Future Random Matrix Tools for Large Dimensional Signal Processing EUSIPCO 2014, Lisbon, Portugal.

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High-dimensional data

- Consider *n* observations x_1, \dots, x_n of size *N*, independent and identically distributed with zero-mean and covariance C_N , i.e. $\mathbb{E}[x_1x_1^H] = C_N$,
- ► Let $\mathbf{X}_N = [\mathbf{x}_1, \dots, \mathbf{x}_n]$. The sample covariance estimate \hat{S}_N of \mathbf{C}_N is given by: $\hat{S}_N = \frac{1}{n} \mathbf{X}_N \mathbf{X}_N^{\mathsf{H}} = \frac{1}{n} \sum_{i=1}^n x_i x_i^*$,
- From the law of large numbers, as $n \to +\infty$,

$$\hat{S}_N \xrightarrow{\text{a.s.}} \mathbf{C}_N$$

 \longrightarrow Convergence in the operator norm

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- ▶ From the law of large numbers, as $n \to +\infty$,

$$\hat{S}_N \xrightarrow{\text{a.s.}} \mathbf{C}_N$$

- \longrightarrow Convergence in the operator norm
 - ▶ In practice, it might be difficult to afford $n \to +\infty$,
 - if $n \gg N$, \hat{S}_N can be sufficiently accurate,
 - if $N/n = \mathcal{O}(1)$, we model this scenario by the following assumption: $N \to +\infty$ and $n \to +\infty$ with $\frac{N}{n} \to c$,
 - Ünder this assumption, we have pointwise convergence to each element of C_N , i.e,

$$\left(\hat{S}_{N}\right)_{i,j} \xrightarrow{\text{a.s.}} (C_{N})_{i,j}$$

but $||S_N - C_N||$ does not converge to zero.

 $\longrightarrow\,$ The convergence in the operator norm does not hold.

Illustration

Consider $C_N = I_N$, the spectrum of \hat{S}_N is different from that of C_N

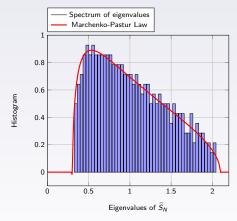


Figure: Spectrum of eigenvalues when N = 400 and n = 2000

 \rightarrow The asymptotic spectrum can be characterized by the Marchenko-Pastur Law.

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Reasons of interest for signal processing

- Scale similarity in array processing applications: large antenna arrays vs limited number of observations,
- Need for detection and estimation based on large dimensional random inputs: subspace methods in array processing.
- ▶ The assumption "number of obervations ≫ dimension of observation" is no longer valid: large arrays, systems with fast dynamics.

Example

MUSIC with "few" samples (or in large arrays) Call $\mathbf{A}(\Theta) = [\mathbf{a}(\theta_1), \dots, \mathbf{a}(\theta_K)] \in \mathbb{C}^{N \times K}$, N large, K small, the steering vectors to identify and $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n] \in \mathbb{C}^{N \times n}$ the n samples, taken from

$$\mathbf{x}_t = \sum_{k=1}^{K} \mathbf{a}(\theta_k) \sqrt{\rho}_k \mathbf{s}_{k,t} + \sigma \mathbf{w}_t.$$

The MUSIC localization function reads $\gamma(\theta) = \mathbf{a}(\theta)^{H} \hat{\mathbf{U}}_{W} \hat{\mathbf{U}}_{W}^{H} \mathbf{a}(\theta)$ in the "signal vs. noise" spectral decomposition $\mathbf{X}\mathbf{X}^{H} = \hat{\mathbf{U}}_{S}\hat{\boldsymbol{\Lambda}}_{S}\hat{\mathbf{U}}_{S}^{H} + \hat{\mathbf{U}}_{W}\hat{\boldsymbol{\Lambda}}_{W}\hat{\mathbf{U}}_{W}^{H}$.

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$$\hat{\mathbf{U}}_{W}\hat{\mathbf{U}}_{W}^{\mathsf{H}}
eq \mathbf{U}_{W}\mathbf{U}_{W}^{\mathsf{H}}$$

 \Rightarrow Music is NOT consistent in the large *N*, *n* regime! We need improved RMT-based solutions.

Outline

Part 1: Fundamentals of Random Matrix Theory

- 1.1. The Stieltjes Transform Method
- 1.2 Extreme eigenvalues
- 1.3 Extreme eigenvalues: the spiked models
- 1.4 Spectrum Analysis and G-estimation

Application to Signal Sensing and Array Processing

- 2.1 Eigenvalue-based detectior
- 2.2 The spiked G-MUSIC algorithm

Advanced Random Matrix Models for Robust Estimation

- 3.1 Robust Estimation of Scatter
- 3.2 Spiked model extension and robust G-MUSIC
- 3.3 Robust shrinkage and application to mathematical finance
- 3.4 Optimal robust GLRT detectors

Future Directions

- 4.1 Kernel matrices and kernel methods
- 4.2 Neural networks

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Stieltjes Transform

Definition

Let F be a real probability distribution function. The Stieltjes transform m_F of F is the function defined, for $z \in \mathbb{C}^+$, as

$$m_F(z) = \int \frac{1}{\lambda - z} dF(\lambda)$$

For a < b continuity points of F, denoting z = x + iy, we have the inverse formula

$$F(b) - F(a) = \lim_{y \to 0} \frac{1}{\pi} \int_a^b \mathfrak{I}[m_F(x + iy)] dx$$

If F has a density f at x, then

$$f(x) = \lim_{y \to 0} \frac{1}{\pi} \Im[m_F(x + iy)]$$

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Equivalence $F \leftrightarrow m_F$

Similar to the Fourier transform, knowing m_F is the same as knowing F.

Stieltjes transform of a Hermitian matrix

• Let **X** be a $N \times N$ random matrix. Denote by dF^X the empirical measure of its eigenvalues $\lambda_1, \dots, \lambda_N$, i.e. $dF^X = \frac{1}{N} \sum_{i=1}^N \delta_{\lambda_i}$. The Stieltjes transform of **X** denoted by $m_{\mathbf{X}} = m_F$ is the stieltjes transform of its empirical measure:

$$m_{\mathbf{X}}(z) = \int \frac{1}{\lambda - z} dF(\lambda) = \frac{1}{N} \sum_{i=1}^{N} \frac{1}{\lambda_i - z} = \frac{1}{N} \operatorname{tr} (\mathbf{X} - z \mathbf{I}_N)^{-1}.$$

- The Stieltjes transform of a random matrix is the trace of the resolvent matrix $\mathbf{Q}(z) = (\mathbf{X} z\mathbf{I}_N)^{-1}$. The resolvent matrix plays a key role in the derivation of many of the results of random matrix theory.
- For compactly supported F, $m_F(z)$ is linked to the moments $M_k = \mathbb{E} \frac{1}{N} \operatorname{tr} \mathbf{X}^k$,

$$m_F(z) = -\sum_{k=0}^{+\infty} M_k z^{-k-1}$$

• m_F is defined in general on \mathbb{C}_+ but exists everywhere outside the support of F.

Side remark: the "Shannon"-transform

A. M. Tulino, S. Verdù, "Random matrix theory and wireless communications," Now Publishers Inc., 2004.

Definition

Let F be a probability distribution, m_F its Stieltjes transform, then the Shannon-transform \mathcal{V}_F of F is defined as

$$\mathcal{V}_{F}(x) \triangleq \int_{0}^{\infty} \log(1+x\lambda) dF(\lambda) = \int_{x}^{\infty} \left(\frac{1}{t} - m_{F}(-t)\right) dt$$

- This quantity is fundamental to wireless communication purposes!
- Note that m_F itself is of interest, not F!

Proof of the Marčenko-Pastur law

V. A. Marčenko, L. A. Pastur, "Distributions of eigenvalues for some sets of random matrices", Math USSR-Sbornik, vol. 1, no. 4, pp. 457-483, 1967.

The theorem to be proven is the following

Theorem

Let $\mathbf{X}_N \in \mathbb{C}^{N \times n}$ have i.i.d. zero mean variance 1/n entries with finite eighth order moments. As $n, N \to \infty$ with $\frac{N}{n} \to c \in (0, \infty)$, the e.s.d. of $\mathbf{X}_N \mathbf{X}_N^H$ converges almost surely to a nonrandom distribution function F_c with density f_c given by

$$f_c(x) = (1 - c^{-1})^+ \delta(x) + \frac{1}{2\pi c x} \sqrt{(x - a)^+ (b - x)^+}$$

where $a = (1 - \sqrt{c})^2$, and $b = (1 + \sqrt{c})^2$.

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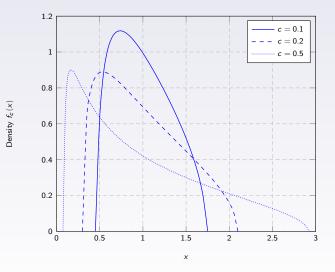


Figure: Marčenko-Pastur law for different limit ratios $c = \lim_{N \to \infty} N/n$.

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Diagonal entries of the resolvent

Since we want an expression of m_F , we start by identifying the diagonal entries of the resolvent $(\mathbf{X}_N \mathbf{X}_N^H - z \mathbf{I}_N)^{-1}$ of $\mathbf{X}_N \mathbf{X}_N^H$. Denote

$$\mathbf{X}_{N} = \begin{bmatrix} \mathbf{y}^{\mathsf{H}} \\ \mathbf{Y} \end{bmatrix}$$

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$$\mathbf{X}_{N} = \begin{bmatrix} \mathbf{y}^{\mathsf{H}} \\ \mathbf{Y} \end{bmatrix}$$

Now, for $z \in \mathbb{C}^+$, we have

$$\begin{pmatrix} \mathbf{X}_{N}\mathbf{X}_{N}^{\mathsf{H}} - z\mathbf{I}_{N} \end{pmatrix}^{-1} = \begin{bmatrix} \mathbf{y}^{\mathsf{H}}\mathbf{y} - z & \mathbf{y}^{\mathsf{H}}\mathbf{Y}^{\mathsf{H}} \\ \mathbf{Y}\mathbf{y} & \mathbf{Y}\mathbf{Y}^{\mathsf{H}} - z\mathbf{I}_{N-1} \end{bmatrix}^{-1}$$

Consider the first diagonal element of $(\mathbf{R}_N - z\mathbf{I}_N)^{-1}$. From the matrix inversion lemma,

$$\begin{pmatrix} \textbf{A} & \textbf{B} \\ \textbf{C} & \textbf{D} \end{pmatrix}^{-1} = \begin{pmatrix} (\textbf{A} - \textbf{B}\textbf{D}^{-1}\textbf{C})^{-1} & -\textbf{A}^{-1}\textbf{B}(\textbf{D} - \textbf{C}\textbf{A}^{-1}\textbf{B})^{-1} \\ -(\textbf{A} - \textbf{B}\textbf{D}^{-1}\textbf{C})^{-1}\textbf{C}\textbf{A}^{-1} & (\textbf{D} - \textbf{C}\textbf{A}^{-1}\textbf{B})^{-1} \end{pmatrix}$$

which here gives

$$\left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} - z \mathbf{I}_{N} \right)^{-1} \right]_{11} = \frac{1}{-z - z \mathbf{y}^{\mathsf{H}} (\mathbf{Y}^{\mathsf{H}} \mathbf{Y} - z \mathbf{I}_{n})^{-1} \mathbf{y}}$$

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Trace Lemma

Z. Bai, J. Silverstein, "Spectral Analysis of Large Dimensional Random Matrices", Springer Series in Statistics, 2009.

To go further, we need the following result,

Theorem

Let $\{\mathbf{A}_N\} \in \mathbb{C}^{N \times N}$ with bounded spectral norm. Let $\{\mathbf{x}_N\} \in \mathbb{C}^N$, be a random vector of *i.i.d.* entries with zero mean, variance 1/N and finite 8th order moment, independent of \mathbf{A}_N . Then

$$\mathbf{x}_{N}^{\mathsf{H}}\mathbf{A}_{N}\mathbf{x}_{N}-\frac{1}{N}tr\mathbf{A}_{N}\xrightarrow{\mathrm{a.s.}}0$$

For large N, we therefore have approximately

$$\left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} - z \mathbf{I}_{N} \right)^{-1} \right]_{11} \simeq \frac{1}{-z - z \frac{1}{N} \operatorname{tr} \left(\mathbf{Y}^{\mathsf{H}} \mathbf{Y} - z \mathbf{I}_{N} \right)^{-1}}$$

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Rank-1 perturbation lemma

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

It is somewhat intuitive that adding a single column to Y won't affect the trace in the limit.

Theorem

Let **A** and **B** be $N \times N$ with **B** Hermitian positive definite, and $\mathbf{v} \in \mathbb{C}^N$. For $z \in \mathbb{C} \setminus \mathbb{R}^-$,

$$\left|\frac{1}{N}tr\left((\mathbf{B}-z\mathbf{I}_N)^{-1}-(\mathbf{B}+\mathbf{v}\mathbf{v}^{\mathsf{H}}-z\mathbf{I}_N)^{-1}\right)\mathbf{A}\right| \leqslant \frac{1}{N}\frac{\|\mathbf{A}\|}{\operatorname{dist}(z,\mathbb{R}^+)}$$

with $\|\mathbf{A}\|$ the spectral norm of \mathbf{A} , and $\operatorname{dist}(z, A) = \inf_{y \in A} \|y - z\|$. Therefore, for large N, we have approximately,

$$\begin{split} \left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} - z \mathbf{I}_{N} \right)^{-1} \right]_{11} &\simeq \frac{1}{-z - z \frac{1}{N} \operatorname{tr} (\mathbf{Y}^{\mathsf{H}} \mathbf{Y} - z \mathbf{I}_{n})^{-1}} \\ &\simeq \frac{1}{-z - z \frac{1}{N} \operatorname{tr} (\mathbf{X}_{N}^{\mathsf{H}} \mathbf{X}_{N} - z \mathbf{I}_{n})^{-1}} \\ &= \frac{1}{-z - z \frac{n}{N} m_{\underline{F}}(z)} \end{split}$$

in which we recognize the Stieltjes transform m_E of the l.s.d. of $X_N^H X_N$.

End of the proof

We have again the relation

$$\frac{n}{N}m_{\underline{F}}(z) = m_{F}(z) + \frac{N-n}{N}\frac{1}{z}$$

hence

$$\left[\left(\mathbf{X}_{N}\mathbf{X}_{N}^{\mathsf{H}}-z\mathbf{I}_{N}\right)^{-1}\right]_{11}\simeq\frac{1}{\frac{n}{N}-1-z-zm_{F}(z)}$$

Note that the choice (1,1) is irrelevant here, so the expression is valid for all pair (i, i). Summing over the N terms and averaging, we finally have

$$m_{F}(z) = \frac{1}{N} \operatorname{tr} \left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} - z \mathbf{I}_{N} \right)^{-1} \simeq \frac{1}{c - 1 - z - z m_{F}(z)}$$

which solve a polynomial of second order. Finally

$$m_F(z) = rac{c-1}{2z} - rac{1}{2} + rac{\sqrt{(c-1-z)^2 - 4z}}{2z}.$$

From the inverse Stieltjes transform formula, we then verify that m_F is the Stieltjes transform of the Marčenko-Pastur law.

Related bibliography

- V. A. Marčenko, L. A. Pastur, "Distributions of eigenvalues for some sets of random matrices", Math USSR-Sbornik, vol. 1, no. 4, pp. 457-483, 1967.
- J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.
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- ▶ V. L. Girko, "Theory of Random Determinants," Kluwer, Dordrecht, 1990.
- A. M. Tulino, S. Verdù, "Random matrix theory and wireless communications," Now Publishers Inc., 2004.

17/142

Asymptotic results involving Stieltjes transform

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

Theorem

Let $\mathbf{Y}_N = \frac{1}{\sqrt{n}} \mathbf{X}_N \mathbf{C}_N^{\frac{1}{2}}$, where $\mathbf{X}_N \in \mathbb{C}^{n \times N}$ has *i.i.d* entries of mean 0 and variance 1. Consider the regime $n, N \to +\infty$ with $\frac{N}{n} \to c$. Let $\underline{\hat{m}}_N$ be the Stieltjes transform associated to $\mathbf{X}_N \mathbf{X}_N^*$. Then, $\underline{\hat{m}}_N - \underline{m}_N \to 0$ almost surely for all $z \in \mathbb{C} \setminus \mathbb{R}_+$, where $\underline{m}_N(z)$ is the unique solution in the set $\{z \in \mathbb{C}_+, \underline{m}_N(z) \in \mathbb{C}_+\}$ to:

$$\underline{m}_{N}(z) = \left(\int \frac{ctdF^{\mathsf{C}_{N}}}{1 + t\underline{m}_{N}(z)} - z\right)^{-1}$$

17/142

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$$\underline{m}_{N}(z) = \left(\int \frac{ctdF^{C_{N}}}{1 + t\underline{m}_{N}(z)} - z\right)^{-1}$$

- ▶ in general, no explicit expression for \underline{F}_N , the distribution whose Stietljes transform is $\underline{m}_N(z)$.
- The theorem above characterizes also the Stieltjes transform of $\mathbf{B}_N = \mathbf{X}_N^H \mathbf{X}_N$ denoted by m_N ,

$$m_N = c\underline{m}_N + (c-1)\frac{1}{z}$$

This gives access to the spectrum of the sample covariance matrix model of x, when $\mathbf{y}_i = \mathbf{C}_N^{\frac{1}{2}} \mathbf{x}_i$, \mathbf{x}_i i.i.d., $\mathbf{C}_N = E[\mathbf{y}\mathbf{y}^H]$.

▶ Remember that, for *a* < *b* real,

$$F'(x) = \lim_{y \to 0} \frac{1}{\pi} \Im[m_F(x + iy)]$$

where m_F is (up to now) only defined on \mathbb{C}^+ .

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- to plot the density F',
 - First approach: span z = x + iy on the line $\{x \in \mathbb{R}, y = \varepsilon\}$ parallel but close to the real axis, solve $m_F(z)$ for each z, and plot $\Im[m_F(z)]$.

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 - refined approach: spectral analysis, to come next.

