Crash Course on Random Matrix Theory Part I: Basic notions and applications to wireless communications Morning Session: Basic notions of RMT

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SUPELEC

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Outline

General Introduction to the Course

From Small to Large Dimensional Random Matrices

Moment Methods and Free Probability

The Stieltjes Transform Method Definition and results Proof of the Marčenko-Pastur law

Deterministic Equivalents

Definition and method Toy example: Sum of doubly-correlated i.i.d. matrices A Central Limit Theorem

Research Today: Iterative Deterministic Equivalents

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From the law of large numbers, as $n \to \infty$,

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with $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n] \in \mathbb{C}^{N \times n}$.

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• if $n \gg N$,

$$\mathbf{R}_n = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i \mathbf{x}_i^{\mathsf{H}}$$

is a "good" estimator of **R**.

▶ if N/n = O(1), and if both (n, N) are large, we can still say, for all (i, j),

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What about the global behaviour? What about the eigenvalue distribution? Assume $\mathbf{R} = \mathbf{I}_N$ and draw the eigenvalues of \mathbf{R}_n for n, N large.

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Empirical and limit spectra of Wishart matrices



Figure: Histogram of the eigenvalues of \mathbf{R}_n for n = 2000, N = 500, $\mathbf{R} = \mathbf{I}_N$

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Definitions

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Let Ω be some probability space, and let $\omega \in \Omega$. A random matrix $\mathbf{X} = \mathbf{X}(\omega)$ is a random variable whose value lies in some matrix space.

Note:

- \blacktriangleright the probability space Ω is often neglected; it is e.g. the propagation environment for MIMO channel matrices.
- for asymptotic considerations, $\omega \in \Omega$ will be the realization of an infinite sequence $X_1(\omega), X_2(\omega), \ldots$ of size $1, 2, \ldots$ random matrices.

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In practice, we are mostly interested into Hermitian matrices and especially in the distribution of their eigenvalues.

Definition

The distribution function F_N of the eigenvalues of the $N \times N$ random Hermitian matrix $\mathbf{X}_N = \mathbf{X}_N(\omega)$ is called the empirical spectrum distribution (e.s.d.) of \mathbf{X}_N . If F_N has a limit F when $N \to \infty$, this limit is called the limit spectral distribution of \mathbf{X}_N .

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Finite size and asymptotic considerations

The field of random matrices is often segmented into

- Finite-size random matrices:
 - of interest are: joint entry distributions, ordered eigenvalue distributions, e.s.d., expectation of functionals
 - particularly suitable to small size matrices
 - however, much problems arise for models more involved than i.i.d. Gaussian

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 - however, much problems arise for models more involved than i.i.d. Gaussian
- Limiting results:
 - of interest are: limit spectral distributions (l.s.d.), functionals of l.s.d., central limit theorems etc.
 - suitable to large matrices, but often good approximation to smaller matrices
 - much easier to work with than finite size, more flexible (i.i.d., Kronecker, variance profile models, structured matrices)
 - possesses a variety of powerful tools: Stieltjes transform, free probability

Remark: This course will mainly focus on limiting results and almost no finite size considerations.

Why is this useful to wireless communications?

- increasing number of parameters: multi-user systems, multiple concurrent cells, multiple antennas
- matrices with random entries are the basis for MIMO channels, CDMA codes
- it is no longer possible to treat large dimensional problems with classical probability approaches
- random matrices answer a widening panel of problems: system performance, detection, estimation...

Example

MIMO channel capacity Call $\mathbf{H} \in \mathbb{C}^{n \times N}$ the realization of a MIMO channel matrix whose entries and distributed according to some random process. We have the per-antenna mutual information

$$C(\sigma^2) = \frac{1}{N} \log \det \left[\mathbf{I}_N + \frac{1}{\sigma^2} \mathbf{H} \mathbf{H}^{\mathsf{H}} \right]$$

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Note that, with \mathbf{h}_i the *i*th column of \mathbf{H} , $\mathbf{H}\mathbf{H}^{H} = \sum_{i=1}^{N} \mathbf{h}_i \mathbf{h}_i^{H}$. If \mathbf{H} has i.i.d. entries, then, as both $n, N \to \infty, n/N \to c$,

$$C(\sigma^2) \rightarrow \int \log\left[1 + \frac{t}{\sigma^2}\right] dF_c(t)$$

with F_c the Marčenko-Pastur law with parameter c.

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Wishart matrices

J. Wishart, "The generalized product moment distribution in samples from a normal multivariate population", Biometrika, vol. 20A, pp. 32-52, 1928.

First random matrix considerations date back to Wishart (1928) who studies the joint distribution of *Gaussian sample covariance matrices* R_n = XX^H = ∑ⁿ_{i=1} x_ix^H_i, x_i ∈ C^N ~ N(0, R),

$$P_{\mathbf{R}_n}(\mathbf{B}) = \frac{\pi^{N(N-1)/2}}{\det \mathbf{R}^n \prod_{i=1}^N (n-i)!} e^{-\operatorname{tr}(\mathbf{R}^{-1}\mathbf{B})} \det \mathbf{B}^{n-N}$$

Subsequent work provide expressions of the joint and marginal eigenvalue distributions,

$$P_{(\lambda_i)}(\lambda_1,\ldots,\lambda_N) = \frac{\det(\{e^{-r_j^{-1}\lambda_i}\}_N)}{\Delta(\mathbf{R}^{-1})}\Delta(\mathbf{L})\prod_{j=1}^N \frac{\lambda_j^{n-N}}{j!(n-j)!}$$

with $r_1 \ge \ldots \ge r_N$ the eigenvalues of **R** and $L = \text{diag}(\lambda_1 \ge \ldots \ge \lambda_N)$ and

$$p_{\lambda}(\lambda) = \frac{1}{M} \sum_{k=0}^{N-1} \frac{k!}{(k+n-N)!} [L_k^{n-N}]^2 \lambda^{n-N} e^{-\lambda}$$

where L_n^k are the Laguerre polynomials defined as

$$L_n^k(\lambda) = \frac{e^{\lambda}}{k!\lambda^n} \frac{d^k}{d\lambda^k} (e^{-\lambda} \lambda^{n+k})$$

Marčenko-Pastur law, Semi-circle law, Full circle law...

V. A. Marčenko, L. A. Pastur, "Distributions of eigenvalues for some sets of random matrices", Math USSR-Sbornik, vol. 1, no. 4, pp. 457-483, 1967.

▶ If $\mathbf{X}_N \in \mathbb{C}^{N \times n}$ has i.i.d. entries of mean 0, variance 1/n, then (almost surely) $F^{\mathbf{X}_N \mathbf{X}_N^H} \Rightarrow F_c$ as $N, n \to \infty, N/n \to c$, with F_c the Marčenko-Pastur law with density

$$f_c(x) = (1 - c^{-1})^+ \delta(x) + \frac{1}{2\pi c x} \sqrt{(x - a)^+ (b - x)^+}, \quad a = (1 - \sqrt{c})^2, \ b = (1 + \sqrt{c})^2.$$

E. Wigner, "Characteristic vectors of bordered matrices with infinite dimensions," The annals of mathematics, vol. 62, pp. 546-564, 1955.

▶ If $\mathbf{X}_N \in \mathbb{C}^{N \times N}$ is Hermitian with i.i.d. entries of mean 0, variance 1/N, then (almost surely) $F^{\mathbf{X}_N} \Rightarrow F$ where F has density f the semi-circle law

$$f(x) = \frac{1}{2\pi} \sqrt{(4 - x^2)^+}.$$

If X_N ∈ C^{N×N} has with i.i.d. 0 mean, variance 1/N entries, then asymptotically its complex eigenvalues distribute uniformly on the complex unit circle.

Marčenko-Pastur law



Figure: Histogram of the eigenvalues of \mathbf{R}_n for n = 2000, N = 500, $\mathbf{R} = \mathbf{I}_N$

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Semi-circle law



Figure: Histogram of the eigenvalues of Wigner matrices and the semi-circle law, for N = 500

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- ▶ For $\mathbf{X} \in \mathbb{C}^{N \times N}$ Hermitian with $X_{ij} \sim \mathcal{CN}(0, 1/N)$, the limiting density f of the eigenvalues

$$\begin{split} &\lim_{\mathsf{N}\to\infty}\frac{1}{\mathsf{N}}\mathsf{tr}\,(\mathbf{X}^{2k+1})=\mathbf{0}\\ &\lim_{\mathsf{N}\to\infty}\frac{1}{\mathsf{N}}\mathsf{tr}\,(\mathbf{X}^{2k})=\frac{1}{k+1}C_k^{2l} \end{split}$$

known as the Catalan numbers.

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These are exactly the moments of a semi-cicle distribution!

$$\begin{split} \alpha_{2k} &= \frac{1}{\pi} \int_{-2}^{2} x^{2k} \sqrt{4 - x^2} dx = -\frac{1}{2\pi} \int_{-2}^{2} \frac{-x}{\sqrt{4 - x^2}} x^{2k - 1} (4 - x^2) dx \\ &= \frac{1}{2\pi} \int_{-2}^{2} \sqrt{4 - x^2} (x^{2k - 1} (4 - x^2))' dx = 4(2k - 1) \alpha_{2k - 2} - (2k + 1) \alpha_{2k}. \end{split}$$

which gives the recursive relation

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Proof impractical for more involved models

Difficult in general to move from moments to distributions / to compute the moments directly.

Circular law



Figure: Eigenvalues of X_N with i.i.d. standard Gaussian entries, for N = 500.

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More involved matrix models

- > much study has surrounded the Marčenko-Pastur law, the Wigner semi-circle law etc.
- for practical purposes, we often need more general matrix models
 - products and sums of random matrices
 - i.i.d. models with correlation/variance profile
 - distribution of inverses etc.

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Tools for random matrix theory

To study these models, a consistent powerful mathematical framework is required.

Related bibliography

- E. Wigner, "Characteristic vectors of bordered matrices with infinite dimensions," The Annals of Mathematics, vol. 62, no. 3, pp. 548-564, 1955.
- V. A. Marčenko and L. A. Pastur, "Distributions of eigenvalues for some sets of random matrices," Math USSR-Sbornik, vol. 1, no. 4, pp. 457-483, 1967.
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- T. Ratnarajah and R. Vaillancourt, "Complex singular Wishart matrices and applications," Computers and Mathematics with Applications, vol. 50, no. 3-4, pp. 399-411, 2005.

Various approaches used to deal with random matrices.

Asymptotic spectrum:

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Tools for RMT

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 - Orthogonal polynomials and Fredholm determinants: study hole probability, e.g. extreme eigenvalue distribution through determinantal equations [e.g. Johnstone, Tracy, Widom, Guionnet]
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DAY 2 – Afternoon:

- Apply eigenspectrum analysis and eigen-inference methods to signal processing.
- Study of hypothesis tests in small/large dimensional random matrix scenarios.
- Study of eigen-inference methods to extend subspace methods: distance/DoA estimation.

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$$c_k(A+B) = c_k(A) + c_k(B)$$

with $c_k(X)$ the cumulants of X (polynomial functions of the moments m_k of X).

