of the eigenvalues of $\hat{C}_{N}$ (left) and $\hat{S}_{N}$ (right) for $n=2500, N=500$, $C_{N}=\operatorname{diag}\left(I_{125}, 3 I_{125}, 10 I_{250}\right), \tau_{1}$ with $\Gamma(.5,2)$-distribution.

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Figure: Histogram of the eigenvalues of $\hat{C}_{N}$ (left) and $\hat{S}_{N}$ (right) for $n=2500, N=500$, $C_{N}=\operatorname{diag}\left(I_{125}, 3 I_{125}, 10 I_{250}\right), \tau_{1}$ with $\Gamma(.5,2)$-distribution.

- Remark/Corollary: Spectrum of $\hat{C}_{N}$ a.s. bounded uniformly on $n$.


## Hint on potential applications

- Spectrum boundedness: for impulsive noise scenarios,
- SCM spectrum grows unbounded
- robust scatter estimator spectrum remains bounded
$\Rightarrow$ Robust estimators improve spectrum separability (important for many statistical inference techniques seen previously)


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- spikes are swallowed by the bulk in SCM context
- we expect spikes to re-emerge in robust scatter context
$\Rightarrow$ We shall see that we get even better than this...


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- Application scenarios:
- Radar detection in impulsive noise (non-Gaussian noise, possibly clutter)
- Financial data analytics
- Any application where Gaussianity is too strong an assumption...


## Outline

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## System Setting

## - Signal model:

$$
\begin{aligned}
& y_{i}=\sum_{l=1}^{L} \sqrt{p_{l}} a_{l} s_{l i}+\sqrt{\tau_{i}} w_{i}=A_{i} \bar{w}_{i} \\
& A_{i} \triangleq\left[\begin{array}{llll}
\sqrt{p_{1}} a_{1} & \ldots & \sqrt{p_{L}} a_{L} & \sqrt{\tau_{i}} I_{N}
\end{array}\right], \quad \bar{w}_{i} \triangleq\left[s_{1 i}, \ldots, s_{L i}, w_{i}\right]^{\top} .
\end{aligned}
$$

with $y_{1}, \ldots, y_{n} \in \mathbb{C}^{N}$ satisfying:

1. $\tau_{1}, \ldots, \tau_{n}>0$ random such that $v_{n} \triangleq \frac{1}{n} \sum_{i=1}^{n} \delta_{\tau_{i}} \rightarrow v$ weakly and $\int t v(d t)=1$;
2. $w_{1}, \ldots, w_{n} \in \mathbb{C}^{N}$ random independent unitarily invariant $\sqrt{N}$-norm;
3. $L \in \mathbb{N}, p_{1} \geqslant \ldots \geqslant p_{L} \geqslant 0$ deterministic;
4. $a_{1}, \ldots, a_{L} \in \mathbb{C}^{N}$ deterministic or random with $A^{*} A \xrightarrow{\text { a.s. }} \operatorname{diag}\left(p_{1}, \ldots, p_{L}\right)$ as $N \rightarrow \infty$, with $A \triangleq\left[\sqrt{p_{1}} a_{1}, \ldots, \sqrt{p_{L}} a_{L}\right] \in \mathbb{C}^{N \times L}$.
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- Relation to previous model: If $L=0, y_{i}=\sqrt{\tau_{i}} w_{i}$.
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$\Rightarrow$ Elliptical model with covariance a low-rank ( $L$ ) perturbation of $I_{N}$.
$\Rightarrow$ We expect a spiked version of previous results.
- Application contexts:
- wireless communications: signals $s_{l i}$ from $L$ transmitters, $N$-antenna receiver; $a_{l}$ random i.i.d. channels $\left(a_{l}^{*} a_{l} \rightarrow \delta_{I-l \prime}\right.$, e.g. $\left.a_{l} \sim \mathcal{C N}\left(0, I_{N} / N\right)\right)$;
- array processing: $L$ sources emit signals $s_{l i}$ at steering angle $a_{l}=a\left(\theta_{l}\right)$. For ULA,

$$
[a(\theta)]_{j}=N^{-\frac{1}{2}} \exp (2 \pi \imath d j \sin (\theta))
$$

## Some intuition

- Signal detection/estimation in impulsive environments: Two scenarios
- heavy-tailed noise (elliptical, Gaussian mixtures, etc.)
- Gaussian noise with spurious impulsions


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- Problems expected with SCM: Respectively,
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- isolated eigenvalues due to spikes in time direction
$\Rightarrow$ False alarms induced by noise impulses!
- Our results: In a spiked model with noise impulsions,
- whatever noise impulsion type, spectrum of $\hat{C}_{N}$ remains bounded
- isolated largest eigenvalues may appear, two classes:
- isolated eigenvalues due to noise impulses CANNOT exceed a threshold!
- all isolated eigenvalues beyond this threshold are due to signal
$\Rightarrow$ Detection criterion: everything above threshold is signal.


## Theoretical results

Theorem (Extension to spiked robust model)
Under the same assumptions as in previous section,

$$
\left\|\hat{C}_{N}-\hat{S}_{N}\right\| \xrightarrow{\text { a.s. }} 0
$$

where

$$
\hat{S}_{N} \triangleq \frac{1}{n} \sum_{i=1}^{n} v\left(\tau_{i} \gamma\right) A_{i} \bar{w}_{i} \bar{w}_{i}^{*} A_{i}^{*}
$$

with $\gamma$ the unique solution to

$$
1=\int \frac{\psi(t \gamma)}{1+c \psi(t \gamma)} v(d t)
$$

and we recall

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\end{array}\right]^{\top} .
\end{aligned}
$$

- Remark: For $L=0, A_{i}=\left[0, \ldots, 0, I_{N}\right]$.
$\Rightarrow$ Recover previous result $A_{i} \bar{w}_{i}$ becomes $w_{i}$.