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Example (Sample covariance matrix)

For N multiple of 3, let $F^{C}(x) = \frac{1}{3}\mathbf{1}_{x \leq 1} + \frac{1}{3}\mathbf{1}_{x \leq 3} + \frac{1}{3}\mathbf{1}_{x \leq K}$ and let $\mathbf{B}_{N} = \frac{1}{n}\mathbf{C}_{N}^{\frac{1}{2}}\mathbf{Z}_{N}^{\mathsf{H}}\mathbf{Z}_{N}\mathbf{C}_{N}^{\frac{1}{2}}$ with $F^{B_{N}} \to F$, then

$$\begin{split} m_F &= cm_{\underline{F}} + (c-1)\frac{1}{z} \\ m_{\underline{F}}(z) &= \left(c\int \frac{t}{1+tm_{\underline{F}}(z)}dF^C(t) - z\right)^{-1} \end{split}$$

We take c = 1/10 and alternatively K = 7 and K = 4.

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Spectrum of the sample covariance matrix

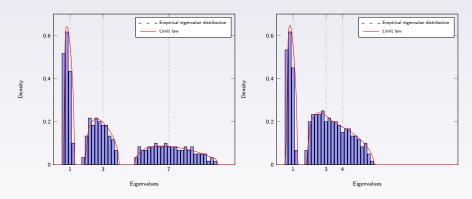


Figure: Histogram of the eigenvalues of $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^{\frac{1}{2}} \mathbf{Z}_N^{\mathsf{H}} \mathbf{Z}_N \mathbf{C}_N^{\frac{1}{2}}$, N = 3000, n = 300, with \mathbf{C}_N diagonal composed of three evenly weighted masses in (i) 1, 3 and 7 on top, (ii) 1, 3 and 4 at bottom.

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20/142

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Support of a distribution

The support of a density f is the closure of the set $\{x, f(x) \neq 0\}$. For instance the support of the marčenko-Pastur law is $[(1 - \sqrt{c})^2, (1 + \sqrt{c})^2]$.

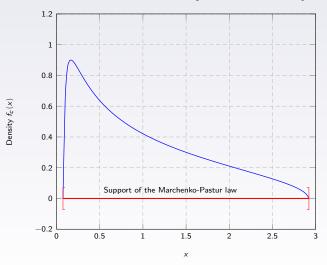


Figure: Marčenko-Pastur law for different limit ratios c = 0.5.

Extreme eigenvalues

- Limiting spectral results are insufficient to infer about the location of extreme eigenvalues.
- Example: Consider $dF_N(x) = \frac{1}{N} \sum_{k=1}^N \delta_{a_k}$. Then, $dF_N^0 = \frac{N-1}{N} dF_N + \frac{1}{N} \delta_{A_N}(x)$ and dF_N with $A_N \ge a_N$ satisfy:

$$dF_N - dF_N^0 \Rightarrow 0$$

• However, the supports of F_N and F_{N_0} differ by the mass A_N .

Question: How is the behaviour of the extreme eigenvalues of random covariance matrices?

No eigenvalue outside the support of sample covariance matrices

Z. D. Bai, J. W. Silverstein, "No eigenvalues outside the support of the limiting spectral distribution of large-dimensional sample covariance matrices," The Annals of Probability, vol. 26, no.1 pp. 316-345, 1998.

Theorem

Let $X_N \in \mathbb{C}^{N \times n}$ with i.i.d. entries with zero mean, unit variance and infinite fourth order. Let $C_N \in \mathbb{C}^{N \times N}$ be nonrandom and bounded in norm. Let \underline{m}_N be the unique solution in \mathbb{C}_+ of

$$\underline{m}_{N} = -\left(z - \frac{N}{n}\int \frac{\tau}{1 + \tau\underline{m}_{N}} dF^{\mathsf{C}_{N}}(\tau)\right)^{-1}, \quad \underline{m}_{N}(z) = \frac{N}{n}m_{N}(z) + \frac{N-n}{n}\frac{1}{z}, z \in \mathbb{C}_{+},$$

Let F_N be the distribution associated to the Stieltjes transform $m_N(z)$. Consider $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^1 \mathbf{X}_N \mathbf{X}_N^H \mathbf{C}_N^{\frac{1}{2}}$. We know that $F^{\mathbf{B}_N} - F_N$ converge weakly to zero. Choose $N_0 \in \mathbb{N}$ and [a, b], a > 0, outside the support of F_N for all $N \ge N_0$. Denote \mathcal{L}_N the set of eigenvalues of \mathbf{B}_N . Then,

 $P(\mathcal{L}_N \cap [a, b] \neq \emptyset \text{ i.o.}) = 0.$

No eigenvalue outside the support: which models?

J. W. Silverstein, P. Debashis, "No eigenvalues outside the support of the limiting empirical spectral distribution of a separable covariance matrix," J. of Multivariate Analysis vol. 100, no. 1, pp. 37-57, 2009.

- \blacktriangleright It has already been shown that (for all large N) there is no eigenvalues outside the support of
 - ▶ Marčenko-Pastur law: XX^H, X i.i.d. with zero mean, variance 1/N, finite 4th order moment.
 - Sample covariance matrix: C^{1/2} XX^HC^{1/2} and X^HCX, X i.i.d. with zero mean, variance 1/N, finite 4th order moment.
 - Doubly-correlated matrix: R^{1/2} XCX^HR^{1/2}, X with i.i.d. zero mean, variance 1/N, finite 4th order moment.

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J. W. Silverstein, Z.D. Bai, Y.Q. Yin, "A note on the largest eigenvalue of a large dimensional sample covariance matrix," Journal of Multivariate Analysis, vol. 26, no. 2, pp. 166-168, 1988.

If 4th order moment is infinite,

$$\limsup_{N} \lambda_{\max}^{\mathbf{X}\mathbf{X}^{\mathsf{H}}} = \infty$$

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J. Silverstein, Z. Bai, "No eigenvalues outside the support of the limiting spectral distribution of information-plus-noise type matrices" to appear in Random Matrices: Theory and Applications.

> Only recently, information plus noise models, **X** with i.i.d. zero mean, variance 1/N, finite 4^{th} order moment

$$(\mathbf{X} + \mathbf{A})(\mathbf{X} + \mathbf{A})^{\mathsf{H}},$$

and the generally correlation model where each column of X has correlation R_{i}

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Extreme eigenvalues: Deeper into the spectrum

 In order to derive statistical detection tests, we need more information on the extreme eigenvalues.

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Extreme eigenvalues: Deeper into the spectrum

- In order to derive statistical detection tests, we need more information on the extreme eigenvalues.
- We will study the fluctuations of the extreme eigenvalues (second order statistics)
- However, the Stieltjes transform method is not adapted here!

Distribution of the largest eigenvalues of **XX**^H

C. A. Tracy, H. Widom, "On orthogonal and symplectic matrix ensembles," Communications in Mathematical Physics, vol. 177, no. 3, pp. 727-754, 1996.
K. Johansson, "Shape Fluctuations and Random Matrices," Comm. Math. Phys. vol. 209, pp. 437-476, 2000.

Theorem

Let $\mathbf{X} \in \mathbb{C}^{N \times n}$ have i.i.d. Gaussian entries of zero mean and variance 1/n. Denoting λ_N^+ the largest eigenvalue of \mathbf{XX}^H , then

$$N^{\frac{2}{3}} \frac{\lambda_{N}^{+} - (1 + \sqrt{c})^{2}}{(1 + \sqrt{c})^{\frac{4}{3}} c^{\frac{1}{2}}} \Rightarrow X^{+} \sim F^{+}$$

with $c = \lim_{N} N/n$ and F^+ the Tracy-Widom distribution given by

$$F^{+}(t) = \exp\left(-\int_{t}^{\infty} (x-t)^2 q^2(x) dx\right)$$

with q the Painlevé II function that solves the differential equation

$$q''(x) = xq(x) + 2q^{3}(x)$$
$$q(x) \sim_{x \to \infty} \operatorname{Ai}(x)$$

in which Ai(x) is the Airy function.

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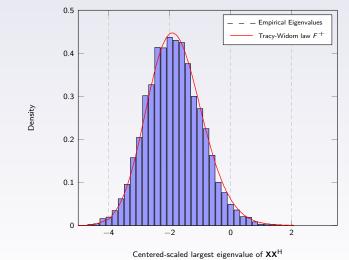


Figure: Distribution of $N^{\frac{2}{3}}c^{-\frac{1}{2}}(1+\sqrt{c})^{-\frac{4}{3}}[\lambda_N^+ - (1+\sqrt{c})^2]$ against the distribution of X^+ (distributed as Tracy-Widom law) for N = 500, n = 1500, c = 1/3, for the covariance matrix model **XX**^H. Empirical distribution taken over 10,000 Monte-Carlo simulations.

Method of proof requires very different tools:

 orthogonal (Laguerre) polynomials: to write joint unordered eigenvalue distribution as a kernel determinant.

$$p_N(\lambda_1,\ldots,\lambda_p) = \det_{i,j=1}^p K_N(\lambda_i,\lambda_j)$$

with K(x, y) the kernel Laguerre polynomial.

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Fredholm determinants: we can write hole probability as a Fredholm determinant.

$$P\left(N^{2/3}\left(\lambda_{i}-(1+\sqrt{c})^{2}\right)\in A, i=1,\ldots,N\right)=1+\sum_{k\geqslant 1}\frac{(-1)^{k}}{k!}\int_{A^{c}}\cdots\int_{A^{c}}\det_{i,j=1}^{k}K_{N}(x_{i},x_{j})\prod dx_{i}$$
$$\triangleq \det(\mathbf{I}_{N}-\mathcal{K}_{N}).$$

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kernel theory: show that K_N converges to a Airy kernel.

$$K_{N}(x,y) \rightarrow K_{\operatorname{Airy}}(x,y) = \frac{\operatorname{Ai}(x)\operatorname{Ai}'(y) - \operatorname{Ai}'(x)\operatorname{Ai}(y)}{x-y}$$

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▶ differential equation tricks: hole probability in [t, ∞) gives right-most eigenvalue distribution, which is simplified as solution of a Painelvé differential equation: the Tracy-Widom distribution.

$$F^+(t) = e^{-\int_t^\infty (x-t)q(x)^2 dx}, \quad q'' = tq + 2q^3, \ q(x) \sim_{x \to \infty} \operatorname{Ai}(x).$$

Comments on the Tracy-Widom law

- deeper result than limit eigenvalue result
- gives a hint on convergence speed
- ► fairly biased on the left: even fewer eigenvalues outside the support.

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Comments on the Tracy-Widom law

- deeper result than limit eigenvalue result
- gives a hint on convergence speed
- fairly biased on the left: even fewer eigenvalues outside the support.
- ► can be shown to hold for other distributions than Gaussian under mild assumptions

Outline

Part 1: Fundamentals of Random Matrix Theory

- 1.1. The Stieltjes Transform Method
- 1.2 Extreme eigenvalues
- 1.3 Extreme eigenvalues: the spiked models
- 1.4 Spectrum Analysis and G-estimation

Application to Signal Sensing and Array Processing

- 2.1 Eigenvalue-based detectior
- 2.2 The spiked G-MUSIC algorithm

Advanced Random Matrix Models for Robust Estimation

- 3.1 Robust Estimation of Scatter
- 3.2 Spiked model extension and robust G-MUSIC
- 3.3 Robust shrinkage and application to mathematical finance
- 3.4 Optimal robust GLRT detectors

Future Directions

- 4.1 Kernel matrices and kernel methods
- 4.2 Neural networks

Spiked models

- We consider *n* independent observations x_1, \dots, x_n of size *N*,
- The correlation structure is in general "white + low rank",

$$\mathbb{E}\left[\mathbf{x}_{1}\mathbf{x}_{1}^{\mathsf{H}}\right]=\mathbf{I}+\mathbf{P}$$

where ${\boldsymbol{\mathsf{P}}}$ is of low rank,

Objective: to infer the eigenvalues and/or the eigenvectors of P

The first result

J. Baik, J. W. Silverstein, "Eigenvalues of large sample covariance matrices of spiked population models," Journal of Multivariate Analysis, vol. 97, no. 6, pp. 1382-1408, 2006.

Theorem

Let $\mathbf{B}_N = \frac{1}{n} (\mathbf{I} + \mathbf{P})^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^{\mathsf{H}} (\mathbf{I} + \mathbf{P})^{\frac{1}{2}}$, where $\mathbf{X}_N \in \mathbb{C}^{N \times n}$ has i.i.d., zero mean and unit variance entries, and $\mathbf{P}_N \in \mathbb{R}^{N \times N}$ with eigenvalues given by:

$$\operatorname{eig}(\mathbf{P}) = \operatorname{diag}(\omega_1, \dots, \omega_K, \underbrace{0, \dots, 0}_{N-K})$$

with $\omega_1 > \ldots > \omega_K > -1$, $c = \lim_N N/n$. Let $\lambda_1, \cdots, \lambda_N$ be the eigenvalues of B_N . We then have

- if $\omega_j > \sqrt{c}$, $\lambda_j \xrightarrow{\text{a.s.}} 1 + \omega_j + c \frac{1 + \omega_j}{\omega_j}$ (i.e. beyond the Marčenko–Pastur bulk!)
- if $\omega_j \in (0, \sqrt{c}]$, $\lambda_j \xrightarrow{a.s.} (1 + \sqrt{c})^2$ (i.e. right-edge of the Marčenko–Pastur bulk!)
- if $\omega_j \in [-\sqrt{c}, 0)$, $\lambda_j \xrightarrow{\text{a.s.}} (1 \sqrt{c})^2$ (i.e. left-edge of the Marčenko–Pastur bulk!)

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with $\omega_1>\ldots>\omega_K>-1,$ $c=\lim_NN/n.$ Let $\lambda_1,\cdots,\lambda_N$ be the eigenvalues of $B_N.$ We then have

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- for the other eigenvalues, we discriminate over c:
 - if $\omega_j < -\sqrt{c}$, c < 1, $\lambda_j \xrightarrow{a.s.} 1 + \omega_j + c \frac{1 + \omega_j}{\omega_j}$ (i.e. beyond the Marčenko–Pastur bulk!)
 - $\blacktriangleright \ \ \text{if} \ \omega_j < -\sqrt{c}, \ c>1, \ \lambda_j \xrightarrow{\mathrm{a.s.}} (1-\sqrt{c})^2 \ \ \text{(i.e. left-edge of the Marčenko–Pastur bulk!)}$

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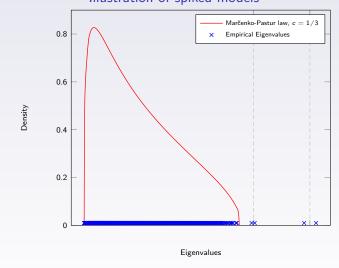


Illustration of spiked models

Figure: Eigenvalues of $\mathbf{B}_N = \frac{1}{n} (\mathbf{P} + \mathbf{I})^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^H (\mathbf{P} + \mathbf{I})^{\frac{1}{2}}$, where $\omega_1 = \omega_2 = 1$ and $\omega_3 = \omega_4 = 2$ Dimensions: N = 500, n = 1500.

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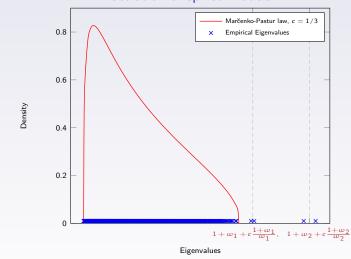


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Interpretation of the result

if c is large, or alternatively, if some "population spikes" are small, part to all of the population spikes are attracted by the support!

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- ▶ if so, no way to decide on the existence of the spikes from looking at the largest eigenvalues
- ▶ in signal processing words, signals might be missed using largest eigenvalues methods.

Interpretation of the result

- if c is large, or alternatively, if some "population spikes" are small, part to all of the population spikes are attracted by the support!
- ▶ if so, no way to decide on the existence of the spikes from looking at the largest eigenvalues
- ▶ in signal processing words, signals might be missed using largest eigenvalues methods.
- as a consequence,
 - the more the sensors (N),
 - the larger $c = \lim N/n$,
 - the more probable we miss a spike

• We start with a study of the limiting extreme eigenvalues.

- We start with a study of the limiting extreme eigenvalues.
- ▶ Let x > 0, then

$$\begin{aligned} \det(\mathbf{B}_N - x\mathbf{I}_N) &= \det(\mathbf{I}_N + \mathbf{P}) \det(\mathbf{X}\mathbf{X}^{\mathsf{H}} - x\mathbf{I}_N + x[\mathbf{I}_N - (\mathbf{I}_N + \mathbf{P})^{-1}]) \\ &= \det(\mathbf{I}_N + \mathbf{P}) \det(\mathbf{X}\mathbf{X}^{\mathsf{H}} - x\mathbf{I}_N)^{-1} \det(\mathbf{I}_N + x\mathbf{P}(\mathbf{I}_N + \mathbf{P})^{-1}(\mathbf{X}\mathbf{X}^{\mathsf{H}} - x\mathbf{I}_N)^{-1}). \end{aligned}$$

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• if x eigenvalue of \mathbf{B}_N but not of \mathbf{XX}^H , then for n large, $x > (1 + \sqrt{c})^2$ (edge of MP law support) and

$$\det(\mathbf{I}_N + x\mathbf{P}(\mathbf{I}_N + \mathbf{P})^{-1}(\mathbf{X}\mathbf{X}^{\mathsf{H}} - x\mathbf{I}_N)^{-1}) = \det(\mathbf{I}_r + x\mathbf{\Omega}(\mathbf{I}_N + \mathbf{\Omega})^{-1}\mathbf{U}^{\mathsf{H}}(\mathbf{X}\mathbf{X}^{\mathsf{H}} - x\mathbf{I}_N)^{-1}\mathbf{U}) = 0$$

with $\mathbf{P} = \mathbf{U} \mathbf{\Omega} \mathbf{U}^{\mathsf{H}}$, $\mathbf{U} \in \mathbb{C}^{N \times r}$.