• The cumulants c_n are connected to the moments m_n through formulas invoking partitions,

$$m_n = \sum_{\pi \in \mathcal{P}(n)} \prod_{V \in \pi} c_{|V|}$$

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with $c_k(X)$ the cumulants of X (polynomial functions of the moments m_k of X).

• The cumulants c_n are connected to the moments m_n through formulas invoking partitions,

$$m_n = \sum_{\pi \in \mathcal{P}(n)} \prod_{V \in \pi} c_{|V|}$$

If A, B are Hermitian matrices, we feel that, if they have independent entries, there should exist a relationship between the *eigenvalue distribution moments* M_k(A + B) = E_ω[M̂_k(A(ω) + B(ω))]

- Moments of eigenvalue distributions,
 - The e.s.d. of an $N \times N$ Hermitian matrix $\mathbf{X}_N(\omega)$ has successive *empirical* moments \hat{M}_k , k = 1, 2, ...,

$$\hat{M}_k = \frac{1}{N} \sum_{i=1}^N \lambda_i^k$$

• if F_N denotes the e.s.d. of $\mathbf{X}_N(\omega)$, M_k is

$$\hat{M}_k = \int \lambda^k dF(\lambda)$$

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Free probability

An extension to non-commutative random variables exists: Free probability.

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Free probability

D. V. Voiculescu, K. J. Dykema, A. Nica, "Free random variables," American Mathematical Society, 1992.

Free probability applies to asymptotically large random matrices. We assume here all matrices have infinite size

- ▶ To connect the moments of $\mathbf{A} + \mathbf{B}$ to those of \mathbf{A} and \mathbf{B} , independence is not enough. One needs for $\mathbf{A} = \mathbf{A}(\omega)$ and $\mathbf{B}(\omega)$ to be realizations of free sub-algebras of random matrices. Roughly speaking, \mathbf{A} and \mathbf{B} need to be independent and to have "disconnected eigen-directions".
 - two Gaussian matrices are free
 - a Gaussian matrix and any deterministic matrix are free
 - unitary (Haar distributed) matrices are free
 - a Haar matrix and a Gaussian matrix are free etc.

Free probability

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 - two Gaussian matrices are free
 - a Gaussian matrix and any deterministic matrix are free
 - unitary (Haar distributed) matrices are free
 - a Haar matrix and a Gaussian matrix are free etc.
- Similarly as in classical probability, we define free cumulants C_k ,

$$C_1 = M_1$$

$$C_2 = M_2 - M_1^2$$

$$C_3 = M_3 - 3M_1M_2 + 2M_1^2$$

 A combinatorial description of the relation moments-cumulants invokes non-crossing partitions,

$$M_n = \sum_{\pi \in \mathcal{NC}(n)} \prod_{V \in \pi} C_{|V|}$$

Non-crossing partitions



Figure: Non-crossing partition $\pi = \{\{1, 3, 4\}, \{2\}, \{5, 6, 7\}, \{8\}\}$ of *NC*(8).

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Moments of sums and products of random matrices

R. Speicher, "Combinatorial theory of the free product with amalgamation and operator-valued free probability theory," Mem. A.M.S., vol. 627, 1998.

Combinatorial calculus of all moments

Theorem

For free random matrices A and B, we have the relationship,

$$C_k(\mathbf{A} + \mathbf{B}) = C_k(\mathbf{A}) + C_k(\mathbf{B})$$

$$M_n(\mathbf{AB}) = \sum_{(\pi_1, \pi_2) \in NC(n)} \prod_{\substack{V_1 \in \pi_1 \\ V_2 \in \pi_2}} C_{|V_1|}(\mathbf{A}) C_{|V_2|}(\mathbf{B})$$

in conjunction with free moment-cumulant formula, gives all moments of sum and product.

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in conjunction with free moment-cumulant formula, gives all moments of sum and product.

• Denote $m_F(z)$ the moment-generating function of the l.s.d. *F* of a random Hermitian matrix **X**, also called *Stieltjes transform*,

$$m_F(z) = -\sum_{k=0}^{\infty} M_k z^{-k-1}$$

▶ If *F* is a compactly supported distribution function, then m_F above exists for all $z \in \mathbb{C}^*$ and gives access to *F* through an inverse Stieltjes-transform formula.

Free convolution

▶ In classical probability theory, for independent A, B,

$$f_{A+B}(x) = f_A(x) * f_B(x) \triangleq \int f_A(t) f_B(x-t) dt$$

▶ In free probability, for free A, B, we use the notations

$$\mu_{\textbf{A}+\textbf{B}}=\mu_{\textbf{A}}\boxplus\mu_{\textbf{B}},\ \mu_{\textbf{A}}=\mu_{\textbf{A}+\textbf{B}}\boxplus\mu_{\textbf{B}},\ \mu_{\textbf{A}\textbf{B}}=\mu_{\textbf{A}}\boxtimes\mu_{\textbf{B}},\ \mu_{\textbf{A}}=\mu_{\textbf{A}+\textbf{B}}\boxtimes\mu_{\textbf{B}}$$

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▶ In free probability, for free A, B, we use the notations

$$\mu_{\textbf{A}+\textbf{B}} = \mu_{\textbf{A}} \boxplus \mu_{\textbf{B}}, \ \mu_{\textbf{A}} = \mu_{\textbf{A}+\textbf{B}} \boxminus \mu_{\textbf{B}}, \ \mu_{\textbf{A}\textbf{B}} = \mu_{\textbf{A}} \boxtimes \mu_{\textbf{B}}, \ \mu_{\textbf{A}} = \mu_{\textbf{A}+\textbf{B}} \boxtimes \mu_{\textbf{B}}$$

Ø. Ryan, M. Debbah, "Multiplicative free convolution and information-plus-noise type matrices," Arxiv preprint math.PR/0702342, 2007.

Theorem

Convolution of the information-plus-noise model Let $\mathbf{X}_N \in \mathbb{C}^{N \times n}$ have i.i.d. Gaussian entries of mean 0 and variance 1, $\mathbf{R}_N \in \mathbb{C}^{N \times n}$, such that $\mu_{\frac{1}{n}\mathbf{R}_N\mathbf{R}_N^H} \Rightarrow \mu_{\Gamma}$, as $n/N \to c$. Then the e.s.d. of

$$\mathbf{B}_{N} = \frac{1}{n} \left(\mathbf{R}_{N} + \sigma \mathbf{X}_{N} \right) \left(\mathbf{R}_{N} + \sigma \mathbf{X}_{N} \right)^{\mathsf{H}}$$

converges weakly and almost surely to μ_B such that

$$\mu_{B} = \left(\left(\mu_{\Gamma} \boxtimes \mu_{c} \right) \boxplus \delta_{\sigma^{2}} \right) \boxtimes \mu_{c}$$

with μ_c the Marčenko-Pastur law.

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Similarities between classical and free probability

	Classical Probability	Free probability
Moments	$m_k = \int x^k dF(x)$	$M_k = \int x^k dF(x)$
Cumulants	$m_n = \sum_{i \in V} \prod_{i \in V_i} c_{iV_i}$	$M_n = \sum \prod C_{ V }$
	$\pi \in \mathcal{P}(n) V \in \pi$	$\pi \in \mathcal{NC}(n) V \in \pi$
Independence	classical independence	freeness
Additive convolution	$f_{A+B} = f_A * f_B$	$\mu_{\mathbf{A}+\mathbf{B}} = \mu_{\mathbf{A}} \boxplus \mu_{\mathbf{B}}$
Multiplicative convolution	f _{AB}	$\mu_{\textbf{A}\textbf{B}} = \mu_{\textbf{A}} \boxtimes \mu_{\textbf{B}}$
Sum Rule	$c_k(A+B) = c_k(A) + c_k(B)$	$C_k(\mathbf{A} + \mathbf{B}) = C_k(\mathbf{A}) + C_k(\mathbf{B})$
Central Limit	$\frac{1}{\sqrt{n}}\sum_{i=1}^{n}x_{i}\rightarrow \mathcal{N}(0,1)$	$\frac{1}{\sqrt{n}}\sum_{i=1}^n X_i \Rightarrow$ semi-circle law

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General Introduction to the Course

From Small to Large Dimensional Random Matrices

Moment Methods and Free Probability

The Stieltjes Transform Method

Definition and results Proof of the Marčenko-Pastur law

Deterministic Equivalents

Definition and method Toy example: Sum of doubly-correlated i.i.d. matrices A Central Limit Theorem

Research Today: Iterative Deterministic Equivalents

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The Stieltjes transform

Definition

Let *F* be a probability distribution function. The Stieltjes transform m_F of *F* is the function defined, for $z \in \mathbb{C}^+$, as

$$m_F(z) = \int \frac{1}{\lambda - z} dF(\lambda)$$

For a < b real, denoting z = x + iy, we have the inverse formula

$$F(b) - F(a) = \lim_{y \to 0} \frac{1}{\pi} \int_{a}^{b} \Im[m_{F}(x + iy)] dx$$

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If F has a density f, then

$$f(x) = \lim_{y \to 0} \frac{1}{\pi} \Im[m_F(x + iy)]$$

Remark on the Stieltjes transform

▶ If F is the e.s.d. of a Hermitian matrix $\mathbf{X} \in \mathbb{C}^{N \times N}$, we might denote $m_{\mathbf{X}} \triangleq m_{F}$, and

$$m_{\mathbf{X}}(z) = \int \frac{1}{\lambda - z} dF(\lambda) = \frac{1}{N} \sum_{i=1}^{N} \frac{1}{\lambda_i - z} = \frac{1}{N} \operatorname{tr} \left(\operatorname{diag}(\{\lambda_i\}_{i=1}^{N}) - z \mathbf{I}_N \right)^{-1} = \frac{1}{N} \operatorname{tr} \left(\mathbf{X}_N - z \mathbf{I}_N \right)^{-1}$$

For compactly supported F, $m_F(z)$ is linked to the moments $M_k = E[\frac{1}{N} \operatorname{tr} (\mathbf{X}^k)]$

$$m_F(z) = -\sum_{k=0}^{\infty} M_k z^{-k-1}$$

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The Stieltjes transform is more powerful than the moment approach!

- ▶ conveys more information than any K-finite sequence M₁,..., M_K.
- is not handicapped by the support compactness constraint.
- ▶ However, Stieltjes transform methods, while stronger, are more painful to work with.

Properties of the Stieltjes transform

- m_F defined in general on \mathbb{C}^+ but exists everywhere outside the support of F.
- ▶ if $\mathbf{X} \in \mathbb{C}^{N \times n}$, the spectral distribution of $\mathbf{X}\mathbf{X}^{\mathsf{H}}$ and $\mathbf{X}^{\mathsf{H}}\mathbf{X}$ only differ by a mass of |N n| zeros. Say $N \ge n$,

$$m_{\mathbf{XX}^{\mathsf{H}}}(z) = \frac{1}{N} \sum_{i=1}^{N} \frac{1}{\lambda_{i} - z} = \frac{1}{N} \sum_{i=1}^{n} \frac{1}{\lambda_{i} - z} + \frac{1}{N} (N - n) \frac{-1}{z}$$

hence

$$m_{\mathbf{X}\mathbf{X}^{\mathsf{H}}}(z) = \frac{n}{N}m_{\mathbf{X}^{\mathsf{H}}\mathbf{X}} - \frac{N-n}{N}\frac{1}{z}$$

Asymptotic results using the Stieltjes transform

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

Theorem

Let $\underline{\mathbf{B}}_N = \mathbf{X}_N \mathbf{T}_N \mathbf{X}_N^{\mathsf{H}} \in \mathbb{C}^{N \times N}$, where $\mathbf{X}_N \in \mathbb{C}^{N \times n}$ has i.i.d. entries of mean 0 and variance 1/N, $F^{\mathsf{T}_N} \Rightarrow F^{\mathsf{T}}$ and $n/N \to c$. Then, F^{B_N} converges weakly and almost surely to \underline{F} with Stieltjes transform

$$m_{\underline{F}}(z) = \left(c \int \frac{t}{1 + tm_{\underline{F}}(z)} dF^{T}(t) - z\right)^{-1}$$

whose solution is unique in the set $\{z \in \mathbb{C}^+, m_{\underline{F}}(z) \in \mathbb{C}^+\}$.