## Localization of eigenvalues

## Theorem (Eigenvalue localization)

Denote

- $u_{k}$ eigenvector of $k$-th largest eigenvalue of $A A^{*}=\sum_{i=1}^{L} p_{i} a_{i} a_{i}^{*}$
- $\hat{u}_{k}$ eigenvector of $k$-th largest eigenvalue of $\hat{C}_{N}$

Also define $\delta(x)$ unique positive solution to

$$
\delta(x)=c\left(-x+\int \frac{t v_{c}(t \gamma)}{1+\delta(x) t v_{c}(t \gamma)} v(d t)\right)^{-1}
$$

Further denote

$$
p_{-} \triangleq \lim _{x \downarrow S^{+}}-c\left(\int \frac{\delta(x) v_{c}(t \gamma)}{1+\delta(x) t v_{c}(t \gamma)} v(d t)\right)^{-1}, \quad S^{+} \triangleq \frac{\phi_{\infty}(1+\sqrt{c})^{2}}{\gamma\left(1-c \phi_{\infty}\right)}
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$$

Then, if $p_{j}>p_{-}, \hat{\lambda}_{j} \xrightarrow{\text { a.s. }} \Lambda_{j}>S^{+}$, otherwise $\lim \sup _{n} \hat{\lambda}_{j} \leqslant S^{+}$a.s., with $\Lambda_{j}$ unique positive solution to

$$
-c\left(\delta\left(\Lambda_{j}\right) \int \frac{v_{c}(\tau \gamma)}{1+\delta\left(\Lambda_{j}\right) \tau v_{c}(\tau \gamma)} v(d \tau)\right)^{-1}=p_{j}
$$

## Simulation



Figure: Histogram of the eigenvalues of $\frac{1}{n} \sum_{i} y_{i} y_{i}^{*}$ against the limiting spectral measure, $L=2, p_{1}=p_{2}=1$, $N=200, n=1000$, Sudent-t impulsions.

## Simulation



Figure: Histogram of the eigenvalues of $\hat{C}_{N}$ against the limiting spectral measure, for $u(x)=(1+\alpha) /(\alpha+x)$ with $\alpha=0.2, L=2, p_{1}=p_{2}=1, N=200, n=1000$, Student-t impulsions.

## Comments

- SCM vs robust: Spikes invisible in SCM in impulsive noise, reborn in robust estimate of scatter.


## Comments

- SCM vs robust: Spikes invisible in SCM in impulsive noise, reborn in robust estimate of scatter.
- Largest eigenvalues:
- $\lambda_{i}\left(\hat{C}_{N}\right)>S^{+} \Rightarrow$ Presence of a source!
- $\lambda_{i}\left(\hat{C}_{N}\right) \in\left(\sup (\right.$ Support $\left.), S^{+}\right) \Rightarrow$ May be due to a source or to a noise impulse.
- $\lambda_{i}\left(\hat{C}_{N}\right)<\sup ($ Support $) \Rightarrow$ As usual, nothing can be said.
$\Rightarrow$ Induces a natural source detection algorithm.


## Eigenvalue and eigenvector projection estimates

- Two scenarios:
- known $v=\lim _{n} \frac{1}{n} \sum_{i=1}^{n} \boldsymbol{\delta}_{\tau_{i}}$
- unknown $v$


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## - Two scenarios:

- known $v=\lim _{n} \frac{1}{n} \sum_{i=1}^{n} \delta_{\tau_{i}}$
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## Theorem (Estimation under known $v$ )

1. Power estimation. For each $p_{j}>p_{-}$,

$$
-c\left(\delta\left(\hat{\lambda}_{j}\right) \int \frac{v_{c}(\tau \gamma)}{1+\delta\left(\hat{\lambda}_{j}\right) \tau v_{c}(\tau \gamma)} v(d \tau)\right)^{-1} \xrightarrow{\text { a.s. }} p_{j}
$$

2. Bilinear form estimation. For each $a, b \in \mathbb{C}^{N}$ with $\|a\|=\|b\|=1$, and $p_{j}>p_{-}$

$$
\sum_{k, p_{k}=p_{j}} a^{*} u_{k} u_{k}^{*} b-\sum_{k, p_{k}=p_{j}} w_{k} a^{*} \hat{u}_{k} \hat{u}_{k}^{*} b \xrightarrow{\text { a.s. }} 0
$$

where

$$
w_{k}=\frac{\int \frac{v_{c}(t \gamma)}{\left(1+\delta\left(\hat{\lambda}_{k}\right) t v_{c}(t \gamma)\right)^{2}} v(d t)}{\int \frac{v_{c}(t \gamma)}{1+\delta\left(\hat{\lambda}_{k}\right) t v_{c}(t \gamma)} v(d t)\left(1-\frac{1}{c} \int \frac{\delta\left(\hat{\lambda}_{k}\right)^{2} t^{2} v_{c}(t \gamma)^{2}}{\left(1+\delta\left(\hat{\lambda}_{k}\right) t v_{c}(t \gamma)\right)^{2}} v(d t)\right)} .
$$

## Eigenvalue and eigenvector projection estimates

Theorem (Estimation under unknown v)