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due to unitary invariance of X,

$$\mathbf{U}^{\mathsf{H}}(\mathbf{X}\mathbf{X}^{\mathsf{H}}-x\mathbf{I}_{N})^{-1}\mathbf{U}\xrightarrow{\mathrm{a.s.}}\int (t-x)^{-1}dF^{MP}(t)\mathbf{I}_{r}\triangleq m(x)\mathbf{I}_{r}$$

with F^{MP} the MP law, and m(x) the Stieltjes transform of the MP law (often known for r = 1 as trace lemma).

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with F^{MP} the MP law, and m(x) the Stieltjes transform of the MP law (often known for r = 1 as trace lemma).

- ▶ finally, we have that the *limiting* solutions x_k satisfy $x_k m(x_k) + (1 + \omega_k) \omega_k^{-1} = 0$.
- replacing m(x), this is finally:

$$\lambda_k \xrightarrow{\text{a.s.}} x_k \triangleq 1 + \omega_k + c(1 + \omega_k)\omega_k^{-1}, \text{ if } \omega_k > \sqrt{c}$$

Comments on the result

► there exists a "phase transition" when the largest population eigenvalues move from inside to outside (0, 1 + √c).

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Comments on the result

- ► there exists a "phase transition" when the largest population eigenvalues move from inside to outside (0, 1 + √c).
- more importantly, for $t_1 < 1 + \sqrt{c}$, we still have the same Tracy-Widom,
 - no way to see the spike even when zooming in
 - in fact, simulation suggests that convergence rate to the Tracy-Widom is slower with spikes.

Outline

Part 1: Fundamentals of Random Matrix Theory

- 1.1. The Stieltjes Transform Method
- 1.2 Extreme eigenvalues
- 1.3 Extreme eigenvalues: the spiked models
- 1.4 Spectrum Analysis and G-estimation

Application to Signal Sensing and Array Processing

- 2.1 Eigenvalue-based detectior
- 2.2 The spiked G-MUSIC algorithm

Advanced Random Matrix Models for Robust Estimation

- 3.1 Robust Estimation of Scatter
- 3.2 Spiked model extension and robust G-MUSIC
- 3.3 Robust shrinkage and application to mathematical finance
- 3.4 Optimal robust GLRT detectors

Future Directions

- 4.1 Kernel matrices and kernel methods
- 4.2 Neural networks

Stieltjes transform inversion for covariance matrix models

J. W. Silverstein, S. Choi, "Analysis of the limiting spectral distribution of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 295-309, 1995.

▶ We know for the model $C_N^{\frac{1}{2}} X_N$, $X_N \in \mathbb{C}^{N \times n}$ that, if $F^{\mathbf{C}_N} \Rightarrow F^{\mathbf{C}}$, the Stieltjes transform of the e.s.d. of $\underline{\mathbf{B}}_N = \frac{1}{n} X_N^{\mathsf{H}} \mathbf{C}_N X_N$ satisfies $m_{\underline{\mathbf{B}}_N}(z) \xrightarrow{\text{a.s.}} m_{\underline{\mathbf{F}}}(z)$, with

$$m_{\underline{F}}(z) = \left(-z - c \int \frac{t}{1 + tm_{\underline{F}}(z)} dF^{C}(t)\right)^{-1}$$

which is unique on the set $\{z \in \mathbb{C}^+, m_{\underline{F}}(z) \in \mathbb{C}^+\}$.

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This can be inverted into

$$z_{\underline{F}}(m) = -\frac{1}{m} - c \int \frac{t}{1+tm} dF^{C}(t)$$

for $m \in \mathbb{C}^+$.

39/142

Stieltjes transform inversion and spectrum characterization

Remember that we can evaluate the spectrum density by taking a complex line close to \mathbb{R} and evaluating $\Im[m_F(z)]$ along this line. Now we can do better.

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It is shown that

$$\lim_{\substack{z \to x \in \mathbb{R}^* \\ z \in \mathbb{C}^+}} m_{\underline{F}}(z) = m_0(x) \quad \text{exists.}$$

We also have,

► for x_0 inside the support, the density $\underline{f}(x)$ of \underline{F} in x_0 is $\frac{1}{\pi} \Im[m_0]$ with m_0 the unique solution $m \in \mathbb{C}^+$ of

$$[z_{\underline{F}}(m) =] x_0 = -\frac{1}{m} - c \int \frac{t}{1 + tm} dF^{C}(t)$$

▶ let $m_0 \in \mathbb{R}^*$ and x_E the equivalent to z_E on the real line. Then " x_0 outside the support of \underline{F} " is equivalent to " $x'_F(m_E(x_0)) > 0$, $m_E(x_0) \neq 0$, $-1/m_E(x_0)$ outside the support of F^{C} ".

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This provides another way to determine the support!. For $m \in (-\infty, 0)$, evaluate $x_{\underline{F}}(m)$. Whenever x_{F} decreases, the image is outside the support. The rest is inside.

Another way to determine the spectrum: spectrum to analyze

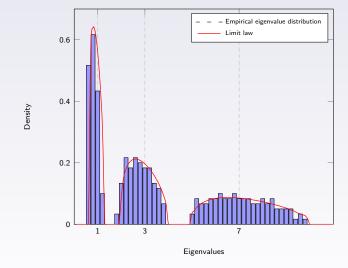


Figure: Histogram of the eigenvalues of $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^{\mathsf{H}} \mathbf{C}_N^{\frac{1}{2}}$, N = 300, n = 3000, with \mathbf{C}_N diagonal composed of three evenly weighted masses in 1, 3 and 7.

Another way to determine the spectrum: inverse function method

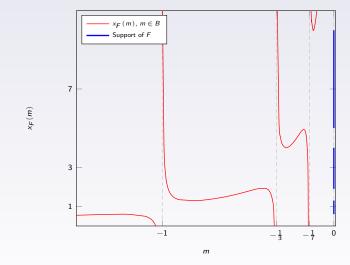


Figure: Stieltjes transform of $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^H \mathbf{C}_N^{\frac{1}{2}}$, N = 300, n = 3000, with \mathbf{C}_N diagonal composed of three evenly weighted masses in 1, 3 and 7. The support of F is read on the vertical axis, whenever m_F is decreasing.

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42/142

Cluster boundaries in sample covariance matrix models

Xavier Mestre, "Improved estimation of eigenvalues of covariance matrices and their associated subspaces using their sample estimates," IEEE Transactions on Information Theory, vol. 54, no. 11, Nov. 2008.

Theorem

Let $\mathbf{X}_N \in \mathbb{C}^{N \times n}$ have i.i.d. entries of zero mean, unit variance, and \mathbf{C}_N be diagonal such that $F^{\mathbf{C}_N} \Rightarrow F^{\mathbf{C}}$, as $n, N \to \infty$, $N/n \to c$, where $F^{\mathbf{C}}$ has K masses in t_1, \ldots, t_K with multiplicity n_1, \ldots, n_K respectively. Then the l.s.d. of $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^{\mathsf{H}} \mathbf{C}_N^{\frac{1}{2}}$ has support \$ given by

$$S = [x_1^-, x_1^+] \cup [x_2^-, x_2^+] \cup \ldots \cup [x_Q^-, x_Q^+]$$

with $x_q^- = x_F(m_q^-)$, $x_q^+ = x_F(m_q^+)$, and

$$x_F(m) = -\frac{1}{m} - c\frac{1}{n}\sum_{k=1}^{K}n_k\frac{t_k}{1+t_km}$$

with 2*Q* the number of real-valued solutions counting multiplicities of $x'_F(m) = 0$ denoted in order $m_1^- < m_1^+ \leqslant m_2^- < m_2^+ \leqslant \ldots \leqslant m_Q^- < m_Q^+$.

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Comments on spectrum characterization

Previous results allows to determine

- the spectrum boundaries
- the number Q of clusters
- ▶ as a consequence, the total separation (Q = K) or not (Q < K) of the spectrum in K clusters.

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- ▶ as a consequence, the total separation (Q = K) or not (Q < K) of the spectrum in K clusters.

Mestre goes further: to determine local separability of the spectrum,

• identify the K inflexion points, i.e. the K solutions m_1, \ldots, m_K to

 $x_F''(m) = 0$

- check whether $x'_F(m_i) > 0$ and $x'_F(m_{i+1}) > 0$
- if so, the cluster in between corresponds to a single population eigenvalue.

Exact eigenvalue separation

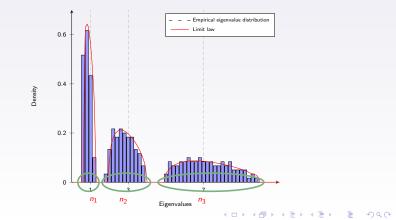
Z. D. Bai, J. W. Silverstein, "Exact Separation of Eigenvalues of Large Dimensional Sample Covariance Matrices," The Annals of Probability, vol. 27, no. 3, pp. 1536-1555, 1999.

- Recall that the result on "no eigenvalue outside the support"
 - says where eigenvalues are not to be found
 - does not say, as we feel, that (if cluster separation) in cluster k, there are exactly n_k eigenvalues.

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- Recall that the result on "no eigenvalue outside the support"
 - says where eigenvalues are not to be found
 - **b** does not say, as we feel, that (if cluster separation) in cluster k, there are exactly n_k eigenvalues.
- This is in fact the case,



▶ *Reminder:* for a sequence $\mathbf{x}_1, \ldots, x_n \in \mathbb{C}^N$ of independent random variables,

$$\hat{\mathsf{C}}_N = rac{1}{n}\sum_{k=1}^n \mathsf{x}_k \mathsf{x}_k^{\mathsf{H}}$$

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- ▶ If *n*, *N* have comparable sizes, this no longer holds.
- Typically, n, N-consistent estimators of the full C_N matrix perform very badly.
- If only the eigenvalues of C_N are of interest, things can be done. The process of retrieving information about eigenvalues, eigenspace projections, or functional of these is called eigen-inference.

Girko and the G-estimators

V. Girko, "Ten years of general statistical analysis,"

http://www.general-statistical-analysis.girko.freewebspace.com/chapter14.pdf

- Girko has come up with more than 50 N, n-consistent estimators, called G-estimators (Generalized estimators). Among those, we find
 - G₁-estimator of generalized variance. For

$$G_1(\hat{\mathbf{C}}_N) = \alpha_n^{-1} \left[\log \det(\mathbf{C}_N) + \log \frac{n(n-1)^N}{(n-N) \prod_{k=1}^N (n-k)} \right]$$

with α_n any sequence such that $\alpha_n^{-2} \log(n/(n-N)) \rightarrow 0$, we have

$$G_1(\hat{\mathbf{C}}_N) - \alpha_n^{-1} \log \det(\mathbf{C}_N) \to 0$$

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However, Girko's proofs are rarely readable, if existent.

A long standing problem

X. Mestre, "Improved estimation of eigenvalues and eigenvectors of covariance matrices using their sample estimates," IEEE trans. on Information Theory, vol. 54, no. 11, pp. 5113-5129, 2008.

- Consider the model $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^H \mathbf{C}_N^{\frac{1}{2}}$, where $F^{\mathbf{C}_N}$ is formed of a finite number of masses t_1, \ldots, t_K .
- ▶ It has long been thought the inverse problem of estimating t_1, \ldots, t_K from the Stieltjes transform method was not possible.
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- ▶ It has long been thought the inverse problem of estimating t_1, \ldots, t_K from the Stieltjes transform method was not possible.
- Only trials were iterative convex optimization methods.
- The problem was partially solved by Mestre in 2008!
- His technique uses elegant complex analysis tools. The description of this technique is the subject of this course.

Reminders

- Consider the sample covariance matrix model $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^{\mathsf{H}} \mathbf{C}_N^{\frac{1}{2}}$.
- Up to now, we saw:
 - that there is no eigenvalue outside the support with probability 1 for all large N.
 - that for all large N, when the spectrum is divided into clusters, the number of empirical eigenvalues in each cluster is exactly as we expect.

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- Consider the sample covariance matrix model $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^{\mathsf{H}} \mathbf{C}_N^{\frac{1}{2}}$.
- Up to now, we saw:
 - that there is no eigenvalue outside the support with probability 1 for all large N.
 - that for all large N, when the spectrum is divided into clusters, the number of empirical eigenvalues in each cluster is exactly as we expect.
- these results are of crucial importance for the following.

49/142

Eigen-inference for the sample covariance matrix model

X. Mestre, "Improved estimation of eigenvalues and eigenvectors of covariance matrices using their sample estimates," IEEE trans. on Information Theory, vol. 54, no. 11, pp. 5113-5129, 2008.

Theorem

Consider the model $\mathbf{B}_N = \frac{1}{n} \mathbf{C}_N^{\frac{1}{2}} \mathbf{X}_N \mathbf{X}_N^H \mathbf{C}_N^{\frac{1}{2}}$, with $\mathbf{X}_N \in \mathbb{C}^{N \times n}$, i.i.d. with entries of zero mean, unit variance, and $\mathbf{C}_N \in \mathbb{R}^{N \times N}$ is diagonal with K distinct entries t_1, \ldots, t_K of multiplicity N_1, \ldots, N_K of same order as n. Let $k \in \{1, \ldots, K\}$. Then, if the cluster associated to t_k is separated from the clusters associated to k - 1 and k + 1, as $N, n \to \infty$, $N/n \to c$,

$$\hat{t}_k = \frac{n}{N_k} \sum_{m \in \mathcal{N}_k} \left(\lambda_m - \mu_m \right)$$

is an N, n-consistent estimator of t_k , where $\mathcal{N}_k = \{N - \sum_{i=k}^{K} N_i + 1, \dots, N - \sum_{i=k+1}^{K} N_i\}, \lambda_1, \dots, \lambda_N$ are the eigenvalues of \mathbf{B}_N and μ_1, \dots, μ_N are the N solutions of

$$\underline{\textit{m}}_{\boldsymbol{X}_{\textit{N}}^{H}\boldsymbol{C}_{\textit{N}}\boldsymbol{X}_{\textit{N}}}(\boldsymbol{\mu})=\boldsymbol{0}$$

or equivalently, μ_1, \ldots, μ_N are the eigenvalues of $\text{diag}(\lambda) - \frac{1}{N}\sqrt{\lambda}\sqrt{\lambda}^T$.

Remarks on Mestre's result

Assuming cluster separation, the result consists in

- taking the empirical ordered λ_i's inside the cluster (note that exact separation ensures there are N_k of these!)
- getting the *ordered* eigenvalues μ_1, \ldots, μ_N of

$$\mathsf{diag}(\lambda) - \frac{1}{N}\sqrt{\lambda}\sqrt{\lambda}^{\mathsf{T}}$$

with $\lambda = (\lambda_1, \dots, \lambda_N)^T$. Keep only those of index inside \mathcal{N}_k .

take the difference and scale.

How to obtain this result?

Major trick requires tools from complex analysis

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How to obtain this result?

- Major trick requires tools from complex analysis
- Silverstein's Stieltjes transform identity: for the *conjugate* model $\underline{\mathbf{B}}_N = \frac{1}{n} \mathbf{X}_N^{\mathsf{H}} \mathbf{C}_N \mathbf{X}_N$,

$$\underline{m}_{N}(z) = \left(-z - c \int \frac{t}{1 + t\underline{m}_{N}(z)} dF^{\mathsf{C}_{N}}(t)\right)^{-1}$$

with \underline{m}_N the deterministic equivalent of $m_{\underline{B}_N}$. This is the only random matrix result we need.

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with \underline{m}_N the deterministic equivalent of $m_{\underline{B}_N}$. This is the only random matrix result we need. • Before going further, we need some reminders from complex analysis.

Limiting spectrum of the sample covariance matrix

- J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," J. of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995. Reminder:
 - If $F^{C_N} \Rightarrow F^C$, then $m_{B_N}(z) \xrightarrow{\text{a.s.}} m_F(z)$ such that

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$$m_{\underline{F}}(z) = \left(c \int \frac{t}{1 + tm_{\underline{F}}(z)} dF^{C}(t) - z\right)^{-1}$$

or equivalently

$$m_{FC}\left(-1/m_{\underline{F}}(z)\right) = -zm_{\underline{F}}(z)m_{F}(z)$$

with $m_{\underline{F}}(z) = cm_F(z) + (c-1)\frac{1}{z}$ and $N/n \rightarrow c$.

Reminders of complex analysis

Cauchy integration formula

Theorem

Let $U \subset \mathbb{C}$ be an open set and $f: U \to \mathbb{C}$ be holomorphic on U. Let $\gamma \subset U$ be a continuous contour (i.e. closed path). Then, for a **inside** the surface formed by γ , we have

$$\frac{1}{2\pi i} \oint_{\gamma} \frac{f(z)}{z-a} dz = f(a)$$

while for a **outside** the surface formed by γ ,

$$\frac{1}{2\pi i}\oint_{\gamma}\frac{f(z)}{z-a}dz=0.$$

From Cauchy integral formula, denoting \mathcal{C}_k a contour enclosing only t_k ,

$$t_k = \frac{1}{2\pi i} \oint_{\mathcal{C}_k} \frac{\omega}{\omega - t_k} d\omega$$

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• After the variable change $\omega = -1/m_{\underline{F}}(z)$,

$$t_{k} = \frac{N}{N_{k}} \frac{1}{2\pi i} \oint_{\mathcal{C}_{\underline{F},k}} zm_{F}(z) \frac{m_{\underline{F}}'(z)}{m_{\underline{F}}^{2}(z)} dz$$

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When the system dimensions are large,

$$m_F(z) \simeq m_{\mathbf{B}_N}(z) \triangleq \frac{1}{N} \sum_{k=1}^N \frac{1}{\lambda_k - z}, \quad \text{with} \quad (\lambda_1, \dots, \lambda_N) = \operatorname{eig}(\mathbf{B}_N) = \operatorname{eig}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}}).$$

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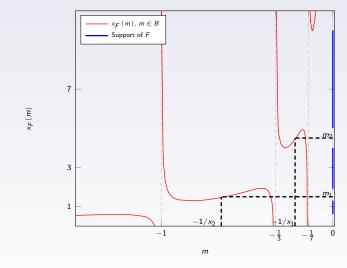
When the system dimensions are large,

$$m_F(z) \simeq m_{\mathbf{B}_N}(z) \triangleq \frac{1}{N} \sum_{k=1}^N \frac{1}{\lambda_k - z}, \quad \text{with} \quad (\lambda_1, \dots, \lambda_N) = \operatorname{eig}(\mathbf{B}_N) = \operatorname{eig}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}}).$$

Dominated convergence arguments then show

$$t_k - \hat{t}_k \xrightarrow{\text{a.s.}} 0 \quad \text{with} \quad \hat{t}_k = \frac{N}{N_k} \frac{1}{2\pi i} \oint_{\mathcal{C}_{\underline{F},k}} zm_{\mathbf{B}_N}(z) \frac{m'_{\underline{B}_N}(z)}{m'_{\underline{B}_N}(z)} dz$$

Understanding the contour change



▶ **IF** $C_{F,k}$ encloses cluster k with real points $m_1 < m_2$

► THEN $-1/m_1 = x_1 < t_k < x_2 = -1/m_2$ and \mathcal{C}_k encloses t_k .