The proof of a more general theorem will be given later in this course.

- ▶ in general, no explicit expression for <u>F</u>.
- the theorem above characterizes also the Stieltjes transform of $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}} \mathbf{X}_N^H \mathbf{X}_N \mathbf{T}_N^{\frac{1}{2}}$ with asymptotic distribution *F*,

$$m_F = cm_{\underline{F}} + (c-1)\frac{1}{z}$$

This gives access to the spectrum of the sample covariance matrix model of y, when $y_i = T_N^{\frac{1}{2}} x_i$, x_i i.i.d., $T_N = E[yy^H]$.

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• Remember that, for a < b real,

$$F'(x) = \lim_{y \to 0} \frac{1}{\pi} \Im[m_F(x + iy)]$$

where m_F is (up to now) only defined on \mathbb{C}^+ . (we will show in Part 3 that it can be somehow extended to \mathbb{C}^*)

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- to plot the density F',
 - ▶ first approach: span z = x + iy on the line $\{x \in \mathbb{R}, y = \varepsilon\}$ parallel but close to the real axis, solve $m_F(z)$ for each z, and plot $\Im[m_F(z)]$.

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 - refined approach: see second part of the course.

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Example (Sample covariance matrix)

For N multiple of 3, let $F'^{\mathsf{T}_N}(x) = \frac{1}{3}\delta(x-1) + \frac{1}{3}\delta(x-3) + \frac{1}{3}\delta(x-K)$ and let $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}} \mathbf{X}_N^{\mathsf{H}} \mathbf{X}_N \mathbf{T}_N^{\frac{1}{2}}$ with $F^{\mathbf{B}_N} \to F$, then

$$m_F = cm_{\underline{F}} + (c-1)\frac{1}{z}$$
$$n_{\underline{F}}(z) = \left(c\int \frac{t}{1+tm_{\underline{F}}(z)}dF^T(t) - z\right)^{-1}$$

We take c = 1/10 and alternatively K = 7 and K = 4.

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Spectrum of the sample covariance matrix



Figure: Histogram of the eigenvalues of $\mathbf{B}_N = \mathbf{T}_N^{\frac{1}{2}} \mathbf{X}_N^{\mathsf{H}} \mathbf{X}_N \mathbf{T}_N^{\frac{1}{2}}$, N = 3000, n = 300, with \mathbf{T}_N diagonal composed of three evenly weighted masses in (i) 1, 3 and 7 on top, (ii) 1, 3 and 4 at bottom.

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The "Shannon" - transform

A. M. Tulino, S. Verdù, "Random matrix theory and wireless communications," Now Publishers Inc., 2004.

Definition

Let F be a probability distribution, m_F its Stieltjes transform, then the Shannon-transform \mathcal{V}_F of F is defined as

$$\mathcal{V}_{F}(x) \triangleq \int_{0}^{\infty} \log(1+x\lambda) dF(\lambda) = \int_{x}^{\infty} \left(\frac{1}{t} - m_{F}(-t)\right) dt$$

This quantity is fundamental to wireless communication purposes!

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Research Today: Iterative Deterministic Equivalents

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The Marčenko-Pastur law

V. A. Marčenko, L. A. Pastur, "Distributions of eigenvalues for some sets of random matrices", Math USSR-Sbornik, vol. 1, no. 4, pp. 457-483, 1967.

The theorem to be proven is the following

Theorem

Let $\mathbf{X}_N \in \mathbb{C}^{N \times n}$ have i.i.d. zero mean variance 1/n entries with finite eighth order moments. As $n, N \to \infty$ with $\frac{N}{n} \to c \in (0, \infty)$, the e.s.d. of $\mathbf{X}_N \mathbf{X}_N^H$ converges almost surely to a nonrandom distribution function F_c with density f_c given by

$$f_c(x) = (1 - c^{-1})^+ \delta(x) + \frac{1}{2\pi c x} \sqrt{(x - a)^+ (b - x)^+}$$

where $a = (1 - \sqrt{c})^2$, and $b = (1 + \sqrt{c})^2$.





Figure: Marčenko-Pastur law for different limit ratios $c = \lim_{N \to \infty} N/n$.

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Diagonal entries of the resolvent

Since we want an expression of m_F , we start by identifying the diagonal entries of the resolvent $(\mathbf{X}_N \mathbf{X}_N^H - z \mathbf{I}_N)^{-1}$ of $\mathbf{X}_N \mathbf{X}_N^H$. Denote

$$\mathbf{X}_{N} = \begin{bmatrix} \mathbf{y}^{\mathsf{H}} \\ \mathbf{Y} \end{bmatrix}$$

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Diagonal entries of the resolvent

Since we want an expression of m_F , we start by identifying the diagonal entries of the resolvent $(\mathbf{X}_N \mathbf{X}_N^H - z \mathbf{I}_N)^{-1}$ of $\mathbf{X}_N \mathbf{X}_N^H$. Denote

$$\mathbf{X}_{N} = \begin{bmatrix} \mathbf{y}^{\mathsf{H}} \\ \mathbf{Y} \end{bmatrix}$$

Now, for $z \in \mathbb{C}^+$, we have

$$\begin{pmatrix} \mathbf{X}_{N}\mathbf{X}_{N}^{\mathsf{H}} - z\mathbf{I}_{N} \end{pmatrix}^{-1} = \begin{bmatrix} \mathbf{y}^{\mathsf{H}}\mathbf{y} - z & \mathbf{y}^{\mathsf{H}}\mathbf{Y}^{\mathsf{H}} \\ \mathbf{Y}\mathbf{y} & \mathbf{Y}\mathbf{Y}^{\mathsf{H}} - z\mathbf{I}_{N-1} \end{bmatrix}^{-1}$$

Consider the first diagonal element of $(\mathbf{R}_N - z \mathbf{I}_N)^{-1}$. From the matrix inversion lemma,

$$\begin{pmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{C} & \mathbf{D} \end{pmatrix}^{-1} = \begin{pmatrix} (\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1} & -\mathbf{A}^{-1}\mathbf{B}(\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B})^{-1} \\ -(\mathbf{A} - \mathbf{B}\mathbf{D}^{-1}\mathbf{C})^{-1}\mathbf{C}\mathbf{A}^{-1} & (\mathbf{D} - \mathbf{C}\mathbf{A}^{-1}\mathbf{B})^{-1} \end{pmatrix}$$

which here gives

$$\left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} - z \mathbf{I}_{N} \right)^{-1} \right]_{11} = \frac{1}{-z - z \mathbf{y}^{\mathsf{H}} (\mathbf{Y}^{\mathsf{H}} \mathbf{Y} - z \mathbf{I}_{n})^{-1} \mathbf{y}}$$

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Trace Lemma

Z. Bai, J. Silverstein, "Spectral Analysis of Large Dimensional Random Matrices", Springer Series in Statistics, 2009.

To go further, we need the following result,

Theorem

Let $\{\mathbf{A}_N\} \in \mathbb{C}^{N \times N}$ with bounded spectral norm. Let $\{\mathbf{x}_N\} \in \mathbb{C}^N$, be a random vector of *i.i.d.* entries with zero mean, variance 1/N and finite 8th order moment, independent of \mathbf{A}_N . Then

$$\mathbf{x}_{N}^{\mathsf{H}}\mathbf{A}_{N}\mathbf{x}_{N}-\frac{1}{N}tr\mathbf{A}_{N}\xrightarrow{\mathrm{a.s.}}0$$

For large N, we therefore have approximately

$$\left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} - z \mathbf{I}_{N} \right)^{-1} \right]_{11} \simeq \frac{1}{-z - z \frac{1}{N} \operatorname{tr} \left(\mathbf{Y}^{\mathsf{H}} \mathbf{Y} - z \mathbf{I}_{N} \right)^{-1}}$$

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Rank-1 perturbation lemma

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

It is somewhat intuitive that adding a single column to Y won't affect the trace in the limit.

Theorem

Let **A** and **B** be $N \times N$ with **B** Hermitian positive definite, and $\mathbf{v} \in \mathbb{C}^N$. For $z \in \mathbb{C} \setminus \mathbb{R}^-$,

$$\left|\frac{1}{N}tr\left((\mathbf{B}-z\mathbf{I}_N)^{-1}-(\mathbf{B}+\mathbf{v}\mathbf{v}^{\mathsf{H}}-z\mathbf{I}_N)^{-1}\right)\mathbf{A}\right| \leqslant \frac{1}{N}\frac{\|\mathbf{A}\|}{\operatorname{dist}(z,\mathbb{R}^+)}$$

with $||\mathbf{A}||$ the spectral norm of \mathbf{A} , and $\operatorname{dist}(z, A) = \inf_{y \in A} ||y - z||$. Therefore, for large N, we have approximately,

$$\begin{split} \left[\left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} - z \mathbf{I}_{N} \right)^{-1} \right]_{11} &\simeq \frac{1}{-z - z \frac{1}{N} \operatorname{tr} (\mathbf{Y}^{\mathsf{H}} \mathbf{Y} - z \mathbf{I}_{n})^{-1}} \\ &\simeq \frac{1}{-z - z \frac{1}{N} \operatorname{tr} (\mathbf{X}_{N}^{\mathsf{H}} \mathbf{X}_{N} - z \mathbf{I}_{n})^{-1}} \\ &= \frac{1}{-z - z \frac{n}{N} m_{\underline{F}}(z)} \end{split}$$

in which we recognize the Stieltjes transform m_E of the l.s.d. of $X_N^H X_N$.

End of the proof

We have again the relation

$$\frac{n}{N}m_{\underline{F}}(z) = m_{F}(z) + \frac{N-n}{N}\frac{1}{z}$$

hence

$$\left[\left(\mathbf{X}_{N}\mathbf{X}_{N}^{\mathsf{H}}-z\mathbf{I}_{N}\right)^{-1}\right]_{11}\simeq\frac{1}{\frac{n}{N}-1-z-zm_{F}(z)}$$

Note that the choice (1,1) is irrelevant here, so the expression is valid for all pair (i, i). Summing over the N terms and averaging, we finally have

$$m_{F}(z) = \frac{1}{N} \operatorname{tr} \left(\mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} - z \mathbf{I}_{N} \right)^{-1} \simeq \frac{1}{c - 1 - z - z m_{F}(z)}$$

which solve a polynomial of second order. Finally

$$m_F(z) = rac{c-1}{2z} - rac{1}{2} + rac{\sqrt{(c-1-z)^2 - 4z}}{2z}.$$

From the inverse Stieltjes transform formula, we then verify that m_F is the Stieltjes transform of the Marčenko-Pastur law.