1. Purely empirical power estimation. For each $p_{j}>p_{-}$,

$$
-\left(\hat{\delta}\left(\hat{\lambda}_{j}\right) \frac{1}{N} \sum_{i=1}^{n} \frac{v\left(\hat{\tau}_{i} \hat{\gamma}_{n}\right)}{1+\hat{\delta}\left(\hat{\lambda}_{j}\right) \hat{\tau}_{i} v\left(\hat{\tau}_{i} \hat{\gamma}_{n}\right)}\right)^{-1} \xrightarrow{\text { a.s. }} p_{j}
$$

2. Purely empirical bilinear form estimation. For each $a, b \in \mathbb{C}^{N}$ with $\|a\|=\|b\|=1$, and each $p_{j}>p_{-}$,

$$
\sum_{k, p_{k}=p_{j}} a^{*} u_{k} u_{k}^{*} b-\sum_{k, p_{k}=p_{j}} \hat{w}_{k} a^{*} \hat{u}_{k} \hat{u}_{k}^{*} b \xrightarrow{\text { a.s. }} 0
$$

where

$$
\begin{aligned}
& \hat{w}_{k}=\frac{\frac{1}{n} \sum_{i=1}^{n} \frac{v\left(\hat{\tau}_{i} \hat{\gamma}\right)}{\left(1+\hat{\delta}\left(\hat{\lambda}_{k}\right) \hat{\tau}_{i} v\left(\hat{\tau}_{i} \hat{\gamma}\right)\right)^{2}}}{\frac{1}{n} \sum_{i=1}^{n} \frac{v\left(\hat{\tau}_{i} \hat{\gamma}\right)}{1+\hat{\delta}\left(\hat{\lambda}_{k}\right) \hat{\tau}_{i} v\left(\hat{\tau}_{i} \hat{\gamma}\right)}\left(1-\frac{1}{N} \sum_{i=1}^{n} \frac{\hat{\delta}\left(\hat{\lambda}_{k}\right)^{2} \hat{\tau}_{i}^{2} v\left(\hat{\tau}_{i} \hat{\gamma}\right)^{2}}{\left(1+\hat{\delta}\left(\hat{\lambda}_{k}\right) \hat{\tau}_{i} v\left(\hat{\tau}_{i} \hat{\gamma}\right)\right)^{2}}\right)} \\
& \hat{\gamma} \triangleq \frac{1}{n} \sum_{i=1}^{n} \frac{1}{N} y_{i}^{*} \hat{C}_{(i)}^{-1} y_{i}, \quad \hat{\tau}_{i} \triangleq \frac{1}{\hat{\gamma}} \frac{1}{N} y_{i}^{*} \hat{C}_{(i)}^{-1} y_{i}, \quad \hat{\delta}(x) \text { as } \delta(x) \text { but for }\left(\tau_{i}, \gamma\right) \rightarrow\left(\hat{\tau}_{i}, \hat{\gamma}\right) .
\end{aligned}
$$

## Application to G-MUSIC

- Assume the model $a_{i}=a\left(\theta_{i}\right)$ with

$$
a(\theta)=N^{-\frac{1}{2}}[\exp (2 \pi \imath d j \sin (\theta))]_{j=0}^{N-1} .
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$$

Corollary (Robust G-MUSIC)
Define $\hat{\eta}_{R G}(\theta)$ and $\hat{\eta}_{R G}^{\mathrm{emp}}(\theta)$ as

$$
\begin{gathered}
\hat{\eta}_{\mathrm{RG}}(\theta)=1-\sum_{k=1}^{\left|\left\{j, p_{j}>p_{-}\right\}\right|} w_{k} a(\theta)^{*} \hat{u}_{k} \hat{u}_{k} a(\theta) \\
\hat{\eta}_{\mathrm{RG}}^{\mathrm{emp}}(\theta)=1-\sum_{k=1}^{\left|\left\{j, p_{j}>p-\right\}\right|} \hat{w}_{k} a(\theta)^{*} \hat{u}_{k} \hat{u}_{k} a(\theta) .
\end{gathered}
$$

Then, for each $p_{j}>p_{-}$,

$$
\begin{aligned}
\hat{\theta}_{j} & \xrightarrow{\text { a.s. }} \theta_{j} \\
\hat{\theta}_{j}^{\mathrm{emp}} & \xrightarrow{\text { a.s. }} \theta_{j}
\end{aligned}
$$

where

$$
\begin{aligned}
\hat{\theta}_{j} \triangleq \operatorname{argmin}_{\theta \in \mathcal{R}_{j}^{k}}\left\{\hat{\eta}_{\mathrm{RG}}(\theta)\right\} \\
\hat{\theta}_{j}^{\mathrm{emp}} \triangleq \operatorname{argmin}_{\theta \in \mathcal{R}_{j}^{k}}\left\{\hat{\eta}_{\mathrm{RG}}^{\mathrm{emp}}(\theta)\right\} .
\end{aligned}
$$

## Simulations: Single-shot in elliptical noise



Figure: Random realization of the localization functions for the various MUSIC estimators, with $N=20$, $n=100$, two sources at $10^{\circ}$ and $12^{\circ}$, Student-t impulsions with parameter $\beta=100, u(x)=(1+\alpha) /(\alpha+x)$ with $\alpha=0.2$. Powers $p_{1}=p_{2}=10^{0.5}=5 \mathrm{~dB}$.

