Random Matrices in Wireless Communications Course 2: System performance analysis: capacity and rate regions

> Romain Couillet ST-Ericsson, Supélec, FRANCE romain.couillet@supelec.fr

> > Supélec

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Stieltjes transform methods for more elaborate models

2 Kronecker models and Variance Profiles

3 Capacity expressions, Rate Regions

Touching the boundary: optimal power allocation

5

Case study: exchanging relevant data in large self-organized networks

- Orthogonal CDMA networks
- Spectrum sharing in multiple access channels

# Outline

### Stieltjes transform methods for more elaborate models

- 2 Kronecker models and Variance Profiles
- Capacity expressions, Rate Regions
- 4 Touching the boundary: optimal power allocation
- Case study: exchanging relevant data in large self-organized networks
   Orthogonal CDMA networks
   Spectrum sharing in multiple access channels

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### Reminder and scope

- In Part 1 of this course,
  - we defined the Stieltjes transform:

#### Definition

Let *F* be a distribution function, and  $z \in \mathbb{C}^+$ . Then the Stieltjes transform  $m_F(z)$  of *F* is defined as

$$m_F(z) = \int \frac{1}{\lambda - z} dF(\lambda)$$

For *F* the spectral distribution of an Hermitian matrix  $\mathbf{X} \in \mathbb{C}^{N \times N}$ ,

$$m_F(z) = \frac{1}{N} \operatorname{tr}(\mathbf{X} - z \mathbf{I}_N)^{-1}$$

- We gave limiting distribution results for some matrix models.
- We gave a sketch of the proof of the Marčenko-Pastur law.

#### In Part 2, we will

- extend the notion of limit distributions to deterministic equivalents
- provide sound mathematical techniques to prove convergence/existence/uniqueness of large N results.
- provide first wireless communication results
- apply the results proven above to self-organized networks

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### previously, we showed results of the type:

"let  $\mathbf{X}_N$  be random,  $\mathbf{T}_N$  deterministic with  $F^{\mathbf{T}_N} \Rightarrow F^T$ , etc. Then, when  $N \to \infty$ , the e.s.d. of  $\mathbf{X}_N$  tends to F such that  $m_F$  is solution of a fixed-point equation,

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  - this assumes **T**<sub>N</sub> has a limiting distribution
  - if it does,  $m_{X_N X_N^H}$  can at best be approximated by  $m_F$  which is a function of the limiting  $F^T$ . For finite
    - $N, F^{*}$  may be very different from  $F^{*}$ .
  - any sequence  $T_N$  with l.s.d. F' engenders the same l.s.d.  $F_N$

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In this case,  $m_N^{\circ}$  is a function of  $\mathbf{T}_N$ , for fixed N and does not require any convergence of  $F^{\mathbf{T}_N}$ .

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### Stielties transform methods for more elaborate models Outline of the proofs

It will often be the case that the deterministic equivalent  $m_N^{\circ}(z)$  satisfies an implicit equation. The steps are then:

④ find a suitable function *f*, such that the *true* Stieltjes transform m<sub>X<sub>N</sub></sub>(z) satisfies, for fixed z ∈ C<sup>+</sup>,

$$m_{\mathbf{X}_N}(z) = f(m_{\mathbf{X}_N}(z)) + \varepsilon_N$$

where  $\varepsilon_N \xrightarrow{\text{a.s.}} 0$  as  $N \to \infty$ .

This can be done

- using Pastur's method (see proof of Marčenko-Pastur law in Part 1)
- using guess-work (see Bai and Silverstein's proofs)

Remark: This is as far as we went in Part 1.

2 For fixed *N*, prove the existence of a solution to

m = f(m)

This is often based on extracting a converging subsequence of  $m_N, m_{2N}, \ldots$  such that  $m_{jN}$  "has the same properties as  $m_{X_N}(z)$  for all *j*".

- For this fixed N, prove the uniqueness of the solution. This involves finding a contradiction if two solutions exist.
- ④ Calling  $m_N^{\circ}(z)$  the solution, prove finally that

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R. Couillet, M. Debbah, J. W. Silverstein, "A deterministic equivalent for the capacity analysis of correlated multi-user MIMO channels," *submitted to IEEE Trans. on Information Theory*.

We will give here the method of proof of the following result

#### Theorem

For  $K, N \in \mathbb{N}$ , let

$$\mathbf{B}_{N} = \sum_{k=1}^{K} \mathbf{R}_{k}^{\frac{1}{2}} \mathbf{X}_{k} \mathbf{T}_{k} \mathbf{X}_{k}^{\mathsf{H}} \mathbf{R}_{k}^{\frac{1}{2}} + \mathbf{A} \in \mathbb{C}^{N \times N}$$

where  $\mathbf{X}_k \in \mathbb{C}^{N \times n_k}$  *i.i.d.* of zero mean, variance  $1/n_k$ ;  $\mathbf{R}_k \in \mathbb{C}^{N \times N}$  Hermitian nonnegative definite;  $\mathbf{T}_k = \text{diag}(\tau_1, \ldots, \tau_{n_k}) \in \mathbb{R}^{n_k \times n_k}$ , diagonal with  $\tau_i \geq 0$ ; the sequences  $\{F^{\mathbf{T}_k}\}_{n_k \geq 1}$  and  $\{F^{\mathbf{R}_k}\}_{N \geq 1}$  are tight;  $\mathbf{A} \in \mathbb{C}^{N \times N}$  Hermitian positive definite;  $0 < a \leq \liminf_N c_k \leq \limsup_N c_N \leq b < \infty$  with  $c_k = N/n_k$ . Then

$$m_{\mathbf{B}_N}(z) - m_N^{\circ}(z) \xrightarrow{\text{a.s.}} 0$$

where

$$m_{N}^{\circ}(z) = \frac{1}{N} \operatorname{tr} \left( \mathbf{A} + \sum_{k=1}^{K} \int \frac{\tau_{k} dF^{\mathbf{T}_{k}}(\tau_{k})}{1 + c_{k} \tau_{k} e_{k}(z)} \mathbf{R}_{k} - z \mathbf{I}_{N} \right)^{-1}$$

and the scalars  $\{e_i(z)\}, i \in \{1, \ldots, K\}$ , form the unique solution to

$$\mathbf{e}_{i}(\mathbf{z}) = \frac{1}{N} \operatorname{tr} \mathbf{R}_{i} \left( \mathbf{A} + \sum_{k=1}^{K} \int \frac{\tau_{k} dF^{\mathsf{T}_{k}}(\tau_{k})}{1 + c_{k} \tau_{k} \mathbf{e}_{k}(\mathbf{z})} \mathbf{R}_{k} - \mathbf{z} \mathbf{I}_{N} \right)^{-1}$$

such that  $sgn(\Im[e_i(z)]) = sgn(\Im[z])$ .

# A "telecom-oriented" version of the same result

R. Couillet, M. Debbah, J. W. Silverstein, "A deterministic equivalent for the capacity analysis of correlated multi-user MIMO channels," *submitted to IEEE Trans. on Information Theory.* 

$$\mathbf{B}_N = \sum_{k=1}^{K} \mathbf{H}_k \mathbf{H}_k^{\mathsf{H}}, \text{ with } \mathbf{H}_k = \mathbf{R}_k^{\frac{1}{2}} \mathbf{X}_k \mathbf{T}_k^{\frac{1}{2}}$$

with  $\mathbf{X}_k \in \mathbb{C}^{N \times n_k}$  with i.i.d. entries of zero mean, variance  $1/n_k$ ,  $\mathbf{R}_k$  Hermitian nonnegative definite,  $\mathbf{T}_k$  diagonal. Denote  $c_k = N/n_k$ . Then, as all N and  $n_k$  grow large, with ratio  $c_k$ ,

$$m_{F^{\mathbf{B}_{N}}}(z) - m_{N}^{\circ}(z) \xrightarrow{\mathrm{a.s.}} 0$$

where

$$m_N^{\circ}(z) = \frac{1}{N} \operatorname{tr} \left( -z \left[ \mathbf{I}_N + \sum_{k=1}^K \bar{\mathbf{e}}_k(z) \mathbf{R}_k \right] \right)^{-1}$$

and the set of functions  $\{e_i(z)\}$  form the unique solution to the K equations

$$e_{i}(z) = \frac{1}{N} \operatorname{tr} \mathbf{R}_{i} \left( -z \left[ \mathbf{I}_{N} + \sum_{k=1}^{K} \bar{e}_{k}(z) \mathbf{R}_{k} \right] \right)^{-1}$$
$$\bar{e}_{i}(z) = \frac{1}{n_{i}} \operatorname{tr} \mathbf{T}_{i} \left( -z \left[ \mathbf{I}_{n_{i}} + c_{i} e_{i}(z) \mathbf{T}_{i} \right] \right)^{-1}$$