- we find two sets of poles (outside zeros):
 - $\lambda_1, \ldots, \lambda_N$, the eigenvalues of **B**_N.
 - the solutions μ_1, \ldots, μ_N to $\underline{\hat{m}}_N(z) = 0$.

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$$m_{\mathbf{B}_{N}}(w) = \frac{n}{N}m_{\underline{\mathbf{B}}_{N}}(w) + \frac{n-N}{N}\frac{1}{w}$$

- ► residue calculus, denote $f(w) = \left(\frac{n}{N}wm_{\underline{B}_N}(w) + \frac{n-N}{N}\right)\frac{m'_{\underline{B}_N}(w)}{m_{\underline{B}_N}(w)^2}$,
 - ▶ the \u03c6_k's are poles of order 1 and

$$\lim_{z \to \lambda_k} (z - \lambda_k) f(z) = -\frac{n}{N} \lambda_k$$

the μ_k's are also poles of order 1 and by L'Hospital's rule

$$\lim_{z \to \mu_k} (z - \lambda_k) f(z) = \lim_{z \to \mu_k} \frac{n}{N} \frac{(z - \mu_k) z m_{\underline{B}_N}(z)}{m_{\underline{B}_N}(z)} = \frac{n}{N} \mu_k$$

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So, finally

$$\hat{t}_k = \frac{n}{N_k} \sum_{m \in \text{contour}} \left(\lambda_m - \mu_m \right)$$

Which poles in the contour?

we now need to determine which poles are in the contour of interest.

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 $\lambda_1 < \mu_2 < \lambda_2 < \ldots < \mu_N < \lambda_N$

Which poles in the contour?

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$$\lambda_1 < \mu_2 < \lambda_2 < \ldots < \mu_N < \lambda_N$$

what about µ1? the trick is to use the fact that

$$\frac{1}{2\pi i}\oint_{\mathcal{C}_k}\frac{1}{z}dz=0$$

which leads to

$$\frac{1}{2\pi i} \oint_{\partial \Gamma_k} \frac{m'_E(w)}{m_E(w)^2} dw = 0$$

the empirical version of which is

$$\#\{i:\lambda_i\in\Gamma_k\}-\#\{i:\mu_i\in\Gamma_k\}$$

Since their difference tends to 0, there are as many λ_k 's as μ_k 's in the contour, hence μ_1 is asymptotically in the integration contour.

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Outline

Part 1: Fundamentals of Random Matrix Theory

- 1.1. The Stieltjes Transform Method
- 1.2 Extreme eigenvalues
- 1.3 Extreme eigenvalues: the spiked models
- 1.4 Spectrum Analysis and G-estimation

Application to Signal Sensing and Array Processing

- 2.1 Eigenvalue-based detection
- 2.2 The spiked G-MUSIC algorithm

Advanced Random Matrix Models for Robust Estimation

- 3.1 Robust Estimation of Scatter
- 3.2 Spiked model extension and robust G-MUSIC
- 3.3 Robust shrinkage and application to mathematical finance
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Future Directions

- 4.1 Kernel matrices and kernel methods
- 4.2 Neural networks

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Problem formulation

• We want to test the hypothesis \mathcal{H}_0 against \mathcal{H}_1 ,

 $\mathbb{C}^{N \times n} \ni \mathbf{Y} = \left\{ \begin{array}{l} \mathbf{h} \mathbf{x}^{\mathcal{T}} + \sigma \mathbf{W} & \text{, information plus noise, hypothesis } \mathcal{H}_1 \\ \sigma \mathbf{W} & \text{, pure noise, hpothesis } \mathcal{H}_0 \end{array} \right.$

with $\mathbf{h} \in \mathbb{C}^N$, $\mathbf{x} \in \mathbb{C}^N$, $\mathbf{W} \in \mathbb{C}^{N \times n}$.

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with $\mathbf{h} \in \mathbb{C}^N$, $\mathbf{x} \in \mathbb{C}^N$, $\mathbf{W} \in \mathbb{C}^{N \times n}$.

 We assume no knowledge whatsoever but that W has i.i.d. (non-necessarily Gaussian) entries.

Exploiting the conditioning number

L. S. Cardoso, M. Debbah, P. Bianchi, J. Najim, "Cooperative spectrum sensing using random matrix theory," International Symposium on Wireless Pervasive Computing, pp. 334-338, 2008.

under either hypothesis,

▶ if \mathcal{H}_0 , for *N* large, we expect F_{YYH} close to the Marčenko-Pastur law, of support $[\sigma^2 (1 - \sqrt{c})^2, \sigma^2 (1 + \sqrt{c})^2]$.

- if \mathcal{H}_1 , if population spike more than $1 + \sqrt{\frac{N}{n}}$, largest eigenvalue is further away.
- ▶ the conditioning number of **YY**^H is therefore asymptotically, as $N, n \rightarrow \infty$, $N/n \rightarrow c$, ▶ if \mathcal{H}_0 ,

$$\operatorname{cond}(\mathbf{Y}) \triangleq \frac{\lambda_{\max}}{\lambda_{\min}} \to \frac{(1-\sqrt{c})^2}{(1+\sqrt{c})^2}$$

▶ if H₁,

$$\operatorname{cond}(\mathbf{Y}) \rightarrow t_1 + \frac{ct_1}{t_1 - 1} > \frac{\left(1 - \sqrt{c}\right)^2}{\left(1 + \sqrt{c}\right)^2}$$

with $t_1 = \sum_{k=1}^N |h_k|^2 + \sigma^2$

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with $t_1 = \sum_{k=1}^N |h_k|^2 + \sigma^2$

• the conditioning number is independent of σ . We then have the decision criterion, whether or not σ is known,

decide
$$\begin{cases} \mathcal{H}_{0}: & \text{if } \operatorname{cond}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}}) \leqslant \frac{\left(1-\sqrt{\frac{N}{n}}\right)^{2}}{\left(1+\sqrt{\frac{N}{n}}\right)^{2}} + \varepsilon \\ \mathcal{H}_{1}: & \text{otherwise.} \end{cases}$$

for some security margin ε .

Comments on the method

- Advantages:
 - much simpler than finite size analysis
 - ratio independent of σ , so σ needs not be known

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 - much simpler than finite size analysis
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- Drawbacks:
 - only stands for very large N (dimension N for which asymptotic results arise function of σ !)
 - ad-hoc method, does not rely on performance criterion.

Generalized likelihood ratio test

P. Bianchi, M. Debbah, M. Maida, J. Najim, "Performance of Statistical Tests for Source Detection using Random Matrix Theory," IEEE Trans. on Information Theory, vol. 57, no. 4, pp. 2400-2419, 2011.

Alternative generalized likelihood ratio test (GLRT) decision criterion, i.e.

$$C(\mathbf{Y}) = \frac{\sup_{\sigma^2, \mathbf{h}} P_{\mathbf{Y}|\mathbf{h}, \sigma^2}(\mathbf{Y}, \mathbf{h}, \sigma^2)}{\sup_{\sigma^2} P_{\mathbf{Y}|\sigma^2}(\mathbf{Y}|\sigma^2)}$$

Denote

$$T_N = \frac{\lambda_{\max}(\mathbf{Y}\mathbf{Y}^{\mathsf{H}})}{\frac{1}{N}\mathsf{tr}\,\mathbf{Y}\mathbf{Y}^{\mathsf{H}}}$$

To guarantee a maximum false alarm ratio of α ,

$$\label{eq:decide} \begin{array}{ll} \mbox{decide} \left\{ \begin{array}{ll} \mathcal{H}_1: & \mbox{if } \left(1-\frac{1}{N}\right)^{(1-N)n} \, T_N^{-n} \left(1-\frac{T_N}{N}\right)^{(1-N)n} > \xi_N \\ \mathcal{H}_0: & \mbox{otherwise.} \end{array} \right. \end{array}$$

for some threshold ξ_N that can be explicitly given as a function of α .

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for some threshold ξ_N that can be explicitly given as a function of α .

- Optimal test with respect to GLR.
- Performs better than conditioning number test.

Performance comparison for unknown σ^2 , P

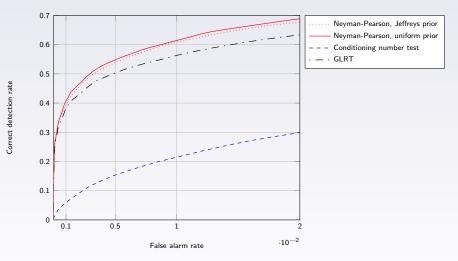


Figure: ROC curve for a priori unknown σ^2 of the Neyman-Pearson test, conditioning number method and GLRT, K = 1, N = 4, M = 8, SNR = 0 dB. For the Neyman-Pearson test, both uniform and Jeffreys prior, with exponent $\beta = 1$, are provided.

67/142

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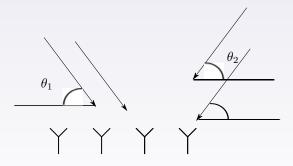
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Source localization

A uniform array of M antennas receives signal from K radio sources during n signal snapshots. Objective: Estimate the arrival angles $\theta_1, \dots, \theta_K$.



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Source Localization using Music Algorithm

We consider the scenario of K sources and N antenna-array capturing n observations:

$$\mathbf{x}_t = \sum_{k=1}^{K} \mathbf{a}(\mathbf{\theta}_k) \mathbf{s}_{k,t} + \mathbf{\sigma} \mathbf{w}_t, t = 1, \cdots, n$$

►
$$\mathbf{A}_{N} = [\mathbf{a}_{N}(\theta_{1}), \cdots, \mathbf{a}_{N}(\theta_{K})]$$
 with $\mathbf{a}_{N}(\theta) = \begin{bmatrix} 1 \\ e^{i\pi \sin \theta} \\ \vdots \\ e^{i(N-1)\pi \sin \theta} \end{bmatrix}$

- σ^2 is the noise variance and is set 1 for simplicity,
- Objective: infer $\theta_1, \dots, \theta_K$ from the *n* observations
- Let $\mathbf{X}_N = [\mathbf{x}_1, \cdots, \mathbf{x}_n]$, then,

$$\mathbf{X} = \mathbf{A}\mathbf{S} + \mathbf{W} = \begin{bmatrix} \mathbf{A} & \mathbf{I}_{N} \end{bmatrix} \begin{bmatrix} \mathbf{S} \\ \mathbf{W} \end{bmatrix}$$

- If K is finite while $n, N \to +\infty$, the model correponds to the spiked covariance model.
- MUSIC Algorithm: Let Π be the orthogonal projection matrix on the span of AA^* and $\Pi^{\perp} = I_N \Pi$ (orthogonal projector on the noise subspace). Angles $\theta_1, \dots, \theta_K$ are the unique ones verifying

$$\eta(\boldsymbol{\theta}) \triangleq \mathbf{a}_{N}(\boldsymbol{\theta})^{*} \mathbf{\Pi} \mathbf{a}_{N}(\boldsymbol{\theta}) = \mathbf{0}$$

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Traditional MUSIC algorithm

Traditional MUSIC algorithm: Angles are estimated as local minima of:

 $\mathbf{a}_N(\mathbf{\theta})^* \hat{\mathbf{\Pi}} \mathbf{a}_N(\mathbf{\theta})$

where $\hat{\Pi}$ is the orthogonal projection matrix on the eigenspace associated to the K largest eigenvalues of $\frac{1}{a} X_N X_N^*$

- ▶ It is well-known that this estimator is consistent when $n \to +\infty$ with K, N fixed,
- We consider the case of K finite \rightarrow spiked covariance model
- What happens when $n, N \rightarrow +\infty$?

Asymptotic behaviour of the traditional MUSIC (1)

- \rightarrow We first need to understand the spectrum of $\frac{1}{n}XX^{H}$
 - We know that the weak spectrum is the MP law
 - Up to K eigenvalues can leave the support: we identify here these eigenvalues

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 \rightarrow Denote $\mathbf{P} = \mathbf{A}\mathbf{A}^{H} = \mathbf{U}_{S}\Omega\mathbf{U}_{S}^{H}$, $\Omega = \text{diag}(\omega_{1}, \dots, \omega_{K})$, and $\mathbf{Z} = [\mathbf{S}^{T} \ \mathbf{W}^{T}]^{T}$ to recover (up to one row) the generic spiked model

$$\mathbf{X} = (\mathbf{I}_N + \mathbf{P})^{\frac{1}{2}} \mathbf{Z}.$$

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$$\mathbf{X} = (\mathbf{I}_N + \mathbf{P})^{\frac{1}{2}} \mathbf{Z}.$$

▶ Reminder: If x eigenvalue of $\frac{1}{n}XX^{H}$ with $x > (1 + \sqrt{c})^{2}$ (edge of MP law), for all large n,

$$x \triangleq \lambda_k \xrightarrow{\text{a.s.}} \rho_k \triangleq 1 + \omega_k + c(1 + \omega_k)\omega_k^{-1}$$
, if $\omega_k > \sqrt{c}$

for some k.

Asymptotic behaviour of the traditional MUSIC (2) \rightarrow Recall the MUSIC approach: we want to estimate

 $\eta(\theta) = \mathbf{a}(\theta)^H \mathbf{U}_W \mathbf{U}_W^H \mathbf{a}(\theta) \quad (\mathbf{U}_W \in \mathbb{C}^{N \times (N-K)} \text{ such that } \mathbf{U}_W^H \mathbf{U}_S = \mathbf{0})$

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 \rightarrow Instead of this quantity, we start with the study of

$$\mathbf{a}(\theta)^{\mathsf{H}}\hat{\mathbf{u}}_{i}\hat{\mathbf{u}}_{i}^{\mathsf{H}}\mathbf{a}(\theta), \ k = 1, \dots, K$$

with $\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_N$ the eigenvectors belonging to $\lambda_1 \geqslant \dots \geqslant \lambda_N$.

 \rightarrow To fall back on known RMT quantities, we use the Cauchy-integral:

$$\mathbf{a}(\theta)^{\mathsf{H}}\hat{\mathbf{u}}_{i}\hat{\mathbf{u}}_{i}^{\mathsf{H}}\mathbf{a}(\theta) = -\frac{1}{2\pi\iota}\oint_{\mathcal{C}_{i}}\mathbf{a}(\theta)^{\mathsf{H}}(\frac{1}{n}\mathbf{X}\mathbf{X}^{\mathsf{H}} - z\mathbf{I}_{N})^{-1}\mathbf{a}(\theta)dz$$

with \mathcal{C}_i a contour enclosing λ_i only.

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$$\eta(\theta) = \mathbf{a}(\theta)^{\mathsf{H}} \mathbf{U}_{W} \mathbf{U}_{W}^{\mathsf{H}} \mathbf{a}(\theta) \quad (\mathbf{U}_{W} \in \mathbb{C}^{N \times (N-K)} \text{ such that } \mathbf{U}_{W}^{\mathsf{H}} \mathbf{U}_{S} = 0)$$

 \rightarrow Instead of this quantity, we start with the study of

$$\mathbf{a}(\theta)^{\mathsf{H}}\hat{\mathbf{u}}_{i}\hat{\mathbf{u}}_{i}^{\mathsf{H}}\mathbf{a}(\theta), \ k = 1, \dots, K$$

with $\hat{\mathbf{u}}_1, \dots, \hat{\mathbf{u}}_N$ the eigenvectors belonging to $\lambda_1 \geqslant \dots \geqslant \lambda_N$.

 \rightarrow To fall back on known RMT quantities, we use the Cauchy-integral:

$$\mathbf{a}(\theta)^{\mathsf{H}}\hat{\mathbf{u}}_{i}\hat{\mathbf{u}}_{i}^{\mathsf{H}}\mathbf{a}(\theta) = -\frac{1}{2\pi\iota}\oint_{\mathcal{C}_{i}}\mathbf{a}(\theta)^{\mathsf{H}}(\frac{1}{n}\mathbf{X}\mathbf{X}^{\mathsf{H}} - z\mathbf{I}_{N})^{-1}\mathbf{a}(\theta)dz$$

with \mathcal{C}_i a contour enclosing λ_i only.