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General Introduction to the Course

From Small to Large Dimensional Random Matrices

Moment Methods and Free Probability

The Stieltjes Transform Method Definition and results Proof of the Marčenko-Pastur law

Deterministic Equivalents

Definition and method Toy example: Sum of doubly-correlated i.i.d. matrices A Central Limit Theorem

Research Today: Iterative Deterministic Equivalents

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Reminder and scope

- In the first part of this course,
 - we defined the Stieltjes transform:

Definition

Let F be a distribution function, and $z \in \mathbb{C}^+$. Then the Stieltjes transform $m_F(z)$ of F is defined as

$$m_F(z) = \int \frac{1}{\lambda - z} dF(\lambda)$$

For *F* the spectral distribution of an Hermitian matrix $\mathbf{X} \in \mathbb{C}^{N \times N}$,

$$m_F(z) = \frac{1}{N} \operatorname{tr} \left(\mathbf{X} - z \mathbf{I}_N \right)^{-1}$$

- We gave limiting distribution results for some matrix models.
- We gave a sketch of the proof of the Marčenko-Pastur law.

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- We gave limiting distribution results for some matrix models.
- We gave a sketch of the proof of the Marčenko-Pastur law.
- In this second part, we will
 - extend the notion of limit distributions to deterministic equivalents
 - provide sound mathematical techniques to prove convergence/existence/uniqueness of large N results.
 - provide first wireless communication results

Limiting results against deterministic equivalents

previously, we showed results of the type:

"let \mathbf{X}_N be random, \mathbf{T}_N deterministic with $F^{\mathbf{T}_N} \Rightarrow F^{\mathbf{T}}$, etc. Then, when $N \to \infty$, the e.s.d. of \mathbf{X}_N tends to F such that m_F is solution of a fixed-point equation,

 $m_{\mathbf{X}_N}(z) \rightarrow m_F(z)$ "

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- this has major drawbacks
 - this assumes T_N has a limiting distribution
 - ▶ if it does, $m_{\mathbf{X}_N \mathbf{X}_N^H}$ can at best be approximated by m_F which is a function of the limiting F^T . For finite N, F^{T_N} may be very different from F^T .
 - any sequence \mathbf{T}_N with l.s.d. F^T engenders the same l.s.d. F.

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instead, we shall use results of the type

"let X_N be random, T_N deterministic with $F^{T_N} \Rightarrow F^T$, etc. Then the e.s.d. of X_N tends to F such that m_F is solution of a fixed-point equation has Stieltjes transform m_{X_N} well approximated by the deterministic m_N , which is the unique solution of a fixed-point equation and such that

$$m_{\mathbf{X}_{N}}(z) - m_{N}(z) \xrightarrow{\text{a.s.}} 0$$
'

In this case, m_N is a function of \mathbf{T}_N , for fixed N and does not require any convergence of $F^{\mathbf{T}_N}$.

It will often be the case that the deterministic equivalent $m_N(z)$ satisfies an implicit equation. The steps are then:

1. find a suitable function f , such that the true Stieltjes transform $m_{{\bf X}_N}(z)$ satisfies, for fixed $z\in \mathbb{C}^+$,

$$m_{\mathbf{X}_N}(z) = f(m_{\mathbf{X}_N}(z)) + \varepsilon_N$$

where $\epsilon_N \xrightarrow{\text{a.s.}} 0$ as $N \to \infty$.

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- using Pastur's method (see proof of Marčenko-Pastur law)
- using guess-work (see Bai and Silverstein's proofs)

Remark: This is as far as we went in the first part.

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2. For fixed N, prove the existence of a solution to

$$m = f(m)$$

This is often based on extracting a converging subsequence of m_N, m_{2N}, \ldots such that m_{jN} "has the same properties as $m_{\mathbf{X}_N}(z)$ for all j".

3. For this fixed *N*, prove the uniqueness of the solution. This involves finding a contradiction if two solutions exist.

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- 3. For this fixed *N*, prove the uniqueness of the solution. This involves finding a contradiction if two solutions exist.
- 4. Calling $m_N(z)$ the solution, prove finally that

$$m_{\mathbf{X}_N}(z) - m_N(z) \xrightarrow{\mathrm{a.s.}} 0$$

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Stieltjes transform of a sum of doubly-correlated matrices

R. Couillet, M. Debbah, J. W. Silverstein, "A deterministic equivalent for the capacity analysis of correlated multi-user MIMO channels," vol. 57, no. 6, pp. 3493-3514, 2011.

Theorem

$$\mathbf{B}_{N} = \sum_{k=1}^{K} \mathbf{H}_{k} \mathbf{H}_{k}^{\mathsf{H}}, \text{ with } \mathbf{H}_{k} = \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k}^{\frac{1}{2}}$$

 $\mathbf{X}_k \in \mathbb{C}^{N \times n_k}$ with i.i.d. entries of zero mean, variance $1/n_k$, \mathbf{R}_k Hermitian nonnegative definite, \mathbf{T}_k diagonal nonnegative, $\limsup_N \max(||\mathbf{R}_k||, ||\mathbf{T}_k||) < \infty$. Denote $c_k = N/n_k$. Then, as all N and n_k grow large, with bounded ratio c_k , for $z \in \mathbb{C} \setminus \mathbb{R}^-$,

$$m_{\mathbf{B}_{N}}(z) - m_{N}(z) \xrightarrow{\text{a.s.}} 0, \quad m_{N}(z) = \frac{1}{N} tr \left(-z \mathbf{I}_{N} + \sum_{k=1}^{K} \overline{\mathbf{e}}_{k}(z) \mathbf{R}_{k} \right)^{-1}$$

with $e_1(z), \ldots, e_K(z)$ the unique solutions in $\{z \in \mathbb{C}^+, e_i(z) \in \mathbb{C}^+\}$ or $\{z \in \mathbb{R}^-, e_i(z) \in \mathbb{R}^+\}$ of

$$e_i(z) = \frac{1}{N} tr \mathbf{R}_i \left(-z \mathbf{I}_N + \sum_{k=1}^K \bar{e}_k(z) \mathbf{R}_k \right)^{-1}$$
$$\bar{e}_i(z) = \frac{1}{n_i} tr \mathbf{T}_i \left(\mathbf{I}_{n_i} + c_i e_i(z) \mathbf{T}_i \right)^{-1}$$

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Pastur's method

Pastur's method is *not* applicable here, unless all \mathbf{R}_k 's are diagonal.

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Pastur's method

Pastur's method is *not* applicable here, unless all \mathbf{R}_k 's are diagonal.

Consider K = 2 and denote $\mathbf{H}_k = \mathbf{R}_k^{\frac{1}{2}} \mathbf{X}_k \mathbf{T}_k^{\frac{1}{2}}$, with diagonal \mathbf{R}_k . By block-matrix inversion, we have

$$\begin{aligned} \left(\mathbf{H}_{1}\mathbf{H}_{1}^{\mathsf{H}} + \mathbf{H}_{2}\mathbf{H}_{2}^{\mathsf{H}} - z\mathbf{I}_{N} \right)_{11}^{-1} &= \left(\begin{bmatrix} \mathbf{h}_{1}^{\mathsf{H}} & \mathbf{h}_{2}^{\mathsf{H}} \\ \mathbf{U}_{1} & \mathbf{U}_{2} \end{bmatrix} \begin{bmatrix} \mathbf{h}_{1} & \mathbf{U}_{1}^{\mathsf{H}} \\ \mathbf{h}_{2} & \mathbf{U}_{2}^{\mathsf{H}} \end{bmatrix} - z\mathbf{I}_{N} \right)_{11}^{-1} \\ &= \left[-z - z[\mathbf{h}_{1}^{\mathsf{H}}\mathbf{h}_{2}^{\mathsf{H}}] \left(\begin{bmatrix} \mathbf{U}_{1}^{\mathsf{H}} \\ \mathbf{U}_{2}^{\mathsf{H}} \end{bmatrix} [\mathbf{U}_{1}\mathbf{U}_{2}] - z\mathbf{I}_{n_{1}+n_{2}} \right)^{-1} \begin{bmatrix} \mathbf{h}_{1} \\ \mathbf{h}_{2} \end{bmatrix} \right]^{-1} \end{aligned}$$

with the definition $\mathbf{H}_{i}^{H} = [\mathbf{h}_{i}\mathbf{U}_{i}^{H}]$. The inner inverse matrix is

$$\left(\begin{bmatrix} \mathbf{U}_1^{\mathrm{H}} \\ \mathbf{U}_2^{\mathrm{H}} \end{bmatrix} [\mathbf{U}_1 \mathbf{U}_2] - z \mathbf{I}_{n_1 + n_2} \right)^{-1} = \begin{bmatrix} \mathbf{U}_1^{\mathrm{H}} \mathbf{U}_1 - z \mathbf{I}_{n_1} & \mathbf{U}_1^{\mathrm{H}} \mathbf{U}_2 \\ \mathbf{U}_2^{\mathrm{H}} \mathbf{U}_1 & \mathbf{U}_2^{\mathrm{H}} \mathbf{U}_2 - z \mathbf{I}_{n_2} \end{bmatrix}^{-1}$$

on which we apply another block matrix inverse lemma. The upper-left $(n_1 \times n_1)$ entry equals

$$\left(-z\mathbf{U}_{1}^{\mathsf{H}}(\mathbf{U}_{2}\mathbf{U}_{2}^{\mathsf{H}}-z\mathbf{I}_{N-1})^{-1}\mathbf{U}_{1}-z\mathbf{I}_{n_{1}}\right)^{-1}$$

For the second block diagonal entry, it suffices to revert all 1's in 2's and vice-versa.