## Simulations: Elliptical noise



Figure: Means square error performance of the estimation of $\theta_{1}=10^{\circ}$, with $N=20, n=100$, two sources at $10^{\circ}$ and $12^{\circ}$, Student-t impulsions with parameter $\beta=10, u(x)=(1+\alpha) /(\alpha+x)$ with $\alpha=0.2, p_{1}=p_{2}$.

## Simulations: Spurious impulses



Figure: Means square error performance of the estimation of $\theta_{1}=10^{\circ}$, with $N=20, n=100$, two sources at $10^{\circ}$ and $12^{\circ}$, sample outlier scenario $\tau_{i}=1, i<n, \tau_{n}=100, u(x)=(1+\alpha) /(\alpha+x)$ with $\alpha=0.2, p_{1}=p_{2}$.

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## Context

Ledoit and Wolf, 2004. A well-conditioned estimator for large-dimensional covariance matrices. Pascal, Chitour, Quek, 2013. Generalized robust shrinkage estimator - Application to STAP data. Chen, Wiesel, Hero, 2011. Robust shrinkage estimation of high-dimensional covariance matrices.

- Shrinkage covariance estimation: For $N>n$ or $N \simeq n$, shrinkage estimator

$$
(1-\rho) \frac{1}{n} \sum_{i=1}^{n} x_{i} x_{i}^{*}+\rho I_{N}, \text { for some } \rho \in[0,1] .
$$

- allows for invertibility, better conditioning
- $\rho$ may be chosen to minimize an expected error metric


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- Limitation of Maronna's estimator:
- Maronna and Tyler estimators limited to $N<n$, otherwise do not exist
- introducing shrinkage in robust estimator cannot do much harm anyhow...
- Introducing the robust-shrinkage estimator: The literature proposes two such estimators

$$
\begin{align*}
& \hat{C}_{N}(\rho)=(1-\rho) \frac{1}{n} \sum_{i=1}^{n} \frac{x_{i} x_{i}^{*}}{\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1}(\rho) x_{i}}+\rho I_{N}, \rho \in\left(\max \left\{0, \frac{N-n}{N}\right\}, 1\right] \quad \text { (Pasca }  \tag{Pascal}\\
& \check{C}_{N}(\rho)=\frac{\check{B}_{N}(\rho)}{\frac{1}{N} \operatorname{tr} \check{B}_{N}(\rho)}, \check{B}_{N}(\rho)=(1-\rho) \frac{1}{n} \sum_{i=1}^{n} \frac{x_{i} x_{i}^{*}}{\frac{1}{N} x_{i}^{*} \hat{C}_{N}^{-1}(\rho) x_{i}}+\rho I_{N}, \rho \in(0,1] \tag{Chen}
\end{align*}
$$

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Having asked to authors of both papers, their estimator was much better than the other, but the arguments we received were quite vague...

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Having asked to authors of both papers, their estimator was much better than the other, but the arguments we received were quite vague...

- Our result: In the random matrix regime, both estimators tend to be one and the same!


## Main theoretical result

- Which estimator is better?

Having asked to authors of both papers, their estimator was much better than the other, but the arguments we received were quite vague...

- Our result: In the random matrix regime, both estimators tend to be one and the same!
- Assumptions: As before, "elliptical-like" model

$$
x_{i}=\tau_{i} C_{N}^{\frac{1}{2}} w_{i}
$$

$\longrightarrow$ This time, $C_{N}$ cannot be taken $I_{N}$ (due to $+\rho I_{N}$ )!
$\longrightarrow$ Maronna-based shrinkage is possible but more involved...

## Pascal's estimator

## Theorem (Pascal's estimator)

For $\varepsilon \in\left(0, \min \left\{1, c^{-1}\right\}\right)$, define $\hat{\mathcal{R}}_{\varepsilon}=\left[\varepsilon+\max \left\{0,1-c^{-1}\right\}, 1\right]$. Then, as $N, n \rightarrow \infty$, $N / n \rightarrow c \in(0, \infty)$,

$$
\sup _{\rho \in \hat{\mathfrak{R}}_{\varepsilon}}\left\|\hat{C}_{N}(\rho)-\hat{S}_{N}(\rho)\right\| \xrightarrow{\text { a.s. }} 0
$$

where

$$
\begin{aligned}
& \hat{C}_{N}(\rho)=(1-\rho) \frac{1}{n} \sum_{i=1}^{n} \frac{x_{i} x_{i}^{*}}{\frac{1}{N} x_{i}^{*} \hat{C}_{N}(\rho)^{-1} x_{i}}+\rho I_{N} \\
& \hat{S}_{N}(\rho)=\frac{1}{\hat{\gamma}(\rho)} \frac{1-\rho}{1-(1-\rho) c} \frac{1}{n} \sum_{i=1}^{n} C_{N}^{\frac{1}{2}} w_{i} w_{i}^{*} C_{N}^{\frac{1}{2}}+\rho I_{N}
\end{aligned}
$$

and $\hat{\gamma}(\rho)$ is the unique positive solution to the equation in $\hat{\gamma}$

$$
1=\frac{1}{N} \sum_{i=1}^{N} \frac{\lambda_{i}\left(C_{N}\right)}{\hat{\gamma} \rho+(1-\rho) \lambda_{i}\left(C_{N}\right)} .
$$

Moreover, $\rho \mapsto \hat{\gamma}(\rho)$ is continuous on $(0,1]$.