R. Couillet (Supélec)

## Pastur's method

### Pastur's method is *not* applicable here, unless all $\mathbf{R}_k$ 's are diagonal.

Consider K = 2,  $\mathbf{A} = 0$  and denote  $\mathbf{H}_k = \mathbf{R}_k^{\frac{1}{2}} \mathbf{X}_k \mathbf{T}_k^{\frac{1}{2}}$ , with diagonal  $\mathbf{R}_k$ . By block-matrix inversion, we have

$$\begin{pmatrix} \mathbf{H}_{1}\mathbf{H}_{1}^{H} + \mathbf{H}_{2}\mathbf{H}_{2}^{H} - z\mathbf{I}_{N} \end{pmatrix}_{11}^{-1} = \left( \begin{bmatrix} \mathbf{h}_{1}^{H} \mathbf{h}_{2}^{H} \\ \mathbf{U}_{1} \mathbf{U}_{2} \end{bmatrix} \begin{bmatrix} \mathbf{h}_{1} \mathbf{U}_{1}^{H} \\ \mathbf{h}_{2} \mathbf{U}_{2}^{H} \end{bmatrix} - z\mathbf{I}_{N} \right)_{11}^{-1}$$
$$= \left[ -z - z[\mathbf{h}_{1}^{H}\mathbf{h}_{2}^{H}] \left( \begin{bmatrix} \mathbf{U}_{1}^{H} \\ \mathbf{U}_{2}^{H} \end{bmatrix} [\mathbf{U}_{1}\mathbf{U}_{2}] - z\mathbf{I}_{n_{1}+n_{2}} \right)^{-1} \begin{bmatrix} \mathbf{h}_{1} \\ \mathbf{h}_{2} \end{bmatrix} \right]^{-1}$$

with the definition  $\mathbf{H}_{i}^{H} = [\mathbf{h}_{i}\mathbf{U}_{i}^{H}]$ . The inner inverse matrix is

$$\begin{pmatrix} \begin{bmatrix} \mathbf{U}_1^H \\ \mathbf{U}_2^H \end{bmatrix} \begin{bmatrix} \mathbf{U}_1 \mathbf{U}_2 \end{bmatrix} - z\mathbf{I}_{n_1+n_2} \end{pmatrix}^{-1} = \begin{bmatrix} \mathbf{U}_1^H \mathbf{U}_1 - z\mathbf{I}_{n_1} & \mathbf{U}_1^H \mathbf{U}_2 \\ \mathbf{U}_2^H \mathbf{U}_1 & \mathbf{U}_2^H \mathbf{U}_2 - z\mathbf{I}_{n_2} \end{bmatrix}^{-1}$$

on which we apply another block matrix inverse lemma. The upper-left ( $n_1 \times n_1$ ) entry equals

$$\left(-z\mathbf{U}_{1}^{\mathsf{H}}(\mathbf{U}_{2}\mathbf{U}_{2}^{\mathsf{H}}-z\mathbf{I}_{N-1})^{-1}\mathbf{U}_{1}-z\mathbf{I}_{n_{1}}\right)^{-1}$$

For the second block diagonal entry, it suffices to revert all 1's in 2's and vice-versa.

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# Pastur's method (2)

The other two terms do not depend on  $h_1$ ,  $h_2$ . We now use both results,

For  $\mathbf{x} \in \mathbb{C}^N$ ,  $\mathbf{y} \in \mathbb{C}^N$  i.i.d. with zero mean, variance 1/N,  $\mathbf{A} \in \mathbb{C}^{N \times N}$  Hermitian with bounded spectral norm,

$$\mathbf{x}^{\mathsf{H}}\mathbf{A}\mathbf{x} - \frac{1}{N} \operatorname{tr} \mathbf{A} \stackrel{\text{a.s.}}{\longrightarrow} \mathbf{0}$$
  
 $\mathbf{x}^{\mathsf{H}}\mathbf{A}\mathbf{y} \stackrel{\text{a.s.}}{\longrightarrow} \mathbf{0}$ 

Since  $\mathbf{R}_1$ ,  $\mathbf{R}_2$  are diagonal,  $\mathbf{h}_i = \sqrt{r_{i1} \mathbf{T}_i^2} \mathbf{x}_i$ , with the notation  $\mathbf{R}_i = \text{diag}(r_{i1}, \dots, r_{iN})$ . Therefore, using the trace and rank-1 perturbation lemma,

$$\left( \mathbf{H}_{1}\mathbf{H}_{1}^{H} + \mathbf{H}_{2}\mathbf{H}_{2}^{H} - z\mathbf{I}_{N} \right)_{11}^{-1} \rightarrow \left[ -z - zr_{11}\frac{1}{n_{1}} \operatorname{tr} \mathbf{T}_{1} \left( -z\mathbf{H}_{1}^{H}(\mathbf{H}_{2}\mathbf{H}_{2}^{H} - z\mathbf{I}_{N})^{-1}\mathbf{H}_{1} - z\mathbf{I}_{n_{1}} \right)^{-1} - zr_{21}\frac{1}{n_{2}} \operatorname{tr} \mathbf{T}_{2} \left( -z\mathbf{H}_{2}^{H}(\mathbf{H}_{1}\mathbf{H}_{1}^{H} - z\mathbf{I}_{N})^{-1}\mathbf{H}_{1} - z\mathbf{I}_{n_{2}} \right)^{-1} \right]$$

#### ecker models and Variance Profiles

# Pastur's method (3)

Now, denoting  $\mathbf{H}_i = [\tilde{\mathbf{h}}_i \tilde{\mathbf{U}}_i]$  (column selection instead of row),

$$\mathbf{T}_{1} \left( -z\mathbf{H}_{1}^{H}(\mathbf{H}_{2}\mathbf{H}_{2}^{H} - z\mathbf{I}_{N})^{-1}\mathbf{H}_{1} - z\mathbf{I}_{n_{1}} \right)_{11}^{-1} = \tau_{11} \left[ -z - z\tilde{\mathbf{h}}_{1}^{H} \left( \tilde{\mathbf{U}}_{1}\tilde{\mathbf{U}}_{1}^{H} + \mathbf{H}_{2}\mathbf{H}_{2}^{H} - z\mathbf{I}_{N} \right)^{-1} \tilde{\mathbf{h}}_{1} \right]^{-1} \\ \rightarrow \tau_{11} \left[ -z - zc_{1}\tau_{11}\frac{1}{N} \operatorname{tr} \mathbf{R}_{1} \left( \mathbf{H}_{1}\mathbf{H}_{1}^{H} + \mathbf{H}_{2}\mathbf{H}_{2}^{H} - z\mathbf{I}_{N} \right)^{-1} \right]^{-1}$$

with  $\tau_{ij}$  the j<sup>th</sup> diagonal entry of  $\mathbf{T}_i$ . A similar result holds when changing 1's in 2's. Call now

$$f_i = \frac{1}{N} \operatorname{tr} \mathbf{R}_i \left( \mathbf{H}_1 \mathbf{H}_1^{\mathsf{H}} + \mathbf{H}_2 \mathbf{H}_2^{\mathsf{H}} - z \mathbf{I}_N \right)^{-2}$$

and

$$\bar{f}_i = \frac{1}{n_i} \operatorname{tr} \mathbf{T}_i \left( -z \mathbf{H}_1^{\mathsf{H}} (\mathbf{H}_2 \mathbf{H}_2^{\mathsf{H}} - z \mathbf{I}_N)^{-1} \mathbf{H}_1 - z \mathbf{I}_{n_1} \right)^{-1}$$

we have shown

$$f_i = \lim_{N \to \infty} \frac{1}{N} \operatorname{tr} \mathbf{R}_i \left( -z \overline{f}_1 \mathbf{R}_1 - z \overline{f}_2 \mathbf{R}_2 - z \mathbf{I}_N \right)^{-1}$$
  
$$\overline{f}_i = \lim_{N \to \infty} \frac{1}{n_i} \operatorname{tr} \mathbf{T}_i \left( -z c_i f_i \mathbf{T}_i - z \mathbf{I}_{n_i} \right)^{-1}$$

We will use here the "guess-work" method to find the deterministic equivalent. Consider the simpler case K = 1.

Back to the original notations, we seek a matrix **D** such that

$$\frac{1}{N}\operatorname{tr}(\mathbf{B}_N - z\mathbf{I}_N)^{-1} - \frac{1}{N}\operatorname{tr}\mathbf{D}^{-1} \xrightarrow{\text{a.s.}} 0$$

as  $N \to \infty$ .