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Pastur's method (2)

$$\begin{split} & \left(\mathbf{H}_{1}\mathbf{H}_{1}^{\mathsf{H}} + \mathbf{H}_{2}\mathbf{H}_{2}^{\mathsf{H}} - z\mathbf{I}_{N}\right)_{11}^{-1} = \\ & \left[-z - z[\mathbf{h}_{1}^{\mathsf{H}}\mathbf{h}_{2}^{\mathsf{H}}] \begin{bmatrix} \left(-z\mathbf{U}_{1}^{\mathsf{H}}(\mathbf{U}_{2}\mathbf{U}_{2}^{\mathsf{H}} - z\mathbf{I}_{N-1})^{-1}\mathbf{U}_{1} - z\mathbf{I}_{n_{1}}\right)^{-1} & \star \\ & \star & \left(-z\mathbf{U}_{2}^{\mathsf{H}}(\mathbf{U}_{1}\mathbf{U}_{1}^{\mathsf{H}} - z\mathbf{I}_{N-1})^{-1}\mathbf{U}_{2} - z\mathbf{I}_{n_{2}}\right)^{-1} \end{bmatrix} \begin{bmatrix} \mathbf{h}_{1} \\ \mathbf{h}_{2} \end{bmatrix} \end{bmatrix}^{-1} \end{split}$$

The other two terms do not depend on h_1 , h_2 . We now use both results,

For $\mathbf{x} \in \mathbb{C}^N$, $\mathbf{y} \in \mathbb{C}^N$ i.i.d. with zero mean, variance 1/N, $\mathbf{A} \in \mathbb{C}^{N \times N}$ Hermitian with bounded spectral norm,

$$\mathbf{x}^{\mathsf{H}}\mathbf{A}\mathbf{x} - rac{1}{N}\mathsf{tr}\,\mathbf{A} \stackrel{\mathrm{a.s.}}{\longrightarrow} \mathbf{0}$$

 $\mathbf{x}^{\mathsf{H}}\mathbf{A}\mathbf{y} \stackrel{\mathrm{a.s.}}{\longrightarrow} \mathbf{0}$

Since \mathbf{R}_1 , \mathbf{R}_2 are diagonal, $\mathbf{h}_i = \sqrt{r_{i1}} \mathbf{T}_i^{\frac{1}{2}} \mathbf{x}_i$, with the notation $\mathbf{R}_i = \text{diag}(r_{i1}, \dots, r_{iN})$. Therefore, using the trace and rank-1 perturbation lemma,

$$\left(\mathbf{H}_{1}\mathbf{H}_{1}^{H} + \mathbf{H}_{2}\mathbf{H}_{2}^{H} - z\mathbf{I}_{N} \right)_{11}^{-1} \rightarrow \left[-z - zr_{11}\frac{1}{n_{1}} \operatorname{tr} \mathbf{T}_{1} \left(-z\mathbf{H}_{1}^{H}(\mathbf{H}_{2}\mathbf{H}_{2}^{H} - z\mathbf{I}_{N})^{-1}\mathbf{H}_{1} - z\mathbf{I}_{n_{1}} \right)^{-1} - zr_{21}\frac{1}{n_{2}} \operatorname{tr} \mathbf{T}_{2} \left(-z\mathbf{H}_{2}^{H}(\mathbf{H}_{1}\mathbf{H}_{1}^{H} - z\mathbf{I}_{N})^{-1}\mathbf{H}_{1} - z\mathbf{I}_{n_{2}} \right)^{-1} \right]^{-1}$$

Pastur's method (3)

Now, denoting $\mathbf{H}_i = [\tilde{\mathbf{h}}_i \tilde{\mathbf{U}}_i]$ (column selection instead of row),

$$\mathbf{T}_{1} \left(-z\mathbf{H}_{1}^{\mathsf{H}} (\mathbf{H}_{2}\mathbf{H}_{2}^{\mathsf{H}} - z\mathbf{I}_{N})^{-1}\mathbf{H}_{1} - z\mathbf{I}_{n_{1}} \right)_{11}^{-1} = \tau_{11} \left[-z - z\tilde{\mathbf{h}}_{1}^{\mathsf{H}} \left(\tilde{\mathbf{U}}_{1}\tilde{\mathbf{U}}_{1}^{\mathsf{H}} + \mathbf{H}_{2}\mathbf{H}_{2}^{\mathsf{H}} - z\mathbf{I}_{N} \right)^{-1} \tilde{\mathbf{h}}_{1} \right]^{-1}$$

$$\rightarrow \tau_{11} \left[-z - zc_{1}\tau_{11}\frac{1}{N} \operatorname{tr} \mathbf{R}_{1} \left(\mathbf{H}_{1}\mathbf{H}_{1}^{\mathsf{H}} + \mathbf{H}_{2}\mathbf{H}_{2}^{\mathsf{H}} - z\mathbf{I}_{N} \right)^{-1} \right]^{-1}$$

with τ_{ij} the j^{th} diagonal entry of \mathbf{T}_i . A similar result holds when changing 1's in 2's. Call now

$$f_i = \frac{1}{N} \operatorname{tr} \mathbf{R}_i \left(\mathbf{H}_1 \mathbf{H}_1^{\mathsf{H}} + \mathbf{H}_2 \mathbf{H}_2^{\mathsf{H}} - z \mathbf{I}_N \right)^{-1}$$

and

$$\bar{f}_i = \frac{1}{n_i} \operatorname{tr} \mathbf{T}_i \left(\mathbf{H}_1^{\mathsf{H}} (\mathbf{H}_2 \mathbf{H}_2^{\mathsf{H}} - z \mathbf{I}_N)^{-1} \mathbf{H}_1 + \mathbf{I}_{n_1} \right)^{-1}.$$

We have shown

$$f_i = \lim_{N \to \infty} \frac{1}{N} \operatorname{tr} \mathbf{R}_i \left(\overline{f}_1 \mathbf{R}_1 + \overline{f}_2 \mathbf{R}_2 - z \mathbf{I}_N \right)^{-1}$$

$$\overline{f}_i = \lim_{N \to \infty} \frac{1}{n_i} \operatorname{tr} \mathbf{T}_i \left(c_i f_i \mathbf{T}_i i + \mathbf{I}_{n_i} \right)^{-1}.$$

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Deterministic equivalent approach: guess work

We will use here the "guess-work" method to find the deterministic equivalent. Consider the simpler case K = 1. Back to the original notations, we seek a matrix **D** such that

$$\frac{1}{N} \operatorname{tr} \left(\mathbf{B}_N - z \mathbf{I}_N \right)^{-1} - \frac{1}{N} \operatorname{tr} \mathbf{D}^{-1} \xrightarrow{\text{a.s.}} \mathbf{0}$$

as $N \to \infty$.

Resolvent lemma For invertible **A**, **B** matrices,

$$A^{-1} - B^{-1} = -A^{-1}(A - B)B^{-1}$$

Taking the matrix differences,

$$D^{-1} - (B_N - zI_N)^{-1} = D^{-1}(R^{\frac{1}{2}}XTX^HR^{\frac{1}{2}} - zI_N - D)(B_N - zI_N)^{-1}$$

It seems convenient to take $\mathbf{D} = -\mathbf{z}\mathbf{I}_N + \tilde{\mathbf{e}}_{\mathbf{B}_N}\mathbf{R}$ with $\tilde{\mathbf{e}}_{\mathbf{B}_N}$ left to be defined (the notation \mathbf{B}_N in $\tilde{\mathbf{e}}_{\mathbf{B}_N}$ reminds that we do not look *yet* for a deterministic quantity).

Deterministic equivalent approach: guess work (2) With $\mathbf{D} = -z\mathbf{I}_N + \bar{\mathbf{e}}_{\mathbf{B}_N}\mathbf{R}$,

$$\begin{split} \mathbf{D}^{-1} - (\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} &= \mathbf{D}^{-1}(\mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} - z\mathbf{I}_{N} - \mathbf{D})(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} \\ &= \mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\left(\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\right)\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} - \bar{\mathbf{e}}_{\mathbf{B}_{N}}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} \\ \\ \begin{bmatrix} \mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}} = \sum_{j=1}^{n} \tau_{j}\mathbf{x}_{j}\mathbf{x}_{j}^{\mathsf{H}} \end{bmatrix} = \mathbf{D}^{-1}\sum_{j=1}^{n} \tau_{j}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}\mathbf{x}_{j}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} - \bar{\mathbf{e}}_{\mathbf{B}_{N}}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} \\ \end{split}$$

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Deterministic equivalent approach: guess work (2) With $\mathbf{D} = -z\mathbf{I}_N + \bar{\mathbf{e}}_{\mathbf{B}_N}\mathbf{R}$, $\mathbf{D}^{-1} - (\mathbf{B}_N - z\mathbf{I}_N)^{-1} = \mathbf{D}^{-1}(\mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} - z\mathbf{I}_N - \mathbf{D})(\mathbf{B}_N - z\mathbf{I}_N)^{-1}$ $= \mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}(\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}})\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_N - z\mathbf{I}_N)^{-1} - \bar{\mathbf{e}}_{\mathbf{B}_N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_N - z\mathbf{I}_N)^{-1}$ $\begin{bmatrix}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}} = \sum_{j=1}^{n} \tau_j \mathbf{x}_j \mathbf{x}_j^{\mathsf{H}}\end{bmatrix} = \mathbf{D}^{-1}\sum_{j=1}^{n} \tau_j \mathbf{R}^{\frac{1}{2}}\mathbf{x}_j \mathbf{x}_j^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_N - z\mathbf{I}_N)^{-1} - \bar{\mathbf{e}}_{\mathbf{B}_N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_N - z\mathbf{I}_N)^{-1}$

Taking the trace, we notice that

$$\operatorname{tr} \mathbf{D}^{-1} \sum_{j=1}^{n} \tau_{j} \mathbf{R}^{\frac{1}{2}} \mathbf{x}_{j} \mathbf{x}_{j}^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}} (\mathbf{B}_{N} - z \mathbf{I}_{N})^{-1} = \sum_{j=1}^{n} \tau_{j} \mathbf{x}_{j}^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}} (\mathbf{B}_{N} - z \mathbf{I}_{N})^{-1} \mathbf{D}^{-1} \mathbf{R}^{\frac{1}{2}} \mathbf{x}_{j}$$

and we want to apply the trace lemma! But \mathbf{B}_N is NOT independent of \mathbf{x}_i .

Deterministic equivalent approach: guess work (2) With $\mathbf{D} = -z\mathbf{I}_N + \bar{\mathbf{e}}_{\mathbf{B}_N}\mathbf{R}$, $\mathbf{D}^{-1} - (\mathbf{B}_N - z\mathbf{I}_N)^{-1} = \mathbf{D}^{-1}(\mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} - z\mathbf{I}_N - \mathbf{D})(\mathbf{B}_N - z\mathbf{I}_N)^{-1}$ $= \mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\left(\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\right)\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_N - z\mathbf{I}_N)^{-1} - \bar{\mathbf{e}}_{\mathbf{B}_N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_N - z\mathbf{I}_N)^{-1}$ $\begin{bmatrix} \mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}} = \sum_{i=1}^{n} \tau_i \mathbf{x}_i \mathbf{x}_i^{\mathsf{H}} \end{bmatrix} = \mathbf{D}^{-1}\sum_{i=1}^{n} \tau_j \mathbf{R}^{\frac{1}{2}} \mathbf{x}_i \mathbf{x}_j^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}}(\mathbf{B}_N - z\mathbf{I}_N)^{-1} - \bar{\mathbf{e}}_{\mathbf{B}_N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_N - z\mathbf{I}_N)^{-1}$

Taking the trace, we notice that

$$\operatorname{tr} \mathbf{D}^{-1} \sum_{j=1}^{n} \tau_{j} \mathbf{R}^{\frac{1}{2}} \mathbf{x}_{j} \mathbf{x}_{j}^{H} \mathbf{R}^{\frac{1}{2}} (\mathbf{B}_{N} - z \mathbf{I}_{N})^{-1} = \sum_{j=1}^{n} \tau_{j} \mathbf{x}_{j}^{H} \mathbf{R}^{\frac{1}{2}} (\mathbf{B}_{N} - z \mathbf{I}_{N})^{-1} \mathbf{D}^{-1} \mathbf{R}^{\frac{1}{2}} \mathbf{x}_{j}$$

and we want to apply the trace lemma! But B_N is NOT independent of x_j . We need a further step:

A matrix inversion lemma (MIL)

