

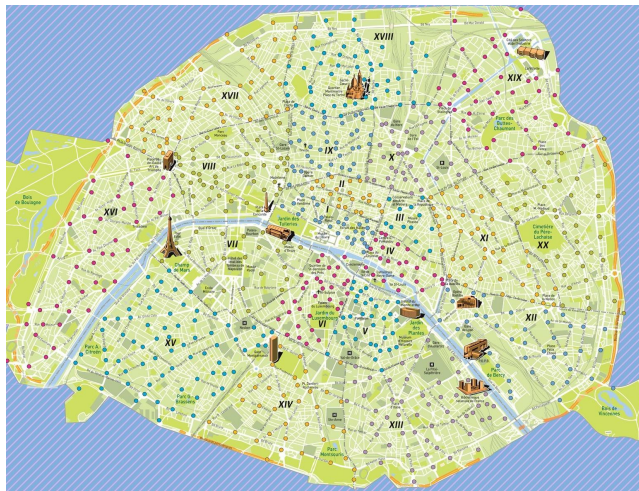
The Power of Two Choices on Graphs: the Pair-Approximation is Accurate

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Inria

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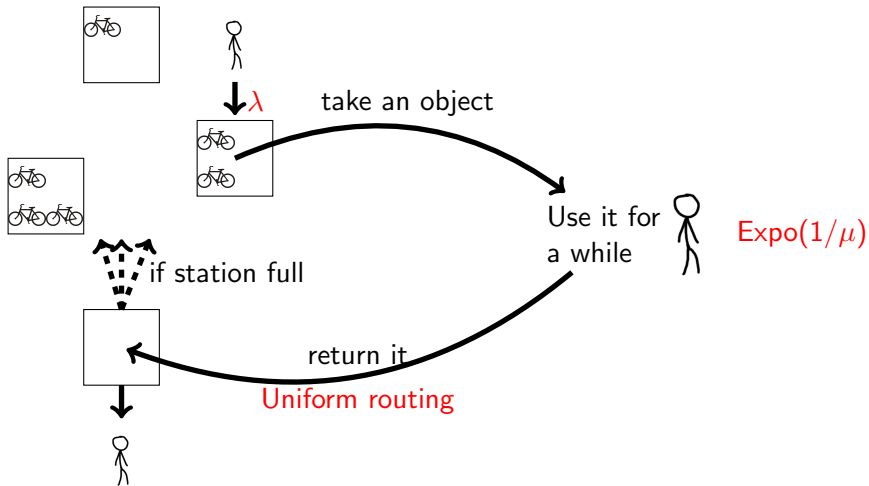
Motivating scenario is to study incentives in bike-sharing systems



- 1200 stations
- 20k bikes

Map of Velib' stations (Paris)

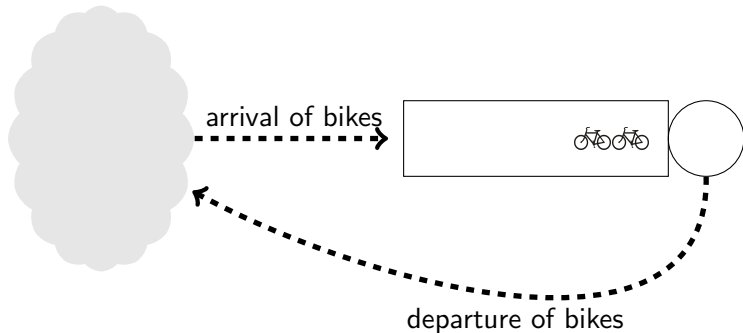
These system can be viewed as closed queuing-networks



N stations, capacity C bikes per station.