#### **Resolvent lemma**

For invertible A, B matrices,

$$A^{-1} - B^{-1} = -A^{-1}(A - B)B^{-1}$$

Taking the matrix differences,

$$-\mathbf{D}^{-1} + (\mathbf{B}_N - z\mathbf{I}_N)^{-1} = \mathbf{D}^{-1}(\mathbf{A} + \mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} - z\mathbf{I}_N - \mathbf{D})(\mathbf{B}_N - z\mathbf{I}_N)^{-1}$$

It seems convenient to take  $\mathbf{D} = \mathbf{A} - z\mathbf{I}_N - zp_N \mathbf{R}$  with  $p_N$  left to be defined

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### "Silverstein's" lemma

Let A be Hermitian invertible, then for any vector x and scalar  $\tau$  such that  $\mathbf{A} + \tau \mathbf{x} \mathbf{x}^{H}$  is invertible

$$\mathbf{x}^{\mathsf{H}}(\mathbf{A} + au \mathbf{x} \mathbf{x}^{\mathsf{H}})^{-1} = rac{\mathbf{x}^{\mathsf{H}} \mathbf{A}^{-1}}{1 + au \mathbf{x} \mathbf{A}^{-1} \mathbf{x}^{\mathsf{H}}}$$

With  $\mathbf{D} = \mathbf{A} - z\mathbf{I}_N - zp_N\mathbf{R}$ ,

$$-\mathbf{D}^{-1} + (\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} = \mathbf{D}^{-1}(\mathbf{A} + \mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} - z\mathbf{I}_{N} - \mathbf{D})(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$
  
$$= \mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\left(\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\right)\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} + zp_{N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$
  
$$= \mathbf{D}^{-1}\sum_{j=1}^{n}\tau_{j}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}\mathbf{x}_{j}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} + zp_{N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$
  
$$= \sum_{j=1}^{n}\tau_{j}\frac{\mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}\mathbf{x}_{j}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1}}{1 + \tau_{j}\mathbf{x}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}} + zp_{N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$
  
poice of  $p_{N}$ :  $p_{N} = -\frac{1}{2}\sum_{j=1}^{n}\sqrt{\frac{\tau_{j}}{1 + \tau_{j}\mathbf{x}^{\mathsf{H}}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}}$ 

$$\frac{1}{N}\operatorname{tr}(\mathbf{B}_{N}-z\mathbf{I}_{N})^{-1} - \frac{1}{N}\operatorname{tr}\mathbf{D}^{-1} = \sum_{j=1}^{n} \tau_{j} \left[ \frac{\mathbf{x}_{j}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)}-z\mathbf{I}_{N})^{-1}\mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}}{1 + \tau_{j}\mathbf{x}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)}-z\mathbf{I}_{N})^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}} - \frac{\frac{1}{N}\operatorname{tr}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N}-z\mathbf{I}_{N})^{-1}\mathbf{R}\mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}}{1 + c\tau_{j}\frac{1}{N}\operatorname{tr}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N}-z\mathbf{I}_{N})^{-1}}\mathbf{R}^{\frac{1}{2}}\mathbf{R}^{\frac{1}{2}}\right]$$

### "Silverstein's" lemma

Let A be Hermitian invertible, then for any vector x and scalar  $\tau$  such that  $\mathbf{A} + \tau \mathbf{x} \mathbf{x}^{H}$  is invertible

$$\mathbf{x}^{\mathsf{H}}(\mathbf{A} + au\mathbf{x}\mathbf{x}^{\mathsf{H}})^{-1} = rac{\mathbf{x}^{\mathsf{H}}\mathbf{A}^{-1}}{1 + au\mathbf{x}\mathbf{A}^{-1}\mathbf{x}^{\mathsf{H}}}$$

With  $\mathbf{D} = \mathbf{A} - z\mathbf{I}_N - zp_N\mathbf{R}$ ,

$$-\mathbf{D}^{-1} + (\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} = \mathbf{D}^{-1}(\mathbf{A} + \mathbf{R}^{\frac{1}{2}}\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}} - z\mathbf{I}_{N} - \mathbf{D})(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$

$$= \mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\left(\mathbf{X}\mathbf{T}\mathbf{X}^{\mathsf{H}}\right)\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} + zp_{N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$

$$= \mathbf{D}^{-1}\sum_{j=1}^{n}\tau_{j}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}\mathbf{x}_{j}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1} + zp_{N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$

$$= \sum_{j=1}^{n}\tau_{j}\frac{\mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}\mathbf{x}_{j}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1}}{1 + \tau_{j}\mathbf{x}^{\mathsf{H}}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)} - z\mathbf{I}_{N})^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}} + zp_{N}\mathbf{D}^{-1}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$$
Choice of  $p_{N}$ :  $p_{N} = -\frac{1}{z}\sum_{j=1}^{n}\frac{\tau_{j}}{1 + \tau_{j}c\frac{\pi}{N}}\mathbf{t}\mathbf{R}(\mathbf{B}_{N} - z\mathbf{I}_{N})^{-1}$ 

$$\frac{1}{N}\operatorname{tr}(\mathbf{B}_{N}-z\mathbf{I}_{N})^{-1} - \frac{1}{N}\operatorname{tr}\mathbf{D}^{-1} = \sum_{j=1}^{n} \tau_{j} \left[ \frac{\mathbf{x}_{j}^{H}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)}-z\mathbf{I}_{N})^{-1}\mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}}{1 + \tau_{j}\mathbf{x}^{H}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{(j)}-z\mathbf{I}_{N})^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{x}_{j}} - \frac{\frac{1}{N}\operatorname{tr}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N}-z\mathbf{I}_{N})^{-1}\mathbf{R}\mathbf{D}^{-1}\mathbf{R}^{\frac{1}{2}}\mathbf{R}}{1 + c\tau_{j}\frac{1}{N}\operatorname{tr}\mathbf{R}^{\frac{1}{2}}(\mathbf{B}_{N}-z\mathbf{I}_{N})^{-1}\mathbf{R}} \right]$$

R. Couillet (Supélec

The same can be done for  $\frac{1}{N}$  tr  $\mathbf{R}(\mathbf{B}_N - z\mathbf{I}_N)^{-1}$  and we get

$$\frac{1}{N}\operatorname{tr} \mathbf{R}(\mathbf{B}_N - z\mathbf{I}_N)^{-1} - \frac{1}{N}\operatorname{tr} \mathbf{R}\mathbf{D}^{-1} \to 0$$

To show that the convergence is almost sure, we use truncation and centralization.

Truncation and centralization

Replace  $\mathbf{X}_N$ ,  $\mathbf{T}_N$  and  $\mathbf{R}_N$  by  $\overline{\mathbf{X}}_N$ ,  $\overline{\mathbf{T}}_N$  and  $\overline{\mathbf{R}}_N$  in the following fashion

$$\left(\mathbf{\bar{X}}_{N}\right)_{ij} = (\mathbf{X}_{N})_{ij} \cdot I_{\{(\mathbf{X}_{N})_{ij} < g_{N}\}}$$

for  $g_N$  that grows

- fast enough to ensure  $F^{\mathbf{B}_N} F^{\mathbf{\overline{B}}_N} \Rightarrow 0$
- slow enough to ensure  $\frac{1}{N} \operatorname{tr}(\bar{\mathbf{B}}_N z\mathbf{I}_N)^{-1} \frac{1}{N} \operatorname{tr} \bar{\mathbf{R}} \bar{\mathbf{D}}^{-1} \xrightarrow{\text{a.s.}} 0$

Showing that some moment of the terms appearing in the difference is summable, applying Borel-Cantelli lemma, we have almost sure convergence.

DQA

#### Kronecker models and Variance Profiles Application of the Borel-Cantelli lemma

To complete the proof of almost sure convergence, denote

$$w_N = rac{1}{N} \operatorname{tr} \mathbf{R} (\mathbf{B}_N - z \mathbf{I}_N)^{-1} - rac{1}{N} \operatorname{tr} \mathbf{R} \mathbf{D}^{-1}$$

We divide  $w_N$  is 4 successive differences  $w_N = w_N^1 + \ldots + w_N^4$ . The strategy is as follows:

for all i, show that

$$\mathrm{E}|w_N^i|^6 < h_N^i$$

where  $h_N^i$  is summable

• for  $\varepsilon > 0$ , applying Markov's inequality,

$$P(|h_N^i| > arepsilon) < rac{1}{arepsilon^6} \mathrm{E} |w_N^i|^6$$

which is summable.

- from Borel-Cantelli, this implies  $P(|h_N^i| > \varepsilon \text{ i.o.}) = 0$
- therefore the set {ω : lim<sub>N</sub> m<sub>B<sub>N</sub>(ω)</sub>(z) − m<sup>o</sup><sub>N</sub>(z) = 0}<sup>c</sup> = ∪<sub>ε</sub> {|m<sub>B<sub>N</sub>(z)</sub> − m<sup>o</sup><sub>N</sub>(z)| ≥ ε i.o.} is a sum of zero probability sets.
- the union above can be done on rational ε's and then the union has probability zero.
- for the z in question, there therefore exists Ω<sub>z</sub> ⊂ Ω for which lim<sub>N</sub> m<sub>B<sub>N</sub>(ω)</sub>(z) − m<sup>c</sup><sub>N</sub>(z) = 0. It suffices then to countably sample C<sup>+</sup> to generate a dense set of z's which satisfy convergence with probability 1. By local analyticity of m<sup>c</sup><sub>N</sub> and m<sub>B<sub>N</sub></sub>, this is true for all z ∈ C<sup>+</sup>.