 \rightarrow Woodbury's identity $(\textit{A} + \textit{UCV})^{-1} = \textit{A}^{-1} - \textit{A}^{-1}\textit{U}(\textit{C}^{-1} + \textit{V}\textit{A}^{-1}\textit{U})^{-1}\textit{V}\textit{A}^{-1}$ gives:

$$\mathbf{a}^{\mathsf{H}}\hat{\mathbf{u}}_{i}\hat{\mathbf{u}}_{i}^{\mathsf{H}}\mathbf{a} = \frac{-1}{2\pi\iota}\oint_{\mathcal{C}_{i}}\mathbf{a}^{\mathsf{H}}(\mathbf{I}_{N}+\mathbf{P})^{-\frac{1}{2}}(\frac{\mathbf{Z}\mathbf{Z}^{\mathsf{H}}}{n}-z\mathbf{I}_{N})^{-1}(\mathbf{I}_{N}+\mathbf{P})^{-\frac{1}{2}}\mathbf{a}dz + \frac{1}{2\pi\iota}\oint_{\mathcal{C}_{i}}\hat{\mathbf{a}}_{i}^{\mathsf{H}}\widehat{\mathbf{H}}^{-1}\hat{\mathbf{a}}_{2}dz$$

where $\mathbf{P} = \mathbf{U}_{S} \mathbf{\Omega} \mathbf{U}_{S}^{H}$, and

Asymptotic behaviour of the traditional MUSIC (3)

▶ For large *n*, the first term has no pole, while the second converges to

$$T_{i} \triangleq \frac{1}{2\pi\iota} \oint_{\mathcal{C}_{i}} \mathbf{a}_{1}^{\mathsf{H}} \mathbf{H}^{-1} \mathbf{a}_{2} dz, \text{ with } \begin{cases} \mathbf{H} &= \mathbf{I}_{\mathcal{K}} + zm(z) \mathbf{\Omega} (\mathbf{I}_{\mathcal{K}} + \mathbf{\Omega})^{-1} \\ \mathbf{a}_{1}^{\mathsf{H}} &= zm(z) \mathbf{a}^{*} (\mathbf{I}_{\mathcal{N}} + \mathbf{P})^{-\frac{1}{2}} \mathbf{U}_{\mathcal{S}} \\ \mathbf{a}_{2} &= m(z) \mathbf{\Omega} (\mathbf{I}_{\mathcal{K}} + \mathbf{\Omega})^{-1} \mathbf{U}_{\mathcal{S}}^{\mathsf{H}} (\mathbf{I}_{\mathcal{N}} + \mathbf{P})^{-\frac{1}{2}} \mathbf{a} \end{cases}$$

which after development is

$$T_i = \sum_{\ell=1}^{K} \frac{1}{1+\omega_{\ell}} \frac{1}{2\pi \iota} \oint_{\mathcal{C}_i} \frac{zm^2(z)}{\frac{1+\omega_{\ell}}{\omega_{\ell}} + zm(z)} dz.$$

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• Using residue calculus, the sole pole is in ρ_i and we find

$$\mathbf{a}(\theta)^{\mathsf{H}} \hat{\mathbf{u}}_{i} \hat{\mathbf{u}}_{i}^{\mathsf{H}} \mathbf{a}(\theta) \xrightarrow{\mathrm{a.s.}} \frac{1 - c \omega_{i}^{-2}}{1 + c \omega_{i}^{-1}} \mathbf{a}(\theta)^{\mathsf{H}} \mathbf{u}_{i} \mathbf{u}_{i}^{\mathsf{H}} \mathbf{a}(\theta).$$

Therefore,

$$\hat{\eta}(\boldsymbol{\theta}) = \boldsymbol{a}(\boldsymbol{\theta})^{\mathsf{H}} \hat{\boldsymbol{\Pi}} \boldsymbol{a}(\boldsymbol{\theta}) \xrightarrow{\mathrm{a.s.}} \boldsymbol{a}(\boldsymbol{\theta}) \boldsymbol{a}(\boldsymbol{\theta})^{\mathsf{H}} - \sum_{i=1}^{K} \frac{1 - c \omega_{i}^{-2}}{1 + c \omega_{i}^{-1}} \boldsymbol{a}(\boldsymbol{\theta})^{\mathsf{H}} \boldsymbol{u}_{i} \boldsymbol{u}_{i}^{\mathsf{H}} \boldsymbol{a}(\boldsymbol{\theta})$$

Improved G-MUSIC

Recall that:

$$\mathbf{a}(\theta)^{\mathsf{H}}\mathbf{u}_{k}\mathbf{u}_{k}^{\mathsf{H}}\mathbf{a}(\theta) - \frac{1 + c\omega_{k}^{-1}}{1 - c\omega_{k}^{-2}}\mathbf{a}(\theta)^{\mathsf{H}}\hat{\mathbf{u}}_{k}\hat{\mathbf{u}}_{k}^{\mathsf{H}}\mathbf{a}(\theta) \xrightarrow{\text{a.s.}} \mathbf{0}$$

ightarrow The ω_k are however unknown. But they can be estimated from

$$\lambda_k \xrightarrow{\mathrm{a.s.}} \rho_k = 1 + \omega_k + c(1 + \omega_k)\omega_k^{-1}$$

 \rightarrow This gives finally

$$\hat{\eta}_{\boldsymbol{G}}(\boldsymbol{\theta}) \simeq \boldsymbol{a}(\boldsymbol{\theta})^{\mathsf{H}} \boldsymbol{a}(\boldsymbol{\theta}) - \sum_{k=1}^{K} \frac{1 + c \hat{\boldsymbol{\omega}}_{k}^{-1}}{1 - c \hat{\boldsymbol{\omega}}_{k}^{-2}} \boldsymbol{a}(\boldsymbol{\theta})^{\mathsf{H}} \hat{\boldsymbol{u}}_{k} \hat{\boldsymbol{u}}_{k}^{\mathsf{H}} \boldsymbol{a}(\boldsymbol{\theta})$$

with

$$\hat{\omega}_k = \frac{\hat{\lambda}_k - (c+1)}{2} + \sqrt{(c+1-\hat{\lambda}_k)^2 - 4c)}$$

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with

$$\hat{\omega}_k = \frac{\hat{\lambda}_k - (c+1)}{2} + \sqrt{(c+1-\hat{\lambda}_k)^2 - 4c)}$$

 \rightarrow We then obtain another (N, n)-consistent MUSIC estimator, only valid for K finite!

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Simulation results

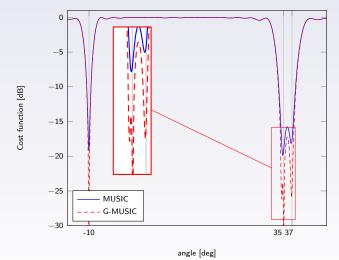


Figure: MUSIC against G-MUSIC for DoA detection of K = 3 signal sources, N = 20 sensors, M = 150 samples, SNR of 10 dB. Angles of arrival of 10°, 35°, and 37°.

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Covariance estimation and sample covariance matrices

P.J. Huber, "Robust Statistics", 1981.

 \longrightarrow Many statistical inference techniques rely on the sample covariance matrix (SCM) taken from i.i.d. observations x_1, \ldots, x_n of a r.v. $x \in \mathbb{C}^N$.

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The main reasons are:

Assuming E[x] = 0, $E[xx^*] = C_N$, with $X = [x_1, \dots, x_n]$, by the LLN

$$\hat{S}_N \triangleq \frac{1}{n} X X^* \stackrel{\text{a.s.}}{\longrightarrow} C_N \text{ as } n \to \infty.$$

 \rightarrow Hence, if $\theta = f(C_N)$, we often use the *n*-consistent estimate $\hat{\theta} = f(\hat{S}_N)$.

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- ► The SCM \hat{S}_N is the ML estimate of C_N for Gaussian x→ One therefore expects $\hat{\theta}$ to closely approximate θ for all finite n.
- This approach however has two limitations:
 - if N, n are of the same order of magnitude,

$$\|\hat{S}_N - C_N\| \not\to 0$$
 as $N, n \to \infty, N/n \to c > 0$, so that in general $|\hat{\theta} - \theta| \not\to 0$

- \rightarrow This motivated the introduction of G-estimators.
- if x is not Gaussian, but has heavier tails, \hat{S}_N is a poor estimator for C_N .
 - \rightarrow This motivated the introduction of robust estimators.

J. T. Kent, D. E. Tyler, "Redescending M-estimates of multivariate location and scatter", 1991.
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- \rightarrow The objectives of robust estimators:
 - Replace the SCM \hat{S}_N by another estimate \hat{C}_N of C_N which:
 - rejects (or downscales) observations deterministically
 - or rejects observations inconsistent with the full set of observations
 - \rightarrow **Example**: Huber estimator, \hat{C}_N defined as solution of

$$\hat{C}_N = \frac{1}{n} \sum_{i=1}^n \beta_i x_i x_i^* \text{ with } \beta_i = \alpha \min\left\{1, \frac{k^2}{\frac{1}{N} x_i^* \hat{C}_N^{-1} x_i}\right\} \text{ for some } \alpha > 1, k^2 \text{ function of } \hat{C}_N.$$

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- Provide scale-free estimators of C_N :
 - \rightarrow **Example**: Tyler's estimator: if one observes $x_i = \tau_i z_i$ for unknown scalars τ_i ,

$$\hat{C}_N = \frac{1}{n} \sum_{i=1}^n \frac{1}{\frac{1}{N} x_i^* \hat{C}_N^{-1} x_i} x_i x_i^*$$

- existence and uniqueness of \hat{C}_N defined up to a constant.
- Fiew constraints on x_1, \ldots, x_n (N + 1 of them must be linearly independent)

 \rightarrow The objectives of robust estimators:

- replace the SCM \hat{S}_N by the ML estimate for C_N .
 - \rightarrow **Example**: Maronna's estimator for elliptical x

$$\hat{C}_N = \frac{1}{n} \sum_{i=1}^n u\left(\frac{1}{N} x_i^* \hat{C}_N^{-1} x_i\right) x_i x_i^*$$

with u(s) such that

(i) u(s) is continuous and non-increasing on $[0,\infty)$ (ii) $\varphi(s) = su(s)$ is non-decreasing, bounded by $\varphi_{\infty} > 1$. Moreover, $\varphi(s)$ increases where $\varphi(s) < \varphi_{\infty}$. (note that Huber's estimator is compliant with Maronna's estimators)

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(note that Huber's estimator is compliant with Maronna's estimators)

- existence is not too demanding
- uniqueness imposes strictly increasing u(s) (inconsistent with Huber's estimate)
- consistency result: $\hat{C}_N \to C_N$ if u(s) meets the ML estimator for C_N .

Robust Estimation and RMT

 \rightarrow So far, RMT has mostly focused on the SCM \hat{S}_N .

• $x = A_N w$, w having i.i.d. zero-mean unit variance entries,

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Robust RMT estimation

Can we study the performance of estimators based on the \hat{C}_N ?

- what are the spectral properties of \hat{C}_N ?
- can we generate RMT-based estimators relying on \hat{C}_N ?

Setting and assumptions

Assumptions:

- ▶ Take $x_1, ..., x_n \in \mathbb{C}^N$ "elliptical-like" random vectors, i.e. $x_i = \sqrt{\tau_i} C_N^{\frac{1}{2}} w_i$ where
 - $\tau_1, \ldots, \tau_n \in \mathbb{R}^+$ random or deterministic with $\frac{1}{n} \sum_{i=1}^n \tau_i \xrightarrow{\text{a.s.}} 1$
 - $w_1, \ldots, w_n \in \mathbb{C}^N$ random independent with w_i / \sqrt{N} uniformly distributed over the unit-sphere
 - $C_N \in \mathbb{C}^{N \times N}$ deterministic, with $C_N \succ 0$ and $\limsup_N ||C_N|| < \infty$
- ▶ We denote $c_N \triangleq N/n$ and consider the growth regime $c_N \rightarrow c \in (0, 1)$.

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- Maronna's estimator of scatter: (almost sure) unique solution to

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where u satisfies

- (i) $u: [0,\infty) \to (0,\infty)$ nonnegative continuous and non-increasing
- (ii) $\phi: x \mapsto xu(x)$ increasing and bounded with $\lim_{x\to\infty} \phi(x) \triangleq \phi_{\infty} > 1$ (iii) $\phi_{\infty} < c_{\perp}^{-1}$.

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- (iii) $\phi_{\infty} < c_{+}^{-1}$.
- Additional technical assumption: Let $v_n \triangleq \frac{1}{n} \sum_{i=1}^n \delta_{\tau_i}$. For each a > b > 0, a.s.

$$\limsup_{t\to\infty}\frac{\limsup_n\nu_n((t,\infty))}{\phi(at)-\phi(bt)}=0.$$

 \rightarrow Controls relative speed of the tail of v_n versus the flattening speed of $\varphi(x)$ as $x \rightarrow \infty$. Examples:

- $\tau_i < M$ for each *i*. In this case, $\nu_n((t, \infty)) = 0$ a.s. for t > M.
- For $u(t) = (1 + \alpha)/(\alpha + t)$, $\alpha > 0$, and τ_i i.i.d., it is sufficient to have $E[\tau_1^{1+\epsilon}] < \infty$.

- Major issues with \hat{C}_N :
 - Defined implicitly

Sum of non-independent rank-one matrices from vectors $\sqrt{u(\frac{1}{N}x_i^*\hat{C}_N^{-1}x_i)x_i}$ (\hat{C}_N depends on all x_j 's).

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Sum of non-independent rank-one matrices from vectors $\sqrt{u(\frac{1}{N}x_i^*\hat{C}_N^{-1}x_i)}x_i$ (\hat{C}_N depends on all x_j 's).

- But there is some hope:
 - First remark: we can work with $C_N = I_N$ without generality restriction!
 - Denote

$$\hat{C}_{(j)} = \frac{1}{n} \sum_{i \neq j}^{n} u\left(\frac{1}{N} x_i^* \hat{C}_N^{-1} x_i\right) x_i x_i^*$$

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Our heuristic approach:

• Rewrite
$$\frac{1}{N}x_i^*\hat{C}_N^{-1}x_i$$
 as $f(\frac{1}{N}x_i^*\hat{C}_{(i)}^{-1}x_i)$ for some function f (later called g^{-1})

Deduce that

$$\hat{C}_{N} = \frac{1}{n} \sum_{i=1}^{n} (u \circ f) \left(\frac{1}{N} x_{i}^{*} \hat{C}_{(i)}^{-1} x_{i} \right) x_{i} x_{i}^{*}$$

• Use $\frac{1}{N} x_i^* \hat{C}_{(i)}^{-1} x_i \simeq \tau_i \frac{1}{N} \operatorname{tr} \hat{C}_N^{-1}$ to get

$$\hat{C}_N \simeq \frac{1}{n} \sum_{i=1}^n (u \circ f) \left(\tau_i \frac{1}{N} \operatorname{tr} \hat{C}_N^{-1} \right) x_i x_i^*$$

• Use random matrix results to find a limiting value γ for $\frac{1}{N}$ tr \hat{C}_N^{-1} , and conclude

$$\hat{C}_N \simeq \frac{1}{n} \sum_{i=1}^n (u \circ f)(\tau_i \gamma) x_i x_i^*.$$

Heuristic approach in detail: f and γ

• Determination of f: Recall the identity $(A + tvv^*)^{-1}v = A^{-1}/(1 + tv^*A^{-1}v)$. Then

$$\frac{1}{N}x_i^*\hat{C}_N^{-1}x_i = \frac{\frac{1}{N}x_i^*\hat{C}_{(i)}^{-1}x_i}{1 + c_N u(\frac{1}{N}x_i^*\hat{C}_N^{-1}x_i)\frac{1}{N}x_i^*\hat{C}_{(i)}^{-1}x_i}$$

so that

$$\frac{1}{N}x_{i}^{*}\hat{C}_{(i)}^{-1}x_{i} = \frac{\frac{1}{N}x_{i}^{*}\hat{C}_{N}^{-1}x_{i}}{1 - c_{N}\phi(\frac{1}{N}x_{i}^{*}\hat{C}_{N}^{-1}x_{i})}.$$

Now the function $g: x \mapsto x/(1 - c_N \phi(x))$ is monotonous increasing (we use the assumption $\phi_{\infty} < c^{-1}$!), hence, with $f = g^{-1}$,

$$\frac{1}{N} x_i^* \hat{C}_N^{-1} x_i = g^{-1} \left(\frac{1}{N} x_i^* \hat{C}_{(i)}^{-1} x_i \right).$$

Heuristic approach in detail: f and γ

Determination of γ : From previous calculus, we expect

$$\hat{C}_N \simeq \frac{1}{n} \sum_{i=1}^n (u \circ g^{-1}) \left(\tau_i \frac{1}{N} \operatorname{tr} \hat{C}_N^{-1} \right) x_i x_i^* \simeq \frac{1}{n} \sum_{i=1}^n (u \circ g^{-1}) (\tau_i \gamma) x_i x_i^*.$$

Hence

$$\gamma \simeq \frac{1}{N} \operatorname{tr} \hat{C}_N^{-1} \simeq \frac{1}{N} \operatorname{tr} \left(\frac{1}{n} \sum_{i=1}^n (u \circ g^{-1}) (\tau_i \gamma) \tau_i w_i w_i^* \right)^{-1}$$

Since τ_i are independent of w_i and γ deterministic, this is a Bai-Silverstein model

$$\frac{1}{n}WDW^*, W = [w_1, \ldots, w_n], D = \operatorname{diag}(D_{ii}) = u \circ g^{-1}(\tau_i \gamma).$$

And we have:

$$\begin{split} \gamma \simeq \frac{1}{N} \mathrm{tr} \, \left(\frac{1}{n} W D W^*\right)^{-1} &= m_{\frac{1}{n} W D W^*}(0) \simeq \left(0 + \int \frac{t(u \circ g^{-1})(t\gamma)}{1 + c(u \circ g^{-1})(t\gamma) m_{\frac{1}{n} W D W^*}(0)} v_N(dt)\right)^{-1} \\ &= \left(\frac{1}{n} \sum_{i=1}^n \frac{\tau_i(u \circ g^{-1})(\tau_i \gamma)}{1 + c\tau_i(u \circ g^{-1})(\tau_i \gamma) m_{\frac{1}{n} W D W^*}(0)}\right)^{-1}. \end{split}$$

Since $\gamma\simeq m_{\frac{1}{n}WDW^*}(0),$ this defines γ as a solution of a fixed-point equation:

$$\gamma = \left(\frac{1}{n} \sum_{i=1}^{n} \frac{\tau_i(u \circ g^{-1})(\tau_i \gamma)}{1 + c\tau_i(u \circ g^{-1})(\tau_i \gamma)\gamma}\right)^{-1}.$$

Main result

R. Couillet, F. Pascal, J. W. Silverstein, "The Random Matrix Regime of Maronna's M-estimator with elliptically distributed samples", (submitted to) Elsevier Journal of Multivariate Analysis.