## Chen's estimator

Theorem (Chen's estimator)
For $\varepsilon \in(0,1)$, define $\check{\mathcal{R}}_{\varepsilon}=[\varepsilon, 1]$. Then, as $N, n \rightarrow \infty, N / n \rightarrow c \in(0, \infty)$,

$$
\sup _{\rho \in \check{\mathfrak{R}}_{\varepsilon}}\left\|\check{C}_{N}(\rho)-\check{S}_{N}(\rho)\right\| \xrightarrow{\text { a.s. }} 0
$$

where

$$
\begin{aligned}
& \check{C}_{N}(\rho)=\frac{\check{B}_{N}(\rho)}{\frac{1}{N} \operatorname{tr} \check{B}_{N}(\rho)}, \check{B}_{N}(\rho)=(1-\rho) \frac{1}{n} \sum_{i=1}^{n} \frac{x_{i} x_{i}^{*}}{\frac{1}{N} x_{i}^{*} \check{C}_{N}(\rho)^{-1} x_{i}}+\rho I_{N} \\
& \check{S}_{N}(\rho)=\frac{1-\rho}{1-\rho+T_{\rho}} \frac{1}{n} \sum_{i=1}^{n} C_{N}^{\frac{1}{2}} w_{i} w_{i}^{*} C_{N}^{\frac{1}{2}}+\frac{T_{\rho}}{1-\rho+T_{\rho}} I_{N}
\end{aligned}
$$

in which $T_{\rho}=\rho \check{\gamma}(\rho) F(\check{\gamma}(\rho) ; \rho)$ with, for all $x>0$,

$$
F(x ; \rho)=\frac{1}{2}(\rho-c(1-\rho))+\sqrt{\frac{1}{4}(\rho-c(1-\rho))^{2}+(1-\rho) \frac{1}{x}}
$$

and $\check{\gamma}(\rho)$ is the unique positive solution to the equation in $\check{\gamma}$

$$
1=\frac{1}{N} \sum_{i=1}^{N} \frac{\lambda_{i}\left(C_{N}\right)}{\check{\gamma} \rho+\frac{1-\rho}{(1-\rho) c+F(\check{\gamma} ; \rho)} \lambda_{i}\left(C_{N}\right)} .
$$

Moreover, $\rho \mapsto \check{\gamma}(\rho)$ is continuous on $(0,1]$.

## Asymptotic Model Equivalence

Theorem (Model Equivalence)
For each $\rho \in(0,1]$, there exist unique $\hat{\rho} \in\left(\max \left\{0,1-c^{-1}\right\}, 1\right]$ and $\check{\rho} \in(0,1]$ such that

$$
\frac{\hat{S}_{N}(\hat{\rho})}{\frac{1}{\hat{\gamma}(\hat{\rho})} \frac{1-\hat{\rho}}{1-(1-\hat{\rho}) c}+\hat{\rho}}=\check{S}_{N}(\check{\rho})=(1-\rho) \frac{1}{n} \sum_{i=1}^{n} C_{N}^{\frac{1}{2}} w_{i} w_{i}^{*} C_{N}^{\frac{1}{2}}+\rho I_{N} .
$$

Besides, $(0,1] \rightarrow\left(\max \left\{0,1-c^{-1}\right\}, 1\right], \rho \mapsto \hat{\rho}$ and $(0,1] \rightarrow(0,1], \rho \mapsto \check{\rho}$ are increasing and onto.

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- Up to normalization, both estimators behave the same!
- Both estimators behave the same as an impulsion-free Ledoit-Wolf estimator
- About uniformity: Uniformity over $\rho$ in the theorems is essential to find optimal values of $\rho$.


## Optimal Shrinkage parameter

- Chen sought for a Frobenius norm minimizing $\rho$ but got stuck by implicit nature of $\check{C}_{N}(\rho)$


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- Our results allow for a simplification of the problem for large $N, n$ !
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## Optimal Shrinkage parameter

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- Model equivalence says only one problem needs be solved.


## Theorem (Optimal Shrinkage)

For each $\rho \in(0,1]$, define

$$
\hat{D}_{N}(\rho)=\frac{1}{N} \operatorname{tr}\left(\left(\frac{\hat{C}_{N}(\rho)}{\frac{1}{N} \operatorname{tr} \hat{C}_{N}(\rho)}-C_{N}\right)^{2}\right), \check{D}_{N}(\rho)=\frac{1}{N} \operatorname{tr}\left(\left(\check{C}_{N}(\rho)-C_{N}\right)^{2}\right)
$$

Denote $D^{\star}=c \frac{M_{2}-1}{c+M_{2}-1}, \rho^{\star}=\frac{c}{c+M_{2}-1}, M_{2}=\lim _{N} \frac{1}{N} \sum_{i=1}^{N} \lambda_{i}^{2}\left(C_{N}\right)$ and $\hat{\rho}^{\star}, \check{\rho}^{\star}$ unique solutions to

$$
\frac{\hat{\rho}^{\star}}{\frac{1}{\hat{\gamma}\left(\hat{\rho}^{\star}\right)} \frac{1-\hat{\rho}^{\star}}{1-\left(1-\hat{\rho}^{\star}\right) c}+\hat{\rho}^{\star}}=\frac{T_{\grave{\rho}^{\star}}}{1-\check{\rho}^{\star}+T_{\check{\rho}^{\star}}}=\rho^{\star} .
$$

Then, letting $\varepsilon$ small enough,

$$
\begin{gathered}
\inf _{\rho \in \hat{\mathscr{R}}_{\varepsilon}} \hat{D}_{N}(\rho) \xrightarrow{\text { a.s. }} D^{\star}, \quad \inf _{\rho \in \check{\mathscr{R}}_{\varepsilon}} \check{D}_{N}(\rho) \xrightarrow{\text { a.s. }} D^{\star} \\
\hat{D}_{N}\left(\hat{\rho}^{\star}\right) \xrightarrow{\text { a.s. }} D^{\star}, \quad \check{D}_{N}\left(\check{\rho}^{\star}\right) \xrightarrow{\text { a.s. }} D^{\star} .
\end{gathered}
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## Estimating $\hat{\rho}^{\star}$ and ${ }^{\star}{ }^{\star}$

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- Proposition below provides one example.