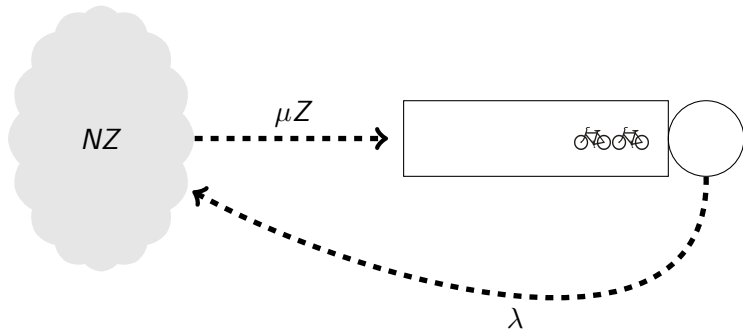
When the number of stations $N \rightarrow \infty$, we can show that the model boils down to a single (open) queue.

Moving bikes



When the number of stations $N \rightarrow \infty$, we can show that the model boils down to a single (open) queue.

Moving bikes



$i \mapsto i + 1$ at rate μZ $(i < K)$

$i \mapsto i - 1$ at rate λ $(i > 0)$

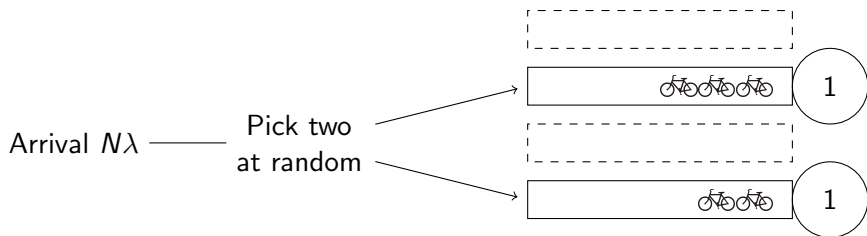
Can we improve performance?

- Even in a uniform scenario, the proportion of problematic stations (*i.e.* empty or full) is at least $1/(C + 1)$.

What if a user chooses to go to a less crowded station?

In this talk, I study a generalization of the two-choice models

- N identical servers
- Exponential service time



What happens when we restrict the choice to two neighbors?

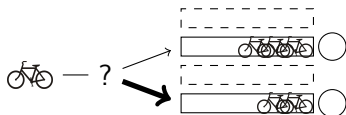
Outline

- 1 The classical two-choice model
- 2 Construction of the pair approximation equations
- 3 Numerical validation: the pair approximation is accurate!
- 4 Remarks and open questions

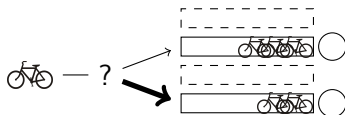
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Two-choice rule: each incoming job/bike is routed to the least loaded of two servers picked at random.



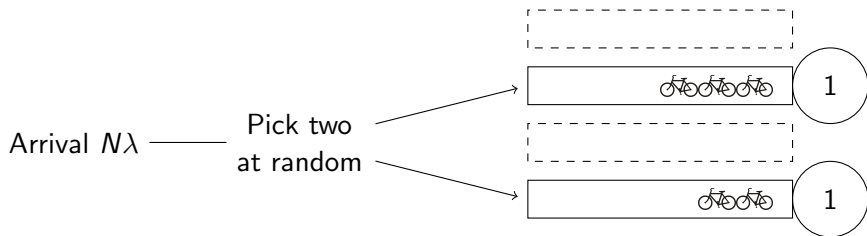
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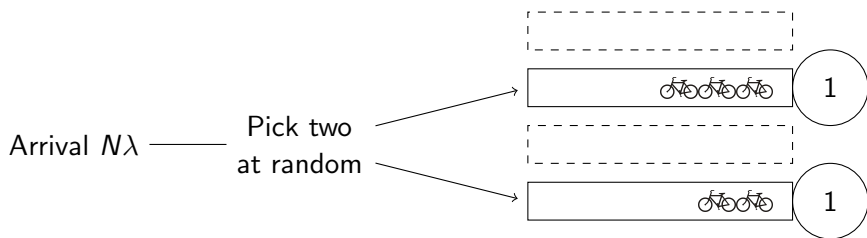
Paradigm known as “*the power of two choices*”:

- Comes from balls and bins [Azar et al. 94]:
 - ▶ Throw n balls into n bins: what is the maximal number of balls in a bin?
 - ★ $\log(n)$ if no choice
 - ★ $\log(\log(n))$ is two choices.
- Drastic improvement of service time in server farm [Vvedenskaya 96, Mitzenmacher 96]
 - ▶ $P(\#jobs \geq i) \rho^i$ (no choice)
 - ▶ $P(\#jobs \geq i) = 2^{\lambda^{i+1}-1}$ (two choices)
- Interesting advances for non-exponential service times (Bramson 2000, Ramanan 2014)

We use mean-field to solve the two-choice equations



We use mean-field to solve the two-choice equations



Let x_j be the proportion of stations with j bikes.

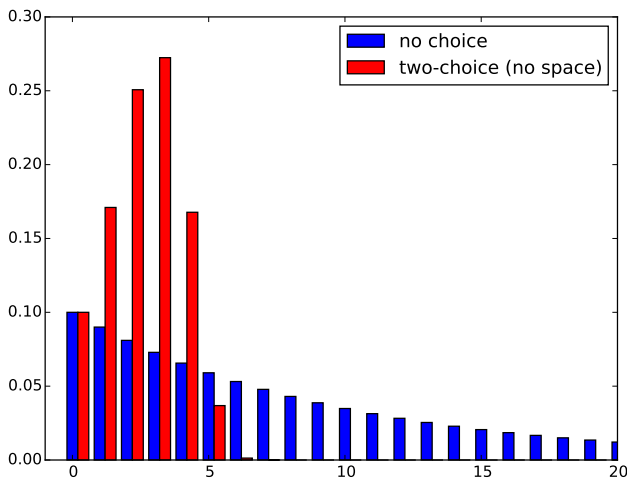
$(i \mapsto i - 1)$ at rate 1

$(i \mapsto i + 1)$ at rate $\lambda(x_i + 2 \sum_{j=i+1}^{\infty} x_j)$

Note: the rate of change of x_i has to be multiplied by x_i .

With no geometry, we can solve the equation in close-form

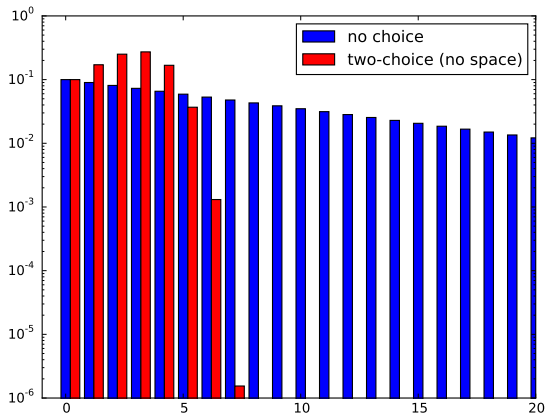
$$x_i = \lambda^{2^i} - \lambda^{2^{i+1}}$$



For bike-sharing, choosing two stations **at random**, decreases the number of problematic stations from $1/C$ to $\sqrt{C}2^{-C/2}$

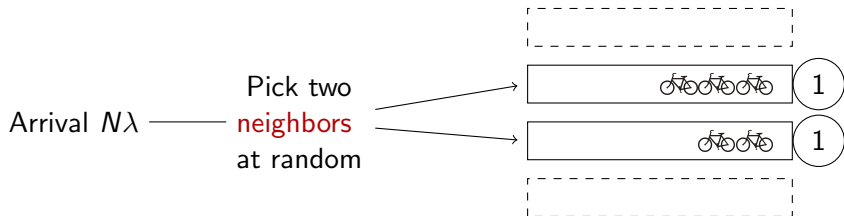
With no geometry, we can solve the equation in **close-form**

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What if we add geometry?