Theorem (Asymptotic Equivalence)

Under the assumptions defined earlier, we have

$$\left\|\hat{C}_{N}-\hat{S}_{N}\right\| \xrightarrow{\text{a.s.}} 0, \text{ where } \hat{S}_{N} \triangleq \frac{1}{n} \sum_{i=1}^{n} v(\tau_{i}\gamma) x_{i} x_{i}^{i}$$

 $v(x)=(u\circ g^{-1})(x), \ \psi(x)=xv(x), \ g(x)=x/(1-c\varphi(x)) \ \text{and} \ \gamma>0 \ \text{unique solution of}$

$$1 = \frac{1}{n} \sum_{i=1}^{n} \frac{\psi(\tau_i \gamma)}{1 + c \psi(\tau_i \gamma)}.$$

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 - Th. says: first order substitution of \hat{C}_N by \hat{S}_N allowed for large N, n.
 - It turns out that v ~ u and ψ ~ φ in general behavior.
 - Corollaries:

$$\max_{1 \leq i \leq n} \left| \lambda_i(\hat{S}_N) - \lambda_i(\hat{C}_N) \right| \stackrel{\text{a.s.}}{\to} 0$$

$$\frac{1}{V} \operatorname{tr}(\hat{C}_N - zI_N)^{-1} - \frac{1}{N} \operatorname{tr}(\hat{S}_N - zI_N)^{-1} \stackrel{\text{a.s.}}{\to} 0$$

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 \rightarrow Important feature for detection and estimation.

Proof: So far in the tutorial, we do not have a rigorous proof!

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Fundamental idea: Showing that all $\frac{1}{\tau_i} \frac{1}{N} x_i^* \hat{C}_{(i)}^{-1} x_i$ converge to the same limit γ .



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- **Technical trick:** Denote

$$\mathbf{e}_{i} \triangleq \frac{\mathbf{v}\left(\frac{1}{N}\mathbf{x}_{i}^{*}\hat{C}_{(i)}^{-1}\mathbf{x}_{i}\right)}{\mathbf{v}(\tau_{i}\gamma)}$$

and relabel terms such that

$$e_1 \leqslant \ldots \leqslant e_n$$

We shall prove that, for each $\ell > 0$,

$$e_1 > 1 - \ell$$
 i.o. and $e_n < 1 + \ell$ i.o.

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► Some basic inequalities: Denoting $d_i \triangleq \frac{1}{\tau_i} \frac{1}{N} x_i^* \hat{C}_{(i)}^{-1} x_i = \frac{1}{N} w_i^* \hat{C}_{(i)}^{-1} w_i$, we have

$$e_{j} = \frac{v\left(\tau_{j}\frac{1}{N}w_{j}^{*}\left(\frac{1}{n}\sum_{i\neq j}\tau_{i}v(\tau_{i}d_{i})w_{i}w_{i}^{*}\right)^{-1}w_{j}\right)}{v(\tau_{j}\gamma)} = \frac{v\left(\tau_{j}\frac{1}{N}w_{j}^{*}\left(\frac{1}{n}\sum_{i\neq j}\tau_{i}v(\tau_{i}\gamma)e_{i}w_{i}w_{i}^{*}\right)^{-1}w_{j}\right)}{v(\tau_{j}\gamma)}$$

$$\leq \frac{v\left(\tau_{j}\frac{1}{N}w_{j}^{*}\left(\frac{1}{n}\sum_{i\neq j}\tau_{i}v(\tau_{i}\gamma)e_{n}w_{i}w_{i}^{*}\right)^{-1}w_{j}\right)}{v(\tau_{j}\gamma)} = \frac{v\left(\frac{\tau_{j}}{e_{n}}\frac{1}{N}w_{j}^{*}\left(\frac{1}{n}\sum_{i\neq j}\tau_{i}v(\tau_{i}\gamma)w_{i}w_{i}^{*}\right)^{-1}w_{j}\right)}{v(\tau_{j}\gamma)}$$

Proof

Specialization to *e_n*:

$$e_n \leqslant \frac{\nu\left(\frac{\tau_n}{e_n}\frac{1}{N}w_n^*\left(\frac{1}{n}\sum_{i\neq n}\tau_i\nu(\tau_i\gamma)w_iw_i^*\right)^{-1}w_n\right)}{\nu(\tau_n\gamma)}$$

or equivalently, recalling $\psi(x) = x v(x)$,

$$\frac{\frac{1}{N}w_{n}^{*}\left(\frac{1}{n}\sum_{i\neq n}\tau_{i}v(\tau_{i}\gamma)w_{i}w_{i}^{*}\right)^{-1}w_{n}}{\gamma} \leq \frac{\psi\left(\frac{\tau_{n}}{e_{n}}\frac{1}{N}w_{n}^{*}\left(\frac{1}{n}\sum_{i\neq n}\tau_{i}v(\tau_{i}\gamma)w_{i}w_{i}^{*}\right)^{-1}w_{n}\right)}{\psi(\tau_{n}\gamma)}$$

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- Random Matrix results:
 - By trace lemma, we should have

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- DANGER: by relabeling, w_n no longer independent of w₁,..., w_{n-1}! ⇒ Broken trace lemma!
- Solution: uniform convergence result.
 By (higher order) moment bounds, Markov inequality, and Borel Cantelli, for all large n a.s.

$$\max_{1 \leq j \leq n} \left| \frac{1}{N} w_j^* \left(\frac{1}{n} \sum_{i \neq j} \tau_i v(\tau_i \gamma) w_i w_i^* \right)^{-1} w_j - \gamma \right| < \varepsilon.$$

• Back to original problem: For all large *n* a.s., we then have (using growth of ψ)

$$\frac{\gamma - \varepsilon}{\gamma} \leqslant \frac{\psi\left(\frac{\tau_n}{e_n}(\gamma + \varepsilon)\right)}{\psi(\tau_n \gamma)}$$



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▶ Bounded support for τ_i : If $0 < \tau_- < \tau_i < \tau_+ < \infty$ for all *i*, *n*, then on a subsequence where $\tau_n \rightarrow \tau_0$,

$$\underbrace{\frac{\gamma-\epsilon}{\gamma}}_{\rightarrow 1 \text{ as } \epsilon \rightarrow 0} \leqslant \underbrace{\frac{\psi\left(\frac{\tau_0}{1+\ell}\left(\gamma+\epsilon\right)\right)}{\psi(\tau_0\gamma)}}_{\rightarrow \frac{\psi\left(\frac{\tau_0}{1+\ell}\gamma\right)}{\psi(\tau_0\gamma)} < 1 \text{ as } \epsilon \rightarrow 0} \text{ CONTRADICTION!}$$

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• Unbounded support for τ_i : Importance of relative growth of τ_n versus convergence of ψ to ψ_{∞} . Proof consists in dividing $\{\tau_i\}$ in two groups: few large ones versus all others. Sufficient condition:

$$\limsup_{t \to \infty} \frac{\limsup_{n \to \infty} \nu_n((t, \infty))}{\varphi(at) - \varphi(bt)} = 0$$

92/142

Simulations

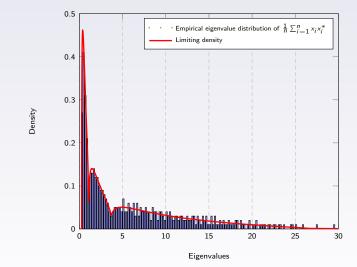


Figure: Histogram of the eigenvalues of $\frac{1}{n}\sum_{i=1}^{n} x_i x_i^*$ for n = 2500, N = 500, $C_N = \text{diag}(I_{125}, 3I_{125}, 10I_{250})$, τ_1 with $\Gamma(.5, 2)$ -distribution.

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Simulations

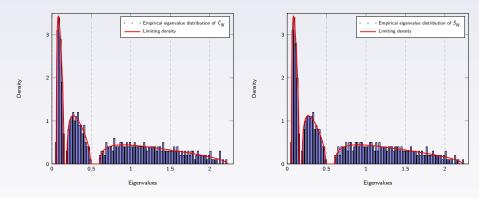


Figure: Histogram of the eigenvalues of \hat{C}_N (left) and \hat{S}_N (right) for n = 2500, N = 500, $C_N = \text{diag}(I_{125}, 3I_{125}, 10I_{250})$, τ_1 with $\Gamma(.5, 2)$ -distribution.

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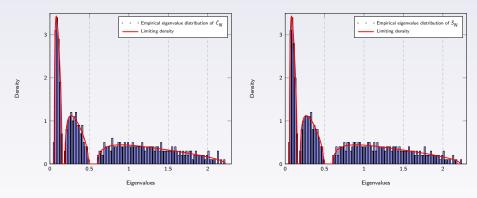


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Remark/Corollary: Spectrum of \hat{C}_N a.s. bounded uniformly on *n*.

Hint on potential applications

Spectrum boundedness: for impulsive noise scenarios,

- SCM spectrum grows unbounded
- robust scatter estimator spectrum remains bounded

 \Rightarrow Robust estimators improve spectrum separability (important for many statistical inference techniques seen previously)

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Application scenarios:

- Radar detection in impulsive noise (non-Gaussian noise, possibly clutter)
- Financial data analytics
- Any application where Gaussianity is too strong an assumption...

Outline

Part 1: Fundamentals of Random Matrix Theory

- 1.1. The Stieltjes Transform Method
- 1.2 Extreme eigenvalues
- 1.3 Extreme eigenvalues: the spiked models
- 1.4 Spectrum Analysis and G-estimation

Application to Signal Sensing and Array Processing

- 2.1 Eigenvalue-based detectior
- 2.2 The spiked G-MUSIC algorithm

Advanced Random Matrix Models for Robust Estimation

- 3.1 Robust Estimation of Scatter
- 3.2 Spiked model extension and robust G-MUSIC
- 3.3 Robust shrinkage and application to mathematical finance
- 3.4 Optimal robust GLRT detectors

Future Directions

- 4.1 Kernel matrices and kernel methods
- 4.2 Neural networks

System Setting

Signal model:

$$y_i = \sum_{l=1}^{L} \sqrt{p_l} a_l s_{li} + \sqrt{\tau_i} w_i = A_i \bar{w}_i$$
$$A_i \triangleq \left[\sqrt{p_1} a_1 \quad \dots \quad \sqrt{p_L} a_L \quad \sqrt{\tau_i} I_N \right], \quad \bar{w}_i \triangleq \left[s_{1i}, \dots, s_{Li}, w_i \right]^{\mathsf{T}}.$$

with $y_1, \ldots, y_n \in \mathbb{C}^N$ satisfying:

- 1. $\tau_1, \ldots, \tau_n > 0$ random such that $\nu_n \triangleq \frac{1}{n} \sum_{i=1}^n \delta_{\tau_i} \to \nu$ weakly and $\int t\nu(dt) = 1$;
- 2. $w_1, \ldots, w_n \in \mathbb{C}^N$ random independent unitarily invariant \sqrt{N} -norm;
- 3. $L \in \mathbb{N}$, $p_1 \ge \ldots \ge p_L \ge 0$ deterministic;
- 4. $a_1, \ldots, a_L \in \mathbb{C}^N$ deterministic or random with $A^*A \xrightarrow{\text{a.s.}} \text{diag}(p_1, \ldots, p_L)$ as $N \to \infty$, with $A \triangleq [\sqrt{p_1}a_1, \ldots, \sqrt{p_L}a_L] \in \mathbb{C}^{N \times L}$.
- 5. $s_{1,1}, \ldots, s_{Ln} \in \mathbb{C}$ independent with zero mean, unit variance.

System Setting

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 - \Rightarrow Elliptical model with covariance a low-rank (L) perturbation of I_N .
 - \Rightarrow We expect a spiked version of previous results.
- Application contexts:
 - wireless communications: signals s_{li} from L transmitters, N-antenna receiver; a_l random i.i.d. channels (a_l^{*} a_l' → δ_{1-l'}, e.g. a_l ~ CN(0, I_N/N));
 - ▶ array processing: L sources emit signals s_{li} at steering angle $a_l = a(\theta_l)$. For ULA,

$$[a(\theta)]_j = N^{-\frac{1}{2}} \exp(2\pi \iota dj \sin(\theta))$$

Some intuition

Signal detection/estimation in impulsive environments: Two scenarios

- heavy-tailed noise (elliptical, Gaussian mixtures, etc.)
- Gaussian noise with spurious impulsions

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 invalidates G-MUSIC
- isolated eigenvalues due to spikes in time direction
 - \Rightarrow False alarms induced by noise impulses!

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- ► isolated eigenvalues due to spikes in *time direction* ⇒ False alarms induced by noise impulses!

Our results: In a spiked model with noise impulsions,

- whatever noise impulsion type, spectrum of \hat{C}_N remains bounded
- isolated largest eigenvalues may appear, two classes:
 - isolated eigenvalues due to noise impulses CANNOT exceed a threshold!
 - all isolated eigenvalues beyond this threshold are due to signal
 - \Rightarrow Detection criterion: everything above threshold is signal.

Theoretical results

Theorem (Extension to spiked robust model)

Under the same assumptions as in previous section,

$$\|\hat{C}_N - \hat{S}_N\| \xrightarrow{\mathrm{a.s.}} 0$$

where

$$\hat{S}_{N} \triangleq \frac{1}{n} \sum_{i=1}^{n} v(\tau_{i}\gamma) A_{i} \bar{w}_{i} \bar{w}_{i}^{*} A_{i}^{*}$$

with γ the unique solution to

$$1 = \int \frac{\psi(t\gamma)}{1 + c\psi(t\gamma)} v(dt)$$

and we recall

$$A_i \triangleq \begin{bmatrix} \sqrt{p_1} a_1 & \dots & \sqrt{p_L} a_L & \sqrt{\tau_i} I_N \end{bmatrix}$$

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$$\bar{w}_i = [s_{1i}, \dots, s_{Li}, w_i]^{\mathsf{T}}.$$

▶ **Remark:** For L = 0, $A_i = [0, ..., 0, I_N]$. ⇒ Recover previous result $A_i \bar{w}_i$ becomes w_i .

Localization of eigenvalues

Theorem (Eigenvalue localization)

Denote

- u_k eigenvector of k-th largest eigenvalue of $AA^* = \sum_{i=1}^{L} p_i a_i a_i^*$
- \hat{u}_k eigenvector of k-th largest eigenvalue of \hat{C}_N

Also define $\delta(\boldsymbol{x})$ unique positive solution to

$$\delta(x) = c \left(-x + \int \frac{t v_c(t\gamma)}{1 + \delta(x) t v_c(t\gamma)} v(dt) \right)^{-1}.$$

Further denote

$$p_{-} \triangleq \lim_{x \downarrow S^{+}} -c \left(\int \frac{\delta(x)v_{c}(t\gamma)}{1 + \delta(x)tv_{c}(t\gamma)} v(dt) \right)^{-1}, \quad S^{+} \triangleq \frac{\phi_{\infty}(1 + \sqrt{c})^{2}}{\gamma(1 - c\phi_{\infty})}.$$

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Then, if $p_j > p_-$, $\hat{\lambda}_j \xrightarrow{a.s.} \Lambda_j > S^+$, otherwise $\limsup_n \hat{\lambda}_j \leq S^+$ a.s., with Λ_j unique positive solution to

$$-c\left(\delta(\Lambda_j)\int \frac{v_c(\tau\gamma)}{1+\delta(\Lambda_j)\tau v_c(\tau\gamma)}\nu(d\tau)\right)^{-1}=p_j.$$

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Simulation

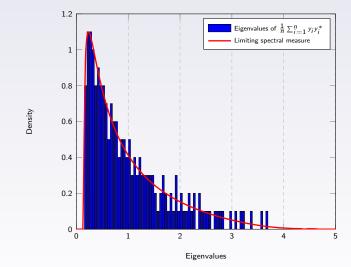


Figure: Histogram of the eigenvalues of $\frac{1}{n}\sum_{i} y_i y_i^*$ against the limiting spectral measure, L = 2, $p_1 = p_2 = 1$, N = 200, n = 1000, Sudent-t impulsions.

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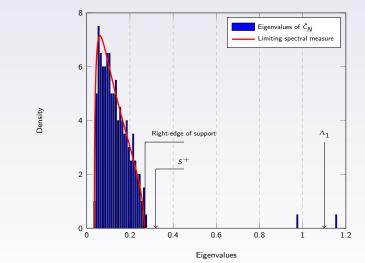


Figure: Histogram of the eigenvalues of \hat{C}_N against the limiting spectral measure, for $u(x) = (1 + \alpha)/(\alpha + x)$ with $\alpha = 0.2$, L = 2, $p_1 = p_2 = 1$, N = 200, n = 1000, Student-t impulsions.

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Comments

 SCM vs robust: Spikes invisible in SCM in impulsive noise, reborn in robust estimate of scatter.

Comments

- SCM vs robust: Spikes invisible in SCM in impulsive noise, reborn in robust estimate of scatter.
- Largest eigenvalues:
 - $\lambda_i(\hat{C}_N) > S^+ \Rightarrow$ Presence of a source!
 - $\lambda_i(\hat{C}_N) \in (\sup(\text{Support}), S^+) \Rightarrow May \text{ be due to a source or to a noise impulse.}$
 - ▶ $\lambda_i(\hat{C}_N) < \sup(\text{Support}) \Rightarrow As usual, nothing can be said.$
 - \Rightarrow Induces a natural source detection algorithm.