Image: A matrix

Fix now N and consider the implicit equation in e

$$\mathbf{e} = \frac{1}{N} \operatorname{tr} \mathbf{R}_{i} \left( \mathbf{A} + \int \frac{\tau d F^{\mathsf{T}}(\tau)}{1 + c \tau \mathbf{e}} \mathbf{R} - z \mathbf{I}_{N} \right)^{-1}$$

• Existence: for existence, consider the matrices  $T_{[j]} = T \otimes I_j$ ,  $R_{[j]} = R \otimes I_j$ ,  $A_{[j]} = A \otimes I_j$ . The value of

$$f(\mathbf{e}) = \frac{1}{N} \operatorname{tr} \mathbf{R} \left( \mathbf{A}_{[j]} + \int \frac{\tau d F^{\mathsf{T}_{[j]}}(\tau)}{1 + c\tau e} \mathbf{R}_{[j]} - z \mathbf{I}_{N} \right)^{-1}$$

is constant whatever *m*. Now, take  $\omega \in \Omega$  such that  $w_N(\omega) \to 0$ . For this  $\omega$ , write

$$\tilde{e}(z) = \frac{1}{N} \operatorname{tr}(\mathbf{B}_N(\omega) - z \mathbf{I}_N)^{-1}$$

Showing that  $\tilde{e}(z)$  and  $\frac{\tau}{1+c\tau e}$  are uniformly bounded over *j*, we can take a subsequence of  $\tilde{e}(z)$  that goes to, say e. For this e,  $w_N = 0$  and then it's a solution.

• Uniqueness: Uniqueness is shown by taking a second solution <u>e</u> and by proving that

$$\mathbf{e} - \underline{\mathbf{e}} = \gamma(\mathbf{e} - \underline{\mathbf{e}})$$

with  $\gamma < 1$ .

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Deterministic equivalent approach: existence and uniqueness

Fix now N and consider the implicit equation in e

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• Existence: for existence, consider the matrices  $\mathbf{T}_{[j]} = \mathbf{T} \otimes \mathbf{I}_j$ ,  $\mathbf{R}_{[j]} = \mathbf{R} \otimes \mathbf{I}_j$ ,  $\mathbf{A}_{[j]} = \mathbf{A} \otimes \mathbf{I}_j$ . The value of

$$f(e) = \frac{1}{N} \operatorname{tr} \mathbf{R} \left( \mathbf{A}_{[j]} + \int \frac{\tau dF^{\mathsf{T}_{[j]}}(\tau)}{1 + c\tau e} \mathbf{R}_{[j]} - z \mathbf{I}_N \right)^{-1}$$

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Showing that  $\tilde{e}(z)$  and  $\frac{\tau}{1+c\tau e}$  are uniformly bounded over *j*, we can take a subsequence of  $\tilde{e}(z)$  that goes to, say *e*. For this *e*,  $w_N = 0$  and then it's a solution.

• Uniqueness: Uniqueness is shown by taking a second solution <u>e</u> and by proving that

$$\mathbf{e} - \underline{\mathbf{e}} = \gamma(\mathbf{e} - \underline{\mathbf{e}})$$

with  $\gamma < 1$ .

• It then suffices to show that  $\frac{1}{N}$  tr  $\mathbf{R}(\mathbf{B}_N - z\mathbf{I}_N)^{-1} - e \xrightarrow{\text{a.s.}} 0$ 

This exploits the fact that, for some  $\omega$  in a probability one space,  $\frac{1}{N}$  tr  $\mathbf{R}(\mathbf{B}_N(\omega) - z\mathbf{I}_N)^{-1}$  is  $w_N$  away from  $\frac{1}{N}\mathbf{D}^{-1}\mathbf{R}$ . Using the same argument as for uniqueness, we have

$$\mathbf{e} - \frac{1}{N} \operatorname{tr} \mathbf{R} (\mathbf{B}_N(\omega) - z \mathbf{I}_N)^{-1} = \gamma (\mathbf{e} - \frac{1}{N} \operatorname{tr} \mathbf{R} (\mathbf{B}_N(\omega) - z \mathbf{I}_N)^{-1}) + w_N$$

for  $\gamma < 1$ .

• The same argument applies to  $m_N(z) - m_N^{\circ}(z)$ .

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### Remember now that

$$\int \log(1+xt)dF(t) = \int_{1/x}^{\infty} \left(\frac{1}{t} - m_F(-t)\right)dt$$

R. Couillet, M. Debbah, J. W. Silverstein, "A deterministic equivalent for the capacity analysis of correlated multi-user MIMO channels," *submitted to IEEE Trans. on Information Theory.* 

#### Theorem

Under the previous model for  $\mathbf{B}_N$ , as N,  $n_k$  grow large,

$$\frac{1}{N}\log\det(\mathbf{B}_N + x\mathbf{I}_N) - \left[\frac{1}{N}\log\det\left(\mathbf{I}_N + \sum_{k=1}^{K}\bar{\mathbf{e}}_k(-1/x)\mathbf{R}_k\right) + \sum_{k=1}^{K}\frac{1}{N}\log\det\left(\mathbf{I}_{n_k} + c_k\mathbf{e}_k(-1/x)\mathbf{T}_k\right) - \frac{1}{x}\sum_{k=1}^{K}\bar{\mathbf{e}}_k(-1/x)\mathbf{e}_k(-1/x)\right] \xrightarrow{\text{a.s.}} 0$$

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(a)

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# Variance profile

W. Hachem, Ph. Loubaton, J. Najim, "Deterministic equivalents for certain functionals of large random matrices," Annals of Applied Probability, vol. 17, no. 3, pp. 875-930, 2007.

#### Theorem

Let  $\mathbf{X}_N \in \mathbb{C}^{N \times n}$  have independent entries with  $(i, j)^{th}$  entry of zero mean and variance  $\frac{1}{n}\sigma_{ij}^2$ . Let  $\mathbf{A}_N \in \mathbb{R}^{N \times n}$  be deterministic with uniformly bounded column norm. Then

$$\frac{1}{N}\operatorname{tr}\left((\mathbf{X}_N+\mathbf{A}_N)(\mathbf{X}_N+\mathbf{A}_N)^{\mathsf{H}}-z\mathbf{I}_N\right)^{-1}-\frac{1}{N}\operatorname{tr}\mathbf{T}_N(z)\xrightarrow{\mathrm{a.s.}}0$$

where  $\mathbf{T}_N(z)$  is the unique function that solves

$$\mathbf{T}_N(z) = \left(\Psi^{-1}(z) - z\mathbf{A}_N\tilde{\Psi}(z)\mathbf{A}_N^{\mathsf{T}}\right)^{-1}, \quad \tilde{\mathbf{T}}_N(z) = \left(\tilde{\Psi}^{-1}(z) - z\mathbf{A}_N^{\mathsf{T}}\Psi(z)\mathbf{A}_N\right)^{-1}$$

with  $\Psi(z) = \text{diag}(\psi_i(z)), \tilde{\Psi}(z) = \text{diag}(\tilde{\psi}_i(z))$ , with entries defined as

$$\psi_i(z) = -\left(z(1+\frac{1}{n}\operatorname{tr} \tilde{\mathbf{D}}_i \tilde{\mathbf{T}}(z))\right)^{-1}, \quad \tilde{\psi}_j(z) = -\left(z(1+\frac{1}{n}\operatorname{tr} \mathbf{D}_j \mathbf{T}(z))\right)^{-1}$$

and  $\mathbf{D}_j = \text{diag}(\sigma_{ij}^2, 1 \le i \le N), \, \tilde{\mathbf{D}}_i = \text{diag}(\sigma_{ij}^2, 1 \le j \le n)$ 

W. Hachem, Ph. Loubaton, J. Najim, "Deterministic equivalents for certain functionals of large random matrices," Annals of Applied Probability, vol. 17, no. 3, pp. 875-930, 2007.

#### Theorem

For the previous model, we also have that

$$\frac{1}{N} \operatorname{E} \log \det \left( \mathbf{I}_{N} + \frac{1}{\sigma^{2}} (\mathbf{X}_{N} + \mathbf{A}_{N}) (\mathbf{X}_{N} + \mathbf{A}_{N})^{\mathsf{H}} \right)$$

has deterministic equivalent

$$\frac{1}{N}\log\det\left[\frac{1}{\sigma^2}\Psi(-\sigma^2)^{-1} + \mathbf{A}_N\tilde{\Psi}(-\sigma^2)\mathbf{A}_N^{\mathsf{T}}\right] + \frac{1}{N}\log\det\frac{1}{\sigma^2}\Psi(-\sigma^2)^{-1} - \frac{\sigma^2}{nN}\sum_{i,j}\sigma_{ij}^2\mathbf{T}_{ii}(-\sigma^2)\tilde{\mathbf{T}}_{jj}(-\sigma^2)$$

necker models and Variance Profiles

# Alternative strategies

There exists alternative proof strategies for specific models.

- The Gaussian method:
  - this technique is meant for random Gaussian X matrices
  - based on two ingredients: a Gaussian integration by parts formula, and the Nash-Poincaré inequality.
  - advantages:
    - sequential method, easy to use
    - give results on convergence speed
    - proves convergence of Gaussian-based models of type  $N(Em_N m_N^{\circ}) \rightarrow 0$
    - ⇒ very convenient to prove total capacity convergence, instead of average capacity.
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    - somewhat painful to use, leads to much calculus, less "elegant"
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    - ightarrow ightarrow less powerful than almost sure results
    - → limited to Gaussian.
- Diagrammatic approaches: moment "drawing"-based approach that uses combinatorics to infer limiting results
- Replica methods: physics-based method, non-mathematically accurate, to conjecture limiting results.