Let **A** be Hermitian invertible, then for any vector **x** and scalar τ such that $\mathbf{A} + \tau \mathbf{x} \mathbf{x}^{\mathsf{H}}$ is invertible

$$\mathbf{x}^{\mathsf{H}}(\mathbf{A} + \tau \mathbf{x} \mathbf{x}^{\mathsf{H}})^{-1} = \frac{\mathbf{x}^{\mathsf{H}} \mathbf{A}^{-1}}{1 + \tau \mathbf{x} \mathbf{A}^{-1} \mathbf{x}^{\mathsf{H}}}$$

Deterministic equivalent approach: guess work (2b)

Applying the MIL on $\textbf{A}=\textbf{B}_{N}-\tau_{j}\textbf{R}^{\frac{1}{2}}\textbf{x}_{j}\textbf{x}_{j}^{H}\textbf{R}^{\frac{1}{2}}$ and $\textbf{A}+\tau\textbf{x}\textbf{x}^{H}=\textbf{B}_{N}$ ($\tau=\tau_{j},\,\textbf{x}=\textbf{R}^{\frac{1}{2}}\textbf{x}_{j}$),

$$\mathbf{D}^{-1} - (\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} = \sum_{j=1}^{n} \tau_{j} \frac{\mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}\mathbf{x}_{j}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1}}{1 + \tau_{j}\mathbf{x}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}} - \bar{\mathbf{e}}_{\mathbf{B}_{N}}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$

with $\mathbf{B}_{(j)} = \mathbf{B}_N - \tau_j \mathbf{R}^{\frac{1}{2}} \mathbf{x}_j \mathbf{x}_j^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}}$. Choice of $\bar{\mathbf{e}}_{\mathbf{B}_N}$:

$$\bar{\mathbf{e}}_{\mathbf{B}_{N}} = \frac{1}{n} \sum_{j=1}^{n} \frac{\tau_{j}}{1 + \tau_{j} c \frac{1}{N} \operatorname{tr} \mathbf{R}(\mathbf{B}_{N} - z \mathbf{I}_{N})^{-1}} \triangleq \frac{1}{n} \operatorname{tr} \mathbf{T} \left(\mathbf{I}_{n} + \mathbf{T} c \mathbf{e}_{\mathbf{B}_{N}} \right)^{-1}$$

$$\begin{split} &\frac{1}{N} \operatorname{tr} \mathbf{R} \mathbf{D}^{-1} - \frac{1}{N} \operatorname{tr} \mathbf{R} (\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} \\ &= \frac{1}{N} \operatorname{tr} \mathbf{R} \left(\overline{\mathbf{e}}_{\mathbf{B}_{N}} \mathbf{R} - z\mathbf{I}_{N} \right)^{-1} - \mathbf{e}_{\mathbf{B}_{N}} \\ &= \frac{1}{N} \sum_{j=1}^{n} \tau_{j} \left[\frac{\mathbf{x}_{j}^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}} (\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1} \mathbf{R} \mathbf{D}^{-1} \mathbf{R}^{\frac{1}{2}} \mathbf{x}_{j}}{1 + \tau_{j} \mathbf{x}^{\mathsf{H}} \mathbf{R}^{\frac{1}{2}} (\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1} \mathbf{R}^{\frac{1}{2}} \mathbf{x}_{j}} - \frac{\frac{1}{n} \operatorname{tr} \mathbf{R}^{\frac{1}{2}} (\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} \mathbf{R} \mathbf{D}^{-1} \mathbf{R}^{\frac{1}{2}}}{1 + c\tau_{j} \frac{1}{N} \operatorname{tr} \mathbf{R}^{\frac{1}{2}} (\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} \mathbf{R}^{\frac{1}{2}}} \right] \\ \xrightarrow{\text{a.s.}}{} 0. \end{split}$$

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Deterministic equivalent approach: guess work (3)

We now use the trace lemma and standard inequalities to show

$$\sum_{N} E\left[\left| \frac{1}{N} \operatorname{tr} \left(\mathbf{B}_{N} - z \mathbf{I}_{N} \right)^{-1} - \frac{1}{N} \operatorname{tr} \left(\bar{\mathbf{e}}_{\mathbf{B}_{N}} \mathbf{R} - z \mathbf{I}_{N} \right)^{-1} \right|^{p} \right] < \infty.$$

for some integer p, imposing that \mathbf{x}_i has entries of finite moments of order 2p. The same can be done for $\frac{1}{N} \operatorname{tr} \mathbf{R} (\mathbf{B}_N - z \mathbf{I}_N)^{-1}$ and we get

$$\sum_{N} E\left[\left|\frac{1}{N} \operatorname{tr} \mathbf{R} (\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} - \frac{1}{N} \operatorname{tr} \mathbf{R} \mathbf{D}^{-1}\right|^{p}\right] < \infty.$$

Applying Markov inequality and the Borel-Cantelli lemma, we finally have the almost-sure convergence.

to extend to more generic conditions on x_i (only finite variance requirement), truncation steps may be applied.

Truncation tool

J. W. Silverstein, Z. D. Bai, "On the empirical distribution of eigenvalues of a class of large dimensional random matrices," Journal of Multivariate Analysis, vol. 54, no. 2, pp. 175-192, 1995.

Truncation and centralization

Replace X_N , T_N and R_N by \bar{X}_N , \bar{T}_N and \bar{R}_N in the following fashion

$$\left(\mathbf{\bar{X}}_{N}\right)_{ij} = \left(\mathbf{X}_{N}\right)_{ij} \cdot I_{\left\{\left(\mathbf{X}_{N}\right)_{ij} < g_{N}
ight\}}$$

for g_N that grows

- fast enough to ensure $F^{\mathbf{B}_N} F^{\mathbf{\overline{B}}_N} \Rightarrow 0$
- ▶ slow enough to ensure $\frac{1}{N}$ tr $(\bar{B}_N z I_N)^{-1} \frac{1}{N}$ tr $\bar{R}\bar{D}^{-1} \xrightarrow{a.s.} 0$

Deterministic equivalent approach: existence and uniqueness

R. D. Yates, "A framework for uplink power control in cellular radio systems", IEEE Journal on Selected Areas in Communications, vol. 13, no. 7, pp. 1341-1347, 1995.

To prove existence and uniqueness, we use a constructive approach based on results on standard interference functions:

Definition

A function $\mathbf{h}(x_1, \ldots, x_K) \in \mathbb{R}^K$, $\mathbf{h} = (h_1, \ldots, h_K)$, with $x_1, \ldots, x_K \in \mathbb{R}^+$, is a standard function or a standard interference function if

- 1. Positivity: for all j, $h_j(x_1, \ldots, x_K) > 0$,
- 2. *Monotonicity:* if $x_1 > x'_1, ..., x_K > x'_K$, then $h_j(x_1, ..., x_K) > h_j(x'_1, ..., x'_K)$, for all j,
- 3. Scalability: for all $\alpha > 1$ and j, $\alpha h_j(x_1, \ldots, x_K) > h_j(\alpha x_1, \ldots, \alpha x_K)$.

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- 1. Positivity: for all j, $h_j(x_1, \ldots, x_K) > 0$,
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- 3. Scalability: for all $\alpha > 1$ and j, $\alpha h_j(x_1, \ldots, x_K) > h_j(\alpha x_1, \ldots, \alpha x_K)$.

Theorem

If $\mathbf{h}(x_1, \ldots, x_K)$ is a standard interference function and there exists (x_1, \ldots, x_K) such that, for all $j, x_j \ge h_j(x_1, \ldots, x_K)$, then the iteration

$$x_j^{(t+1)} = h_j(x_1^{(t)}, \dots, x_K^{(t)}), \quad x_1^{(0)}, \dots, x_K^{(0)} > 0$$

converges to the unique solution of $x_j = h_j(x_1, \ldots, x_K)$, $j \in \{1, \ldots, K\}$.

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Deterministic equivalent approach: existence and uniqueness (2)

We proceed as follows:

we fix z < 0, and show that the function</p>

$$h: e \mapsto \frac{1}{N} \operatorname{tr} \mathbf{R} \left(\bar{e} \mathbf{R} - z \mathbf{I}_N \right)^{-1}, \quad \bar{e} = \frac{1}{n} \operatorname{tr} \mathbf{T} \left(\mathbf{I}_n + c e(z) \mathbf{T} \right)^{-1}$$

is a standard function.

- we conclude that $e^t(z) = h(e^{t-1}(z))$, $e^0(z) = 0$, converge to e(z).
- ▶ standard holomorphicity arguments (Vitali's convergence theorem) then show that e(z) is defined and holomorphic on $\mathbb{C} \setminus \mathbb{R}^+$.

Deterministic equivalent approach: termination of the proof

It then suffices to show that ¹/_N tr R(B_N − zI_N)⁻¹ − e ^{a.s.}/_→ 0 This exploits the fact that, for some ω in a probability one space,

$$\frac{1}{N}\operatorname{tr} \mathbf{R}(\mathbf{B}_{N}(\omega) - z\mathbf{I}_{N})^{-1} - \frac{1}{N}\operatorname{tr} \mathbf{R}\left(\bar{\mathbf{e}}_{\mathbf{B}_{N}}\mathbf{R} - z\mathbf{I}_{N}\right)^{-1} = w_{N}(\omega) \to 0.$$

For $z \in \mathbb{C} \setminus \mathbb{R}^+$, we have in particular

$$e(z) - \frac{1}{N} \operatorname{tr} \mathbf{R}(\mathbf{B}_{N}(\omega) - z\mathbf{I}_{N})^{-1} = \gamma(z) \left(e - \frac{1}{N} \operatorname{tr} \mathbf{R}(\mathbf{B}_{N}(\omega) - z\mathbf{I}_{N})^{-1} \right) + w_{N}(\omega)$$

where $\gamma(z) \to 0$ as $|z| \to \infty.$ Taking z such that $\gamma(z) < 1$ for all N, n, ω , we have

$$e(z) - \frac{1}{N} \operatorname{tr} \mathbf{R} (\mathbf{B}_N(\omega) - z \mathbf{I}_N)^{-1} = \frac{w_N}{1 - \gamma(z)} \to 0$$

Vitali's convergence theorem extends this result to $z \in \mathbb{C} \setminus \mathbb{R}^+$. The result is proved. The same argument then applies to $m_{B_N}(z) - m_N(z)$.

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Vitali's convergence theorem extends this result to $z \in \mathbb{C} \setminus \mathbb{R}^+$. The result is proved.

- The same argument then applies to $m_{\mathbf{B}_N}(z) m_N(z)$.
- We have proved $F^{B_N} F_N \Rightarrow 0$, almost surely.

Result on the Shannon transform of \mathbf{B}_N

Remember now that

$$\int \log(1+xt)dF(t) = \int_{1/x}^{\infty} \left(\frac{1}{t} - m_F(-t)\right)dt.$$

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R. Couillet, M. Debbah, J. W. Silverstein, "A deterministic equivalent for the capacity analysis of correlated multi-user MIMO channels," IEEE Trans. on Information Theory, vol. 57, no. 6, pp. 3493-3514, 2011..