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Eigenvalue and eigenvector projection estimates

- Two scenarios:
 - known $v = \lim_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \delta_{\tau_i}$
 - unknown ν

Eigenvalue and eigenvector projection estimates

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 - known $v = \lim_{n \to \infty} \frac{1}{n} \sum_{i=1}^{n} \delta_{\tau_i}$
 - unknown ν

Theorem (Estimation under known ν)

1. Power estimation. For each $p_j > p_-$,

$$-c\left(\delta(\hat{\lambda}_j)\int \frac{v_c(\tau\gamma)}{1+\delta(\hat{\lambda}_j)\tau v_c(\tau\gamma)}\nu(d\tau)\right)^{-1} \xrightarrow{\text{a.s.}} p_j.$$

2. Bilinear form estimation. For each a, $b \in \mathbb{C}^N$ with ||a|| = ||b|| = 1, and $p_j > p_-$

$$\sum_{k,p_k=p_j} a^* u_k u_k^* b - \sum_{k,p_k=p_j} w_k a^* \hat{u}_k \hat{u}_k^* b \xrightarrow{\text{a.s.}} 0$$

where

$$w_{k} = \frac{\int \frac{v_{c}(t\gamma)}{\left(1 + \delta(\hat{\lambda}_{k})tv_{c}(t\gamma)\right)^{2}}v(dt)}{\int \frac{v_{c}(t\gamma)}{1 + \delta(\hat{\lambda}_{k})tv_{c}(t\gamma)}v(dt)\left(1 - \frac{1}{c}\int \frac{\delta(\hat{\lambda}_{k})^{2}t^{2}v_{c}(t\gamma)^{2}}{\left(1 + \delta(\hat{\lambda}_{k})tv_{c}(t\gamma)\right)^{2}}v(dt)\right)}.$$

104/142

Eigenvalue and eigenvector projection estimates

Theorem (Estimation under unknown ν)

1. Purely empirical power estimation. For each $p_j > p_-$,

$$-\left(\hat{\delta}(\hat{\lambda}_j)\frac{1}{N}\sum_{i=1}^n\frac{\nu(\hat{\tau}_i\hat{\gamma}_n)}{1+\hat{\delta}(\hat{\lambda}_j)\hat{\tau}_i\nu(\hat{\tau}_i\hat{\gamma}_n)}\right)^{-1}\xrightarrow{\text{a.s.}}p_j.$$

2. Purely empirical bilinear form estimation. For each a, $b \in \mathbb{C}^N$ with ||a|| = ||b|| = 1, and each $p_j > p_-$,

$$\sum_{k,p_k=p_j} a^* u_k u_k^* b - \sum_{k,p_k=p_j} \hat{w}_k a^* \hat{u}_k \hat{u}_k^* b \xrightarrow{\text{a.s.}} 0$$

where

$$\hat{w}_{k} = \frac{\frac{1}{n} \sum_{i=1}^{n} \frac{v(\hat{\tau}_{i}\hat{\gamma})}{\left(1 + \hat{\delta}(\hat{\lambda}_{k})\hat{\tau}_{i}v(\hat{\tau}_{i}\hat{\gamma})\right)^{2}}}{\frac{1}{n} \sum_{i=1}^{n} \frac{v(\hat{\tau}_{i}\hat{\gamma})}{1 + \hat{\delta}(\hat{\lambda}_{k})\hat{\tau}_{i}v(\hat{\tau}_{i}\hat{\gamma})} \left(1 - \frac{1}{N} \sum_{i=1}^{n} \frac{\hat{\delta}(\hat{\lambda}_{k})^{2}\hat{\tau}_{i}^{2}v(\hat{\tau}_{i}\hat{\gamma})^{2}}{\left(1 + \hat{\delta}(\hat{\lambda}_{k})\hat{\tau}_{i}v(\hat{\tau}_{i}\hat{\gamma})\right)^{2}}\right)}$$
$$\hat{\gamma} \triangleq \frac{1}{n} \sum_{i=1}^{n} \frac{1}{N} y_{i}^{*} \hat{C}_{(i)}^{-1} y_{i}, \quad \hat{\tau}_{i} \triangleq \frac{1}{\hat{\gamma}} \frac{1}{N} y_{i}^{*} \hat{C}_{(i)}^{-1} y_{i}, \quad \hat{\delta}(x) \text{ as } \delta(x) \text{ but for } (\tau_{i}, \gamma) \to (\hat{\tau}_{i}, \hat{\gamma}).$$

105/142

Application to G-MUSIC

• Assume the model $a_i = a(\theta_i)$ with

$$a(\theta) = N^{-\frac{1}{2}} \left[\exp(2\pi \iota dj \sin(\theta)) \right]_{j=0}^{N-1}.$$



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Corollary (Robust G-MUSIC)

Define $\hat{\eta}_{RG}(\theta)$ and $\hat{\eta}_{RG}^{emp}(\theta)$ as

$$\begin{split} \hat{\eta}_{\mathrm{RG}}(\theta) &= 1 - \sum_{k=1}^{|\{j, p_j > p_-\}|} w_k a(\theta)^* \hat{u}_k \hat{u}_k a(\theta) \\ \hat{\eta}_{\mathrm{RG}}^{\mathrm{emp}}(\theta) &= 1 - \sum_{k=1}^{|\{j, p_j > p_-\}|} \hat{w}_k a(\theta)^* \hat{u}_k \hat{u}_k a(\theta). \end{split}$$

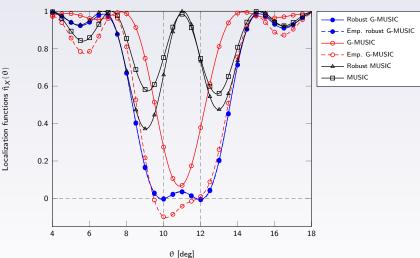
Then, for each $p_i > p_-$,

$$\hat{\theta}_j \xrightarrow{\text{a.s.}} \theta \\ \hat{\theta}_j^{\text{emp}} \xrightarrow{\text{a.s.}} \theta$$

where

$$\hat{\theta}_{j} \triangleq \operatorname{argmin}_{\theta \in \mathcal{R}_{j}^{\kappa}} \{ \hat{\eta}_{\mathrm{RG}}(\theta) \}$$

$$\hat{\theta}_{j}^{\mathrm{emp}} \triangleq \operatorname{argmin}_{\theta \in \mathcal{R}_{j}^{\kappa}} \{ \hat{\eta}_{\mathrm{RG}}^{\mathrm{emp}}(\theta) \} .$$



Simulations: Single-shot in elliptical noise

Figure: Random realization of the localization functions for the various MUSIC estimators, with N = 20, n = 100, two sources at 10° and 12°, Student-t impulsions with parameter $\beta = 100$, $u(x) = (1 + \alpha)/(\alpha + x)$ with $\alpha = 0.2$. Powers $p_1 = p_2 = 10^{0.5} = 5$ dB.



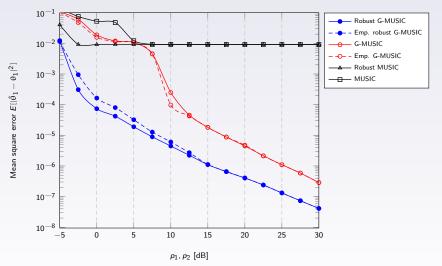
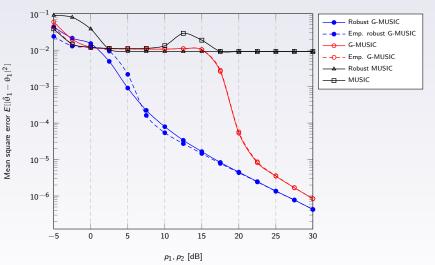


Figure: Means square error performance of the estimation of $\theta_1 = 10^\circ$, with N = 20, n = 100, two sources at 10° and 12° , Student-t impulsions with parameter $\beta = 10$, $u(x) = (1 + \alpha)/(\alpha + x)$ with $\alpha = 0.2$, $p_1 = p_2$.

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Simulations: Spurious impulses

Figure: Means square error performance of the estimation of $\theta_1 = 10^\circ$, with N = 20, n = 100, two sources at 10° and 12° , sample outlier scenario $\tau_i = 1$, i < n, $\tau_n = 100$, $u(x) = (1 + \alpha)/(\alpha + x)$ with $\alpha = 0.2$, $p_1 = p_2$.

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Outline

Part 1: Fundamentals of Random Matrix Theory

- 1.1. The Stieltjes Transform Method
- 1.2 Extreme eigenvalues
- 1.3 Extreme eigenvalues: the spiked models
- 1.4 Spectrum Analysis and G-estimation

Application to Signal Sensing and Array Processing

- 2.1 Eigenvalue-based detectior
- 2.2 The spiked G-MUSIC algorithm

Advanced Random Matrix Models for Robust Estimation

- 3.1 Robust Estimation of Scatter
- 3.2 Spiked model extension and robust G-MUSIC

3.3 Robust shrinkage and application to mathematical finance

3.4 Optimal robust GLRT detectors

Future Directions

- 4.1 Kernel matrices and kernel methods
- 4.2 Neural networks

Context

Ledoit and Wolf, 2004. A well-conditioned estimator for large-dimensional covariance matrices. Pascal, Chitour, Quek, 2013. Generalized robust shrinkage estimator – Application to STAP data. Chen, Wiesel, Hero, 2011. Robust shrinkage estimation of high-dimensional covariance matrices.

Shrinkage covariance estimation: For N > n or $N \simeq n$, shrinkage estimator

$$(1-\rho)\frac{1}{n}\sum_{i=1}^{n}x_{i}x_{i}^{*}+\rho I_{N}, \text{ for some } \rho \in [0,1].$$

- allows for invertibility, better conditioning
- ρ may be chosen to minimize an expected error metric

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- ▶ Maronna and Tyler estimators limited to *N* < *n*, otherwise do not exist
- introducing shrinkage in robust estimator cannot do much harm anyhow...

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- Limitation of Maronna's estimator:
 - ▶ Maronna and Tyler estimators limited to *N* < *n*, otherwise do not exist
 - introducing shrinkage in robust estimator cannot do much harm anyhow...

Introducing the robust-shrinkage estimator: The literature proposes two such estimators

$$\hat{C}_{N}(\rho) = (1-\rho)\frac{1}{n}\sum_{i=1}^{n}\frac{x_{i}x_{i}^{*}}{\frac{1}{N}x_{i}^{*}\hat{C}_{N}^{-1}(\rho)x_{i}} + \rho I_{N}, \ \rho \in (\max\{0, \frac{N-n}{N}\}, 1] \quad (\text{Pascal})$$

$$\check{C}_{N}(\rho) = \frac{\check{B}_{N}(\rho)}{\frac{1}{N}\text{tr}\,\check{B}_{N}(\rho)}, \ \check{B}_{N}(\rho) = (1-\rho)\frac{1}{n}\sum_{i=1}^{n}\frac{x_{i}x_{i}^{*}}{\frac{1}{N}x_{i}^{*}\hat{C}_{N}^{-1}(\rho)x_{i}} + \rho I_{N}, \ \rho \in (0,1] \quad (\text{Chen})$$

Main theoretical result

Which estimator is better?

Having asked to authors of both papers, their estimator was much better than the other, but the arguments we received were quite vague...

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Having asked to authors of both papers, their estimator was much better than the other, but the arguments we received were quite vague...

- Our result: In the random matrix regime, both estimators tend to be one and the same!
- Assumptions: As before, "elliptical-like" model

$$x_i = \tau_i C_N^{\frac{1}{2}} w_i$$

 \rightarrow This time, C_N cannot be taken I_N (due to $+\rho I_N$)!

 \longrightarrow Maronna-based shrinkage is possible but more involved...

Pascal's estimator

Theorem (Pascal's estimator)

For $\varepsilon \in (0, \min\{1, c^{-1}\})$, define $\hat{\mathcal{R}}_{\varepsilon} = [\varepsilon + \max\{0, 1 - c^{-1}\}, 1]$. Then, as $N, n \to \infty$, $N/n \to c \in (0, \infty)$,

$$\sup_{\rho\in\hat{\mathcal{R}}_{\varepsilon}}\left\|\hat{\mathcal{C}}_{N}(\rho)-\hat{\mathcal{S}}_{N}(\rho)\right\|\xrightarrow{\mathrm{a.s.}}0$$

where

$$\hat{C}_{N}(\rho) = (1-\rho)\frac{1}{n}\sum_{i=1}^{n}\frac{x_{i}x_{i}^{*}}{\frac{1}{N}x_{i}^{*}\hat{C}_{N}(\rho)^{-1}x_{i}} + \rho I_{N}$$
$$\hat{S}_{N}(\rho) = \frac{1}{\hat{\gamma}(\rho)}\frac{1-\rho}{1-(1-\rho)c}\frac{1}{n}\sum_{i=1}^{n}C_{N}^{\frac{1}{2}}w_{i}w_{i}^{*}C_{N}^{\frac{1}{2}} + \rho I_{N}$$

and $\hat{\gamma}(\rho)$ is the unique positive solution to the equation in $\hat{\gamma}$

$$1 = \frac{1}{N} \sum_{i=1}^{N} \frac{\lambda_i(C_N)}{\hat{\gamma}\rho + (1-\rho)\lambda_i(C_N)}$$

Moreover, $\rho \mapsto \hat{\gamma}(\rho)$ is continuous on (0, 1].

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Chen's estimator

Theorem (Chen's estimator)

For $\epsilon \in (0,1)$, define $\check{\mathbb{R}}_{\epsilon} = [\epsilon, 1]$. Then, as $N, n \to \infty, N/n \to c \in (0,\infty)$,

ρ

$$\sup_{\in \check{\mathcal{X}}_{\varepsilon}} \left\| \check{\mathcal{C}}_{N}(\rho) - \check{\mathcal{S}}_{N}(\rho) \right\| \stackrel{\text{a.s.}}{\longrightarrow} 0$$

where

$$\begin{split} \check{C}_{N}(\rho) &= \frac{\check{B}_{N}(\rho)}{\frac{1}{N} \operatorname{tr}\check{B}_{N}(\rho)}, \ \check{B}_{N}(\rho) = (1-\rho) \frac{1}{n} \sum_{i=1}^{n} \frac{x_{i}x_{i}^{*}}{\frac{1}{N}x_{i}^{*}\check{C}_{N}(\rho)^{-1}x_{i}} + \rho I_{N} \\ \check{S}_{N}(\rho) &= \frac{1-\rho}{1-\rho+T_{\rho}} \frac{1}{n} \sum_{i=1}^{n} C_{N}^{\frac{1}{2}} w_{i} w_{i}^{*} C_{N}^{\frac{1}{2}} + \frac{T_{\rho}}{1-\rho+T_{\rho}} I_{N} \end{split}$$

in which $T_{\rho}=\rho\check{\gamma}(\rho)F(\check{\gamma}(\rho);\rho)$ with, for all x>0,

$$F(x;\rho) = \frac{1}{2} \left(\rho - c(1-\rho) \right) + \sqrt{\frac{1}{4}} \left(\rho - c(1-\rho) \right)^2 + (1-\rho) \frac{1}{x}$$

and $\check{\gamma}(\rho)$ is the unique positive solution to the equation in $\check{\gamma}$

$$1 = \frac{1}{N} \sum_{i=1}^{N} \frac{\lambda_i(C_N)}{\check{\gamma}\rho + \frac{1-\rho}{(1-\rho)c + F(\check{\gamma};\rho)}\lambda_i(C_N)}$$

Moreover, $\rho \mapsto \check{\gamma}(\rho)$ is continuous on (0, 1].

うせん 前 (中学)(中学)(日)

Asymptotic Model Equivalence

Theorem (Model Equivalence)

For each $\rho\in(0,1],$ there exist unique $\hat{\rho}\in(\text{max}\{0,1-c^{-1}\},1]$ and $\check{\rho}\in(0,1]$ such that

$$\frac{\hat{S}_{N}(\hat{\rho})}{\frac{1}{\hat{\gamma}(\hat{\rho})}\frac{1-\hat{\rho}}{1-(1-\hat{\rho})c}+\hat{\rho}}=\check{S}_{N}(\check{\rho})=(1-\rho)\frac{1}{n}\sum_{i=1}^{n}C_{N}^{\frac{1}{2}}w_{i}w_{i}^{*}C_{N}^{\frac{1}{2}}+\rho I_{N}.$$

 $\textit{Besides, } (0,1] \rightarrow (\text{max}\{0,1-c^{-1}\},1], \ \rho \mapsto \hat{\rho} \textit{ and } (0,1] \rightarrow (0,1], \ \rho \mapsto \check{\rho} \textit{ are increasing and onto.}$

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- Up to normalization, both estimators behave the same!
- Both estimators behave the same as an impulsion-free Ledoit-Wolf estimator

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- Up to normalization, both estimators behave the same!
- Both estimators behave the same as an impulsion-free Ledoit-Wolf estimator
- About uniformity: Uniformity over ρ in the theorems is essential to find optimal values of ρ .

Optimal Shrinkage parameter

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Theorem (Optimal Shrinkage)

For each $\rho \in (0, 1]$, define

$$\hat{D}_{N}(\rho) = \frac{1}{N} tr\left(\left(\frac{\hat{C}_{N}(\rho)}{\frac{1}{N} tr \hat{C}_{N}(\rho)} - C_{N} \right)^{2} \right), \quad \check{D}_{N}(\rho) = \frac{1}{N} tr\left(\left(\check{C}_{N}(\rho) - C_{N} \right)^{2} \right).$$

Denote $D^* = c \frac{M_2 - 1}{c + M_2 - 1}$, $\rho^* = \frac{c}{c + M_2 - 1}$, $M_2 = \lim_{N \to \infty} \frac{1}{N} \sum_{i=1}^N \lambda_i^2(C_N)$ and $\hat{\rho}^*$, $\check{\rho}^*$ unique solutions to

$$\frac{\hat{\rho}^{\star}}{\frac{1}{\hat{\gamma}(\hat{\rho}^{\star})}\frac{1-\hat{\rho}^{\star}}{1-(1-\hat{\rho}^{\star})c}+\hat{\rho}^{\star}}=\frac{\mathcal{T}_{\check{\rho}^{\star}}}{1-\check{\rho}^{\star}+\mathcal{T}_{\check{\rho}^{\star}}}=\rho^{\star}$$

Then, letting ε small enough,

$$\begin{split} \inf_{\rho \in \hat{\mathcal{R}}_{\varepsilon}} \hat{D}_{N}(\rho) & \xrightarrow{\text{a.s.}} D^{\star}, \quad \inf_{\rho \in \check{\mathcal{R}}_{\varepsilon}} \check{D}_{N}(\rho) & \xrightarrow{\text{a.s.}} D^{\star} \\ \hat{D}_{N}(\hat{\rho}^{\star}) & \xrightarrow{\text{a.s.}} D^{\star}, \quad \check{D}_{N}(\check{\rho}^{\star}) & \xrightarrow{\text{a.s.}} D^{\star}. \end{split}$$

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Estimating $\hat{\rho}^{\star}$ and $\check{\rho}^{\star}$

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- Careful control of the proofs provide many ways to estimate these.
- Proposition below provides one example.