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# Outline

Stieltjes transform methods for more elaborate models

2 Kronecker models and Variance Profiles

3 Capacity expressions, Rate Regions

Touching the boundary: optimal power allocation

Case study: exchanging relevant data in large self-organized networks
 Orthogonal CDMA networks

Spectrum sharing in multiple access channels

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### Capacity expressions. Rate Regions Broadcast channel with Kronecker model



Figure: Downlink scenario in multi-user broadcast channel

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S. Vishwanath, N. Jindal and A. Goldsmith, "Duality, Achievable Rates, and Sum-Rate Capacity of Gaussian MIMO Broadcast Channels," IEEE Trans. on Information Theory, vol. 49, no. 10, 2003.

Assume all channels are modeled as Kronecker; for k = 1, ..., K

$$\mathbf{H}_k = \mathbf{R}_k^{\frac{1}{2}} \mathbf{X}_k \mathbf{T}_k^{\frac{1}{2}}$$

• Rate region of multiple access channel for K users with channels  $\mathbf{H} = [\mathbf{H}_1, \dots, \mathbf{H}_K]$ ,

$$\begin{aligned} \mathbf{C}_{\mathrm{MAC}}(P_{1},\ldots,P_{K};\mathbf{H}) &= \\ & \bigcup_{\substack{\mathrm{tr}(\mathbf{P}_{i}) \leq P_{i} \\ \mathbf{P}_{i} \geq 0 \\ i=1,\ldots,K}} \left\{ \{R_{i},1 \leq i \leq K\} : \sum_{i \in \mathcal{S}} R_{i} \leq \frac{1}{N} \log \left| \mathbf{I} + \frac{1}{\sigma^{2}} \sum_{i \in \mathcal{S}} \mathbf{H}_{i} \mathbf{P}_{i} \mathbf{H}_{i}^{\mathsf{H}} \right|, \forall \mathcal{S} \subset \{1,\ldots,K\} \right\} \end{aligned}$$

• Rate region of broadcast channel for  $\mathbf{H}^{H} = [\mathbf{H}_{1}, \dots, \mathbf{H}_{K}]^{H}$  with total transmit power P,

$$\mathbf{C}_{\mathrm{BC}}(P;\mathbf{H}^{\mathrm{H}}) = \bigcup_{\sum_{k=1}^{K} P_k \leq P} \mathbf{C}_{\mathrm{MAC}}(P_1,\ldots,P_K;\mathbf{H})$$

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Under the previous model for  $\mathbf{B}_N$ , as N,  $n_k$  grow large,

$$\begin{aligned} \frac{1}{N} \log \left| \mathbf{I} + \frac{1}{\sigma^2} \sum_{k \in \mathcal{S}} \mathbf{H}_k \mathbf{P}_k \mathbf{H}_k^{\mathsf{H}} \right| &- \left[ \frac{1}{N} \log \det \left( \mathbf{I}_N + \sum_{k \in \mathcal{S}} \bar{\mathbf{e}}_k (-1/x) \mathbf{R}_k \right) \right. \\ &+ \sum_{k \in \mathcal{S}} \frac{1}{N} \log \det \left( \mathbf{I}_{n_k} + c_k e_k (-1/x) \mathbf{T}_k^{\frac{1}{2}} \mathbf{P}_k \mathbf{T}_k^{\frac{1}{2}} \right) \\ &- \frac{1}{x} \sum_{k=1}^K \bar{\mathbf{e}}_k (-1/x) e_k (-1/x) \right] \xrightarrow{\text{a.s.}} 0 \end{aligned}$$

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# Outline

Stieltjes transform methods for more elaborate models

2 Kronecker models and Variance Profiles

3 Capacity expressions, Rate Regions

## Touching the boundary: optimal power allocation

Case study: exchanging relevant data in large self-organized networks
 Orthogonal CDMA networks

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# Rate region boundary

### • it is desirable to determine the boundary of the rate region

- for *theoretical purposes*: to fully determine the rate region and alleviate the  $\bigcup_{P_4,\ldots,P_k}$  sign.
- for practical purposes: to allow users/the base station to transmit at optimal rate.
- it is also desirable to identify the key parameters of the system
  - in theory: to extract physical meanings
  - in theory: to identify the minimum feedback requirements
  - in practice: to minimize information feedback
  - in practice: to ease power allocation processing

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  - in practice: to ease power allocation processing

Consider a subset  $S = \{i_1, \ldots, i_{|S|}\} \subset \{1, \ldots, K\}.$ 

• With  $\mathbf{T}_k = \mathbf{U}_k \mathbf{D}_k \mathbf{U}_k^H$ ,  $\mathbf{D}_k = \text{diag}(\tau_{k1}, \dots, \tau_{kn_k})$  diagonal, the capacity-achieving matrices  $\mathbf{P}_{i_1}^{\star}, \dots, \mathbf{P}_{i_{|S|}}^{\star}$  satisfy

**(1)**  $\mathbf{P}_{k}^{*} = \mathbf{U}_{k} \mathbf{Q}_{k}^{*} \mathbf{U}_{k}^{\mathsf{H}}$ , with  $\mathbf{Q}_{k}^{*}$  diagonal; i.e. the eigenspace of  $\mathbf{P}_{k}^{*}$  is the same as the eigenspace of  $\mathbf{T}_{k}$ . **(2)** with  $\bar{\mathbf{e}}_{k}^{*} = \bar{\mathbf{e}}_{k}(-\sigma^{2}, \mathbf{P}_{k}^{*})$ , the *i*<sup>th</sup> entry  $q_{ki}^{*}$  of  $\mathbf{Q}_{k}^{*}$  satisfies

$$q_{ki}^{\star} = \left(\mu_{k} - \frac{1}{c_{k}e_{k}^{\star}\tau_{ki}}\right)^{+}$$

where the  $\mu_k$ 's are evaluated such that tr $(\mathbf{Q}_k) = P_k$ .

- an iterative water-filling method allows to retrieve the q<sup>\*</sup><sub>ki</sub>'s by successively
  - for a given set  $\mathbf{P}_{i_1}, \ldots, \mathbf{P}_{i_{|S|}}$ , evaluating  $e_{i_1}, \ldots, e_{i_{|S|}}$
  - updating the new optimal solution  $\mathbf{P}_{i_1}, \ldots, \mathbf{P}_{i_{1,S_1}}$  for this system

Iterative water-filling

Upon convergence, the iterative water-filling algorithm leads to the optimal solution.

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 P<sup>\*</sup><sub>k</sub> = U<sub>k</sub>Q<sup>\*</sup><sub>k</sub>U<sup>H</sup><sub>k</sub>, with Q<sup>\*</sup><sub>k</sub> diagonal; i.e. the eigenspace of P<sup>\*</sup><sub>k</sub> is the same as the eigenspace of T<sub>k</sub>.
 with θ<sup>\*</sup><sub>k</sub> = θ<sub>k</sub>(-σ<sup>2</sup>, P<sup>\*</sup><sub>k</sub>), the i<sup>th</sup> entry q<sup>\*</sup><sub>k1</sub> of Q<sup>\*</sup><sub>k</sub> satisfies

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$$\mathbf{q}_{ki}^{\star} = \left(\mu_{k} - \frac{1}{\mathbf{c}_{k}\mathbf{e}_{k}^{\star}\tau_{ki}}\right)^{\dagger}$$

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$$q_{ki}^{\star} = \left(\mu_{k} - \frac{1}{C_{k} e_{k}^{\star} \tau_{ki}}\right)^{+}$$

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 with ē<sup>\*</sup><sub>k</sub> = ē<sub>k</sub>(-σ<sup>2</sup>, P<sup>\*</sup><sub>k</sub>), the *i*<sup>th</sup> entry q<sup>\*</sup><sub>ki</sub> of Q<sup>\*</sup><sub>k</sub> satisfies

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Iterative water-filling

Upon convergence, the iterative water-filling algorithm leads to the optimal solution.