## Estimating $\hat{\rho}^{\star}$ and ${ }^{\circ}{ }^{\star}$

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- Careful control of the proofs provide many ways to estimate these.
- Proposition below provides one example.


## Optimal Shrinkage Estimate

Let $\hat{\rho}_{N} \in\left(\max \left\{0,1-c^{-1}\right\}, 1\right]$ and $\check{\rho}_{N} \in(0,1]$ be solutions (not necessarily unique) to

$$
\begin{array}{r}
\frac{\hat{\rho}_{N}}{\frac{1}{N} \operatorname{tr} \hat{C}_{N}\left(\hat{\rho}_{N}\right)}
\end{array}=\frac{c_{N}}{\frac{1}{N} \operatorname{tr}\left[\left(\frac{1}{n} \sum_{i=1}^{n} \frac{x_{i} x_{i}^{*}}{\frac{1}{N}\left\|x_{i}\right\|^{2}}\right)^{2}\right]-1}
$$

defined arbitrarily when no such solutions exist. Then

$$
\begin{gathered}
\hat{\rho}_{N} \xrightarrow{\text { a.s. }} \hat{\rho}^{\star}, \check{\rho}_{N} \xrightarrow{\text { a.s. }} \check{\rho}^{\star} \\
\hat{D}_{N}\left(\hat{\rho}_{N}\right) \xrightarrow{\text { a.s. }} D^{\star}, \check{D}_{N}\left(\check{\rho}_{N}\right) \xrightarrow{\text { a.s. }} D^{\star} .
\end{gathered}
$$

## Simulations



Figure: Performance of optimal shrinkage averaged over 10000 Monte Carlo simulations, for $N=32$, various values of $n,\left[C_{N}\right]_{i j}=r^{|i-j|}$ with $r=0.7$; $\check{\rho}_{N}$ as above; $\check{\rho}_{O}$ the clairvoyant estimator proposed in (Chen'11).

## Simulations



Figure: Shrinkage parameter $\rho$ averaged over 10000 Monte Carlo simulations, for $N=32$, various values of $n$, $\left[C_{N}\right]_{i j}=r^{|i-j|}$ with $r=0.7 ; \hat{\rho}_{N}$ and $\check{\rho}_{N}$ as above; $\check{\rho}_{O}$ the clairvoyant estimator proposed in (Chen'11); $\hat{\rho}^{\circ}=\operatorname{argmin}_{\left\{\rho \in\left(\max \left\{0,1-c_{N}^{-1}\right\}, 1\right]\right\}}\left\{\hat{D}_{N}(\rho)\right\}$ and $\check{\rho}^{\circ}=\operatorname{argmin}_{\{\rho \in(0,1]\}}\left\{\check{D}_{N}(\rho)\right\}$.

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## Context

- Hypothesis testing problem: Two sets of data
- Initial pure-noise data: $x_{1}, \ldots, x_{n}, x_{i}=\sqrt{\tau_{i}} C_{N}^{\frac{1}{2}} w_{i}$ as before.
- New incoming data $y$ given by:

$$
y= \begin{cases}x & , \mathcal{H}_{0} \\ \alpha p+x & , \mathcal{H}_{1}\end{cases}
$$

with $x=\sqrt{\tau} C_{N}^{\frac{1}{2}} w, p \in \mathbb{C}^{N}$ deterministic known, $\alpha$ unknown.

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- GLRT detection test:

$$
T_{N}(\rho) \underset{\mathcal{H}_{0}}{\stackrel{\mathcal{H}_{1}}{\lessgtr}} \Gamma
$$

for some detection threshold $\Gamma$ where

$$
T_{N}(\rho) \triangleq \frac{\left|y^{*} \hat{C}_{N}^{-1}(\rho) p\right|}{\sqrt{y^{*} \hat{C}_{N}^{-1}(\rho) y} \sqrt{p^{*} \hat{C}_{N}^{-1}(\rho) p}}
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and $\hat{C}_{N}(\rho)$ defined in previous section.

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$$

and $\hat{C}_{N}(\rho)$ defined in previous section.
$\longrightarrow$ In fact, originally found to be $\hat{C}_{N}(0)$ but

- only valid for $N<n$
- introducing $\rho$ may bring improved for arbitrary $N / n$ ratios.


## Objectives and main results

- Initial observations:
- As $N, n \rightarrow \infty, N / n \rightarrow c>0$, under $\mathcal{H}_{0}$,

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- Objectives:
- for each $\rho$, develop central limit theorem to evaluate

$$
\lim _{\substack{N, n \rightarrow \infty \\ N / n \rightarrow c}} P\left(\sqrt{N} T_{N}(\rho)>\gamma\right)
$$

- determine limiting minimizing $\rho$
- empirically estimate minimizing $\rho$


## What do we need?

CLT over $\hat{C}_{N}$ statistics

- We know that $\left\|\hat{C}_{N}(\rho)-\hat{S}_{N}(\rho)\right\| \xrightarrow{\text { a.s. }} 0$
$\rightarrow$ Key result so far!
- What about $\left\|\sqrt{N}\left(\hat{C}_{N}(\rho)-\hat{S}_{N}(\rho)\right)\right\|$ ?