Estimating $\hat{\rho}^*$ and $\check{\rho}^*$

- Theorem only useful if ρ^{*} and ρ^{*} can be estimated!
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Optimal Shrinkage Estimate

Let $\hat{\rho}_N \in (\max\{0, 1 - c^{-1}\}, 1]$ and $\check{\rho}_N \in (0, 1]$ be solutions (not necessarily unique) to

$$\frac{\hat{\rho}_{N}}{\frac{1}{N} \operatorname{tr} \hat{C}_{N}(\hat{\rho}_{N})} = \frac{c_{N}}{\frac{1}{N} \operatorname{tr} \left[\left(\frac{1}{n} \sum_{i=1}^{n} \frac{x_{i} x_{i}^{*}}{\frac{1}{N} ||x_{i}||^{2}} \right)^{2} \right] - 1}$$
$$\frac{\check{\rho}_{N} \frac{1}{n} \sum_{i=1}^{n} \frac{x_{i}^{*} \check{C}_{N}(\check{\rho}_{N})^{-1} x_{i}}{||x_{i}||^{2}}}{1 - \check{\rho}_{N} + \check{\rho}_{N} \frac{1}{n} \sum_{i=1}^{n} \frac{x_{i}^{*} \check{C}_{N}(\check{\rho}_{N})^{-1} x_{i}}{\frac{1}{N} \operatorname{tr} \left[\left(\frac{1}{n} \sum_{i=1}^{n} \frac{x_{i} x_{i}^{*}}{\frac{1}{N} ||x_{i}||^{2}} \right)^{2} \right] - 1}$$

defined arbitrarily when no such solutions exist. Then

$$\hat{\rho}_{N} \xrightarrow{\text{a.s.}} \hat{\rho}^{*}, \ \check{\rho}_{N} \xrightarrow{\text{a.s.}} \check{\rho}^{*}$$
$$\hat{D}_{N}(\hat{\rho}_{N}) \xrightarrow{\text{a.s.}} D^{*}, \ \check{D}_{N}(\check{\rho}_{N}) \xrightarrow{\text{a.s.}} D^{*}.$$

116/142

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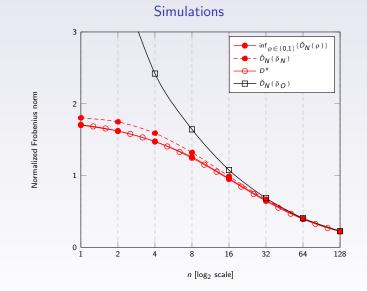


Figure: Performance of optimal shrinkage averaged over 10000 Monte Carlo simulations, for N = 32, various values of n, $[C_N]_{ij} = r^{|i-j|}$ with r = 0.7; $\check{\rho}_N$ as above; $\check{\rho}_O$ the clairvoyant estimator proposed in (Chen'11).

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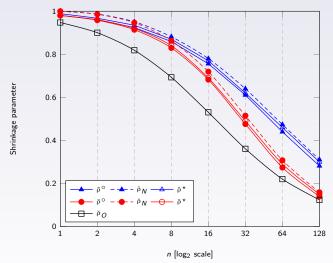


Figure: Shrinkage parameter ρ averaged over 10000 Monte Carlo simulations, for N = 32, various values of n, $[C_N]_{ij} = r^{|i-j|}$ with r = 0.7; $\hat{\rho}_N$ and $\check{\rho}_N$ as above; $\check{\rho}_O$ the clairvoyant estimator proposed in (Chen'11); $\hat{\rho}^\circ = \operatorname{argmin}_{\{\rho \in (0,1]\}} \{\hat{D}_N(\rho)\}$.

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Context

- Hypothesis testing problem: Two sets of data
 - Initial pure-noise data: x₁,..., x_n, x_i = √τ_iC_N^{1/2} w_i as before.
 New incoming data y given by:

$$y = \begin{cases} x & , \mathcal{H}_0 \\ \alpha p + x & , \mathcal{H}_1 \end{cases}$$

with $x = \sqrt{\tau} C_N^{\frac{1}{2}} w$, $p \in \mathbb{C}^N$ deterministic known, α unknown.

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GLRT detection test:

$$T_N(\rho) \stackrel{\mathcal{H}_1}{\underset{\mathcal{H}_0}{\overset{\mathcal{H}_1}{\lesssim}}} \Gamma$$

for some detection threshold Γ where

$$T_N(\rho) \triangleq \frac{|y^* \hat{C}_N^{-1}(\rho)p|}{\sqrt{y^* \hat{C}_N^{-1}(\rho)y} \sqrt{p^* \hat{C}_N^{-1}(\rho)p}}$$

and $\hat{C}_N(\rho)$ defined in previous section.

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and $\hat{C}_N(\rho)$ defined in previous section.

- \longrightarrow In fact, originally found to be $\hat{C}_N(0)$ but
 - only valid for N < n</p>
 - introducing ρ may bring improved for arbitrary N/n ratios.

Initial observations:

▶ As $N, n \to \infty$, $N/n \to c > 0$, under \mathcal{H}_0 ,

$$T_N(\rho) \xrightarrow{\text{a.s.}} 0.$$

 \Rightarrow Trivial result of little interest!

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Turns out the correct non-trivial object is, for γ > 0 fixed

$$P\left(\sqrt{N}T_N(\rho) > \gamma\right) = \min(\rho)$$

Objectives:

for each ρ, develop central limit theorem to evaluate

$$\lim_{\substack{N,n\to\infty\\N/n\to c}} P\left(\sqrt{N}T_N(\rho) > \gamma\right)$$

- determine limiting minimizing ρ
- empirically estimate minimizing ρ

122/142

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What do we need?

CLT over \hat{C}_N statistics

- We know that $\|\hat{C}_N(\rho) \hat{S}_N(\rho)\| \xrightarrow{\text{a.s.}} 0$ \longrightarrow Key result so far!
- What about $\|\sqrt{N}(\hat{C}_N(\rho) \hat{S}_N(\rho))\|$?

122/142

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$$\sqrt{N}(a^*\hat{C}_N^{-1}(\rho)b - a^*\hat{S}_N^{-1}(\rho)b) \xrightarrow{\text{a.s.}} 0$$

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This requires much more delicate treatment, not discussed in this tutorial.

123/142

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Main results

Theorem (Fluctuation of bilinear forms)

Let $a, b \in \mathbb{C}^N$ with ||a|| = ||b|| = 1. Then, as $N, n \to \infty$ with $N/n \to c > 0$, for any $\varepsilon > 0$ and every $k \in \mathbb{Z}$,

$$\sup_{\rho \in \mathcal{R}_{\kappa}} N^{1-\varepsilon} \left| a^* \hat{C}_N^k(\rho) b - a^* \hat{S}_N^k(\rho) b \right| \xrightarrow{\text{a.s.}} 0$$

where $\Re_{\kappa} = [\kappa + \max\{0, 1 - 1/c\}, 1].$

False alarm performance

Theorem (Asymptotic detector performance) As $N, n \to \infty$ with $N/n \to c \in (0, \infty)$,

$$\sup_{\rho \in \mathcal{R}_{\kappa}} \left| P\left(T_{N}(\rho) > \frac{\gamma}{\sqrt{N}} \right) - \exp\left(-\frac{\gamma^{2}}{2\sigma_{N}^{2}(\hat{\rho})} \right) \right| \to 0$$

where $\rho\mapsto\hat{\rho}$ is the aforementioned mapping and

$$\sigma_N^2(\hat{\rho}) \triangleq \frac{1}{2} \frac{p^* C_N Q_N^2(\hat{\rho}) p}{p^* Q_N(\hat{\rho}) p \cdot \frac{1}{N} \operatorname{tr} C_N Q_N(\hat{\rho}) \cdot (1 - c(1 - \rho)^2 m(-\hat{\rho})^2 \frac{1}{N} \operatorname{tr} C_N^2 Q_N^2(\hat{\rho}))}$$

with $Q_N(\hat{\rho}) \triangleq (I_N + (1 - \hat{\rho})m(-\hat{\rho})C_N)^{-1}$.

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with $Q_N(\hat{\rho}) \triangleq (I_N + (1 - \hat{\rho})m(-\hat{\rho})C_N)^{-1}$.

- ► Limiting Rayleigh distribution ⇒ Weak convergence to Rayleigh variable $R_N(\hat{\rho})$
- Remark: σ_N and ρ̂ not a function of γ ⇒ There exists a uniformly optimal ρ!

Simulation

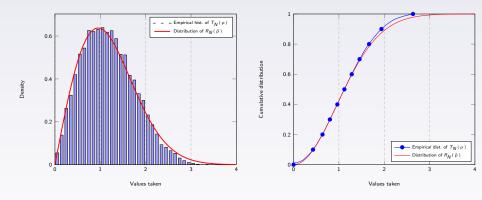


Figure: Histogram distribution function of the $\sqrt{N}T_N(\rho)$ versus $R_N(\hat{\rho})$, N = 20, $p = N^{-\frac{1}{2}}[1, ..., 1]^{\mathsf{T}}$, C_N Toeplitz from AR of order 0.7, $c_N = 1/2$, $\rho = 0.2$.

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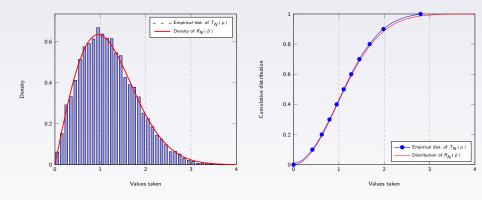


Figure: Histogram distribution function of the $\sqrt{N}T_N(\rho)$ versus $R_N(\hat{\rho})$, N = 100, $\rho = N^{-\frac{1}{2}}[1, ..., 1]^{\mathsf{T}}$, C_N Toeplitz from AR of order 0.7, $c_N = 1/2$, $\rho = 0.2$.

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Empirical estimation of optimal ρ

- Optimal ρ can be found by line search... but C_N unknown!
- We shall successively:
 - empirical estimate σ_N(ρ̂)
 - minimize the estimate
 - prove by uniformity asymptotic optimality of estimate

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 - prove by uniformity asymptotic optimality of estimate

Theorem (Empirical performance estimation) For $\rho \in (\max\{0, 1 - c_N^{-1}\}, 1)$, let

$$\hat{\sigma}_{N}^{2}(\hat{\rho}) \triangleq \frac{1}{2} \frac{1 - \hat{\rho} \cdot \frac{\rho^{*} \hat{c}_{N}^{-2}(\rho)\rho}{\rho^{*} \hat{c}_{N}^{-1}(\rho)\rho} \cdot \frac{1}{N} tr \hat{C}_{N}(\rho)}{\left(1 - c + c\hat{\rho} \frac{1}{N} tr \hat{C}_{N}^{-1}(\rho) \cdot \frac{1}{N} tr \hat{C}_{N}(\rho)\right) \left(1 - \hat{\rho} \frac{1}{N} tr \hat{C}_{N}^{-1}(\rho) \cdot \frac{1}{N} tr \hat{C}_{N}(\rho)\right)}$$

Also let $\hat{\sigma}_N^2(1) \triangleq \lim_{\hat{\rho}\uparrow 1} \hat{\sigma}_N^2(\hat{\rho})$. Then

$$\sup_{\rho \in \mathcal{R}_{\kappa}} \left| \sigma_{N}^{2}(\hat{\rho}) - \hat{\sigma}_{N}^{2}(\hat{\rho}) \right| \xrightarrow{\text{a.s.}} 0.$$

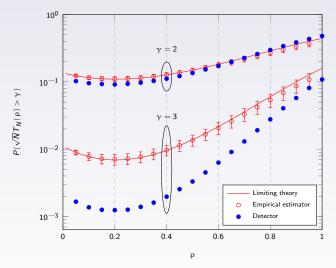
Final result

Theorem (Optimality of empirical estimator) *Define*

$$\hat{\rho}_N^* = \operatorname{argmin}_{\{\rho \in \mathcal{R}_\kappa'\}} \left\{ \hat{\sigma}_N^2(\hat{\rho}) \right\}.$$

Then, for every $\gamma > 0$,

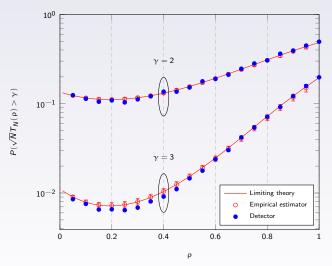
$$P\left(\sqrt{N}T_{N}(\hat{\rho}_{N}^{*}) > \gamma\right) - \inf_{\rho \in \mathcal{R}_{\kappa}} \left\{ P\left(\sqrt{N}T_{N}(\rho) > \gamma\right) \right\} \to 0.$$



Simulations

Figure: False alarm rate $P(\sqrt{N}T_N(\rho) > \gamma)$, N = 20, $\rho = N^{-\frac{1}{2}}[1, ..., 1]^T$, C_N Toeplitz from AR of order 0.7, $c_N = 1/2$.

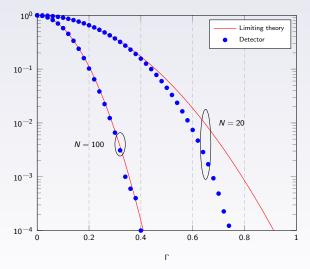
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Figure: False alarm rate $P(T_N(\rho) > \Gamma)$ for N = 20 and N = 100, $p = N^{-\frac{1}{2}}[1, ..., 1]^{\mathsf{T}}$, $[C_N]_{ij} = 0.7^{|i-j|}$, $c_N = 1/2$.

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- ▶ **Objective:** Clustering data $x_1, ..., x_n \in \mathbb{C}^N$ in k similarity classes
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134/142

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 - assumes similarity function, e.g. Gaussian kernel

$$f(x_i, x_j) = \exp\left(-\frac{\|x_i - x_j\|^2}{2\sigma^2}\right)$$

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Motivation: Spectral Clustering

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$$\left\| W - \left(\alpha \mathbf{1} \mathbf{1}^{\mathsf{T}} - \beta \, \frac{1}{n} W W^* \right) \right\| \stackrel{\text{a.s.}}{\longrightarrow} \mathbf{0}$$

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for some α , β depending on f and its derivatives. \Rightarrow Basically, W gets equivalent to a rank-one matrix.

Motivation: Spectral Clustering

Clustering x₁,..., x_n in k often written as:

(RatioCut)
$$\min_{\substack{S_1,\ldots,S_k\\S_1,\ldots,\cup S_k=8\\\forall i\neq j, S_i\cap S_j=\emptyset}} \sum_{i=1}^k \sum_{\substack{j\in S_i, \overline{j}\in S_i^c\\ |S_i|}} \frac{f(x_j, x_{\overline{j}})}{|S_i|}.$$

 \longrightarrow But difficult to solve, NP hard!



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Can be equivalently rewritten

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$$\min_{M \in \mathcal{M}, \ M^{\mathsf{T}}M = I_{k}} \operatorname{tr} \left(M^{\mathsf{T}}LM \right)$$

where $\mathcal{M} = \{M = [m_{ij}]_{1 \leqslant i \leqslant n, 1 \leqslant j \leqslant k}, m_{ij} = |S_j|^{-\frac{1}{2}} \delta_{x_i \in S_j}\}$ and

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▶ Relaxing *M* to unitary leads to a simple eigenvalue/eigenvector problem: ⇒ Spectral clustering.

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Objectives

- Generalization to k distributions for x_1, \ldots, x_n should lead to asymptotically rank-k W matrices.
- ► If established, specific choices of known "good" kernel better understood.
- Eventually, find optimal choices for kernels.

Outline

Part 1: Fundamentals of Random Matrix Theory

- 1.1. The Stieltjes Transform Method
- 1.2 Extreme eigenvalues
- 1.3 Extreme eigenvalues: the spiked models
- 1.4 Spectrum Analysis and G-estimation

Application to Signal Sensing and Array Processing

- 2.1 Eigenvalue-based detectior
- 2.2 The spiked G-MUSIC algorithm

Advanced Random Matrix Models for Robust Estimation

- 3.1 Robust Estimation of Scatter
- 3.2 Spiked model extension and robust G-MUSIC
- 3.3 Robust shrinkage and application to mathematical finance
- 3.4 Optimal robust GLRT detectors

Future Directions

- 4.1 Kernel matrices and kernel methods
- 4.2 Neural networks

Echo-state neural networks

Neural network:

- ▶ Input neuron signal $s_t \in \mathbb{R}$ (could be multivariate)
- Output neuron signal $y_t \in \mathbb{R}$ (could be multivariate)
- N neurons with
 - $\blacktriangleright \quad \text{state } x_t \in \mathbb{R}^N \text{ at time } t$
 - connectivity matrix $W \in \mathbb{R}^{N \times N}$
 - connectivity vector to input $w_I \in \mathbb{R}^N$
 - connectivity vector to output $w_O \in \mathbb{R}^N$
- State evolution x₀ = 0 (say) and

$$x_{t+1} = S\left(Wx_t + w_Is_t\right)$$

with S entry-wise sigmoid function.

Output observation

$$y_t = w_0^T x_t.$$

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Classical neural networks:

- Learning phase: input-output data (s_t, y_t) used to learn W, w_0, w_l (via e.g. LS)
- ▶ Interpolation phase: W, w_0, w_l fixed, we observe output y_t from new data s_t .
- \Rightarrow Poses overlearning problems, difficult to set up, demands lots of learning data.

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- \Rightarrow Poses overlearning problems, difficult to set up, demands lots of learning data.
- Echo-state neural networks: To solve the problems of neural networks
 - W and w_l set to be a random matrix, no longer learned
 - only w_O is learned

 \Rightarrow Reduces amount of data to learn, shows striking performances in some scenarios.

▶ W, w_l being random, performance study involves random matrices. ⇒ Stability, chaos regime, etc. involve extreme eigenvalues of W

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- Performance measures:
 - MSE for training data
 - MSE for interpolated data

 \Rightarrow Optimization to be performed on regression method!, e.g.

$$w_{O} = (X_{\text{train}} X_{\text{train}}^{T} + \gamma I_{N})^{-1} X_{\text{train}} y_{\text{train}}$$

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• In first approximation: S = Id.

 \Rightarrow MSE performance with stationary inputs leads to study

$$\sum_{j=1}^{\infty} W^j w_l w_l^{\mathsf{T}} (W^{\mathsf{T}})^j$$

 \Rightarrow New random matrix model, can be analyzed with usual tools though.

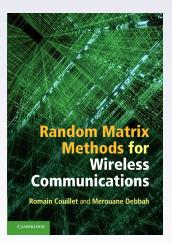
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