R. Couillet (Supélec)

29/10/2009 29 / 57

Consider the functions

$$C(\mathbf{P}_{i_{1}},\ldots,\mathbf{P}_{i_{|\mathcal{S}|}}) = \sum_{k\in\mathcal{S}}\frac{1}{N}\log\det\left(\mathbf{I}_{n_{k}}+c_{k}e_{k}\mathbf{T}_{k}\mathbf{P}_{k}\right) + \frac{1}{N}\log\det\left(\mathbf{I}_{N}+\sum_{k\in\mathcal{S}}\bar{\mathbf{e}}_{k}\mathbf{R}_{k}\right) - \sigma^{2}\sum_{k\in\mathcal{S}}\bar{\mathbf{e}}_{k}(-\sigma^{2})e_{k}(-\sigma^{2})$$

where

$$\mathbf{e}_{i} = \mathbf{e}_{i}(\mathbf{P}_{i_{1}}, \dots, \mathbf{P}_{i_{|S|}}) = \frac{1}{N} \operatorname{tr} \mathbf{T}_{i} \left( \sigma^{2} \left[ \mathbf{I}_{N} + \sum_{k \in S} \bar{\mathbf{e}}_{k} \mathbf{T}_{k} \right] \right)^{-1}$$
$$\bar{\mathbf{e}}_{i} = \bar{\mathbf{e}}_{i}(\mathbf{P}_{i_{1}}, \dots, \mathbf{P}_{i_{|S|}}) = \frac{1}{n_{i}} \operatorname{tr} \mathbf{R}_{i} \mathbf{P}_{i} \left( \sigma^{2} \left[ \mathbf{I}_{n_{i}} + c_{i} \mathbf{e}_{i}(z) \mathbf{R}_{i} \mathbf{P}_{i} \right] \right)^{-1}$$

and  $V : (\mathbf{P}_{i_1}, \dots, \mathbf{P}_{i_{|S|}}, \bar{\mathbf{e}}_{i_1}, \dots, \bar{\mathbf{e}}_{i_{|S|}}, \mathbf{e}_{i_1}, \dots, \mathbf{e}_{i_{|S|}}) \mapsto C(\mathbf{P}_{i_1}, \dots, \mathbf{P}_{i_{|S|}}).$ 

$$\frac{\partial}{\partial \mathbf{P}_{i}}\mathbf{C} = \sum_{k \in S} \frac{\partial V}{\partial \mathbf{e}_{k}} \frac{\partial \mathbf{e}_{k}}{\partial \mathbf{P}_{i}} + \frac{\partial V}{\partial \bar{\mathbf{e}}_{k}} \frac{\partial \bar{\mathbf{e}}_{k}}{\partial \mathbf{P}_{i}} + \frac{\partial V}{\partial \mathbf{P}_{i}}$$

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Consider the functions

$$C(\mathbf{P}_{i_{1}},\ldots,\mathbf{P}_{i_{|\mathcal{S}|}}) = \sum_{k\in\mathcal{S}}\frac{1}{N}\log\det\left(\mathbf{I}_{n_{k}}+c_{k}e_{k}\mathbf{T}_{k}\mathbf{P}_{k}\right) + \frac{1}{N}\log\det\left(\mathbf{I}_{N}+\sum_{k\in\mathcal{S}}\bar{\mathbf{e}}_{k}\mathbf{R}_{k}\right) - \sigma^{2}\sum_{k\in\mathcal{S}}\bar{\mathbf{e}}_{k}(-\sigma^{2})e_{k}(-\sigma^{2})$$

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$$\bar{\mathbf{e}}_{i} = \bar{\mathbf{e}}_{i}(\mathbf{P}_{i_{1}}, \dots, \mathbf{P}_{i_{|S|}}) = \frac{1}{n_{i}} \operatorname{tr} \mathbf{R}_{i} \mathbf{P}_{i} \left( \sigma^{2} \left[ \mathbf{I}_{n_{i}} + c_{i} \mathbf{e}_{i}(z) \mathbf{R}_{i} \mathbf{P}_{i} \right] \right)^{-1}$$

and  $V : (\mathbf{P}_{i_1}, \dots, \mathbf{P}_{i_{|S|}}, \bar{\mathbf{e}}_{i_1}, \dots, \bar{\mathbf{e}}_{i_{|S|}}, \mathbf{e}_{i_1}, \dots, \mathbf{e}_{i_{|S|}}) \mapsto C(\mathbf{P}_{i_1}, \dots, \mathbf{P}_{i_{|S|}}).$ • From chain rule,

$$\frac{\partial}{\partial \mathbf{P}_{i}}\mathbf{C} = \sum_{k \in \mathcal{S}} \frac{\partial V}{\partial \mathbf{e}_{k}} \frac{\partial \mathbf{e}_{k}}{\partial \mathbf{P}_{i}} + \frac{\partial V}{\partial \bar{\mathbf{e}}_{k}} \frac{\partial \bar{\mathbf{e}}_{k}}{\partial \mathbf{P}_{i}} + \frac{\partial V}{\partial \mathbf{P}_{i}}$$

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# Proof of water-filling optimality (2)

Remark that

$$\frac{\partial}{\partial \bar{\mathbf{e}}_{k}} V(\mathbf{P}_{i_{1}}, \dots, \mathbf{P}_{i_{|S|}}, \bar{\mathbf{e}}_{i_{1}}, \dots, \bar{\mathbf{e}}_{i_{|S|}}, \mathbf{e}_{i_{1}}, \dots, \mathbf{e}_{i_{|S|}}) = \frac{1}{N} \operatorname{tr} \left[ \left( \mathbf{I} + \sum_{i \in S} \bar{\mathbf{e}}_{i} \mathbf{R}_{i} \right)^{-1} \mathbf{R}_{k} \right] - \sigma^{2} \mathbf{e}_{k}$$
$$\frac{\partial}{\partial \mathbf{e}_{k}} V(\mathbf{P}_{i_{1}}, \dots, \mathbf{P}_{i_{|S|}}, \bar{\mathbf{e}}_{i_{1}}, \dots, \bar{\mathbf{e}}_{i_{|S|}}, \mathbf{e}_{i_{1}}, \dots, \mathbf{e}_{i_{|S|}}) = c_{k} \frac{1}{N} \operatorname{tr} \left[ (\mathbf{I} + c_{k} \mathbf{e}_{k} \mathbf{T}_{i} \mathbf{P}_{i})^{-1} \mathbf{T}_{k} \mathbf{P}_{k} \right] - \sigma^{2} \bar{\mathbf{e}}_{k}$$

both being null whenever, for all k,  $\mathbf{e}_k = \mathbf{e}_k(-\sigma^2, \mathbf{P}_{i_1}, \dots, \mathbf{P}_{i_{|S|}})$  and

 $\bar{\mathbf{e}}_k = \bar{\mathbf{e}}_k(-\sigma^2, \mathbf{P}_{i_1}, \dots, \mathbf{P}_{i_{|S|}})$ , which is true in particular for the unique power optimal solution  $\mathbf{P}_{i_1}^\star, \dots, \mathbf{P}_{i_{|S|}}^\star$  whenever  $\mathbf{e}_k = \mathbf{e}_k^\star$  and  $\bar{\mathbf{e}}_k = \bar{\mathbf{e}}_k^\star$ .

• When, for all k,  $e_k = e_k^*$ ,  $\bar{e}_k = \bar{e}_k^*$ , the maximum of V over the  $\mathbf{P}_k$ 's is then obtained by maximizing the expressions log det $(\mathbf{I}_{n_k} + c_k e_k^* \mathbf{T}_k \mathbf{P}_k)$  over  $\mathbf{P}_k$ .

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# Proof of water-filling optimality (2)

### Remark that

$$\frac{\partial}{\partial \bar{\mathbf{e}}_{k}} V(\mathbf{P}_{i_{1}}, \dots, \mathbf{P}_{i_{|S|}}, \bar{\mathbf{e}}_{i_{1}}, \dots, \bar{\mathbf{e}}_{i_{|S|}}, \mathbf{e}_{i_{1}}, \dots, \mathbf{e}_{i_{|S|}}) = \frac{1}{N} \operatorname{tr} \left[ \left( \mathbf{I} + \sum_{i \in S} \bar{\mathbf{e}}_{i} \mathbf{R}_{i} \right)^{-1} \mathbf{R}_{k} \right] - \sigma^{2} \mathbf{e}_{k}$$
$$\frac{\partial}{\partial \mathbf{e}_{k}} V(\mathbf{P}_{i_{1}}, \dots, \mathbf{P}_{i_{|S|}}, \bar{\mathbf{e}}_{i_{1}}, \dots, \bar{\mathbf{e}}_{i_{|S|}}, \mathbf{e}_{i_{1}}, \dots, \mathbf{e}_{i_{|S|}}) = c_{k} \frac{1}{N} \operatorname{tr} \left[ (\mathbf{I} + c_{k} \mathbf{e}_{k} \mathbf{T}_{i} \mathbf{P}_{i})^{-1} \mathbf{T}_{k} \mathbf{P}_{k} \right] - \sigma^{2} \bar{\mathbf{e}}_{k}$$

both being null whenever, for all k,  $e_k = e_k(-\sigma^2, \mathbf{P}_{i_1}, \dots, \mathbf{P}_{i_{|S|}})$  and

 $\bar{\mathbf{e}}_k = \bar{\mathbf{e}}_k(-\sigma^2, \mathbf{P}_{i_1}, \dots, \mathbf{P}_{i_{|S|}})$ , which is true in particular for the unique power optimal solution  $\mathbf{P}_{i_1}^{\star}, \dots, \mathbf{P}_{i_{|S|}}^{\star}$  whenever  $\mathbf{e}_k = \mathbf{e}_k^{\star}$  and  $\bar{\mathbf{e}}_k = \bar{\mathbf{e}}_k^{\star}$ .