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- This requires much more delicate treatment, not discussed in this tutorial.


## Main results

Theorem (Fluctuation of bilinear forms)
Let $a, b \in \mathbb{C}^{N}$ with $\|a\|=\|b\|=1$. Then, as $N, n \rightarrow \infty$ with $N / n \rightarrow c>0$, for any $\varepsilon>0$ and every $k \in \mathbb{Z}$,

$$
\sup _{\rho \in \mathcal{R}_{k}} N^{1-\varepsilon}\left|a^{*} \hat{C}_{N}^{k}(\rho) b-a^{*} \hat{S}_{N}^{k}(\rho) b\right| \xrightarrow{\text { a.s. }} 0
$$

where $\mathcal{R}_{\kappa}=[\kappa+\max \{0,1-1 / c\}, 1]$.

## False alarm performance

Theorem (Asymptotic detector performance)
As $N, n \rightarrow \infty$ with $N / n \rightarrow c \in(0, \infty)$,

$$
\sup _{\rho \in \mathcal{R}_{\kappa}}\left|P\left(T_{N}(\rho)>\frac{\gamma}{\sqrt{N}}\right)-\exp \left(-\frac{\gamma^{2}}{2 \sigma_{N}^{2}(\hat{\rho})}\right)\right| \rightarrow 0
$$

where $\rho \mapsto \hat{\rho}$ is the aforementioned mapping and

$$
\sigma_{N}^{2}(\hat{\rho}) \triangleq \frac{1}{2} \frac{p^{*} C_{N} Q_{N}^{2}(\hat{\rho}) p}{p^{*} Q_{N}(\hat{\rho}) p \cdot \frac{1}{N} \operatorname{tr} C_{N} Q_{N}(\hat{\rho}) \cdot\left(1-c(1-\rho)^{2} m(-\hat{\rho})^{2} \frac{1}{N} \operatorname{tr} C_{N}^{2} Q_{N}^{2}(\hat{\rho})\right)}
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with $Q_{N}(\hat{\rho}) \triangleq\left(I_{N}+(1-\hat{\rho}) m(-\hat{\rho}) C_{N}\right)^{-1}$.

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$$

with $Q_{N}(\hat{\rho}) \triangleq\left(I_{N}+(1-\hat{\rho}) m(-\hat{\rho}) C_{N}\right)^{-1}$.

- Limiting Rayleigh distribution $\Rightarrow$ Weak convergence to Rayleigh variable $R_{N}(\hat{\rho})$
- Remark: $\sigma_{N}$ and $\hat{\rho}$ not a function of $\gamma$ $\Rightarrow$ There exists a uniformly optimal $\rho$ !


## Simulation




Figure: Histogram distribution function of the $\sqrt{N} T_{N}(\rho)$ versus $R_{N}(\hat{\rho}), N=20, p=N^{-\frac{1}{2}}[1, \ldots, 1]^{\top}, C_{N}$ Toeplitz from AR of order 0.7, $c_{N}=1 / 2, \rho=0.2$.

## Simulation




Figure: Histogram distribution function of the $\sqrt{N} T_{N}(\rho)$ versus $R_{N}(\hat{\rho}), N=100, p=N^{-\frac{1}{2}}[1, \ldots, 1]^{\top}, C_{N}$ Toeplitz from AR of order $0.7, c_{N}=1 / 2, \rho=0.2$.

## Empirical estimation of optimal $\rho$

- Optimal $\rho$ can be found by line search... but $C_{N}$ unknown!
- We shall successively:
- empirical estimate $\sigma_{N}(\hat{\rho})$
- minimize the estimate
- prove by uniformity asymptotic optimality of estimate


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- minimize the estimate
- prove by uniformity asymptotic optimality of estimate


## Theorem (Empirical performance estimation)

For $\rho \in\left(\max \left\{0,1-c_{N}^{-1}\right\}, 1\right)$, let

$$
\hat{\sigma}_{N}^{2}(\hat{\rho}) \triangleq \frac{1}{2} \frac{1-\hat{\rho} \cdot \frac{p^{*} \hat{C}_{N}^{-2}(\rho) p}{p^{*} \hat{C}_{N}^{-1}(\rho) p} \cdot \frac{1}{N} \operatorname{tr} \hat{C}_{N}(\rho)}{\left(1-c+c \hat{\rho} \frac{1}{N} \operatorname{tr} \hat{C}_{N}^{-1}(\rho) \cdot \frac{1}{N} \operatorname{tr} \hat{C}_{N}(\rho)\right)\left(1-\hat{\rho} \frac{1}{N} \operatorname{tr} \hat{C}_{N}^{-1}(\rho) \cdot \frac{1}{N} \operatorname{tr} \hat{C}_{N}(\rho)\right)} .
$$

Also let $\hat{\sigma}_{N}^{2}(1) \triangleq \lim _{\hat{\rho} \uparrow 1} \hat{\sigma}_{N}^{2}(\hat{\rho})$. Then

$$
\sup _{\rho \in \mathcal{R}_{\kappa}}\left|\sigma_{N}^{2}(\hat{\rho})-\hat{\sigma}_{N}^{2}(\hat{\rho})\right| \xrightarrow{\text { a.s. }} 0 .
$$

## Final result

Theorem (Optimality of empirical estimator)
Define

$$
\hat{\rho}_{N}^{*}=\operatorname{argmin}_{\left\{\rho \in \mathcal{R}_{k}^{\prime}\right\}}\left\{\hat{\sigma}_{N}^{2}(\hat{\rho})\right\} .
$$

Then, for every $\gamma>0$,

$$
P\left(\sqrt{N} T_{N}\left(\hat{\rho}_{N}^{*}\right)>\gamma\right)-\inf _{\rho \in \mathcal{R}_{k}}\left\{P\left(\sqrt{N} T_{N}(\rho)>\gamma\right)\right\} \rightarrow 0 .
$$

## Simulations



Figure: False alarm rate $P\left(\sqrt{N} T_{N}(\rho)>\gamma\right), N=20, p=N^{-\frac{1}{2}}[1, \ldots, 1]^{\top}, C_{N}$ Toeplitz from AR of order 0.7, $c_{N}=1 / 2$.