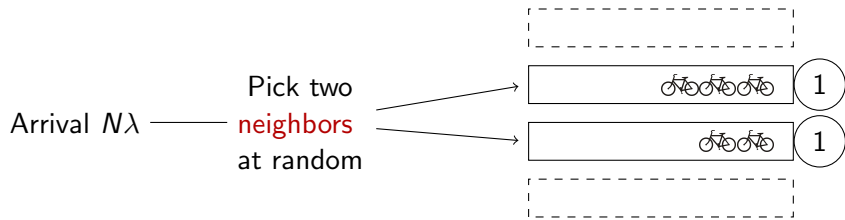
Mean field do not apply (geometry) :(.

- For balls and bins, the power of two-choice does not work (see [Kenthapadi et al. 06])
- Only numerical results?

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I consider that stations are placed on a ring



Let y_{ij} be the proportion of (ordered) pairs having (i, j) jobs.

We track the proportion of (ordered) pairs (i, j)

We focus on the transitions that modify i (equations are similar for j).

$(i, j) \mapsto (i - 1, j)$ at rate 1 *departure*

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$$(i, j) \mapsto (i - 1, j) \quad \text{at rate } 1 \quad \text{departure}$$
$$(i, j) \mapsto (i + 1, j) \quad \text{at rate } \begin{cases} \lambda & \text{if } i < j \\ \lambda/2 & \text{if } i = j \\ 0 & \text{if } i > j \end{cases} \quad \text{arrival on } (i, j)$$

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$(i, j) \mapsto (i + 1, j)$ at rate $\begin{cases} \lambda & \text{if } i < j \\ \lambda/2 & \text{if } i = j \\ 0 & \text{if } i > j \end{cases}$ *arrival on (i, j)*

$(i, j) \mapsto (i + 1, j)$ at rate $\lambda \underbrace{\left(\frac{1}{2} z_{i,i,j} + \sum_{\ell=i+1}^{\infty} z_{\ell,i,j} \right)}_{=: p_i} / y_{ij}$ *arrival on (ℓ, i) ,*

where $z_{\ell,i,j}$ is the proportion of triplets.

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where $z_{\ell,i,j}$ is the proportion of triplets.

The pair approximation is $z_{\ell,i,j} \approx y_{\ell,i} y_{i,j} / x_i$ or:

$$p_i \approx \frac{Y_{ii}/2 + \sum_{k>i} Y_{ki}}{\sum_k Y_{ki}}.$$

The pair approximation ODE is composed of four terms

Y_{ij} decreases at rate:

μY_{ij} (departure)

$\lambda Y_{i,j}$ (arrival on (i,j) when $(i < j)$)

$\lambda Y_{i,j}/2$ (arrival on (i,i) when $i = j$)

$\lambda p_i Y_{i,j}$ (arrival on neighbor)

The pair approximation ODE is composed of four terms

Y_{ij} decreases at rate:

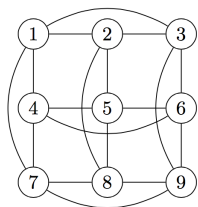
$$\mu Y_{ij} \quad (\textit{departure})$$

$$\lambda Y_{i,j} \frac{2}{k} \quad (\textit{arrival on } (i,j) \textit{ when } (i < j))$$

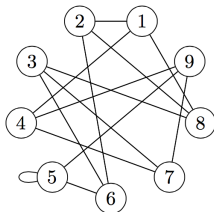
$$\lambda Y_{i,j} / k \quad (\textit{arrival on } (i,i) \textit{ when } i = j)$$

$$\lambda p_i Y_{i,j} 2 \frac{k-1}{k} \quad (\textit{arrival on neighbor})$$

The equations can be generalized to graph with fixed degree $k \geq 2$:

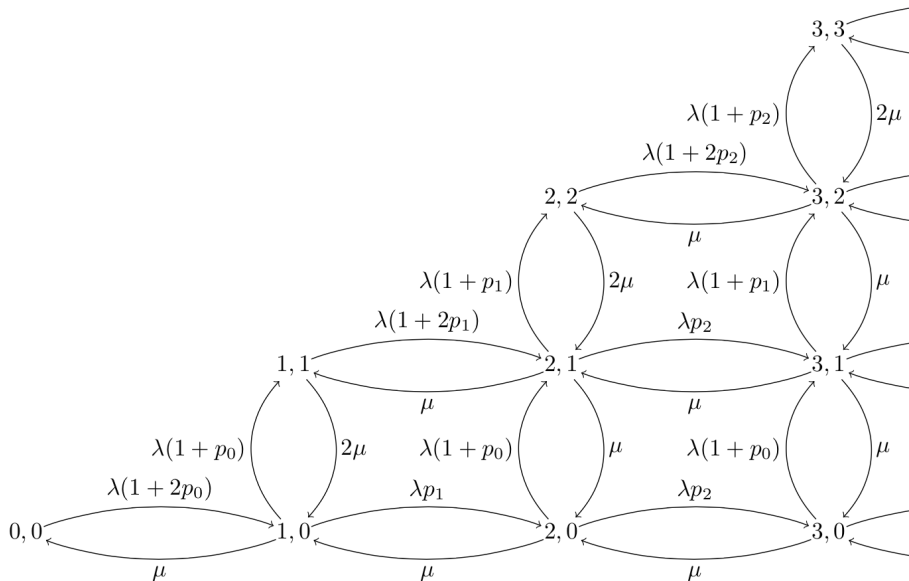


(a) 2D torus



(b) Fixed degree $k = 3$

There is no (known) close-form for the fixed point...



...but we can simulate the ODE!

```
for i in range(0,N):
    xi = sum(y[i]);
    if (xi>0):
        p[i] = (sum (y[i][i+1:N]) + y[i][i]/2) / xi;
for i in range(0,N):
    for j in range(0,N):
        if (i>0):
            derivative[i][j] += lam*p[i-1]*y[i-1][j] - mu*y[i][j];
            derivative[i-1][j] += -lam*p[i-1]*y[i-1][j] + mu*y[i][j];
            if (i<=j):
                derivative[i][j] += lam*y[i-1][j];
                derivative[i-1][j] += -lam*y[i-1][j];
            elif(i-1==j):
                derivative[i][j] += lam*y[i-1][j]/2;
                derivative[i-1][j] += -lam*y[i-1][j]/2;
        if (j>0):
            derivative[i][j] += lam*p[j-1]*y[i][j-1] - mu*y[i][j];
            derivative[i][j-1] += -lam*p[j-1]*y[i][j-1] + mu*y[i][j];
            if (j<=i):
                derivative[i][j] += lam*y[i][j-1];
                derivative[i][j-1] += -lam*y[i][j-1];
            elif (i==j-1):
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```

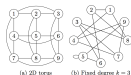
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I compare numerically four values

Simu

Simulation



Pair-approx

Fixed point of the pair-approximation ODE
ODE of size 100×100 .