When, for all k, e<sub>k</sub> = e<sup>\*</sup><sub>k</sub>, ē<sub>k</sub> = ē<sup>\*</sup><sub>k</sub>, the maximum of V over the P<sub>k</sub>'s is then obtained by maximizing the expressions log det(I<sub>nk</sub> + c<sub>k</sub>e<sup>\*</sup><sub>k</sub>T<sub>k</sub>P<sub>k</sub>) over P<sub>k</sub>.

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- deterministic equivalents do not impose any underlying convergence
- truncation and centralization lead to stronger convergence results under the form  $m_N m_N^{\circ} \xrightarrow{\text{a.s.}} 0$  instead of  $Em_N m_N^{\circ} \rightarrow 0$
- loose hypotheses on the  $R_k$ 's and  $T_k$ 's: strong antenna correlation allowed
- the **R**<sub>k</sub>'s and **T**<sub>k</sub>'s are general purpose Hermitian nonnegative, no need of a common eigenspace
- no restriction to Gaussian  $X_k$ 's for diagonal  $T_k$ 's

#### Compact expressions

Only K scalar parameters (the  $e_k$ 's) determine the behaviour of the whole system.

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# Performance of the deterministic equivalent



Figure: (Per-antenna) rate region  $C_{BC}$  for K = 2 users, theory against simulation, N = 8,  $n_1 = n_2 = 4$ , SNR = 20 dB, random transmit-receive solid angle of aperture  $\pi/2$ ,  $d_T/\lambda = 10$ ,  $d_R/\lambda = 1/4$ .

# Performance of the deterministic equivalent (2)



Figure: (Per-antenna) rate region  $C_{BC}$  for K = 2 users, N = 8,  $n_1 = n_2 = 4$ , SNR = -5 dB, random transmit-receive solid angle of aperture  $\pi/2$ ,  $d_T/\lambda = 10$ ,  $d_R/\lambda = 1/4$ . In thick line, capacity limit when  $E[ss^H] = I_N$ .

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R. Couillet, S. Wagner, M. Debbah, D. Slock, "Asymptotic analysis of linear precoding in vector broadcast channels with limited feedback"

Deterministic equivalents of sum-rate capacity for linearly precoded broadcast channels,

- accounting for base station antenna correlation, user path losses
- assuming limited channel state information

Results:

- on optimal number of users to serve
- on optimal regularization parameter
- eventually, optimal feedback time
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Figure: Left: Ergodic sum-rate vs. average SNR with  $\mathbf{R} = \mathbf{I}_{K}$ , M = 10,  $\beta = 1$ ,  $\tau^{2} = 0.1$ . Right: RZF,  $\mathbf{R} = \mathbf{I}_{M}$ ,  $\mathbf{L} = \mathbf{I}_{K}$ , M = 32,  $\beta = 1$ , simulation results are indicated by circle marks

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Stieltjes transform methods for more elaborate models

2 Kronecker models and Variance Profiles

Capacity expressions, Rate Regions

4 Touching the boundary: optimal power allocation

Case study: exchanging relevant data in large self-organized networks
 Orthogonal CDMA networks
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Case study: exchanging relevant data in large self-organized networks • Orthogonal CDMA networks

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# Before to apply the previous results, we consider first an alternative, simpler, better adapted model, which

- provides a deterministic equivalent to a model involving Haar (unitary) matrices
- uses R-, S- and  $\eta$ -transforms
- is a striking example of the feedback minimization discussed before.

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Case study: exchanging relevant data in large self-organized networks Self-Organized Clustered Networks



Figure: Self-organizing CDMA network

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Case study: exchanging relevant data in large self-organized networks Orthogonal CDMA networks
Uplink clustered CDMA networks

- Consider a set of *K* clusters, all using independently orthogonal CDMA transmissions. Each cluster is composed of *at most N* users. We wish
  - to obtain a deterministic equivalent for the achievable uplink sum-rate
  - to provide a cheap feedback solution for the network to organize itself to collectively maximize the uplink rate.
- We denote
  - $L_k = \text{diag}(\lambda_{k1}, \dots, \lambda_{kN})$  the diagonal of channel gains (inverse path losses).
  - $\mathbf{P}_k = \text{diag}(p_{k1}, \dots, p_{kN})$  the diagonal of transmit powers from the users in cell k.
  - $\mathbf{W}_k \in \mathbb{C}^{N \times N}$  the unitary CDMA code matrix used in cell *k*.
  - the received signal  $\mathbf{y} \in \mathbb{C}^N$  at the base station reads

$$\mathbf{y} = \sum_{k=1}^{K} \mathbf{W}_k \mathbf{L}_k^{\frac{1}{2}} \mathbf{P}_k^{\frac{1}{2}} \mathbf{s}_k + \mathbf{n}$$

• the sum-rate  $C(\sigma^2)$  is

$$C(\sigma^{2}) = \frac{1}{N} \log \det \left( \mathbf{I}_{N} + \frac{1}{\sigma^{2}} \sum_{k=1}^{K} \mathbf{W}_{k}(\mathbf{P}_{k}\mathbf{L}_{k})\mathbf{W}_{k}^{\mathrm{H}} \right)$$

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R. Couillet, M. Debbah, "Uplink capacity of self-organizing clustered orthogonal CDMA networks in flat fading channels", ITW 2009 Fall, Taormina, Sicily.

### Theorem

For large N, we have

$$C_N(\sigma^2) - C_N^{\circ}(\sigma^2) \to 0$$

with

$$C_{N}^{\circ}(\sigma^{2}) = \log\left(1 + \frac{1}{\sigma^{2}}\sum_{k=1}^{K}\beta_{k}\right) + \sum_{k=1}^{K}\frac{1}{N}\log\det\left(\frac{\eta}{\sigma^{2}}\mathbf{P}_{k}\mathbf{L}_{k} + \left[1 - \frac{\eta\beta_{k}}{\sigma^{2}}\right]\mathbf{I}_{N}\right)$$

where  $\beta_k$  and  $\eta$  are defined as

$$\eta = \left(1 + \frac{1}{\sigma^2} \sum_{i=1}^{K} \beta_i\right)^{-1}$$

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Case study: exchanging relevant data in large self-organized networks Orthogonal CDMA network
Proof

Instead of working with the Stieltjes transform, we use the (totally equivalent)  $\eta$ -transform. We define  $\eta_1, \ldots, \eta_K$  as

$$\eta_k(\mathbf{x}) = \int \frac{1}{1+\mathbf{x}t} \mu_k(\mathbf{d}t)$$

with  $\mu_k$  the probability distribution of  $\mathbf{P}_k \mathbf{L}_k$ . We will use the *R*-transform for further development. For each *k*, denote  $R_k$  the *R*-transform of  $\mathbf{W}_k \mathbf{L}_k \mathbf{P}_k \mathbf{W}_k^H$ , defined as

$$\eta(-\frac{1}{R(x)+\frac{1}{x}})=xR(x)+1$$

Since the  $\mathbf{W}_k$ 's are isometric and independent, they are free random variables. Hence, the *R*-transform R(x) of the sum of the individual *R*-transforms  $R_1(x), \ldots, R_K(x)$  satisfies asymptotically

$$R(x) = \sum_{k=1}^{K} R_k(x)$$

The strategy is then to use the *R*-transform as a "pivot" in the proof,

- obtain a relation of  $R_k$  as a function of the entries of  $\mathbf{P}_k \mathbf{L}_k$
- obtain an expression of the eigenvalues of  $\sum_{k=1}^{K} W_k P_k L_k W_k^H$  as a function of R

The first relation is obtained by the definition of the  $\eta$ -transform applied in  $-1/(R_k(x)+rac{1}{x})$ 

$$xR_k + 1 = \int \frac{1}{1 - \frac{t}{R_k(x) + \frac{1}{x}}} \mu_k(dt)$$

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$$\eta(-\frac{1}{R(x)+\frac{1}{x}})=xR(x)+1$$

Since the  $\mathbf{W}_k$ 's are isometric and independent, they are free random variables. Hence, the *R*-transform R(x) of the sum of the individual *R*-transforms  $R_1(x), \ldots, R_K(x)$  satisfies asymptotically

$$R(x) = \sum_{k=1}^{K} R_k(x)$$

The strategy is then to use the *R*-transform as a "pivot" in the proof,

- obtain a relation of  $R_k$  as a function of the entries of  $\mathbf{P}_k \mathbf{L}_k$
- obtain an expression of the eigenvalues of  $\sum_{k=1}^{K} \mathbf{W}_k \mathbf{P}_k \mathbf{L}_k \mathbf{W}_k^{\mathsf{H}}$  as a function of R

The first relation is obtained by the definition of the  $\eta$ -transform applied in  $-1/(R_k(x) + \frac{1}{x})$ 

$$xR_k + 1 = \int \frac{1}{1 - \frac{t}{R_k(x) + \frac{1}{x}}} \mu_k(dt)$$

## The expression

$$xR_k(x)+1=\int \frac{1}{1-\frac{t}{R_k(x)+\frac{1}{x}}}\mu_k(dt)$$

leads to

$$R_k(x) = \frac{1}{x} \int \frac{t}{R_k(x) + \frac{1}{x} - t} \mu_k(dt)$$

and, in particular, defining  $\beta_k(x) = R_k(-x\eta)$ , we have

$$\beta_k(\mathbf{x}) = \int \frac{t}{1 - \mathbf{x}\eta\beta_k + \mathbf{x}\eta t} \mu_k(dt)$$

Now, since  $R(x) = \sum_{k=1}^{K} R_k(x)$  asymptotically on *N*, using the reverse definition of the *R*-transform

$$R(-x\eta(x)) = -\frac{1}{x}(1-\frac{1}{\eta}(x))$$

we have

$$\eta(x) = \left(1 + x \sum_{k=1}^{K} R_k(-x\eta)\right)^{-1} = \left(1 + x \sum_{k=1}^{K} \beta_k\right)^{-1}$$

which completes the proof.