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## Simulations



Figure: False alarm rate $P\left(T_{N}(\rho)>\Gamma\right)$ for $N=20$ and $N=100, p=N^{-\frac{1}{2}}[1, \ldots, 1]^{\top},\left[C_{N}\right]_{i j}=0.7^{|i-j|}$, $c_{N}=1 / 2$.

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## Future Directions

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4.1 Kernel matrices and kernel methods
```

4.2 Neural networks

## Motivation: Spectral Clustering

N. El Karoui. The spectrum of kernel random matrices. The Annals of Statistics, 38(1):150, 2010.

- Objective: Clustering data $x_{1}, \ldots, x_{n} \in \mathbb{C}^{N}$ in $k$ similarity classes
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for some $\alpha, \beta$ depending on $f$ and its derivatives.
$\Rightarrow$ Basically, $W$ gets equivalent to a rank-one matrix.

## Motivation: Spectral Clustering

- Clustering $x_{1}, \ldots, x_{n}$ in $k$ often written as:
(RatioCut) $\min _{\substack{S_{1}, \ldots, \mathcal{S}_{k} \\ S_{1} \cup \ldots \cup S_{k}=S \\ \forall i \neq j, S_{i} \cap S_{j}=\emptyset}} \sum_{i=1}^{k} \sum_{j \in \mathcal{S}_{i}, \bar{j} \in \mathcal{S}_{i}^{c}} \frac{f\left(x_{j}, x_{\bar{j}}\right)}{\left|\mathcal{S}_{i}\right|}$.
$\longrightarrow$ But difficult to solve, NP hard!


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where $\mathcal{M}=\left\{M=\left[m_{i j}\right]_{1 \leqslant i \leqslant n, 1 \leqslant j \leqslant k}, m_{i j}=\left|\mathcal{S}_{j}\right|^{-\frac{1}{2}} \mathcal{X}_{x_{i} \in \mathcal{S}_{j}}\right\}$ and

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L=\left[L_{i j}\right]_{1 \leqslant i, j \leqslant n}=[-W+\operatorname{diag}(W \cdot 1)]_{1 \leqslant i, j \leqslant n}=\left[-f\left(x_{i}, x_{j}\right)+\boldsymbol{\delta}_{i, j} \sum_{l=1}^{n} f\left(x_{i}, x_{l}\right)\right]_{1 \leqslant i, j \leqslant n} .
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- Relaxing $M$ to unitary leads to a simple eigenvalue/eigenvector problem: $\Rightarrow$ Spectral clustering.


## Objectives

- Generalization to $k$ distributions for $x_{1}, \ldots, x_{n}$ should lead to asymptotically rank- $k W$ matrices.
- If established, specific choices of known "good" kernel better understood.
- Eventually, find optimal choices for kernels.


## Outline

```
Part 1: Fundamentals of Random Matrix Theory
    1.1. The Stieltjes Transform Method
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## Echo-state neural networks

- Neural network:
- Input neuron signal $s_{t} \in \mathbb{R}$ (could be multivariate)
- Output neuron signal $y_{t} \in \mathbb{R}$ (could be multivariate)
- $N$ neurons with
- state $x_{t} \in \mathbb{R}^{N}$ at time $t$
- connectivity matrix $W \in \mathbb{R}^{N \times N}$
- connectivity vector to input $w_{l} \in \mathbb{R}^{N}$
- connectivity vector to output $w_{O} \in \mathbb{R}^{N}$
- State evolution $x_{0}=0$ (say) and

$$
x_{t+1}=S\left(W x_{t}+w_{l} s_{t}\right)
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with $S$ entry-wise sigmoid function.

- Output observation

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- Learning phase: input-output data ( $s_{t}, y_{t}$ ) used to learn $W, w_{O}, w_{I}$ (via e.g. LS)
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$\Rightarrow$ Poses overlearning problems, difficult to set up, demands lots of learning data.
- Echo-state neural networks: To solve the problems of neural networks
- $W$ and $w_{l}$ set to be a random matrix, no longer learned
- only $w_{O}$ is learned
$\Rightarrow$ Reduces amount of data to learn, shows striking performances in some scenarios.


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- MSE for training data
- MSE for interpolated data
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w_{O}=\left(X_{\text {train }} X_{\text {train }}^{T}+\gamma I_{N}\right)^{-1} X_{\text {train }} y_{\text {train }}
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- In first approximation: $S=I d$.
$\Rightarrow$ MSE performance with stationary inputs leads to study

$$
\sum_{j=1}^{\infty} w^{j} w_{l} w_{l}^{\top}\left(W^{T}\right)^{j}
$$

$\Rightarrow$ New random matrix model, can be analyzed with usual tools though.

## Related biography

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