Theorem

Under the previous model for \mathbf{B}_N , as N, n_k grow large,

$$\begin{split} E\left[\frac{1}{N}\log\det(x\mathbf{B}_{N}+\mathbf{I}_{N})\right] &- \left[\frac{1}{N}\log\det\left(\mathbf{I}_{N}+\sum_{k=1}^{K}\bar{\mathbf{e}}_{k}(-1/x)\mathbf{R}_{k}\right)\right.\\ &+ \sum_{k=1}^{K}\frac{1}{N}\log\det\left(\mathbf{I}_{n_{k}}+c_{k}e_{k}(-1/x)\mathbf{T}_{k}\right)\\ &- \frac{1}{X}\sum_{k=1}^{K}\bar{\mathbf{e}}_{k}(-1/x)e_{k}(-1/x)\right] \xrightarrow{\text{a.s.}} 0 \end{split}$$

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Variance profile

W. Hachem, Ph. Loubaton, J. Najim, "Deterministic equivalents for certain functionals of large random matrices," Annals of Applied Probability, vol. 17, no. 3, pp. 875-930, 2007.

Theorem

Let $X_N \in \mathbb{C}^{N \times n}$ have independent entries with $(i, j)^{th}$ entry of zero mean and variance $\frac{1}{n}\sigma_{ij}^2$. Let $A_N \in \mathbb{R}^{N \times n}$ be deterministic with uniformly bounded column norm. Then

$$\frac{1}{N}tr\left((\mathbf{X}_{N}+\mathbf{A}_{N})(\mathbf{X}_{N}+\mathbf{A}_{N})^{\mathsf{H}}-z\mathbf{I}_{N}\right)^{-1}-\frac{1}{N}tr\mathbf{T}_{N}(z)\xrightarrow{\mathrm{a.s.}}0$$

where $\mathbf{T}_{N}(z)$ is the unique function that solves

$$\mathbf{T}_{N}(z) = \left(\Psi^{-1}(z) - z\mathbf{A}_{N}\tilde{\Psi}(z)\mathbf{A}_{N}^{\mathsf{T}}\right)^{-1}, \quad \tilde{\mathbf{T}}_{N}(z) = \left(\tilde{\Psi}^{-1}(z) - z\mathbf{A}_{N}^{\mathsf{T}}\Psi(z)\mathbf{A}_{N}\right)^{-1}$$

with $\Psi(z) = diag(\psi_i(z))$, $\tilde{\Psi}(z) = diag(\tilde{\psi}_i(z))$, with entries defined as

$$\psi_i(z) = -\left(z(1+\frac{1}{n}tr\tilde{\mathsf{D}}_i\tilde{\mathsf{T}}(z))\right)^{-1}, \quad \tilde{\psi}_j(z) = -\left(z(1+\frac{1}{n}tr\mathsf{D}_j\mathsf{T}(z))\right)^{-1}$$

and $\mathbf{D}_j = diag(\sigma_{ij}^2, 1 \leqslant i \leqslant N)$, $\tilde{\mathbf{D}}_i = diag(\sigma_{ij}^2, 1 \leqslant j \leqslant n)$

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Theorem

For the previous model, we also have that

$$\frac{1}{N} E \log \det \left(\mathbf{I}_N + \frac{1}{\sigma^2} (\mathbf{X}_N + \mathbf{A}_N) (\mathbf{X}_N + \mathbf{A}_N)^{\mathsf{H}} \right)$$

has deterministic equivalent

$$\begin{split} &\frac{1}{N}\log\det\left[\frac{1}{\sigma^2}\Psi(-\sigma^2)^{-1}+\mathbf{A}_N\tilde{\Psi}(-\sigma^2)\mathbf{A}_N^{\mathsf{T}}\right] \\ &+\frac{1}{N}\log\det\frac{1}{\sigma^2}\Psi(-\sigma^2)^{-1}-\frac{\sigma^2}{nN}\sum_{i,j}\sigma_{ij}^2\mathbf{T}_{ii}(-\sigma^2)\tilde{\mathbf{T}}_{jj}(-\sigma^2). \end{split}$$

Haar random matrices

M. Debbah, W. Hachem, P. Loubaton, M. de Courville, "MMSE analysis of certain large isometric random precoded systems", IEEE Transactions on Information Theory, vol. 49, no. 5, pp. 1293-1311, 2003.

Recent results were proposed when the matrices X_N are unitary and unitarily invariant (Haar matrices).

Haar random matrices

M. Debbah, W. Hachem, P. Loubaton, M. de Courville, "MMSE analysis of certain large isometric random precoded systems", IEEE Transactions on Information Theory, vol. 49, no. 5, pp. 1293-1311, 2003.

- Recent results were proposed when the matrices X_N are unitary and unitarily invariant (Haar matrices).
- The central result is the trace lemma

Lemma

Let $\mathbf{W} \in \mathbb{C}^{N \times n}$ be n < N columns of a Haar matrix and \mathbf{w} a column of \mathbf{W} . Let $\mathbf{B}_N \in \mathbb{C}^{N \times N}$ a random matrix, function of all columns of \mathbf{W} except \mathbf{w} . Then, assuming that, for growing N, $c = \sup_n n/N < 1$ and $B = \sup_N ||\mathbf{B}_N|| < \infty$, we have:

$$\mathbf{w}^{\mathsf{H}}\mathbf{B}_{N}\mathbf{w} - \frac{1}{N-n}tr(\mathbf{I}_{N} - \mathbf{W}\mathbf{W}^{\mathsf{H}})\mathbf{B}_{N} \xrightarrow{\text{a.s.}} 0.$$

Haar random matrices (2)

R. Couillet, J. Hoydis, M. Debbah, "Random beamforming over quasi-static and fading channels: a deterministic equivalent approach", to appear in IEEE Trans. on Inf. Theory.

Theorem

Let $\mathbf{T}_i \in \mathbb{C}^{n_i \times n_i}$ be nonnegative diagonal and let $\mathbf{H}_i \in \mathbb{C}^{N \times N_i}$. Define $\mathbf{R}_i \triangleq \mathbf{H}_i \mathbf{H}_i^{\mathrm{H}} \in \mathbb{C}^{N \times N}$, $c_i = \frac{n_i}{N_i}$ and $\bar{c}_i = \frac{N_i}{N}$. Denote

$$\mathbf{B}_{N} = \sum_{i=1}^{K} \mathbf{H}_{i} \mathbf{W}_{i} \mathbf{T}_{i} \mathbf{W}_{i}^{\mathsf{H}} \mathbf{H}_{i}^{\mathsf{H}}.$$

Then, as N, $N_1, \ldots, N_K, n_1, \ldots, n_K \to \infty$ with ratios bounded \bar{c}_i and $0 \leq c_i \leq 1$ for all *i*, almost surely

$$F^{\mathbf{B}_{N}} - F_{N} \Rightarrow 0$$
, with $m_{N}(z) = \frac{1}{N} tr \left(\sum_{i=1}^{K} \overline{e}_{i}(z) \mathbf{R}_{i} - z \mathbf{I}_{N} \right)^{-1}$

where $(\bar{e}_1(z), \ldots, \bar{e}_K(z))$ are the solutions (conditionally unique) of

$$e_{i}(z) = \frac{1}{N} tr \mathbf{R}_{i} \left(\sum_{j=1}^{K} \bar{e}_{j}(z) \mathbf{R}_{j} - z \mathbf{I}_{N} \right)^{-1}$$
$$\bar{e}_{i}(z) = \frac{1}{N} tr \mathbf{T}_{i} \left(e_{i}(z) \mathbf{T}_{i} + [\bar{c}_{i} - e_{i}(z)\bar{e}_{i}(z)] \mathbf{I}_{n_{i}} \right)^{-1} \quad (compare to i.i.d. case!)$$

Alternative strategies

There exists alternative proof strategies for specific models.

- The Gaussian method:
 - this technique is meant for random Gaussian X matrices
 - based on two ingredients: a Gaussian integration by parts formula, and the Nash-Poincaré inequality.
 - advantages:
 - sequential method, easy to use
 - give results on convergence speed: $N(E m_{B_N} m_N) \rightarrow 0$
 - goes beyond the Stieltjes transform method for quadratic forms.
 - drawbacks:
 - somewhat painful to use, leads to much calculus, less "elegant"
 - ▶ proves convergence of Gaussian-based models of type $N(Em_{B_N} m_N) \rightarrow 0$ (but interpolation trick can then be used)

Alternative strategies

There exists alternative proof strategies for specific models.

- The Gaussian method:
 - this technique is meant for random Gaussian X matrices
 - based on two ingredients: a Gaussian integration by parts formula, and the Nash-Poincaré inequality.
 - advantages:
 - sequential method, easy to use
 - give results on convergence speed: $N(E m_{B_N} m_N) \rightarrow 0$
 - goes beyond the Stieltjes transform method for quadratic forms.
 - drawbacks:
 - somewhat painful to use, leads to much calculus, less "elegant"
 - ▶ proves convergence of Gaussian-based models of type $N(\bar{E} m_{B_N} m_N) \rightarrow 0$ (but interpolation trick can then be used)
- Diagrammatic approaches: moment "drawing"-based approach that uses combinatorics from nuclear physics to infer limiting results
- Replica methods: physics-based method, non-mathematically accurate, to conjecture limiting results.

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Definition and method Toy example: Sum of doubly-correlated i.i.d. matrices A Central Limit Theorem

Research Today: Iterative Deterministic Equivalents

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Fluctuations of functionals of the e.s.d.

Z. D. Bai and J. W. Silverstein, "CLT of linear spectral statistics of large dimensional sample covariance matrices," The Annals of Probability, vol. 32, no. 1A, pp. 553-605, 2004.

Theorem

$$\mathbf{B}_{N} = \mathbf{T}_{N}^{\frac{1}{2}} \mathbf{X}_{N} \mathbf{X}_{N}^{\mathsf{H}} \mathbf{T}_{N}^{\frac{1}{2}}, \quad \underline{\mathbf{B}}_{N} = \mathbf{X}_{N}^{\mathsf{H}} \mathbf{T}_{N} \mathbf{X}_{N}$$

as usual with \mathbf{X}_N Gaussian, $F^{\mathsf{T}_N} = diag(\{\tau_i\}) \Rightarrow H$, $|\mathbf{T}_N|$, $\tau_1 \ge \ldots \ge \tau_N$. Denote F and F_N the *l.s.d.* and det. eq. of F^{B_N} , and

$$G_N \triangleq N\left[F^{\mathbf{B}_N} - F_N\right].$$

For f_1, \ldots, f_k well behaved, then

$$\left(\int f_1(x)dG_N(x),\ldots,\int f_k(x)dG_N(x)\right) \Rightarrow (X_{f_1},\ldots,X_{f_k})$$

of zero mean and covariance $\text{Cov}(X_f, X_g)$, $(f, g) \in \{f_1, \dots, f_k\}^2$, such that

$$\operatorname{Cov}(X_f, X_g) = -\frac{1}{2\pi i} \oint \oint \frac{f(z_1)g(z_2)}{(\underline{m}(z_1) - \underline{m}(z_2))^2} \underline{m}'(z_1)\underline{m}'(z_2)dz_1dz_2$$

for $\underline{m}(z)$ the Stieltjes transform of the l.s.d. of $\underline{\mathbf{B}}_{N}$. The integration contours are positively defined with winding number one and enclose the support of F.

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Research Today: Iterative Deterministic Equivalents

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Why iterated deterministic equivalents?

- > Deterministic equivalents for very involved channel models have been established.
- Most works deal with sums of independent random matrices.