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The power allocation policy  $p_{kn} = p_{kn}^{\star}$  optimizing the deterministic approximation of  $C(\sigma^2)$  satisfies, for all k, n, q

$$\boldsymbol{p}_{kn}^{\star} = \left(\alpha_{k} - \frac{\sigma^{2} - \eta^{\star}\beta_{k}^{\star}}{\lambda_{kn}\eta^{\star}}\right)^{-1}$$

where  $\eta^*$ ,  $\beta_k^*$  are the respective values of  $\eta$  and  $\beta_k$  when *C* achieves its maximum, and  $\alpha_k$  is such that  $\sum_k p_{kn}^* = P_k$ .

### Lemma (Iterative Water-filling)

Upon convergence, the following algorithm converges to the optimal power allocation policy,

At initialization, for all 
$$k$$
,  $p_{kn} = \frac{P_k}{N}$ ,  $\eta = 1$ ,  $\beta_k = 1$ .  
while the  $p_{kn}$ 's have not converged do  
for  $k \in \{1, ..., K\}$  do  
Solve fixed-point equation for  $(\eta, \beta_k)$ ,  $p_{kn}$  fixed  
for  $n = 1 ..., N$  do  
Set  $p_{kn} = \left(\alpha_k - \frac{\sigma^2 - \eta\beta_k}{\lambda_{kn}\eta}\right)^+$ , with  $\alpha_k$  such that  $\sum_n p_{kn} = P_k$ .  
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Local optimization: From the formulas of η and β<sub>k</sub>, at step (t) of the iterative water-filling, we can write

• 
$$\eta^{(t)}(\mathbf{x}) = \left(\frac{1}{\eta^{(t-1)}(\mathbf{x})} + \mathbf{x}(\beta_k^{(t)} - \beta_k^{(t-1)})\right)^{-1}$$
  
•  $\beta_k^{(t)} = f(\beta_k^{(t)}, \eta^{(t)})$ 

## This is only dependent on k.

 $\Rightarrow$  Cluster k does not need to know all  $\lambda_{in}$ ,  $i \neq k$ .

- Iterative self-organized process The preceding algorithm can be rewritten such that,
  - at each time step (t), based on  $\eta^{(t-1)}$ , cell k performs self-optimization of  $\mathbf{P}_k$  and updates  $\eta^{(t-1)}$  to  $\eta^{(t)}$
  - cell k forwards  $\eta^{(t)}$  to next cell (k + 1)
  - upon convergence (not proven), this proceeds until convergence to the optimal solution (proven)

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# Case study: exchanging relevant data in large self-organized networks Orthogonal CDMA networks Self-organization in orthogonal CDMA networks



Figure: Self-organization in orthogonal CDMA network

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Figure: Self-organization in orthogonal CDMA network

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Stieltjes transform methods for more elaborate models

2 Kronecker models and Variance Profiles

3 Capacity expressions, Rate Regions

4 Touching the boundary: optimal power allocation

5

Case study: exchanging relevant data in large self-organized networks • Orthogonal CDMA networks

Spectrum sharing in multiple access channels

- Somewhat similarly as  $\eta$  for the clustered CDMA system, user *k* of a multiple-access channel can find its optimal transmit covariance matrix from the estimation of  $e_k$ .
- if *F* frequency bands are shared among the users, the MAC rate region is the set of rates  $R_1, \ldots, R_K$  such that, for any subset  $\mathcal{K} \subset \{1, \ldots, K\}$ ,

$$\sum_{k \in \mathcal{K}} R_k \leq \frac{1}{N} \sum_{f=1}^{F} \log \det \left( \mathbf{I}_N + \frac{1}{\sigma^2} \sum_{k \in \mathcal{K}} \mathbf{H}_{k,f}^{\mathsf{H}} \mathbf{P}_{k,f} \mathbf{H}_{k,f} \right)$$

• the optimal  $\mathbf{P}_{k,f}$ 's have eigenvectors aligned to the transmit correlation matrix and eigenvectors  $q_{k,f,1}, \ldots, q_{k,f,n_k}$  given by

$$q_{k,f,i} = \left(\mu_k - \frac{1}{c_k e_{k,f} t_{k,f,i}}\right)^+$$

with

$$\begin{cases} \mathbf{e}_{k,f} &= \frac{1}{N} \operatorname{tr} \mathbf{R}_{k,f} \left( \sigma^2 \left[ \mathbf{I}_N + \sum_{k' \in \mathcal{K}} \delta_{k',f} \mathbf{R}_{k',f} \right] \right)^{-1} \\ \bar{\mathbf{e}}_{k,f} &= \frac{1}{n_k} \operatorname{tr} \mathbf{T}_{k,f} \left( \sigma^2 \left[ \mathbf{I}_{n_k} + c_k \mathbf{e}_{k,f} \mathbf{P}_{k,f} \mathbf{T}_{k,f} \right] \right)^{-1} . \end{cases}$$

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Iterative water-filling is still optimal in this case.

## Spectrum sharing, alternative approaches

## Classical ways to share spectrum,

- via central entity: may be onerous and/or not possible
- game theoretical considerations: may fall in bad Nash equilibrium
- Through random matrix theory approaches, it seems that the fundamental system parameters naturally appear. In this case,
  - for given  $e_{k,1}, \ldots, e_{k,F}$ , user k can evaluate  $\bar{e}_{k,1}, \ldots, \bar{e}_{k,f}$  and optimize  $\mathbf{P}_{k,1}, \ldots, \mathbf{P}_{k,F}$
  - for given  $\bar{e}_{k,1}, \ldots, \bar{e}_{k,F}$ , the base station can evaluate  $e_{k,1}, \ldots, e_{k,f}$

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R. Couillet, H. V. Poor, M. Debbah, "Self-organized spectrum sharing in large MIMO multiple-access channels", to be submitted to ISIT 2010.

Depending on the correlation pattern at the base station, we obtain two iterative algorithms,

```
Base-station aided algorithm, in case of receive correlation
      Initialization: for all k, f, \bar{e}_{k,f} = 1. Define convergence threshold \varepsilon > 0.
      while \max_{k,f} \|\mathbf{P}_{k,f} - \mathbf{P}_{k,f}^{\star}\| > \varepsilon do
         for k \in \{1, ..., K\} do
            for f \in \{1, ..., F\} do
               The base station computes e_{k,f}
            end for
            The base station transmits (e_{k,1}, \ldots, e_{k,F}) to user k
            for f \in \{1, ..., F\} do
               Based on e_{k,f}, user k computes \mathbf{P}_{k,f}
               Based on e_{k,f} and \mathbf{P}_{k,f}, user k computes \bar{e}_{k,f}
            end for
            User k transmits (\bar{e}_{k,1}, \ldots, \bar{e}_{k,F}) to the base station
         end for
      end while
```

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## Self-organized iterative water-filling, if no correlation at the base station

```
Initialization: for all k, f, \bar{e}_{k,f} = 1. Define convergence threshold \varepsilon > 0.

while \max_{k,f} \|\mathbf{P}_{k,f} - \mathbf{P}_{k,f}^*\| > \varepsilon, do

for k \in \{1, \dots, K\} do

for f \in \{1, \dots, F\} do

Based on e_f, user k computes \mathbf{P}_{k,f}

Based on \{e_f, \mathbf{P}_{k,f}\}, user k computes \bar{e}_{k,f}

Based on \bar{e}_{k,f}, user k updates e_{k,f}

end for

User k transmits (e_{k,1}, \dots, e_{k,F}) to user k + 1 \pmod{K}

end for

end while
```

 however, proposed algorithm is sequential, time harvesting. Next step is to work on asynchronous schemes using,

- gossiping approaches
- graph theory
- coding theory

• transmission bands must be uncorrelated. Currently working on frequency selective channels.

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Case study: exchanging relevant data in large self-organized networks Spectrum sharing in multiple access channels MIMO multi-band multiple access channel



Figure: MIMO multi-band MAC





Figure: MIMO multi-band MAC



Figure: MIMO multi-band MAC



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Figure: MIMO multi-band MAC



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Figure: MIMO multi-band MAC

## Work left to be done

- generalize Stieltjes transform approaches to structured matrices
- use random matrix theory to solve open issues
  - optimal Wiener filter in broadcast channels
  - optimal feedback for communications with imperfect CSI
- decentralized network organization using random matrix theory,
  - propose efficient feedback schemes
  - prove convergence or quasi-convergence
  - develop suboptimal schemes
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