```
for i in 1:100
  for j in 1:100
    M[i,j] = 100 * (1 - M[i,j]) * M[i,j] + M[i,j] * M[i,j] / 100
  end
end
for i in 1:100
  for j in 1:100
    M[i,j] = 100 * (1 - M[i,j]) * M[i,j] + M[i,j] * M[i,j] / 100
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  end
end
```

No choice

Theory for the M/M/1 queue

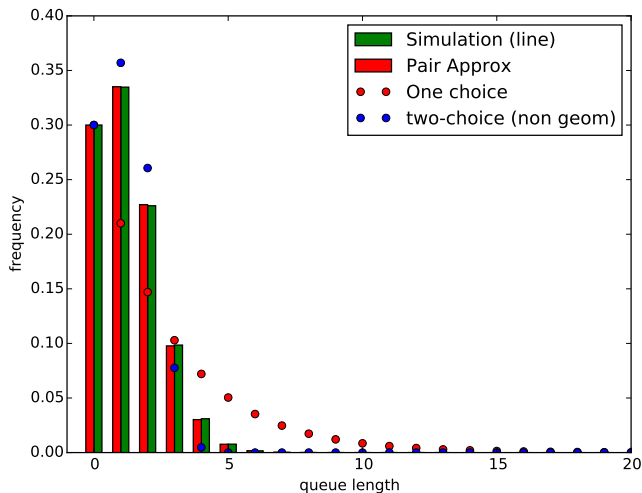
$$x_i = (1 - \lambda)\lambda^i$$

Two-choice

Theory (without geometry)

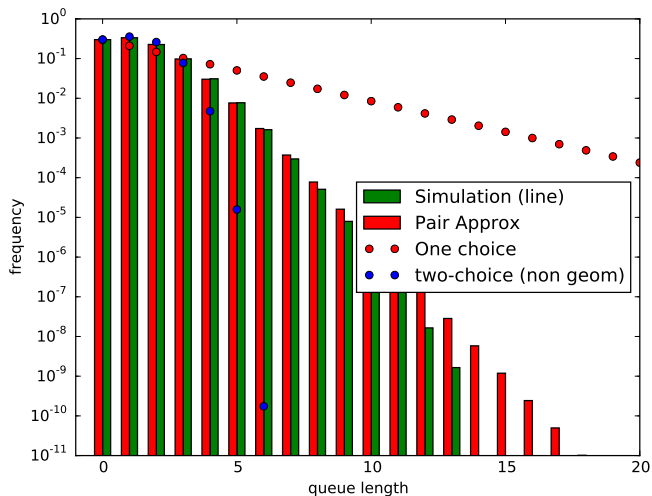
$$x_i = \lambda^{2^i} - \lambda^{2^{i+1}}$$

The fixed point of the pair-approximation is close to the system's steady-state (checked for $\lambda = .5$ to $\lambda = .99$)



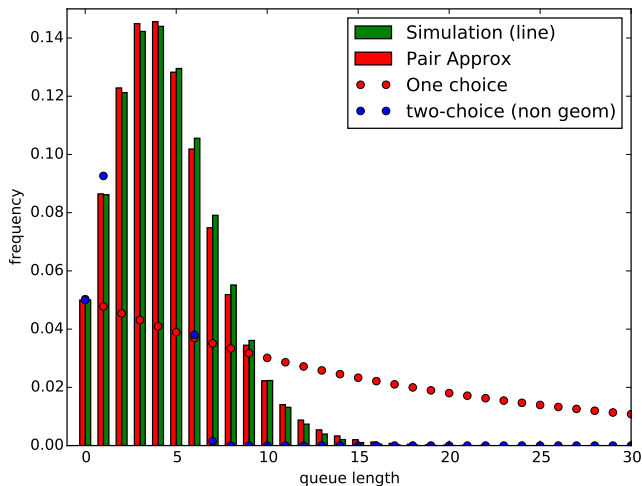
$$\lambda = 0.7$$

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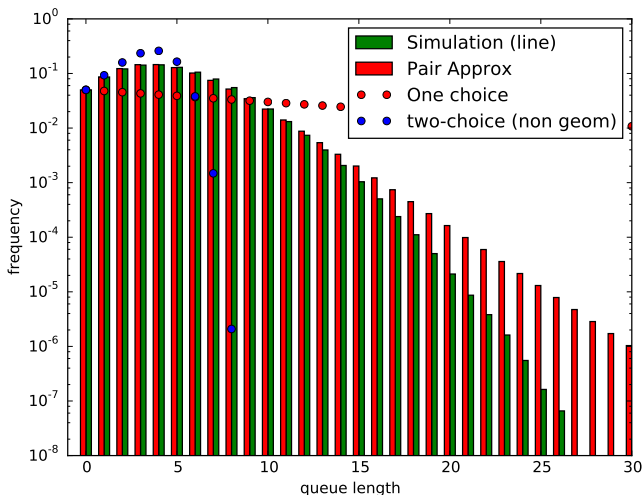
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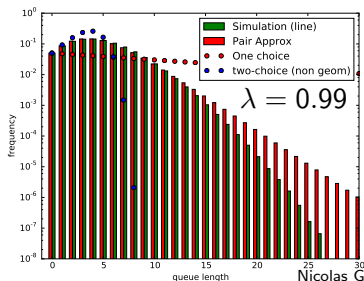
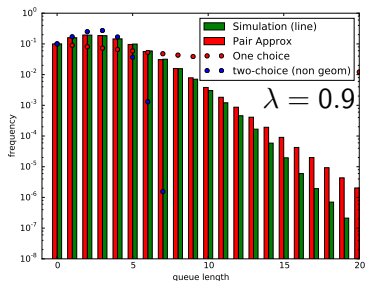
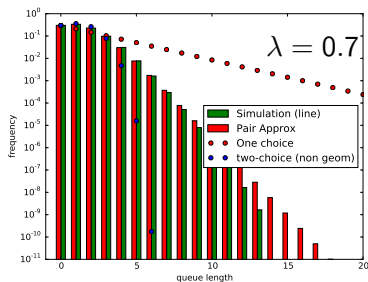
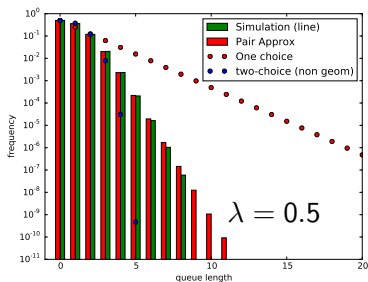
$\lambda = 0.95$

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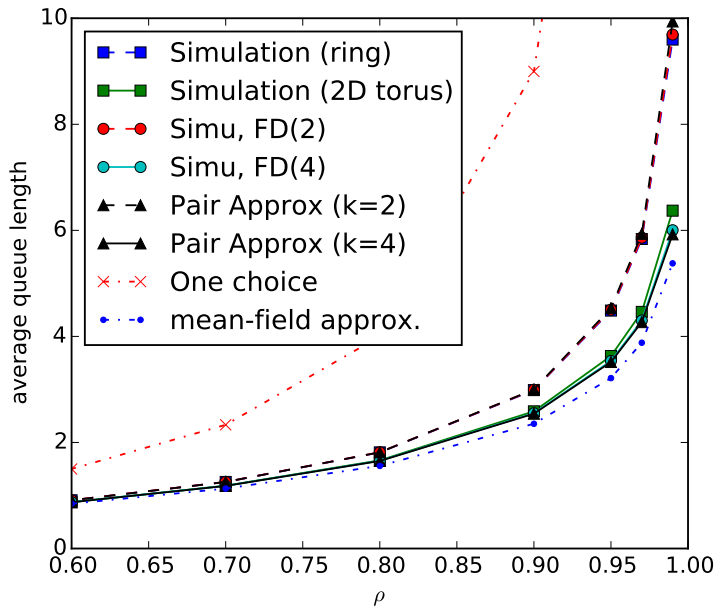


$\lambda = 0.95$

The fixed point of the pair-approximation is close to the system's steady-state (checked for $\lambda = .5$ to $\lambda = .99$)



The (steady-state) average queue length is very well approximated by pair-approximation



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Recap

I study a spatial version of the two-choice model.

- Motivation comes from bike-sharing systems.
- Without geometry, the problem can be solved by using a mean-field approximation (one-choice: $\sum_{j \geq i} x_j = \lambda^i$, two-choice, $\sum_{j \geq i} x_j = \lambda^{2^i - 1}$).
- Pair-approximation:
 - ▶ How to construct the equations
 - ▶ Numerically, they are very accurate

Open questions / Future work

- Why does it work so well? ?
(in some other cases, e.g., SIR, it does not)
- Is the pair approximation exact? No
- For a torus, is the decrease doubly-exponential? No?
(recall: two-choice without geometry: $\sum_{j \geq i} x_j = \lambda^{2^i - 1}$)
- Can we solve analytically the PA equations (or bound?) ?
- Can we add heterogeneity? seems OK
- Non-exponential service time? (maybe later)