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- > Deterministic equivalents for very involved channel models have been established.
- Most works deal with sums of independent random matrices.
- Iterated deterministic equivalents can be used for the study of more complex combinations of independents matrices.
- Applications extend to models that cannot be treated by free probability theory.

Iterated deterministic equivalents: A simple example

 $\mathbf{B}_N = \mathbf{Y}_n \mathbf{X}_n \mathbf{X}_n^{\mathsf{H}} \mathbf{Y}_n^{\mathsf{H}}$

- ▶ $\mathbf{X}_n \in \mathbb{C}^{n \times n}$: $[\mathbf{X}]_{i,j} \sim \mathcal{CN}\left(0, \frac{1}{n}\right)$
- $\mathbf{Y}_n \in \mathbb{C}^{n \times n}$: $[\mathbf{Y}]_{i,j} \sim \mathbb{CN}\left(0, \frac{1}{n}\right)$
- $\limsup_n \|\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}\| < \infty$, almost surely

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Idea: $\mathbf{Y}_n \mathbf{X}_n$ looks like a random matrix \mathbf{X}_n with random left-sided correlation \mathbf{Y}_n .

Iterated deterministic equivalents: A simple example

 $\mathbf{B}_N = \mathbf{Y}_n \mathbf{X}_n \mathbf{X}_n^{\mathsf{H}} \mathbf{Y}_n^{\mathsf{H}}$

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- ▶ $\mathbf{Y}_n \in \mathbb{C}^{n \times n}$: $[\mathbf{Y}]_{i,j} \sim \mathcal{CN}\left(0, \frac{1}{n}\right)$
- $\limsup_n \|\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}\| < \infty$, almost surely

Idea: $\mathbf{Y}_n \mathbf{X}_n$ looks like a random matrix \mathbf{X}_n with random left-sided correlation \mathbf{Y}_n . From Bai and Silverstein result and the Fubini theorem, we have

$$\frac{1}{n} \text{tr} \ (\mathbf{B}_n + x \mathbf{I}_n)^{-1} - \frac{1}{n} \text{tr} \ \left(\frac{\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}}{1 + e_n(x)} + x \mathbf{I}_n \right)^{-1} \xrightarrow{\text{a.s.}} \mathbf{0}$$

where $e_n(x)$ is the unique positive solution to

$$\mathbf{e}_n(x) = \frac{1}{n} \operatorname{tr} \mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}} \left(\frac{\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}}{1 + \mathbf{e}_n(x)} + x \mathbf{I}_n \right)^{-1}$$

Iterated deterministic equivalents: A simple example (2)

After straightforward calculations, we have

$$\begin{split} \frac{1}{n} \mathrm{tr} \, \left(\frac{\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathrm{H}}}{1 + e_{n}(x)} + x \mathbf{I}_{n} \right)^{-1} &= \left(1 + e_{n}(x) \right) \frac{1}{n} \mathrm{tr} \, \left(\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathrm{H}} + x \left(1 + e_{n}(x) \right) \mathbf{I}_{n} \right)^{-1} \\ e_{n}(x) &= \sqrt{\frac{1}{x \frac{1}{n} \mathrm{tr} \, \left(\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathrm{H}} + x \left(1 + e_{n}(x) \right) \mathbf{I}_{n} \right)^{-1}} - 1 \end{split}$$

Iterated deterministic equivalents: A simple example (2)

After straightforward calculations, we have

$$\frac{1}{n} \operatorname{tr} \left(\frac{\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathsf{H}}}{1 + e_{n}(x)} + x \mathbf{I}_{n} \right)^{-1} = (1 + e_{n}(x)) \frac{1}{n} \operatorname{tr} \left(\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathsf{H}} + x \left(1 + e_{n}(x) \right) \mathbf{I}_{n} \right)^{-1}$$
$$e_{n}(x) = \sqrt{\frac{1}{x \frac{1}{n} \operatorname{tr} \left(\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathsf{H}} + x \left(1 + e_{n}(x) \right) \mathbf{I}_{n} \right)^{-1}} - 1$$

Applying Bai and Silverstein again yields:

$$\frac{1}{n}\operatorname{tr}\left(\mathbf{Y}_{n}\mathbf{Y}_{n}^{\mathsf{H}}+x\left(1+e_{n}(x)\right)\mathbf{I}_{n}\right)^{-1}-\frac{\sqrt{1+\frac{4}{x(1+e_{n}(x))}}-1}{2}\xrightarrow{\mathrm{a.s.}}0.$$

Iterated deterministic equivalents: A simple example (2)

After straightforward calculations, we have

$$\frac{1}{n} \operatorname{tr} \left(\frac{\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathsf{H}}}{1 + e_{n}(x)} + x \mathbf{I}_{n} \right)^{-1} = (1 + e_{n}(x)) \frac{1}{n} \operatorname{tr} \left(\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathsf{H}} + x \left(1 + e_{n}(x) \right) \mathbf{I}_{n} \right)^{-1}$$
$$e_{n}(x) = \sqrt{\frac{1}{x \frac{1}{n} \operatorname{tr} \left(\mathbf{Y}_{n} \mathbf{Y}_{n}^{\mathsf{H}} + x \left(1 + e_{n}(x) \right) \mathbf{I}_{n} \right)^{-1}} - 1$$

Applying Bai and Silverstein again yields:

$$\frac{1}{n}\operatorname{tr}\left(\mathbf{Y}_{n}\mathbf{Y}_{n}^{\mathsf{H}}+x\left(1+e_{n}(x)\right)\mathbf{I}_{n}\right)^{-1}-\frac{\sqrt{1+\frac{4}{x(1+e_{n}(x))}-1}}{2}\xrightarrow{\mathrm{a.s.}}0.$$

Thus,

$$e_n(x) - \sqrt{\frac{2}{\sqrt{x^2 + \frac{4x}{1 + e_n(x)}} - x}} + 1 \xrightarrow{\text{a.s.}} 0$$

Iterated deterministic equivalents: A simple example (3/3)

Putting all pieces together, one can show that:

$$(i) \qquad \frac{1}{n} \operatorname{tr} \left(\mathbf{Y}_n \mathbf{X}_n \mathbf{X}_n^{\mathsf{H}} \mathbf{Y}_n^{\mathsf{H}} + x \mathbf{I}_n \right)^{-1} - \frac{1}{n} \operatorname{tr} \left(\frac{\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}}{1 + e_n(x)} + x \mathbf{I}_n \right)^{-1} \quad \xrightarrow{\text{a.s.}} \mathbf{0}$$

Iterated deterministic equivalents: A simple example (3/3)

Putting all pieces together, one can show that:

(*i*)
$$\frac{1}{n} \operatorname{tr} \left(\mathbf{Y}_n \mathbf{X}_n \mathbf{X}_n^{\mathsf{H}} \mathbf{Y}_n^{\mathsf{H}} + x \mathbf{I}_n \right)^{-1} - \frac{1}{n} \operatorname{tr} \left(\frac{\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}}{1 + e_n(x)} + x \mathbf{I}_n \right)^{-1} \xrightarrow{\text{a.s.}} 0$$

(*ii*)
$$\frac{1}{n} \operatorname{tr} \left(\frac{\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}}{1 + e_n(x)} + x \mathbf{I}_n \right)^{-1} - (1 + \bar{e}(x)) \frac{\sqrt{1 + \frac{4}{x(1 + \bar{e}(x))}} - 1}{2} \xrightarrow{\text{a.s.}} 0$$

where $\bar{e}(x)$ is the unique positive solution to

$$ar{\mathbf{e}}(x) = \sqrt{rac{2}{\sqrt{x^2 + rac{4x}{1 + ar{\mathbf{e}}(x)} - x}}} - 1.$$

Iterated deterministic equivalents: A simple example (3/3)

Putting all pieces together, one can show that:

(*i*)
$$\frac{1}{n} \operatorname{tr} \left(\mathbf{Y}_n \mathbf{X}_n \mathbf{X}_n^{\mathsf{H}} \mathbf{Y}_n^{\mathsf{H}} + x \mathbf{I}_n \right)^{-1} - \frac{1}{n} \operatorname{tr} \left(\frac{\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}}{1 + e_n(x)} + x \mathbf{I}_n \right)^{-1} \xrightarrow{\text{a.s.}} 0$$

(*ii*)
$$\frac{1}{n} \operatorname{tr} \left(\frac{\mathbf{Y}_n \mathbf{Y}_n^{\mathsf{H}}}{1 + e_n(x)} + x \mathbf{I}_n \right)^{-1} - (1 + \overline{e}(x)) \frac{\sqrt{1 + \frac{4}{x(1 + \overline{e}(x))}} - 1}{2} \xrightarrow{\text{a.s.}} 0$$

where $\overline{e}(x)$ is the unique positive solution to

$$\overline{\overline{e}}(x) = \sqrt{rac{2}{\sqrt{x^2 + rac{4x}{1 + \overline{e}(x)} - x}}} - 1.$$

- The same result can be obtained by arguments of free probability theory.
- We did not require the asymptotic freeness of X_n, Y_n in the proof.
- The same approach can be extended to more involved channel models.

Application to other models

Multiple models can be analyzed through the iterated deterministic equivalent approach:

R. Couillet, J. Hoydis, M. Debbah, "Random beamforming over quasi-static and fading channels: a deterministic equivalent approach", (to appear in) IEEE Transactions on Information Theory, arXiv Preprint 1011.3717.

- model $\mathbf{B}_N = \mathbf{H}\mathbf{W}\mathbf{P}\mathbf{W}^{\mathsf{H}}\mathbf{H}^{\mathsf{H}}$, with
 - ▶ $\mathbf{W} \in \mathbb{C}^{n \times p}$ Haar,
 - $\bullet \mathbf{H} = [\mathbf{h}_1, \dots, \mathbf{h}_n] \in \mathbb{C}^{N \times n}, \ \mathbf{h}_i = \mathbf{R}_i^{\frac{1}{2}} \mathbf{x}_i, \ \mathbf{x}_i \sim \mathcal{CN}(\mathbf{0}, \mathbf{I}_N),$
 - P Hermitian nonnegative.

J. Hoydis, R. Couillet, M. Debbah, "Asymptotic Analysis of Double-Scattering Channels", Asilomar Conference on Signals, Systems, and Computers, Pacific Grove, CA, USA, 2011.

- model $\mathbf{B}_N = \mathbf{H}_1 \mathbf{H}_2 \mathbf{H}_2^H \mathbf{H}_1^H$ with $\mathbf{H}_1 = \mathbf{R}_1 \mathbf{X}_1 \mathbf{T}_1$, $\mathbf{H}_2 = \mathbf{R}_2 \mathbf{X}_2 \mathbf{T}_2$
 - R₁, R₂, T₁, T₂ Hermitian nonnegative
 - X₁, X₂ independent with i.i.d. entries

J. Hoydis, R. Couillet, M. Debbah, "Iterative deterministic equivalents for the capacity analysis of communication systems", (submitted to) IEEE Transactions on Information Theory, 2011.

► model
$$\mathbf{B}_N = \left(\prod_{i=1}^N \mathbf{H}_i\right) \left(\prod_{i=1}^N \mathbf{H}_i\right)^H$$
, \mathbf{H}_i with i.i.d. entries

Related bibliography

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